

SAMUEL (SAM) MILHAVEN

Curriculum Vitae

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ACADEMIC AND RESEARCH INTERESTS

I am broadly interested in legged/mobile robots, terrain navigation, autonomous vehicles, and control systems. I have conducted research into autonomous motorcycles navigating on uneven terrain, which culminated in physical prototypes that can be used to test safety systems for human riders. In addition to motorcycle research, I'm currently working on a passively grasping foot to allow quadruped platforms to traverse narrow paths.

EDUCATION

Northeastern University , Boston, MA	<i>Expected Spring 2026</i>
M.S. in Robotics with a concentration in Mechanical Engineering	
GPA: 3.95	
Areas of Interest: Legged/mobile robots, terrain navigation, autonomous vehicles, and control systems	
Lafayette College , Easton, PA	<i>2024</i>
B.S. in Integrative Engineering with a concentration in Robotics	
GPA: 3.40 Honors in Integrative Engineering	
Undergraduate Honors Thesis: Autonomous Motorcycle Stabilization on Uneven Terrain	

RESEARCH EXPERIENCE

Honors Thesis Scholar , Mechanical Engineering, Northeastern University	<i>September 2025-present</i>
Advisor: Dr. Alireza Ramezani, Kaushik Venkatesh Krishnamurthy	
Graduate Research Assistant , SiliconSynapse Lab, Boston, MA	<i>November 2024-present</i>
Advisor: Kaushik Venkatesh Krishnamurthy, Dr. Alireza Ramezani	
Independent Researcher	<i>September 2024-present</i>
Collaborator: Dr. Alexander Brown	
Simulating the Effects of a Virtual Motorcycle Passenger on Vehicle Motion and Rider Effort	
Combined steer and rider lean control for a low-cost, small-scale self-balancing motorcycle	
Honors Thesis Scholar , Integrative Engineering, Lafayette College	<i>August 2023- May 2024</i>
Advisors: Dr. Alexander Brown, Dr. Connor Ligeikis, Dr. Michael Nees, Dr. Brett Utter	
Autonomous Motorcycle Stabilization on Uneven Terrain	
Research Assistant , DRIVe Lab, Easton, PA	<i>January 2023- May 2024</i>
Advisor: Dr. Alexander Brown	

CONFERENCE PUBLICATIONS

S. Milhaven, W. Li, R. McClosky, and A. Brown. Simulating the Effects of a Virtual Motorcycle Passenger on Vehicle Motion and Rider Effort, IEEE Intelligent Vehicles Symposium, June 2025

ACCEPTED PUBLICATIONS

S. Milhaven, W. Li, and A. Brown. Combined steer and rider lean control for a low-cost, small-scale self-balancing motorcycle, IEEE Intelligent Vehicles Symposium, June 2026

AWARDS, HONORS, AND GRANTS

Daniel O'Neil Award (\$3,000) *Fall 2023*
• Research funding award given by Lafayette College's Department of Engineering

PROFESSIONAL EXPERIENCE

Robotics R&D Intern, HITT Contracting Inc., Falls Church, VA *Summer 2025*
Collaborated on the Virtual Superintendent project by designing and installing a custom Spot payload that included a 6-DOF arm and tablet to assist in telecommunication on-site.

SKILLS

Proficient in Python, ROS 2, Arduino, Matlab, Simulink, Java, Autodesk Fusion360, Solidworks, Webots (3D physics-based simulator), Control Systems, Drive Systems, Wiring/Soldering, PCB Design, Rapid-prototyping/FDM printing, Machining, and GD&T

PROFESSIONAL MEMBERSHIP

IEEE Young Professionals, Member *2024-present*
IEEE, Student member *2022-present*

REFERENCES

Dr. Alireza Ramezani
Associate Professor of Electrical and Computer Engineering
Northeastern University
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Dr. Alexander Brown
Assistant Department Head of Mechanical Engineering
Associate Professor of Mechanical Engineering
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Dr. Jenn Stroud Rossmann
William Jeffers Dean of Engineering
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