

# SAMUEL (SAM) MILHAVEN

## Curriculum Vitae

15 Edgerly Rd, Apt 26, Boston, MA, 02115 | (781)-985-7247 | [samilhaven@gmail.com](mailto:samilhaven@gmail.com) | [milhaves.github.io](https://milhaves.github.io)

### ACADEMIC AND RESEARCH INTERESTS

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I am broadly interested in autonomous vehicles/mobile robotics, terrain navigation, and control systems. I have conducted research into autonomous motorcycles navigating on uneven terrain, which culminated in physical prototypes that can be used to test safety systems for human riders. In addition to motorcycle research, I'm currently working on a passively grasping foot to allow quadruped platforms to traverse narrow paths.

### EDUCATION

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**Northeastern University**, Boston, MA *Expected Spring 2026*

M.S. in Robotics with a concentration in Mechanical Engineering

**GPA:** 3.92

**Areas of Interest:** Autonomous vehicles/mobile robots, terrain navigation, and control systems

**Lafayette College**, Easton, PA *2024*

B.S. in Integrative Engineering with a concentration in Robotics

**GPA:** 3.40 | Honors in Integrative Engineering

**Undergraduate Honors Thesis:** Autonomous Motorcycle Stabilization on Uneven Terrain

### RESEARCH EXPERIENCE

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**Honors Thesis Scholar**, Mechanical Engineering, Northeastern University *September 2025-present*

**Advisor:** Dr. Alireza Ramezani, Kaushik Venkatesh Krishnamurthy

**Graduate Research Assistant**, SiliconSynapse Lab, Boston, MA *November 2024-present*

**Advisor:** Kaushik Venkatesh Krishnamurthy, Dr. Alireza Ramezani

**Independent Researcher** *September 2024-present*

**Collaborator:** Dr. Alexander Brown

Simulating the Effects of a Virtual Motorcycle Passenger on Vehicle Motion and Rider Effort

**Honors Thesis Scholar**, Integrative Engineering, Lafayette College *August 2023- May 2024*

**Advisors:** Dr. Alexander Brown, Dr. Connor Ligeikis, Dr. Michael Nees, Dr. Brett Utter

Autonomous Motorcycle Stabilization on Uneven Terrain

**Research Assistant**, DRIVe Lab, Easton, PA *January 2023- May 2024*

**Advisor:** Dr. Alexander Brown

### CONFERENCE PUBLICATIONS

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**S. Milhaven**, W. Li, R. McClosky, and A. Brown. Simulating the Effects of a Virtual Motorcycle Passenger on Vehicle Motion and Rider Effort, IEEE Intelligent Vehicles Symposium, June 22-25, 2025

## AWARDS, HONORS, AND GRANTS

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### **Daniel O'Neil Award (\$3,000)**

*Fall 2023*

- Research funding award given by Lafayette College's Department of Engineering

## PROFESSIONAL EXPERIENCE

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### **Robotics R&D Intern**, HITT Contracting Inc., Falls Church, VA

*Summer 2025*

Collaborated on the Virtual Superintendent project by designing and installing a custom Spot payload that included a 6-DOF arm and tablet to assist in telecommunication on-site.

## SKILLS

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Proficient in Python, ROS 2, Arduino, Matlab, Simulink, Java, Autodesk Fusion360, Solidworks, Webots (3D physics-based simulator), Control Systems, Drive Systems, Wiring/Soldering, PCB Design, Rapid-prototyping/FDM printing, and GD&T

## PROFESSIONAL MEMBERSHIP

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IEEE Young Professionals, Member

*2024-present*

ASME, Student member

*2022-present*

IEEE, Student member

*2022-present*

## REFERENCES

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Dr. Alireza Ramezani

Associate Professor of Electrical and Computer Engineering

Northeastern University

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Dr. Alexander Brown

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Dr. Jenn Stroud Rossmann

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