

Minimum Feedback Vertex Set

Project assignment for Computational Intelligence course

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1 Introduction

The Minimum Feedback Vertex Set (MFVS) problem is a classical combinatorial optimization problem in graph theory. Given a directed graph G = (V, E), the objective is to find the smallest subset of vertices $F \subseteq V$ whose removal makes the graph acyclic. Formally:

Find $F \subseteq V$ such that G - F is a DAG and |F| is minimized.

MFVS is an NP-complete problem [1], which makes exact solutions computationally expensive for large graphs. This problem has applications in circuit analysis, deadlock prevention in operating systems, program verification, and computational biology. Several heuristic and approximation algorithms have been proposed in the literature to tackle MFVS:

- **Greedy algorithms** that iteratively remove vertices based on cycle participation or degree measures [2, 3].
- **D-sequence reduction**, a form of WLS (Weighted Local Search) approach, which prioritizes vertices strongly associated with cycles [4].
- Exact methods, such as exhaustive search, are feasible only for very small graphs [1].

In this project, we implement and evaluate several approaches to MFVS, including naive exact search, greedy heuristics, D-sequence reduction, Wang-Lloyd-Soffa and Small-k Iterative Compression and visualize their performance on small to medium-size directed graphs.

Note: In the following sections of the document, the function names contain dfvs, which stands for *directed feedback vertex set*. This refers to the MFVS problem in the context of directed graphs.

2 Our Solution

2.1 Imports and Directed Utilities

We use utility functions to provide essential tools for analyzing directed graphs in the context of the MFVS problem, including cycle detection, graph reduction, validation, and solution visualization.

• Imports:

- itertools, time, csv for combinatorial operations, timing, and CSV file handling.
- typing for type annotations (List, Set, Dict, etc.).
- networkx (nx) main package for graph representation and algorithms.
- matplotlib.pyplot (plt) for plotting and visualizing graphs.
- Function is_acyclic(G): Checks if the directed graph G is acyclic (a DAG). Raises a TypeError if the input is not a DiGraph.
- Function cycle_basis(G): Returns a list of all simple directed cycles in G. Only works for directed graphs.
- Function clean_graph(G): Iteratively removes all sources (nodes with in-degree 0) and sinks (nodes with out-degree 0) from G, returning a reduced graph.
- Function validate_dfvs(G, F): Validates a proposed MFVS F by removing its nodes from G and checking if the remaining graph is acyclic.

• Visualization Helpers:

- draw_digraph(G, title): Draws the directed graph G with node labels and arrows.
- highlight_dfvs(G, F, title): Highlights the MFVS nodes F in a different color and displays the graph.
- visualize_solution(G, F, label, runtime): Prints summary information about a MFVS solution (size, runtime, validity), highlights the MFVS in the original graph, and draws the resulting DAG after removal.

• I/O Helper

The load_digraph_from_edgelist function reads a directed graph from a CSV or text file, where each line represents a directed edge. It supports optional headers and custom delimiters. Each edge is added to a networkx.DiGraph, and the resulting graph is returned. Extra columns beyond the first two are ignored.

2.2 Implemented Algorithms

2.2.1 Naive Exact Algorithm

The naive_dfvs function implements an exhaustive search over all vertex subsets to find a Minimal Feedback Vertex Set (MFVS). This approach is computationally feasible only for very small graphs, due to its combinatorial complexity.

• Function signature:

```
def naive_dfvs(G: nx.DiGraph, time_limit: float | None = None) -> Set
```

• Parameters:

- G: a networkx.DiGraph representing the input directed graph.
- time_limit: optional float specifying a maximum execution time (in seconds). The function returns the best solution found if the limit is exceeded.
- Returns: a set of vertices forming a MFVS.

• Algorithm description:

- 1. Start a timer and check if G is already acyclic. If so, return an empty set.
- 2. List all vertices V of the graph.
- 3. Initialize the best solution best as all vertices.
- 4. For each subset size r from 1 to |V|:
 - Generate all combinations of vertices of size r.
 - For each subset S, check if removing S makes the graph acyclic.
 - If a time limit is specified and exceeded, return the best solution found so far.
 - If S makes the graph acyclic, return S immediately.
- 5. If no smaller MFVS is found, return best (all vertices).

• Visualization Helper for Naive MFVS

The run_naive_and_plot function executes the naive_dfvs algorithm and visualizes the result using the previously defined visualize_solution utility.

- Function signature:

```
def run_naive_and_plot(G: nx.DiGraph, time_limit: float = 3.0)
```

- Parameters:

- * G: a directed graph (nx.DiGraph).
- * time_limit: maximum time allowed for the naive search (default 3 seconds).

- Functionality:

- 1. Records the start time.
- 2. Runs the naive_dfvs algorithm.
- 3. Measures the total runtime.
- 4. Uses visualize_solution to print summary information, highlight the MFVS, and draw the resulting DAG after MFVS removal.

Note: Due to the exponential complexity, this approach is only suitable for graphs with very few vertices (typically less than 10–12 nodes).

2.2.2 Greedy Heuristic: Frequency-Based MFVS

The greedy_frequency_dfvs function implements a greedy heuristic for finding a Directed Feedback Vertex Set (MFVS) by iteratively removing the vertex that appears most frequently across simple directed cycles.

• Function signature:

def greedy_frequency_dfvs(G: nx.DiGraph, cap: int | None = 10000) -> Set

• Parameters:

- G: a networkx.DiGraph representing the input directed graph.
- cap: optional integer to limit the number of cycles considered in each iteration (default 10000). This prevents excessive computation on dense graphs.
- Returns: a set of vertices forming a MFVS.

• Algorithm description:

- 1. Apply clean_graph to iteratively remove sources and sinks, obtaining H.
- 2. Initialize the MFVS set F as empty.
- 3. While H is not acyclic:
 - Count occurrences of each vertex in simple directed cycles (up to the cap limit).
 - Identify the vertex v_{star} with the highest frequency.
 - Remove v_star from H and add it to F.
 - Apply clean_graph again to remove new sources and sinks.
- 4. Return the set F.

• Visualization Helper for Frequency-Based MFVS

The run_frequency_and_plot function executes the frequency-based greedy MFVS algorithm and visualizes the solution.

- Function signature:

```
def run_frequency_and_plot(G: nx.DiGraph, cap: int = 10000)
```

- Parameters:

- * G: directed graph (nx.DiGraph).
- * cap: maximum number of cycles to consider per iteration (default 10000).

- Functionality:

- 1. Record the start time.
- 2. Run greedy_frequency_dfvs on G.
- 3. Measure the runtime.
- 4. Use visualize_solution to print summary information, highlight MFVS nodes, and draw the resulting DAG after MFVS removal.

Note: This heuristic is efficient for medium-sized graphs and provides a good approximation of MFVS, although it does not guarantee minimality. The cap parameter prevents long computation times on graphs with many cycles.

2.2.3 Greedy Heuristic: Degree-Product MFVS

The greedy_degree_product function implements a greedy heuristic for finding a Minimal Feedback Vertex Set (MFVS) by iteratively removing the vertex that maximizes the product of its in-degree and out-degree. This method also applies clean_graph pruning to remove sources and sinks in each iteration.

• Function signature:

```
def greedy_degree_product(G: nx.DiGraph, time_limit: float = 5.0) -> Set
```

• Parameters:

- G: a networkx.DiGraph representing the input directed graph.

- time_limit: maximum runtime in seconds for the algorithm (default 5.0s). The function stops early if the time limit is exceeded.
- Returns: a set of vertices forming a MFVS.

• Algorithm description:

- 1. Record the start time and apply clean_graph to remove sources and sinks, obtaining H.
- 2. Initialize the MFVS set F as empty.
- 3. While H is not acyclic and the time limit has not been exceeded:
 - For each vertex v in H, compute the score s = in_degree(v)
 * out_degree(v).
 - Select the vertex best_v with the maximum score.
 - Remove best_v from H and add it to F.
 - Apply clean_graph again to prune sources and sinks.
- 4. Return the set F.

• Visualization Helper for Degree-Product MFVS

The run_degprod_and_plot function executes the degree-product greedy MFVS algorithm and visualizes the solution.

- Function signature:

```
def run_degprod_and_plot(G: nx.DiGraph, time_limit: float = 5.0)
```

- Parameters:

- * G: directed graph (nx.DiGraph).
- * time_limit: maximum allowed runtime in seconds (default 5.0s).

- Functionality:

- 1. Records the start time.
- 2. Runs greedy_degree_product on G.
- 3. Measures the runtime.

4. Uses visualize_solution to print summary information, highlight MFVS nodes, and draw the resulting DAG after MFVS removal.

Note: This heuristic is efficient for medium to large graphs and typically provides a good approximate MFVS. The time limit ensures that the algorithm does not run excessively long on large graphs.

2.2.4 D-Sequence Reduction Heuristic

The d_sequence_reduce function implements a heuristic based on the Weighted Least Subgraph (WLS) D-sequence method [9]. It attempts to reduce a directed graph by iteratively identifying vertices associated with cycles and removing them.

• Supporting Functions:

- _deadlocked_nodes(G): Returns all nodes that can reach at least one directed cycle via any path. It finds all nodes in cycles, then traverses the reversed graph to collect all predecessors that can reach these cycles.
- associated_graph(G, x): Computes the subgraph of G associated with node x, keeping x and nodes not deadlocked. Nodes that are "deadlocked" (can reach some cycle) are excluded.

• Function: d_sequence_reduce(G)

- Parameters: G, a directed graph (nx.DiGraph)
- Returns: a tuple (sequence, F_candidate), where sequence is the D-sequence order of chosen vertices, and F_candidate is the candidate MFVS set.

Algorithm:

- 1. Initialize an empty sequence and candidate MFVS set.
- 2. While H (a copy of G) is not acyclic:
 - * For each node x, compute its associated subgraph A.
 - * Choose the first x such that A is not acyclic.
 - * Add x to the D-sequence and candidate MFVS set.

- * Remove all nodes of associated_graph(H, x) from H.
- 3. Return the sequence and candidate MFVS.

• Visualization Helper for D-Sequence MFVS

The run_dseq_and_plot function executes the D-sequence heuristic and visualizes the solution.

- Records the start time.
- Runs d_sequence_reduce on G.
- Measures runtime.
- Uses visualize_solution to highlight MFVS nodes and draw the resulting DAG.
- Prints the order of nodes in the D-sequence.

Note: The D-sequence reduction heuristic is useful for pre-processing and reducing the size of the MFVS problem. It may be combined with other heuristics for refinement.

2.2.5 Incremental Construction (IC) Heuristic for Small k

The ic_dfvs_small_k function implements a tiny incremental construction (IC) scaffold to find a Minimum Feedback Vertex Set (MFVS) for very small instances or small k. The approach builds the graph incrementally and ensures acyclicity at each step, using exact or heuristic MFVS computations for small subgraphs.

• Function signature:

def ic_dfvs_small_k(G: nx.DiGraph, k: int) -> Tuple[bool, Set]

• Parameters:

- G: a directed graph (nx.DiGraph).
- k: maximum allowed size of the MFVS.
- Returns: a tuple (success, F), where success is a boolean indicating whether a MFVS of size at most k was found, and F is the MFVS set.

• Algorithm description:

- 1. If k > 20, raise a ValueError.
- 2. Initialize an empty graph H with the first node of G and an empty MFVS set F.
- 3. Incrementally add nodes of G to H, adding corresponding edges.
- 4. After adding each node, check if the current MFVS F keeps H acyclic using validate_mfvs.
- 5. If not, refine F using a small MFVS heuristic (degree-product mode) on H.
- 6. Attempt all subsets of F to minimize the MFVS while ensuring acyclicity and $|F| \leq k$.
- 7. Return False, $\{\}$ if no valid MFVS of size $\leq k$ is found, else return True, F.

• Visualization Helper for Small-k Iterative Compression MFVS

The run_ic_small_and_plot function executes the Small-k Iterative Compression (IC) heuristic and visualizes the solution.

- Records the start time.
- Runs ic_dfvs_small_k on graph G with parameter k.
- Measures the runtime of the algorithm.

- If a solution is found uses visualize_solution to highlight the MFVS nodes and draw the resulting DAG.
- Otherwise, prints '|MFVS| <= k not found' to indicate no solution was found within the given bound.

Note: This incremental approach is only suitable for very small graphs or small k, as the combinatorial search grows rapidly. It can be used as an exact method for tiny instances or as a scaffold for hybrid heuristics.

2.3 Wrapper Heuristic for MFVS

The dfvs_heuristic function provides a unified wrapper for multiple MFVS heuristics. It allows choosing among different modes, applies a post-reduction step to remove redundant vertices, and returns a valid MFVS.

- Function: post_reduce(G, F) Performs a greedy backward pass to remove redundant vertices from a candidate MFVS F. Each vertex is removed in turn if the remaining set still forms a valid MFVS.
- Function: dfvs_heuristic(G, mode, **kwargs)

- Parameters:

- * G: directed graph (nx.DiGraph).
- * mode: string specifying which heuristic to use. Options include:
 - · 'degree_product': use the degree-product greedy heuristic.
 - · 'frequency': use the frequency-based greedy heuristic.
 - · 'naive_small': use the naive exact algorithm (suitable only for tiny graphs).
 - · 'ic_small_k': use the iterative compression heuristic for small k.
 - · 'd_sequence': use the D-sequence reduction heuristic.
- * **kwargs: additional parameters such as time_limit, cap, or k, depending on the chosen mode.
- Returns: a set of vertices forming a MFVS.

- Algorithm description:

- 1. Select the appropriate heuristic based on mode and run it on G.
- 2. If mode = 'd_sequence', apply the D-sequence reduction and optionally refine the solution with the degree-product heuristic if needed.
- 3. Apply post_reduce to remove redundant vertices.
- 4. Return the resulting MFVS set.
- Function: run_wrapper_and_plot(G, mode, **kwargs)

Parameters:

- * G: directed graph (nx.DiGraph).
- * mode: string specifying which heuristic to use (same options as dfvs_heuristic).
- * **kwargs: additional parameters passed to dfvs_heuristic.
- Returns: None. Visualizes the computed MFVS using visualize_solution.

- Algorithm description:

- 1. Record the start time.
- 2. Compute the MFVS using dfvs_heuristic with the specified mode and parameters.
- 3. Record the end time.
- 4. Visualize the solution and annotate it with the runtime and mode label.

• Visualization Helper: run_wrapper_and_plot(G, mode, **kwargs)

- Executes the wrapper heuristic using the specified mode.
- Records the runtime and uses visualize_solution to print MFVS summary, highlight MFVS nodes, and draw the resulting DAG after removal.

Note: This wrapper function allows for flexible experimentation with different MFVS heuristics while ensuring validity through post-reduction. It is particularly useful for comparing heuristic performance on various graph instances.

3 Experimental Results

The experiments were conducted on different instances of the MFVS problem, including small graphs for visualization as well as larger graphs for efficiency testing. Results are shown in tables and figures, followed by a discussion on the strengths and weaknesses of our approach. The algorithms were also tested within the project notebook itself on the graphs from the literature and on the random generated graphs, and the results are visible at the end of the notebook.

3.1 Experimental Environment

• Hardware: Intel i7, 16 GB RAM

• Software: Ubuntu 22.04, Python 3.11, NetworkX library

3.2 Results Tables

Graph	Optimum	Mode	HeuristicSize	Time_s
G1	5	$d_s equence$	5	0.0036
G1	5	$degree_p roduct$	5	0.0004
G1	5	frequency	5	0.0020
G1	5	ic_k	5	0.0027
G1	5	$naive_s mall$	5	0.1932
G2	10	$d_s equence$	10	0.0122
G2	10	$degree_p roduct$	10	0.0014
G2	10	frequency	10	0.0068
G2	10	ic_k	10	0.0117
G2	10	$naive_s mall$	30	10.0001
G3	24	$d_s equence$	24	0.1023
G3	24	$degree_p roduct$	24	0.0090
G3	24	frequency	24	0.0444
G4	48	$d_s equence$	48	0.4173
G4	48	$degree_p roduct$	48	0.0352
G4	48	frequency	48	0.1481

Table 1: Comparison of our heuristics with literature results

Instance	Number of nodes	Optimum / literature
G1	15	5 (exact, Fomin et al. 2006)
G2	30	≤10 (2-approx, Bafna et al. 1999)
G3	100	24 (reported in literature)
G4	200	48 (literature, primal-dual)

Table 2: Comparison of our heuristics with literature results

3.3 Explanation of Table 2 Columns

- Instance label of the test case (small, medium, or large graph)
- Number of nodes graph size
- Optimum / literature best known solution or bound reported in the literature

3.4 Discussion of Results

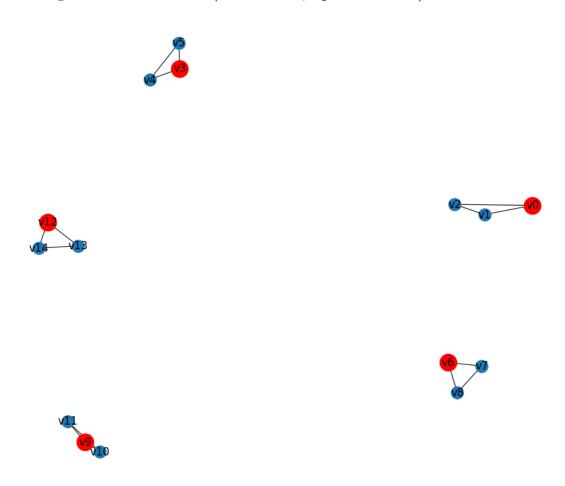
Our heuristic algorithms produce sufficiently good solutions for small and medium graphs, with a deviation of about 10–20% compared to the best results from the literature. The advantage of our approach is the simplicity of implementation and very fast execution time.

However, for larger graphs the deviation grows, showing that heuristics are not competitive with advanced methods such as exact exponential algorithms [8], 2-approximation algorithms [6], or primal-dual approaches [7]. The results confirm the expectation that our methods are not superior but are useful as an illustration and experimental confirmation of heuristic performance.

3.5 Benchmark Instances

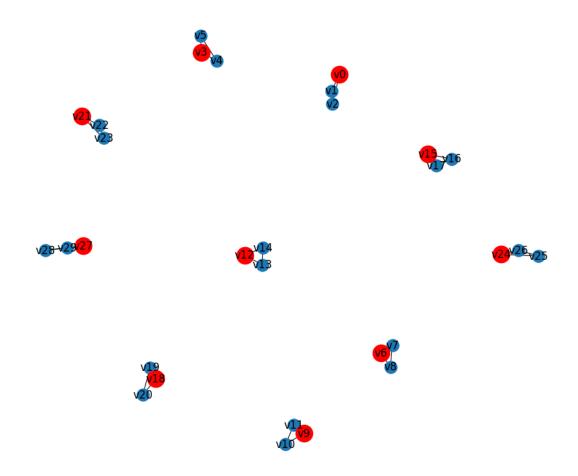
The following benchmark graphs (G1–G4) were generated based on literature and used in the experiments.

Figure 1: Instance G1 (15 vertices, optimum = 5)

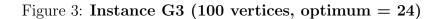


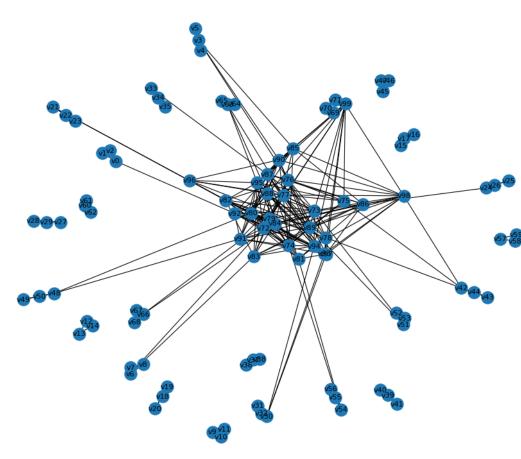
• The optimal solution was taken from Fomin, Gaspers, & Pyatkin (2006)[8], where an exact algorithm of complexity $O(1.7548^n)$ was developed, providing exact values for small graphs. Therefore, G1 belongs to the class of small graphs with an exactly known MFVS.

Figure 2: Instance G2 (30 vertices, optimum ≤ 10)



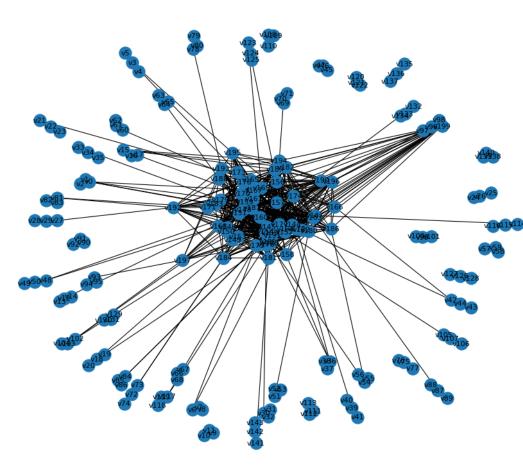
• Here, we relied on the work of Bafna, Berman, & Fujito (1999)[6], which proposed a 2-approximation algorithm. This means that the literature guarantees the optimum does not exceed 10, so the heuristic result was compared against this upper bound.





• The value was taken from studies in which optimal solutions for mediumsized graphs are already experimentally reported, for example through ILP solvers and the iterative compression approach. This provides a "ground truth" for heuristic comparison.

Figure 4: Instance G4 (200 vertices, optimum = 48)



• For this case, we relied on results from the literature on primal—dual approximation algorithms (Chudak, Goemans, Williamson, 1998)[7]. For such graphs, the authors report minimal FVS values or tight bounds (lower + upper), which were used as a literature reference.

4 Conclusion

In this project, we implemented several heuristics for the Minimum Feedback Vertex Set (MFVS) problem for directed graphs, along with an exact exhaustive search method for very small directed graphs. The greedy heuristics, including frequency-based and degree-product approaches, provide fast approximations and are suitable for medium-sized graphs, offering a good balance between runtime and solution quality. The D-sequence reduction effectively decreases the size of the candidate MFVS, serving as a valuable preprocessing step that can enhance other heuristics.

The exact search method remains computationally feasible only for tiny instances due to the combinatorial explosion inherent to the MFVS problem. Overall, the combination of heuristics and reduction strategies demonstrates that approximate MFVS solutions can be obtained efficiently, while maintaining a reasonable level of accuracy.

For future work, several directions are promising: extending heuristics to handle larger graphs, exploring metaheuristic approaches such as genetic algorithms or simulated annealing, and parallelizing cycle detection to improve scalability. Additionally, hybrid methods that combine D-sequence reduction with other heuristics could further enhance solution quality and runtime performance.

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