





HOEFFDING DECOMPOSITION, REVISITED

AND A GENERALIZATION TO DEPENDENT INPUTS

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SIAM Conference on Uncertainty Quantification

Society for Industrial and Applied Mathematics - Trieste, Italy.

March 1st, 2024

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Classical Hoeffding's decomposition: Unique decomposition $G(X) = \sum_{A \in \mathcal{P}_D} G_A(X_A)$ for any square-integrable G(X), where the inputs X are **mutually independent**.

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- Non-perfect <u>functional</u> dependence.
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However... Achieving this result requires an unusual methodological journey.

<u>In this talk:</u> Mix the fields of **probability theory** and **functional analysis**, to **generalize Hoeffding's decomposition to dependent inputs**.

More context

We're not the first to have worked on this generalization.

(see, e.g., Rabitz and Aliş (1999), Peccati (2004), Hooker (2007), Kuo et al. (2009), and Hart and Gremaud (2018))

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<u>Our approach:</u> Understand the relationships between these subspaces of \mathbb{L}^2 when the inputs are **not mutually independent**.

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A measurable mapping from Ω to a cartesian product of Polish spaces $E = X_{i \in D} E_i$.

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 ${}^{\text{\tiny LSP}}\sigma_\emptyset$ is the ${}^{\text{\tiny LSP}}$ -trivial σ -algebra (it contains **every** null event of ${\cal F}$).

Proposition (Resnick 2014). If an \mathbb{R} -valued random variable is σ_{\emptyset} -measurable, it is **constant a.e.**

Definition (Lebesgue space). Let $\mathcal{G} \subset \mathcal{F}$ be a sub- σ -algebra. Denote by $\mathbb{L}^2(\mathcal{G})$ the **Lebesgue space** containing every **real-valued random variables**, which are \mathcal{G} -measurable, and, if $Y \in \mathbb{L}^2(\sigma_{\mathcal{G}})$

$$\mathbb{E}\left[Y^2\right] = \int_{\Omega} Y(\omega)^2 d\mathbb{P}\left(\omega\right) < \infty.$$

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ight\} _{A\in\mathcal{P}_{D}}$ are closed subspace of $\mathbb{L}^{2}\left(\sigma_{X}\right)$.

How are these subspaces related to each other?

Functional dependence

First, we need to control the functional dependence between the inputs.

Otherwise, the subspaces $\mathbb{L}^2(\sigma_A)$ cannot be distinct.

Assumption 1 (Non-perfect functional dependence).

Suppose that:

- $\sigma_{\emptyset} \subset \sigma_i$, i = 1, ..., d (inputs are not constant).
- For $B \subset A$, $\sigma_B \subset \sigma_A$ (inputs add information).
- For every $A, B \in \mathcal{P}_D$, $A \neq B$,

$$\sigma_A \cap \sigma_B = \sigma_{A \cap B}$$
.

Proposition. Suppose that Assumption 1 hold.

Then, for any $A, B \in \mathcal{P}_D$ such that $A \cap B \notin \{A, B\}$, there is no mapping T such that

$$X_B = T(X_A)$$
 a.e.

In other words, if Assumption 1 holds, then the inputs cannot be functions of each other.

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Theorem (Malliavin 1995, Chapter 3). Let X and Y be two random elements. Then:

$$X \perp \!\!\! \perp Y \iff \forall f(X) \in \mathbb{L}^2_0\left(\sigma_X\right), \ \forall g(Y) \in \mathbb{L}^2_0\left(\sigma_Y\right), \quad \mathbb{E}\left[f(X), g(Y)\right] = 0,$$

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To do that:

Definition (Friedrichs' angle (Friedrichs 1937)). Let M, N be **closed** subspaces of a Hilbert space H. The cosine of Friedrichs' angle is defined as

$$c\left(M,N\right):=\sup\left\{\left|\left\langle x,y\right\rangle\right|:\begin{cases}x\in M\cap\left(M\cap N\right)^{\perp},\|x\|\leq1\\y\in N\cap\left(M\cap N\right)^{\perp},\|y\|\leq1\end{cases}\right\},$$

where the orthogonal complement is taken w.r.t. to H.

Assumptions

Definition (Feshchenko matrix). Let Δ be the $(2^d \times 2^d)$, symmetric **set-indexed** matrix, defined elementwise, $\forall A, B \in \mathcal{P}_D$ as

$$\Delta_{AB} = egin{cases} 1 & ext{if } A = B; \ -c\left(\mathbb{L}^2\left(\sigma_A\right), \mathbb{L}^2\left(\sigma_B\right)
ight) & ext{otherwise}. \end{cases}$$

 \triangle can be seen as a "generalization" of **precision matrices**.

Its name comes from the (amazing) work of Ivan Feshchenko (2020).

Why is this matrix interesting?

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Our second assumption

Assumption 2 (Non-degenerate stochastic dependence). Δ is definite-positive.

Direct-sum decompositions

Definition (Direct-sum decomposition). Let W_1, \ldots, W_d be vector subspaces of a vector space W. W is said to admit a **direct-sum decomposition**, denoted:

$$W = \bigoplus_{i=1}^d W_i,$$

if any element $w \in W$ can be written **uniquely** as a sum of elements of the W_i .

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Hence, a Hoeffding-like decomposition of a black-box model entails finding a direct-sum decomposition for $\mathbb{L}^2(\sigma_X)$, i.e., writing

$$\mathbb{L}^{2}\left(\sigma_{X}\right)=\bigoplus_{A\in\mathcal{P}_{D}}V_{A},$$

where the V_A are subspaces that we need to characterize.

Main result

Theorem . Under Assumptions 1 and 2, for every $A \in \mathcal{P}_D$, one has that

$$\mathbb{L}^{2}\left(\sigma_{A}\right)=\bigoplus_{B\in\mathcal{P}_{A}}V_{B}.$$

where $V_{\emptyset}=\mathbb{L}^{2}\left(\sigma_{\emptyset}
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$$V_B = \left[\frac{1}{C \in \mathcal{P}_B, C \neq B} V_C \right]^{\perp_B},$$

where \perp_B denotes the orthogonal complement in $\mathbb{L}^2(\sigma_B)$.

Corollary (Orthocanonical decomposition). Under Assumptions 1 and 2, any $G(X) \in \mathbb{L}^2(\sigma_X)$ can be **uniquely decomposed** as

$$G(X) = \sum_{A \in \mathcal{P}_D} G_A(X_A),$$

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where each $G_A(X_A) \in V_A$.

Intuition behind the result: One input

One input:

- 1. Let $i \in D$, and fix $\mathbb{L}^2(\sigma_i)$ as the ambient space.
- 2. We have that $V_{\emptyset} := \mathbb{L}^{2}\left(\sigma_{\emptyset}\right)$ is a closed subspace of $\mathbb{L}^{2}\left(\sigma_{i}\right)$ (thus it is **complemented**).
- 3. Denote $V_i = [V_{\emptyset}]^{\perp_i}$, the orthogonal complement of V_{\emptyset} in \mathbb{L}^2 (σ_i) .
- 4. One has that $\mathbb{L}^2(\sigma_i) = V_\emptyset \oplus V_i$.
- 5. Since V_{\emptyset} only contains constants, $V_i = \mathbb{L}^2_0\left(\sigma_i\right)$.

In other words, we just showed that any $f(X_i) \in \mathbb{L}^2(\sigma_i)$ can be written as

$$f(X_i) = \underbrace{\mathbb{E}\left[f(X_i)\right]}_{\in V_\emptyset} + \underbrace{\mathbb{E}\left[f(X_i) - \mathbb{E}\left[f(X_i)\right]\right]}_{\in V_i}.$$

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And note that we can do this for any $i \in D$.

Intuition behind the result: Two inputs

Two inputs:

- 1. Let $i, j \in D$, and fix $\mathbb{L}^2(\sigma_{ij})$ as the ambient space.
- 2. We have that $\mathbb{L}^{2}\left(\sigma_{i}\right)$ and $\mathbb{L}^{2}\left(\sigma_{j}\right)$ are **closed subspaces of** $\mathbb{L}^{2}\left(\sigma_{ij}\right)$.
- 3. Assumptions 1 and 2 imply that $\mathbb{L}^2(\sigma_i) + \mathbb{L}^2(\sigma_j)$ is closed in $\mathbb{L}^2(\sigma_{ij})$ (thus it is complemented).
- 4. Notice (previous step) that $\mathbb{L}^2(\sigma_i) + \mathbb{L}^2(\sigma_j) = V_\emptyset + V_i + V_j$.
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And note that we can do this for any pair $i, j \in D$.

In essence, we "centered" a bivariate function from its "univariate and constant parts".

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And we can continue the same induction up to d inputs.

Projectors

Recall that for any $G(X) \in \mathbb{L}^2(\sigma_X)$, we have

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Oblique projections

Denote the operator

$$Q_A: \mathbb{L}^2\left(\sigma_X
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 Q_A is the (canonical) **oblique projection** onto V_A , parallel to $\bigoplus_{B \in \mathcal{P}_D: B \neq A} V_A$.

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Orthogonal projections

Denote the projector

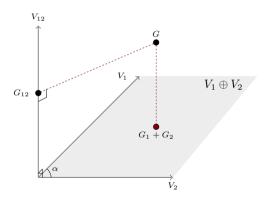
$$P_A: \mathbb{L}^2\left(\sigma_X
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the **orthogonal projection** onto V_A .

Illustration : $\mathbb{L}_0^2(\sigma_{12})$

Hence, for any $G(X) \in \mathbb{L}^2\left(\sigma_X\right)$, one has that, $\forall A \in \mathcal{P}_D$

$$G_A(X_A) = Q_A(G(X)).$$



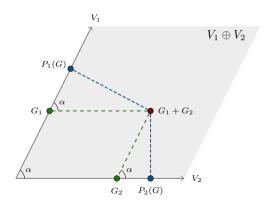
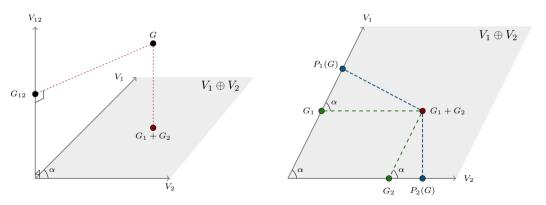


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The oblique projection Q_A usually differ from the oblique projections P_A

Variance decomposition

We propose two complementary approaches for decomposing $\mathbb{V}\left(\mathcal{G}(X)\right)$.

Variance decomposition

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Organic variance decomposition: separate pure interaction effects to dependence effects. The dependence structure of X is unwanted, and one wishes to study its effects.

<u>Canonical variance decomposition:</u> the dependence structure of *X* is **inherent in the** <u>uncertainty modeling</u> of the studied phenomenon. It amounts to quantify **structural** and <u>correlative</u> effects.

Organic variance decomposition: pure interaction

The notion of pure interaction is intrinsically linked with the notion of mutual independence.

Let $\widetilde{X} = (\widetilde{X}_1, \dots, \widetilde{X}_d)^{\top}$ be the random vector such that

 $\widetilde{X}_i \stackrel{d}{=} X_i$, and \widetilde{X} is mutually independent.

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Definition (Pure interaction). For every $A \in \mathcal{P}_D$, define the **pure interaction of** X_A **on** G(X) as

$$S_A = rac{\mathbb{V}\left(P_A(G(\widetilde{X}))
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This approach **strongly resembles the "independent Sobol' indices"** proposed by Mara, Tarantola, and Annoni (2015).

(see, also, Lebrun and Dutfoy (2009a, 2009b))

Recall that **usually,** $P_A(G(X))$ **and** $Q_A(G(X))$ **differ**. In fact,

Proposition. Under Assumptions 1 and 2,

$$P_A(G(X)) = Q_A(G(X))$$
 a.s. $\forall A \in \mathcal{P}_D \iff X$ is mutually independent.

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Proposition. Under Assumptions 1 and 2,

$$S_A^D = 0, \forall A \in \mathcal{P}_D, \iff X \text{ is mutually independent.}$$

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Open question: What do they sum up to ?...

Probably some interesting multivariate dependence measure!

Canonical variance decomposition

The structural effects represent the variance of each of the $G_A(X_A)$. It amounts to perform a **covariance decomposition** (Hart and Gremaud 2018; Da Veiga et al. 2021).

Definition (Structural effects). For every $A \in \mathcal{P}_D$, define the **structural effects of** X_A **on** G(X) as

$$S_A^U = \mathbb{V}(G_A(X_A)).$$

The **correlative effects** represent the part of variance that is due to the correlation between the $G_A(X_A)$.

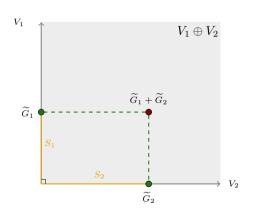
Definition (Correlative effects). For every $A \in \mathcal{P}_D$, define the correlative effects of X_A on G(X) as

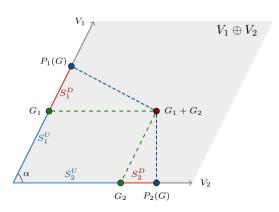
$$S_A^C = \operatorname{Cov}\left(G_A(X_A), \sum_{B \in \mathcal{P}_D: B \neq A} G_B(X_B)\right).$$

Variance decomposition: Intuition



Structural and dependence effects





Conclusion

Main take-aways:

- Hoeffding-like decomposition of function with dependent inputs is achievable under reasonable assumptions.
- Mixing probability, functional analysis (and combinatorics) lead to an interesting framework for studying multivariate stochastic problems.
- We can define meaningful (i.e., intuitive) decompositions of quantities of interest, which intrinsically encompasses the dependence between the inputs.
- We proposed candidates to separate and quantify pure interaction from dependence effects.

Perspective

Main challenge: Estimation.

• We haven't found an off-the-shelf method to estimate these oblique projections...

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A few perspectives:

- Links with already-established results (e.g., on copulas).
- Non \mathbb{R} -valued output.
- Many methodological questions that seemed unreachable so far, but appear approachable using this framework.

Checkout our pre-print!

To go further + illustrations (HAL/ResearchGate/arXiv)

Understanding black-box models with dependent inputs through a generalization of Hoeffding's decomposition

Marouane II Idrissi $^{a,b,c,e},$ Nicolas Bousquet $^{a,b,d},$ Fabrice Gamboa c, Bertrand Iooss $^{a,b,c},$ Jean-Michel Loubes c

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THANK YOU FOR YOUR ATTENTION!

ANY QUESTIONS?

Example: Two Bernoulli inputs

Let $E = \{0, 1\}^2$, and let $X = (X_1, X_2)$, where

$$X_1 \sim \mathcal{B}\left(\mathbf{q_1}\right), \quad \text{and } X_2 \sim \mathcal{B}\left(\mathbf{q_2}\right).$$

The joint law of X can be express using three parameters:

$$p_{00}=1- extbf{q}_1- extbf{q}_2+
ho, \quad p_{01}= extbf{q}_2-
ho, \quad p_{10}= extbf{q}_1-
ho, \quad p_{11}=
ho$$

where $p_{ij} = \mathbb{P}(\{X_1 = i\} \cap \{X_2 = j\}).$

Any function $G:\{0,1\}^2 \to \mathbb{R}$ can be expressed as the vector $G=(G_{00},G_{01},G_{10},G_{11})^{\top}$.

Each value $G_{ij} = G(i,j)$, can be observed with probability p_{ij} .

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Each value $G_{ij} = G(i,j)$, can be observed with probability p_{ij} .

In this case, we can compute everything analytically.

It requires to solving 13 equations with 13 unknowns*.

Feshchenko matrix and the Fréchet bounds

For the **Feshchenko matrix** Δ to be definite positive, one has that:

$$\max\left\{0,q_1q_2-\sqrt{q_1q_2(1-q_1)(1-q_2)}\right\}<\rho<\min\left\{1,q_1q_2-\sqrt{q_1q_2(1-q_1)(1-q_2)}\right\}.$$

However, the classical Fréchet bounds for ρ for bivariate Bernoulli random variables (Joe 1997, p.210) are equal to

$$\max \{0, q_1 + q_2 - 1\} \le \rho \le \min \{q1, q2\},\,$$

and are more restrictive than the previous ones.

ho strictly contained in the Fréchet bounds \implies Assumptions 1 and 2 hold.

Our decomposition hold for virtually any dependence structure between two Bernoullis.

More projectors

Recall that:

- Q_A is the oblique projection onto V_A .
- P_A is the **orthogonal projection** onto V_A .

But what about projections onto the subspaces $\left\{\mathbb{L}^{2}\left(\sigma_{A}\right)\right\}_{A\in\mathcal{P}_{D}}$?

• (Canonical) oblique projection onto $\mathbb{L}^2(\sigma_A)$:

$$\mathbb{M}_A: \mathbb{L}^2\left(\sigma_X
ight)
ightarrow \mathbb{L}^2\left(\sigma_X
ight) \ G(X) \mapsto \sum_{B \in \mathcal{P}_A} G_B(X_B)$$

• Orthogonal projection onto $\mathbb{L}^2\left(\sigma_A\right)$:

$$\mathbb{E}_A : \mathbb{L}^2(\sigma_X) \to \mathbb{L}^2(\sigma_X)$$
, such that $\operatorname{Ran}(\mathbb{E}_A) = \mathbb{L}^2(\sigma_A)$ and $\operatorname{Ker}(P_A) = \mathbb{L}^2(\sigma_A)^{\perp}$, a.k.a the conditional expectation w.r.t. to X_A (i.e., $\mathbb{E}[\cdot \mid X_A]$).

Is it possible to express the projections Q_A using \mathbb{M}_A ?

Generalized Möbius inversion

Yes, because we're working on the power-set \mathcal{P}_D !

Corollary (Möbius inversion on power-sets (Rota 1964)). Let $D = \{1, \dots, d\}$. For any two set functions:

$$f: \mathcal{P}_D \to \mathbb{A}, \quad g: \mathcal{P}_D \to \mathbb{A},$$

where ${\mathbb A}$ is an **abelian group**, the following equivalence holds:

$$f(A) = \sum_{B \in \mathcal{P}_A} g(B), \quad \forall A \in \mathcal{P}_D \quad \Longleftrightarrow \quad g(A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A| - |B|} f(B), \quad \forall A \in \mathcal{P}_D.$$

In our case, we have, by definition of the oblique projection onto $\mathbb{L}^2(\sigma_A)$, that

$$\mathbb{M}_A(G(X)) = \sum_{B \in \mathcal{P}_A} G_B(X_B), \quad \forall A \in \mathcal{P}_D,$$

which is equivalent to

$$G_A(X_A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A|-|B|} \mathbb{M}_B(G(X)), \quad \forall A \in \mathcal{P}_D.$$

(This is what we call the "model-centric" approach)

Generalized Hoeffding decomposition

If the inputs are mutually independent, from Hoeffding (1948), we have that:

$$G_A(X_A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A|-|B|} \mathbb{E} [G(X) \mid X_B], \quad \forall A \in \mathcal{P}_D.$$

In our approach, under Assumptions 1 and 2, we have that:

$$G_A(X_A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A|-|B|} \underline{\mathbb{M}}_B(G(X)), \quad \forall A \in \mathcal{P}_D.$$

In addition:

Proposition. Under Assumptions 1 and 2,

$$\mathbb{E}\left[G(X)\mid X_A\right]=\mathbb{M}_A(G(X)) \text{ a.s. }, \forall A\in\mathcal{P}_D \quad \Longleftrightarrow \quad X \text{ is mutually independent.}$$

Our approach actually generalizes Hoeffding's decomposition!