

System

consistent

inconsistent

1 ∞

approx

AR

Normal Eqⁿ

Pseudoinv



lecture notes

linear equation: $a_1x_1 + a_2x_2 + \dots + a_nx_n = b$

linear system: m eqns in n unknowns

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

\vdots

\vdots

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

can have
0 or 1 or only
many
solutions

no of soln \rightarrow 1, ∞

homogeneous system: all $b_i = 0$

\downarrow always consistent

trivial solution: $x_1 = 0, x_2 = 0, \dots, x_n = 0$

Ques

1. Is the system consistent (does soln exist?)
2. If soln exists, is it the only one? (is soln unique?)

EROs: elementary row operations (on matrices)

pivot: first non-zero element of a row

row echelon: all-zero rows should be at the bottom of the matrix, and every pivot should be on the right of the pivot in the previous row

- reduced row echelon: (RRE) ↗ all that + every pivot should be part of a column that has only zeros (not including the pivot)
- gaussian elimination: transform to row echelon
- gaussian jordan: — " — to reduced — " —

pivot perspective

(1) $m = n$ $m = \text{no. of eqn.}, n = \text{no. of rows.}$
 \therefore square matrix (order $m \times n$)

(2) non-homogeneous system

RREF (f = form) of augmented matrix

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 & \alpha \\ 0 & 1 & 0 & \beta \\ 0 & 0 & 1 & \gamma \end{bmatrix}}_{\begin{matrix} x & y & z & b \end{matrix}} \begin{matrix} \longrightarrow x = \alpha \\ \longrightarrow y = \beta \\ \longrightarrow z = \gamma \end{matrix} \Rightarrow \text{unique soln}$$

every column except the last is a pivot column

RREF

$$\begin{bmatrix} 1 & 0 & 0 & \alpha=0 \\ 0 & 1 & 0 & \beta=0 \\ 0 & 0 & 0 & \gamma=1 \end{bmatrix} \rightarrow 0x + 0y + 0z = 1 \quad \begin{matrix} \text{pivot in last colm} \\ \uparrow \\ \text{no solution} \end{matrix}$$

if $\gamma = 0$, ∞ soln \Rightarrow last colm and some other col has no pivot

lams notes

- linear equation of n variables :

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

conditions : a_i, b are constants and not all 0

- linear system of m equations in n unknowns

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

\vdots

\vdots

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

→ if all b 's = 0, the system is homogeneous

- a solution of a linear system in n unknowns x_1, x_2, \dots, x_n is a sequence of n numbers s_1, s_2, \dots, s_n for which every substitution results in a true statement.

- consistent system : at least 1 solution

inconsistent system : no solutions

- linear systems have zero, one or infinite solutions

of 2 unknowns

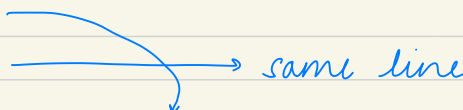
is this a condition?

parallel

once intersecting (skew)

same line

HOMOGENEOUS SYSTEM

- always consistent i.e. the values = 0 \rightarrow "trivial solution"
- if other solutions exist, they are called *nontrivial solutions*
- it has 1 (trivial) or ∞ solutions  \rightarrow same line
- all lines intersect at the origin

MATRIX NOTATION

$$\begin{aligned} 5x + y &= 3 \\ 2x - y &= 4 \end{aligned}$$

coeff. matrix : $\begin{bmatrix} 5 & 1 \\ 2 & -1 \end{bmatrix}$

augmented matrix : $\left[\begin{array}{cc|c} 5 & 1 & 3 \\ 2 & -1 & 4 \end{array} \right]$

$$\begin{bmatrix} 5 & 1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

linear combination
of vectors \rightarrow

$$\begin{bmatrix} 5 \\ 2 \end{bmatrix} x + \begin{bmatrix} 1 \\ -1 \end{bmatrix} y = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

1.3 FUNDAMENTAL QUESTIONS

1. is it consistent aka. does at least 1 solution **exist**?
2. if a solution exists, is it **unique**?

answer by converting augmented matrix into a row equivalent matrix

⇓
done by using EROs (elementary row operations)

- multiply a row by a non-zero constant
- interchange two rows
- add a row to another

ROW ECHELON FORM

- all zero rows are at the bottom
- every **pivot** is on the right of the pivot in the previous row
↳ first non-zero number in the row

- can be obtained using **gaussian elimination** using EROs
↳ diff sequence \Rightarrow diff row echelon matrix

REDUCED ROW ECHELON FORM

matrix is in echelon form

every column containing a pivot has pivot value = 1 and all other elements in the column are 0

- can be obtained by **gaussian-jordan elimination** using eros; a **RRE** is unique per matrix

pt is to eliminate every variable but one from each row

aka convert into I matrix

- gaussian elimination : basically find the pivot and make everything under it 0.
- jordan : get echelon, then make rest 0

$\underbrace{\hspace{10em}}_{\substack{\uparrow \\ \text{forward} \\ \text{phase} \\ 0 \text{ under pivot}}}$

$\underbrace{\hspace{10em}}_{\substack{\uparrow \\ \text{backward phase} \\ 0 \text{ above pivot,} \\ \text{pivot} = 1}}$

ANSWERING THE QUESTIONS

- system \rightarrow augmented matrix \rightarrow row echelon \rightarrow new system

impossible $0x_1 + 0x_2 + 0x_3 = i$ $\begin{bmatrix} a & b & c & d \\ e & f & g & h \\ 0 & 0 & 0 & i \end{bmatrix}$ if any row has all except last element = 0 \leftarrow infer \Rightarrow no solution

- reduced row form gives solution
 pivoted variables are called leading variables
 others are called free variables \rightarrow can take any value $\therefore \infty$ sol
 \downarrow
 get eqns with the leading as subjects

\downarrow
 replace rhs variables w/ letters / number

stop there? \rightarrow yes

\downarrow
 then rep all as eqns
 \nearrow w/ those variables
 those are the solutions

1.5 LINEAR COMBINATION OF VECTORS

$$y = c_1 v_1 + \dots + c_p v_p$$

vector linear combination of $\underbrace{v_1, v_2, \dots, v_p}_{\text{vectors}}$; with weights $\underbrace{c_1, c_2, \dots, c_p}_{\text{scalars}}$

eg. $\vec{a}_1 = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}$ $\vec{a}_2 = \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}$ $\vec{b} = \begin{bmatrix} 7 \\ 4 \\ 3 \end{bmatrix}$

- same as asking if b exists in the span of a_1, a_2

can b be rep'd as a linear combo of a_1, a_2

$$x_1 a_1 + x_2 a_2 = b \rightarrow \text{is a linear system}$$

↓

make the augmented matrix

↳ iff it has a soln \Rightarrow b can be reped \leftarrow

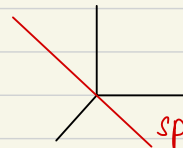
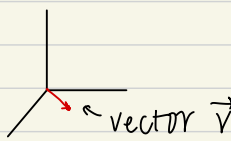
■ answer

1.6 SPAN

- \mathbb{R}^n : n dimensional space of real vectors
- all linear combinations of v_1, v_2, \dots, v_p is denoted by $\text{Span}\{v_1, v_2, v_3 \dots v_p\}$ and is called the subset of \mathbb{R}^n spanned (or generated) by $v_1, v_2 \dots v_p$.
- $\text{Span}\{v_1, v_2 \dots v_p\}$ = collection of all the vectors that can be written as $c_1 v_1 + c_2 v_2 + \dots + c_p v_p$ with scalars $c_1, c_2 \dots c_p$
- geometric view

$\text{Span}\{v\}$

↓
scalar multiples
of v = set of points
in the line in \mathbb{R}^3 through v and 0



span of v

basically $c v$
 $c \in \{\text{scalars}\}$

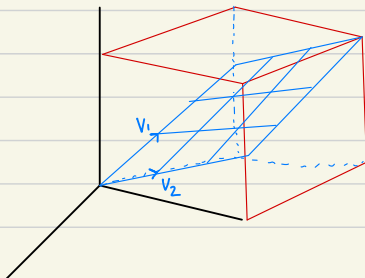
$\text{Span}\{u, v\}$

↓

plane in \mathbb{R}^3 containing u, v and 0

if they arent collinear, in 2-D, the span is the entire plane. if they are collinear,

the span is still the line they lie on



very important

lec 2

Pivot's perspective

- a) unique : every column except the last is a pivot column
- b) no soln : pivot in the last column \leftarrow aug.
- c) infinite : last column and some other column is not a pivot column

m : no of eq ; n : no of variables

$m = n$ coeff : square

$m < n$ coeff : FAT

$m > n$ coeff : TALL

2 planes in 3D

$$\begin{aligned} \text{eqn of a plane} &: a_1x + b_1y + c_1z = d_1 \\ &a_2x + b_2y + c_2z = d_2 \end{aligned}$$

solution is along the line of intersection
and \therefore there are infinite

- pivot in every row \Rightarrow consistent. (+ spans)
- non-pivot col \Rightarrow its a linear combo of pivot cols.
- pivot in every col \rightarrow no free variable

ex 12 $\left(\begin{array}{cc|c} 1 & 1 & 5 \\ 1 & 2 & 8 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1 & 5 \\ 0 & 1 & 3 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 3 \end{array} \right)$

- if an equation is a multiple of the other, the system is that of redundant equations.

ex 19. $\left(\begin{array}{cccc|c} 1 & 1 & 0 & 5 & 1 \\ 0 & 1 & 0 & 2 & 6 \\ 0 & 0 & 1 & 4 & 8 \end{array} \right)$
 $\sim \left(\begin{array}{cccc|c} 1 & 0 & 0 & 3 & -5 \\ 0 & 1 & 0 & 2 & 6 \\ 0 & 0 & 1 & 4 & 8 \end{array} \right)$

$$x + 3w = -5$$

$$y + 2w = 6$$

$$z + 4w = 8$$

$$w + 0 = w$$

$$x = -5 - 3w$$

$$y = 6 - 2w$$

$$z = 8 - 4w$$

$$w = w$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \begin{pmatrix} -5 \\ 6 \\ 8 \\ 0 \end{pmatrix} + w \begin{pmatrix} -3 \\ -2 \\ -4 \\ 1 \end{pmatrix}$$

soln set: $\begin{pmatrix} -5 \\ 6 \\ 8 \\ 0 \end{pmatrix} + d \begin{pmatrix} -3 \\ -2 \\ -4 \\ 1 \end{pmatrix} : d \in \mathbb{R}$

solution: put all pivot variables on one side, and free variables \leftarrow non-pivot on the other-side, add a trivial equation to obtain a system where its easy to read off the solution

ex 20

$$\left(\begin{array}{cccc|c} 1 & 0 & 7 & 0 & 4 \\ 0 & 1 & 3 & 4 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$x + 7z = 4$$

$$y + 3z + 4w = 1$$

$$x = 4 - 7z$$

$$y = 1 - 3z - 4w$$

$$z = z$$

$$w = w$$

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = \left\{ \begin{pmatrix} 4 \\ 1 \\ 0 \\ 0 \end{pmatrix} + z \begin{pmatrix} 7 \\ 3 \\ 1 \\ 0 \end{pmatrix} + w \begin{pmatrix} 0 \\ -4 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$z, w \in \mathbb{R}$

↑
soln set

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$$\begin{array}{lcl}
 1. & \begin{array}{l} w + 3a = 1 \\ x + a = 2 \\ y + a = 3 \\ z + 2a = 0 \\ a = a \end{array} & \begin{pmatrix} w \\ x \\ y \\ z \\ a \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 0 \\ 0 \end{pmatrix} + a \begin{pmatrix} -3 \\ -1 \\ -1 \\ -2 \\ 1 \end{pmatrix}
 \end{array}$$

2. homogeneous.
trivial soln: all 0

$$\begin{array}{lcl}
 3. & \begin{array}{l} a + b + d + f = 1 \quad a + b + d = 2 \\ c + 2d + 2f = -1 \quad c + 2d = 1 \\ e + 3f = 1 \quad e = 4 \\ 2f = -2 \quad f = -1 \\ g = 1 \end{array} &
 \end{array}$$

$$\begin{array}{lcl}
 a = 2 - b - d \\
 c = 1 - 2d \\
 d = d \\
 e = 4 \\
 f = -1 \\
 g = 1 \\
 b = b
 \end{array}
 = \begin{pmatrix} 2 \\ 0 \\ 1 \\ 0 \\ 4 \\ -1 \\ 1 \end{pmatrix} + b \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + d \begin{pmatrix} -1 \\ 0 \\ -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$2. \begin{pmatrix} 2 & 5 & -8 & 2 & 2 & | & 0 \\ 6 & 2 & -10 & 6 & 8 & | & 6 \\ 3 & 6 & +2 & 3 & 5 & | & 6 \\ 3 & 1 & -5 & 3 & 4 & | & 3 \\ 6 & 7 & -3 & 6 & 9 & | & 9 \end{pmatrix}$$

$$\begin{pmatrix} -1 & -1 & -10 & -1 & -3 & | & -6 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 5 & 7 & 0 & 1 & | & 3 \\ 3 & 1 & -5 & 3 & 4 & | & 3 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 10 & 1 & 3 & | & 6 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 5 & 7 & 0 & 1 & | & 3 \\ 0 & -2 & -20 & 0 & -5 & | & -15 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 10 & 1 & 3 & | & 6 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \\ 0 & 5 & 7 & 0 & 1 & | & 3 \\ 0 & 0 & 0 & +2 & +11 & | & +27 \\ 0 & 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$