

# MA580H Matrix Computations

## Lectures 5 & 6: System of Linear Equations-I

Rafikul Alam  
Department of Mathematics  
IIT Guwahati

# Outline

- Solution of triangular system
- Gaussian elimination
- LU decomposition

# Linear system

Let  $A \in \mathbb{R}^{n \times n}$  be nonsingular and  $b \in \mathbb{R}^n$ .

**Problem:** Solve  $Ax = b$  for  $x \in \mathbb{R}^n$ .

**Idea:** For a nonsingular  $M$ , the solution of  $MAx = Mb$  is given by

$$x = (MA)^{-1}Mb = A^{-1}M^{-1}Mb = A^{-1}b.$$

So, the strategy is to choose  $M$  so that the system

$$MAx = Mb$$

is easy to solve. **Gaussian elimination** provides such an  $M$  for which  $MA$  is **upper triangular**.

The MATLAB command

```
>> x = A\b
```

solves the system  $Ax = b$  using Gaussian elimination.

## Lower triangular linear system

Consider the lower triangular linear system of equations

$$\begin{bmatrix} \ell_{11} & & & \\ \ell_{21} & \ell_{22} & & \\ \vdots & \vdots & \ddots & \\ \ell_{n1} & \ell_{n2} & \cdots & \ell_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

By forward substitution, we have

$$x_1 = b_1 / \ell_{11}$$
$$x_i = \left( b_i - \sum_{j=1}^{i-1} \ell_{ij} x_j \right) / \ell_{ii}, \quad i = 2 : n.$$

**Cost:**  $n^2$  flops

Indeed,  $\sum_{i=1}^n 2i = \int_0^n 2x dx + \text{lower order terms} \simeq n^2$ .

# Column-oriented forward substitution

Writing  $Lx = b$  as

$$L(:, 1)x(1) + \cdots + L(:, n)x(n) = b$$

we obtain column-oriented forward substitution.

```
x = zeros(n,1);
for j=1:n-1
    x(j) = b(j)/L(j,j);
    b(j+1:n) = b(j+1:n)-L(j+1:n,j)*x(j);
end
x(n) = b(n)/L(n,n);
```

- Solving a lower triangular system costs  $n^2$  flops.

# Upper triangular linear system

Consider the upper triangular system

$$\begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n} \\ & u_{22} & \cdots & u_{2n} \\ & & \ddots & \vdots \\ & & & u_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

If  $u_{11}, \dots, u_{nn}$  are nonzero, then by back substitution, we have a unique solution

$$x_n = b_n / u_{nn}$$

$$x_i = \left( b_i - \sum_{j=i+1}^n u_{ij} x_j \right) / u_{ii}, \quad i = n-1, \dots, 1.$$

**Cost:** An upper triangular system is solved by **back substitution** and costs  $n^2$  flops.

## Gaussian elimination

**Strategy:** Transform a given linear system  $Ax = b$  to an equivalent triangular linear system  $\hat{A}x = \hat{b}$ . Consider the system

$$\begin{array}{l} x - y - z = 2 \\ 3x - 3y + 2z = 16 \\ 2x - y + z = 9 \end{array} \iff \underbrace{\left[ \begin{array}{ccc|c} 1 & -1 & -1 & 2 \\ 3 & -3 & 2 & 16 \\ 2 & -1 & 1 & 9 \end{array} \right]}_{\text{augmented matrix}}$$

Use first equation to eliminating  $x$  from 2nd and 3rd equation

$$\begin{array}{l} x - y - z = 2 \\ 5z = 10 \\ y + 3z = 5 \end{array} \iff \left[ \begin{array}{ccc|c} 1 & -1 & -1 & 2 \\ 0 & 0 & 5 & 10 \\ 0 & 1 & 3 & 5 \end{array} \right].$$

Now interchange 2nd and 3rd equations

$$\begin{array}{l} x - y - z = 2 \\ y + 3z = 5 \\ 5z = 10 \end{array} \iff \left[ \begin{array}{ccc|c} 1 & -1 & -1 & 2 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 5 & 10 \end{array} \right] \Rightarrow \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ 2 \end{bmatrix}.$$

## Gaussian elimination

```
function x=gauss(A,b)
% x=gauss(A,b) solves the linear system Ax=b using Gaussian
% elimination with partial pivoting on [A, b].
n=length(b);
norma=norm(A,1);
A=[A,b]; % augmented matrix
for i=1:n
    [maxpv,kmax]=max(abs(A(i:n,i))); % look for Pivot A(kmax,i)
    kmax=kmax+i-1;
    if maxpv < 1e-14*norma; % only small pivots
        error('matrix is singular')
    end
    if i ~= kmax % interchange rows
        A([i, kmax],:) = A([kmax, i], :);
    end
    A(i+1:n,i)=A(i+1:n,i)/A(i,i); % elimination step
    A(i+1:n,i+1:n+1)=A(i+1:n,i+1:n+1)-A(i+1:n,i)*A(i,i+1:n+1);
end
x=backsubs(A,A(:,n+1));
```

# Gaussian elimination (GE)

Gaussian elimination can be rewritten as a method that **factorizes a matrix**. We consider three variants of GE. These variants yield three matrix factorizations, namely,

- LU factorization:  $A = LU$
- Row permuted LU factorization:  $PA = LU$
- Row and column permuted LU factorization:  $PAQ = LU$

Here  $P$  and  $Q$  are permutation matrices. An  $n \times n$  permutation matrix is obtained by permuting rows of the identity matrix  $I_n$ .

The matrix  $L$  is **unit lower triangular** and  $U$  is **upper triangular**. A lower triangular matrix  $L$  is called unit lower triangular if the **diagonal entries** of  $L$  are 1, that is,  $\ell_{jj} = 1$  for  $j = 1 : n$ .

# LU Decomposition

**Definition:** An LU decomposition of a matrix  $A \in \mathbb{R}^{n \times n}$  is a factorization of the form  $A = LU$ , where  $L$  is unit lower triangular and  $U$  is upper triangular. Thus

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix} = \begin{bmatrix} 1 & & & \\ \vdots & \ddots & & \\ \ell_{n1} & \cdots & 1 \end{bmatrix} \begin{bmatrix} u_{11} & \cdots & u_{1n} \\ & \ddots & \vdots \\ & & u_{nn} \end{bmatrix} = LU.$$

We wish to construct a **nonsingular  $M$**  such that  $MA$  is upper triangular. We expect  $M$  to have the following properties:

- $M = L_{n-1}^{-1} L_{n-2}^{-1} \cdots L_1^{-1}$
- Each  $L_j$  is unit lower triangular
- The product  $L := L_1 L_2 \cdots L_{n-1}$  requires NO computation

Then

$$MA = U \implies L_{n-1}^{-1} L_{n-2}^{-1} \cdots L_1^{-1} A = U \implies A = LU,$$

where  $L$  is unit lower-triangular and  $U$  is upper-triangular.

# LU factorization

Suppose  $A$  is  $4 \times 4$  matrix. Then schematically

$$\begin{array}{c} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \xrightarrow{\quad} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \\ \underbrace{A}_{\quad} \qquad \qquad \qquad \underbrace{L_1^{-1}A}_{\quad} \end{array}$$
$$\begin{array}{c} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \xrightarrow{\quad} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \\ \underbrace{L_1^{-1}A}_{\quad} \qquad \qquad \qquad \underbrace{L_2^{-1}L_1^{-1}A}_{\quad} \end{array}$$
$$\begin{array}{c} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \xrightarrow{\quad} \left[ \begin{array}{cccc} \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \\ \times & \times & \times & \times \end{array} \right] \\ \underbrace{L_2^{-1}L_1^{-1}A}_{\quad} \qquad \qquad \qquad \underbrace{L_3^{-1}L_2^{-1}L_1^{-1}A}_{\quad} \end{array}$$

## Example

Let  $A := \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix}$ . Consider  $L_1 := \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 0 & 1 \end{bmatrix}$ . Then

$$L_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ -7 & 0 & 1 \end{bmatrix} \text{ and } L_1^{-1}A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -21 \end{bmatrix}.$$

Now consider  $L_2 := \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$ . Then  $L_2^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$ ,

$$U := L_2^{-1}L_1^{-1}A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & -9 \end{bmatrix} \text{ and } L := L_1L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ 7 & 2 & 1 \end{bmatrix}.$$

Thus we obtain  $A = LU$ .

## Elimination matrix

Define  $\ell_k := \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \ell_{k+1,k} \\ \vdots \\ \ell_{nk} \end{bmatrix}$  and  $L_k := I + \ell_k e_k^\top$  for  $k = 1 : (n - 1)$ .

Then

$$\begin{aligned} L_k &= I + [0 \quad \cdots \quad 0 \quad \ell_k \quad 0 \quad \cdots \quad 0] \\ &= \begin{bmatrix} 1 & & & & & & \\ & \ddots & & & & & \\ & & 1 & & & & \\ & & & \ell_{k+1,k} & 1 & & \\ & & & \vdots & & \ddots & \\ & & & \ell_{nk} & & & 1 \end{bmatrix} \end{aligned}$$

is unit lower triangular.

# Product of elimination matrices

Consider  $L_k = I + \ell_k e_k^\top$ . By construction  $e_k^\top \ell_k = 0$ . Consequently

$$\underbrace{(I + \ell_k e_k^\top)}_{L_k} (I - \ell_k e_k^\top) = I + \ell_k e_k^\top - \ell_k e_k^\top - \ell_k e_k^\top \ell_k e_k^\top = I.$$

This shows that  $L_k^{-1} = I - \ell_k e_k^\top$ . Next observe that

$$L_k L_{k+1} = (I + \ell_k e_k^\top)(I + \ell_{k+1} e_{k+1}^\top) = I + \ell_k e_k^\top + \ell_{k+1} e_{k+1}^\top.$$

Consequently

$$\begin{aligned} L &= L_1 L_2 \cdots L_{n-1} = I + \ell_1 e_1^\top + \ell_2 e_2^\top + \cdots + \ell_{n-1} e_{n-1}^\top \\ &= I + [\ell_1 \quad \ell_2 \quad \cdots \quad \ell_{n-1} \quad 0] = \begin{bmatrix} 1 & & & & \\ \ell_{21} & 1 & & & \\ \ell_{31} & \ell_{32} & 1 & & \\ \vdots & \vdots & \ddots & \ddots & \\ \ell_{n1} & \ell_{n2} & \cdots & \ell_{n,n-1} & 1 \end{bmatrix}. \end{aligned}$$

## Creating zeros via elimination matrix

Applying  $L_k^{-1}$  to the  $k$ -th column of an  $n \times n$  matrix  $A$ , we have

$$L_k^{-1} \begin{bmatrix} a_{1k} \\ \vdots \\ a_{kk} \\ a_{k+1,k} \\ \vdots \\ a_{nk} \end{bmatrix} = (I - \ell_k e_k^\top) \begin{bmatrix} a_{1k} \\ \vdots \\ a_{kk} \\ a_{k+1,k} \\ \vdots \\ a_{nk} \end{bmatrix} = \begin{bmatrix} a_{1k} \\ \vdots \\ a_{kk} \\ a_{k+1,k} \\ \vdots \\ a_{nk} \end{bmatrix} - \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \ell_{k+1,k} \\ \vdots \\ \ell_{nk} \end{bmatrix} a_{kk}$$
$$= \begin{bmatrix} a_{k1} \\ \vdots \\ a_{kk} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \text{when } \ell_{ik} = a_{ik}/a_{kk}, i = k+1 : n.$$

This shows that if  $a_{kk} \neq 0$  then  $L_k$  can be used to create zeros in the  $k$ -th column of  $A$  below  $a_{kk}$ .

# Multiplying a matrix by an elimination matrix

Let  $A \in \mathbb{R}^{n \times n}$  and  $L_k := I + \ell_k e_k e_k^\top \in \mathbb{R}^{n \times n}$ . Then

$$L_k^{-1} A = (I - \ell_k e_k e_k^\top) A = A - \ell_k e_k e_k^\top A = A - \ell_k [a_{k1} \ \cdots \ a_{kn}]$$

$$= \begin{bmatrix} a_{11} & \cdots & a_{kk} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots & \cdots & \vdots \\ a_{k1} & \cdots & a_{kk} & \cdots & a_{kn} \\ a_{k+1,n} & \cdots & a_{k+1,k} & \cdots & a_{k+1,n} \\ \vdots & \cdots & \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nk} & \cdots & a_{nn} \end{bmatrix} - \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \ell_{k+1,k} \\ \vdots \\ \ell_{nk} \end{bmatrix} [a_{k1} \ \cdots \ a_{kn}].$$

The outer product shows that the **first  $k$  rows of  $A$  remain unchanged** when  $L_k^{-1}$  is multiplied to the left of  $A$ . Let  $B := L_k^{-1} A$ . In MATLAB,  $B$  can be written compactly as a rank-1 update (outer product from)

$$B = A(k+1:n,:) - \ell(k+1:n)*A(k,:)$$

# Gaussian elimination = LU decomposition

For  $L_1 := I + \ell_1 e_1^\top$ , with  $\ell_{i1} := a_{i1}/a_{11}$ ,  $i = 2 : n$ , we have

$$L_1^{-1} A = \left[ \begin{array}{c|cccc} a_{11} & a_{12} & \cdots & a_{1n} \\ \hline 0 & a_{22}^{(1)} & \cdots & a_{2n}^{(1)} \\ \vdots & \vdots & & \vdots \\ 0 & a_{n2}^{(1)} & \cdots & a_{nn}^{(1)} \end{array} \right], \text{ where } a_{ij}^{(1)} = a_{ij} - \ell_{i1} a_{1j}.$$

**Cost:**  $2(n-1)^2$  flops.

The elimination is possible only when  $a_{11} \neq 0$ .

The vector  $\ell_1$  can be stored in the first column of  $L_1^{-1} A$  in place of zeros. This will reduce the storage requirement.

Thus overwriting  $A$ , in MATLAB notation, we have

$$A(2 : n, 1) = A(2 : n, 1)/A(1, 1); \quad \% \text{ multipliers}$$

$$A(2 : n, 2 : n) = A(2 : n, 2 : n) - A(2 : n, 1) * A(1, 2 : n);$$

## Gaussian elimination = LU decomposition

For  $L_2 := I + \ell_2 e_2^\top$  with  $\ell_{i2} := a_{i2}^{(1)} / a_{22}^{(1)}$ ,  $i = 3 : n$ , we have

$$L_2^{-1} L_1^{-1} A = \left[ \begin{array}{c|ccccc} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ \hline 0 & a_{22}^{(1)} & a_{23}^{(1)} & \cdots & a_{2n}^{(1)} \\ 0 & 0 & a_{33}^{(2)} & \cdots & a_{3n}^{(2)} \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & a_{n3}^{(2)} & \cdots & a_{nn}^{(2)} \end{array} \right], \text{ where } a_{ij}^{(2)} = a_{ij}^{(1)} - \ell_{i2} a_{2j}^{(1)}. \\ \text{Cost: } 2(n-2)^2 \text{ flops.}$$

The elimination is possible only when  $a_{22}^{(1)} \neq 0$ . The vector  $\ell_2$  can be stored in the second column of  $L_2^{-1} L_1^{-1} A$  in place of zeros.

Again, overwriting  $A$ , in MATLAB notation, we have

$$A(3 : n, 2) = A(3 : n, 2) / A(2, 2); \quad \% \text{ multipliers}$$

$$A(3 : n, 3 : n) = A(3 : n, 3 : n) - A(3 : n, 2) * A(2, 3 : n);$$

Hence we have  $L_{n-1}^{-1} \cdots L_1^{-1} A = U \Rightarrow A = L_1 L_2 \cdots L_{n-1} U = LU$ .

**Cost:**  $2(n-1)^2 + 2(n-2)^2 + \cdots + 2 \simeq 2n^3/3$  flops.

## Example

Consider  $A := \begin{bmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{bmatrix}$ . Then

$$L_1 = I + \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix} e_1^\top, \quad L_1^{-1} A = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 1 & 5 \end{bmatrix},$$

$$L_2 = I + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} e_2^\top, \quad L_2^{-1} L_1^{-1} A = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix}.$$

This gives

$$A = L_1 L_2 \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix}.$$

## Gaussian Elimination with No Pivoting (GENP)

```
function [L, U] = GENP(A);
% [L U] = GENP(A) produces a unit
% lower triangular matrix L and an upper
% triangular matrix U so that A= LU.

[n, n] = size(A);
for k = 1:n-1
    % compute multipliers for k-th step
    A(k+1:n,k) = A(k+1:n,k)/A(k,k);
    % update A(k+1:n,k+1:n)
    j = k+1:n;
    A(j,j) = A(j,j)-A(j,k)*A(k,j);
end
% strict lower triangle of A, plus I
L = eye(n,n)+ tril(A,-1);
U = triu(A); % upper triangle of A
```

## Solution of $Ax = b$ by LU factorization

An  $n \times n$  linear system  $Ax = b$  can be solved in three steps:

- Compute LU factorization  $A = LU$ . Cost:  $\frac{2n^3}{3}$  flops.
- Solve  $Ly = b$  for  $y$ . Cost:  $n^2$  flops.
- Solve  $Ux = y$  for  $x$ . Cost:  $n^2$  flops.

Thus the cost for solving system  $Ax = b$  is  $2n^3/3$  flops.

**Question:** What will be the complexity if the system  $Ax = b$  is solved as  $x = A^{-1} * b$ ? **Answer:**  $2n^3/3 + 2n^3$  flops.

**Question:** Does LU decomposition of  $A$  exist when  $A$  is nonsingular?

**Answer:** Not always. LU decomposition of  $A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$  does not exist.

**Theorem:** Let  $A$  be nonsingular. Then  $A$  admits a unique LU factorization  $\Leftrightarrow$  all leading principal submatrices of  $A$  are nonsingular, that is,  $A(1:j, 1:j)$  is nonsingular for  $j = 1:n$ .

## Existence of LU factorization

**Proof:** Suppose that  $A = LU$  exists and unique. Then writing

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} = \begin{bmatrix} L_{11} & 0 \\ L_{21} & L_{22} \end{bmatrix} \begin{bmatrix} U_{11} & U_{12} \\ 0 & U_{22} \end{bmatrix},$$

we have  $\det(A_{11}) = \det(L_{11})\det(U_{11}) = \det(U_{11}) \neq 0$ . (Why?)

Conversely, suppose that all leading principal submatrices of  $A$  are nonsingular. We prove the result by induction. Suppose the result is true for  $n - 1$ .

Let  $\hat{A} = A(1 : n - 1, 1 : n - 1)$  and  $\hat{A} = \hat{L}\hat{U}$  be unique LU factorization. Then writing

$$A = \begin{bmatrix} \hat{A} & b \\ c & a_{nn} \end{bmatrix} = \begin{bmatrix} \hat{L} & 0 \\ \ell & 1 \end{bmatrix} \begin{bmatrix} \hat{U} & u \\ 0 & d \end{bmatrix} = \begin{bmatrix} \hat{L}\hat{U} & \hat{L}u \\ \ell\hat{U} & \ell u + d \end{bmatrix},$$

we have  $\hat{L}u = b$ ,  $\ell\hat{U} = c$  and  $d = a_{nn} - \ell u$  which give unique  $\ell, u, d$ .

Finally,  $0 \neq \det(A) = \det(\hat{U})d \Rightarrow d \neq 0$ . This completes the proof. ■