

MA579H Scientific Computing

Lectures 2 & 3: Errors and Floating-point Arithmetic

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Lecture outline

- Sources of errors
- Floating-point arithmetic
- Rounding error

Sources of errors

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Example: Suppose we wish to compute surface area of Earth using formula $S = 4\pi r^2$. This involves several approximations:

- **Modeling error:** Earth is modeled as a sphere, idealizing its true shape.
- **Measurement error:** Computation of the radius r is based on empirical measurements.
- **Truncation error:** Computation of π requires truncation of infinite process.
- **Rounding error:** Input data and results of arithmetic operations are rounded in computer.

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 - differential or integral \longrightarrow algebraic
 - nonlinear \longrightarrow linear
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 - complicated \rightarrow simple
- **Rounding error.**

Scientific computing analyzes errors that arise during computation. A small **error** in the input may be **amplified**

- by a problem (**bad problem**)
- by an algorithm (**bad algorithm**) during computation.

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Two common measures of error are

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Relative error is considered for analysis of **rounding errors**.

Anomalous arithmetic

Arithmetic operations on computers are inexact and can produce surprising results. For example, MATLAB produces

$$\begin{aligned}\left(\frac{4}{3} - 1\right) * 3 - 1 &= -2.2204 \times 10^{-16} \\ 5 \times \frac{(1 + \exp(-50)) - 1}{(1 + \exp(-50)) - 1} &= \mathbf{NaN} \\ \frac{\log(\exp(750))}{100} &= \mathbf{Inf}\end{aligned}$$

Normalized floating-point representation

Let $x \in \mathbb{R}$ be nonzero and $\beta > 1$ be an integer. Then we have the normalized floating-point representation

$$x = \pm(\cdot d_1 d_2 \cdots d_t \cdots)_\beta \times \beta^e, \quad 0 \leq d_i < \beta, \quad d_1 \neq 0, \quad e \in \mathbb{Z}.$$

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$$f = (\cdot d_1 d_2 \cdots d_t \cdots)_\beta = \sum_{j=1}^{\infty} \frac{d_j}{\beta^j}.$$

Note that $0 < f \leq 1$ and $x = \pm f \times \beta^e$ is a unique representation. The number of digits allowed in f is called **precision** of the floating-point representation, which in the present case is infinite.

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The fraction $f := (\cdot d_1 d_2 \cdots d_t)_\beta = \sum_{j=1}^t \frac{d_j}{\beta^j} \leq 1 - \beta^{-t} < 1$.

Example: $(\cdot 101)_2 \times 2^2 = (1 \times 2^{-1} + 0 \times 2^{-2} + 1 \times 2^{-3}) \times 2^2 = 5/2$.

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Note that $\#F(\beta, t, e_{\min}, e_{\max}) = 2(\beta - 1)\beta^{t-1} \times (e_{\max} - e_{\min} + 1) + 1$.

Floating-Point System

Underflow threshold (smallest positive floating point number):

- $\text{realmin} := (.10 \dots 0)_{\beta} \times \beta^{e_{\min}} = \beta^{e_{\min}-1}$

Overflow threshold (largest positive floating point number):

- $\text{realmax} := (.(\beta - 1) \dots (\beta - 1))_{\beta} \times \beta^{e_{\max}} = (1 - \beta^{-t}) \beta^{e_{\max}}$

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Machine epsilon/precision: $\mathbf{eps} := \beta^{1-t}$.

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For MATLAB we have the following

	Binary	Decimal
eps	2^{-52}	2.2204×10^{-16}
realmin	2^{-1022}	2.2251×10^{-308}
realmax	$(2 - \text{eps}) \times 2^{1023}$	1.7977×10^{308}

IEEE single precision floating-point representation

IEEE specifies $F(2, t, e_{\min}, e_{\max})$ as follows.

sign (1 bit)	exponent (8 bits)	mantissa (23 bits)
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Exponents: $2^8 = 256$ Largest exponent: $2^8 - 1 = 255$

Exponent range: $0 \leq b \leq 255$ and $-127 \leq e \leq 128$

$$x = (-1)^s \times (1 \cdot d_1 \cdots d_{23})_2 \times 2^{b-127} \text{ where } e = b - 127.$$

Effective exponent range: $-126 \leq e \leq 127$ as $e = -127$ is reserved for ± 0 and $e = 128$ for $\pm \text{inf}$ and NaN

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$$\text{eps} = 2^{-23} \approx 1.192 \times 10^{-7}, \quad \text{realmin} = 2^{-126} \approx 1.175 \times 10^{-38}, \quad \text{realmax} = (2 - \text{eps}) \times 2^{127} \approx 3.403 \times 10^{38}$$

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Gap between floating-point numbers

Let $x \in F(\beta, t, e_{\min}, e_{\max})$ be given by $x = (\cdot d_1 d_2 \cdots d_t)_\beta \times \beta^e$.

Define $\text{ulp}(x) := \beta^{e-t}$. Then $\text{next}(x) := x + \text{ulp}(x)$ is the next floating point number larger than x , that is, $\text{next}(x)$ is the smallest floating-point number larger than x . Hence x and $\text{next}(x)$ are consecutive floating-point numbers.

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This shows that $\text{next}(x) - x = \text{ulp}(x) = \beta^{e-t}$. So, if x is a large number then e is large which implies large gap between x and $\text{next}(x)$. Hence the gap between consecutive floating-point number is nonuniform.

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Example: Consider $x \in F(10, 4, -30, 30)$ given by $x = 10^{-9} = .1000 \times 10^{-8}$. Then $\text{ulp}(x) = 10^{-8-4} = 10^{-12}$ and $\text{next}(x) - x = 10^{-12}$.

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Next, consider $y = 10^{15} = .1000 \times 10^{16}$. Then $\text{ulp}(y) = 10^{16-4} = 10^{12}$ and $\text{next}(y) - y = 10^{12}$.

Relative gap between floating-point numbers

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$$\frac{\text{next}(x) - x}{x} = \frac{\beta^{e-t}}{(.d_1 \cdots d_t)_\beta \times \beta^e} \leq \beta^{1-t} = \text{eps}.$$

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$$\frac{\text{next}(y) - y}{y} = \frac{10^{12}}{10^{15}} = 10^{-3} = \text{eps}. \blacksquare$$

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Define $\text{fl}(x) := \begin{cases} x_L, & \text{round down} \\ x_R, & \text{round up} \\ x_L \text{ or } x_R \text{ whichever is closer to } x, & \text{round to nearest} \end{cases}$

Rounding error

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Proof: Let $x = (\cdot d_1 d_2 \cdots d_t \cdots)_\beta \times \beta^e$. Set $\delta := \frac{\text{fl}(x) - x}{x}$. Then $\text{fl}(x) = x(1 + \delta)$. Note that $|\text{fl}(x) - x| \leq \beta^{e-t}$ for chopping, and $|\text{fl}(x) - x| \leq \beta^{e-t}/2$ for round to nearest. Also $x \geq \beta^{e-1}$.

Rounding error

Unit roundoff: $\mathbf{u} := \begin{cases} \beta^{1-t} & \text{round down,} \\ \frac{1}{2}\beta^{1-t}, & \text{round to nearest} \end{cases}$

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Hence

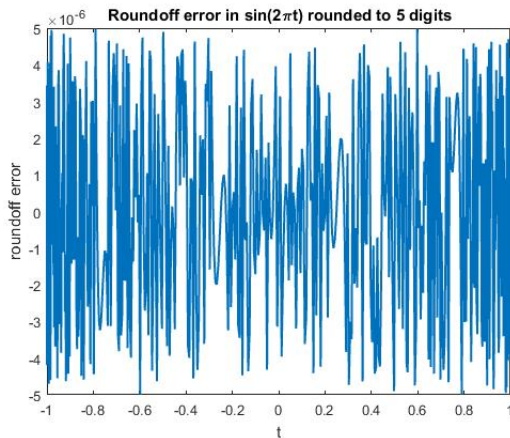
$$|\delta| \leq \frac{|\text{fl}(x) - x|}{|x|} \leq \begin{cases} \beta^{1-t} & \text{round down,} \\ \frac{1}{2}\beta^{1-t}, & \text{round to nearest.} \end{cases}$$

Rounding error

Let $f(t) := \sin(2\pi t)$ for $t \in [0, 1]$. Consider $F(10, 5, -10, 10)$. Then

```
t = 0:.001:1; tt = sin(2*pi*t); rt = round(tt, 5);
```

```
roundoff = tt-rt; plot(tt, roundoff, 'LineWidth',1.5)
```

 produces the following

Floating-point arithmetic

Arithmetic model: If $x, y \in F(\beta, t, e_{\min}, e_{\max})$ and $\oplus \in \{+, -, \times, /\}$ and \mathbf{u} is the unit roundoff then

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Loss of significance (or cancellation): If x and y are not floating-point numbers then we have to start with $\hat{x} := \text{fl}(x) = x(1 + \delta_1)$ and $\hat{y} := \text{fl}(y) = y(1 + \delta_2)$. Then

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Now, if x and y have the same sign then the relative error

$\left| \frac{x\delta_1 + y\delta_2}{x + y} \right| \leq |\delta_1| + |\delta_2| \leq 2\mathbf{u}$ is small but $\left| \frac{x\delta_1 - y\delta_2}{x - y} \right|$ can be arbitrarily large when $x - y$ is very small.

Example

Problem: Solve $ax^2 + bx + c = 0$, where $a, b, c \in \mathbb{R}$

Classical method: Naive use of the formula yields

$$x_1 = \frac{-b - \sqrt{b^2 - 4ac}}{2a}, \quad x_2 = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

does not avoid subtraction whereas the **modified formula**

$$x_1 = -\frac{b + \operatorname{sign}(b)\sqrt{b^2 - 4ac}}{2a}, \quad x_2 = \frac{c}{ax_1}$$

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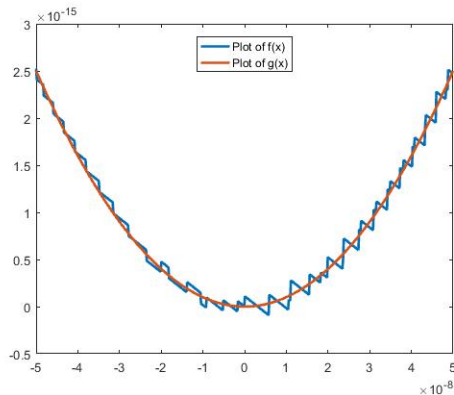
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For $10^{-3}x^2 + 10^7x + 3 = 0$, the **classical method** in MATLAB yields $x_1 = -10^{10}$ and $x_2 = 0$ whereas the **modified method** yields the accurate answer $x_1 = -10^{10}$ and $x_2 = -3.0 \times 10^{-7}$.

Example

Evaluate $f(x) := e^x - \cos(x) - x$ for $-5 \times 10^{-8} \leq x \leq 5 \times 10^{-8}$.



Approximation of $f(x)$ using Taylor series avoids cancellation

$$f(x) = 1 + x + \frac{x^2}{2!} + \cdots - \left(1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \cdots\right) - x \approx x^2 + x^3/6 = g(x).$$

Cancellation and remedy

Let $f(x) := \frac{1 - \cos(x)}{\sin(x)}$ for $x \neq 0$. If a is close to 0 then evaluation of $f(x)$ at a causes cancellation as $\cos(a) \approx 1$. The remedy is to rewrite $f(x)$ as

$$f(x) = \frac{1 - \cos(x)}{\sin(x)} = \frac{\sin(x)}{1 + \cos(x)}$$

which avoids cancellation at $a \approx 0$.

Rounding error of differentiation

Recall that $D_h f(x) := \frac{f(x+h) - f(x)}{h}$ approximates $f'(x)$. For small h , $D_h f(x)$ exhibits cancellation error due to rounding, which is magnified by the division of h .

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This shows that the **rounding error**

$$e_r(x, h) := \frac{|\delta(x+h)f(x+h) - \delta(x)f(x)|}{h} \leq \frac{\mathbf{eps}(|f(x+h)| + |f(x)|)}{h}.$$

Rounding error of differentiation

Recall that $E(x, h) := |f'(x) - D_h f(x)|$. By Taylor theorem

$$f(x + h) = f(x) + f'(x)h + h^2 f''(\xi)/2 \implies E(x, h) = h|f''(\xi)|/2.$$

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For $f(x) = e^x$, we have

