# cādence

# **SD** Host Firmware Driver User Guide

Product Version 5.7.1 April 2020 © 1996-2020 Cadence Design Systems, Inc. All rights reserved.

Cadence Design Systems, Inc. (Cadence), 2655 Seely Ave., San Jose, CA 95134, USA.

**Trademarks:** Trademarks and service marks of Cadence Design Systems, Inc. contained in this document are attributed to Cadence with the appropriate symbol. For queries regarding Cadence's trademarks, contact the corporate legal department at the address shown above or call 800.862.4522. All other trademarks are the property of their respective holders.

Restricted Permission: This document is protected by copyright law and international treaties and contains trade secrets and proprietary information owned by Cadence. Unauthorized reproduction or distribution of this document, or any portion of it, may result in civil and criminal penalties. Except as specified in this permission statement, this document may not be copied, reproduced, modified, published, uploaded, posted, transmitted, or distributed in any way, without prior written permission from Cadence. This document contains the proprietary and confidential information of Cadence or its licensors, and is supplied subject to, and may be used only in accordance with, a written agreement between Cadence and its customer.

Unless otherwise agreed to by Cadence in writing, this statement grants Cadence customers permission to print one (1) hard copy of this document subject to the following conditions:

- 1. This document may not be modified in any way.
- 2. Any authorized copy of this document or portion thereof must include all original copyright, trademark, and other proprietary notices and this permission statement.
- 3. The information contained in this document cannot be used in the development of like products or software, whether for internal or external use, and shall not be used for the benefit of any other party, whether or not for consideration.

Disclaimer: INFORMATION IN THIS DOCUMENT IS SUBJECT TO CHANGE WITHOUT NOTICE AND DOES NOT REPRESENT A COMMITMENT ON THE PART OF CADENCE. EXCEPT AS MAY BE EXPLICITLY SET FORTH IN A WRITTEN AGREEMENT BETWEEN CADENCE AND ITS CUSTOMER, CADENCE DOES NOT MAKE, AND EXPRESSLY DISCLAIMS, ANY REPRESENTATIONS OR WARRANTIES AS TO THE COMPLETENESS, ACCURACY OR USEFULNESS OF THE INFORMATION CONTAINED IN THIS DOCUMENT. CADENCE DOES NOT WARRANT THAT USE OF SUCH INFORMATION WILL NOT INFRINGE ANY THIRD PARTY RIGHTS, AND CADENCE DISCLAIMS ALL IMPLIED WARRANTIES, INCLUDING MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. CADENCE DOES NOT ASSUME ANY LIABILITY FOR DAMAGES OR COSTS OF ANY KIND THAT MAY RESULT FROM USE OF SUCH INFORMATION. CADENCE CUSTOMER HAS COMPLETE CONTROL AND FINAL DECISION-MAKING AUTHORITY OVER ALL ASPECTS OF THE DEVELOPMENT, MANUFACTURE, SALE AND USE OF CUSTOMER'S PRODUCT, INCLUDING, BUT NOT LIMITED TO, ALL DECISIONS WITH REGARD TO DESIGN, PRODUCTION, TESTING, ASSEMBLY, QUALIFICATION, CERTIFICATION, INTEGRATION OF CADENCE PRODUCTS, INSTRUCTIONS FOR USE, LABELING AND DISTRIBUTION, AND CADENCE EXPRESSLY DISAVOWS ANY RESPONSIBILITY WITH REGARD TO ANY SUCH DECISIONS REGARDING CUSTOMER'S PRODUCT.

**Restricted Rights:** Use, duplication, or disclosure by the Government is subject to restrictions as set forth in FAR52.227- 14 and DFAR252.227-7013 et seq. or its successor.

# **SD Host Firmware Driver User Guide**

Cadence Design Systems

Hardware Identifier:82f725edc9078f92a4ed7cea3ba0961e

# **Table of Contents**

	Acronyms		
2.	Document Purpose	2	,
3.	Description		
	3.1. General firmware info	3	3
	3.2. Core driver features		
	3.2.1. SD Host driver structure	3	3
	3.3. Naming convensions		
	3.4. System Usage		
4.	Core Driver Usage Model		
••	4.1. Description		
	4.2. Probing the Hardware		
	4.3. SD Host driver initialisation		
	4.4. Card initialisation		
	4.5. Access mode configuration		
	4.6. Data transfer		
	4.6.1. Using ADMA with manually defined sub buffers		
	4.7. Device specific functions and feaures		
	4.7.1. eMMC devices		
	4.7.2. SD devices (UHSI and legacy modes)		
	4.8. Interrupt mode		
	4.9. PHY configuration		
	4.10. Configuration of SD Host Controller Driver		
	4.11. Platform depending configuration		
5.	Configuration and Hardware Operation Information		
	5.1. Introduction		
6.	Dynamic Data Structures	13	3
	6.1. Introduction	13	3
	6.2. CSDD_SysReq_s	13	3
	6.3. CSDD_Config_s	13	3
	6.4. CSDD_RequestFlags_s	13	3
	6.5. CSDD_CommandField_s	14	1
	6.6. CSDD_Request_s		
	6.7. CSDD_SubBuffer_s		
	6.8. CSDD_DeviceInfo_s		
	6.9. CSDD_PhyDelaySettings_s		
	6.10. CSDD_MemoryCardInfo_s		
	6.11. CSDD_DeviceState_s		
	6.12. CSDD_CQInitConfig_s		
	6.13. CSDD_CQRequestData_s		
	6.14. CSDD_CQRequest_s		
	6.15. CSDD_CQDcmdRequest_s		
	6.16. CSDD_CQIntCoalescingCfg_s		
	6.17. CSDD_SDIO_SlotSettings_s		
	6.18. CSDD_SDIO_CidRegister_s		
	6.19. CSDD_SDIO_Device_s		
	6.20. CSDD_SDIO_Slot_s		
	6.21. CSDD_SDIO_Host_s		
	6.22. CSDD_Callbacks_s		
	6.23. CSDD_CPhyConfigIoDelay_s	24	ļ

6.24.	CSDD_CPhyConfigLvsi_s	25
6.25.	CSDD_CPhyConfigDfiRd_s	25
6.26.	CSDD_CPhyConfigOutputDelay_s	25
6.27.	CSDD_CccrRegAddr	26
6.28.	CSDD_TupleCode	28
	CSDD_CmdType	
	CSDD_CmdCat	
	CSDD_ResponseType	
	CSDD_CardType	
	CSDD_Capacity	
	CSDD_BusWidth	
	CSDD_BusMode	
	CSDD_InterfaceType	
	_ **	
	CSDD_RequestType	
	CSDD_ConfigCmd	
	CSDD_TransferDirection	
	CSDD_SpeedMode	
	CSDD_DmaMode	
	CSDD_ParitionAccess	
	CSDD_ParitionBoot	
	CSDD_MmcConfigCmd	
	CSDD_DriverStrengthType	
	CSDD_DriverCurrentLimit	
6.47.	CSDD_EmmcCmdqTaskDescSize	37
6.48.	CSDD_CQReqStat	38
6.49.	CSDD_PhyDelay	38
	CSDD_MEMORY_CARD_INFO	
	CSDD_PMEMORY_CARD_INFO	
	CSDD_SysReq	
	CSDD_Config	
	CSDD_RequestFlags	
	CSDD_CommandField	
	CSDD_Request	
	CSDD_SubBuffer	
	CSDD_SubBuffer  CSDD DeviceInfo	
	CSDD_PhyDelaySettings	
	CSDD_MemoryCardInfo	
	CSDD_DeviceState	42
	CSDD_CQInitConfig	
	CSDD_CQRequestData	
	CSDD_CQRequest	
	CSDD_CQDcmdRequest	
	CSDD_CQIntCoalescingCfg	
	CSDD_SDIO_SlotSettings	
	CSDD_SDIO_CidRegister	
6.69.	CSDD_SDIO_Device	43
6.70.	CSDD_SDIO_Slot	43
6.71.	CSDD_SDIO_Host	44
	CSDD_Callbacks	
	CSDD_CPhyConfigIoDelay	
	CSDD CPhyConfigLvsi	

6.75. CSDD_CPhyConfigDfiRd	
6.76. CSDD_CPhyConfigOutputDelay	
6.77. CSDD_CardInsertedCallback	
6.78. CSDD_CardRemovedCallback	45
6.79. CSDD_CardInterruptHandlerCallback	45
6.80. CSDD_CardInitializeCallback	. 45
6.81. CSDD_CardDeinitializeCallback	45
6.82. CSDD_AxiErrorCallback	
6.83. CSDD_SetTuneValCallback	
7. Driver Function API	
7.1. Introduction	
7.2. CSDD_Probe	
7.3. CSDD_Init	
7.4. CSDD_Start	
7.5. CSDD_Stop	
7.6. CSDD_ExecCardCommand	
7.7. CSDD_DeviceDetach	
7.8. CSDD_DeviceAttach	
7.8. CSDD_DeviceAttacii 7.9. CSDD_Abort	
7.10. CSDD_StandBy	
7.11. CSDD_Configure	
7.12. CSDD_Isr	
7.13. CSDD_ConfigureHighSpeed	
7.14. CSDD_CheckSlots	
7.15. CSDD_CheckInterrupt	
7.16. CSDD_ConfigureAccessMode	
7.17. CSDD_Tuning	
7.18. CSDD_ClockGeneratorSelect	
7.19. CSDD_PresetValueSwitch	
7.20. CSDD_ConfigureDriverStrength	
7.21. CSDD_MemoryCardLoadDriver	
7.22. CSDD_MemoryCardDataTransfer	
7.23. CSDD_MemoryCardDataTransfer2	
7.24. CSDD_MemoryCardConfigure	60
7.25. CSDD_MemoryCardDataErase	61
7.26. CSDD_MemCardPartialDataXfer	61
7.27. CSDD_MemCardInfXferStart	62
7.28. CSDD_MemCardInfXferContinue	63
7.29. CSDD_MemCardInfXferFinish	64
7.30. CSDD_MemCardDataXferNonBlock	65
7.31. CSDD_MemCardFinishXferNonBlock	
7.32. CSDD_PhySettingsSd3	
7.33. CSDD_PhySettingsSd4	
7.34. CSDD WritePhySet	
7.35. CSDD_ReadPhySet	
7.36. CSDD_ReadCardStatus	
7.37. CSDD SelectCard	
7.38. CSDD_ResetCard	
7.39. CSDD_ExecCmd55Command	
7.39. CSDD_ExecutionScottiniand 7.40. CSDD_AccessCccr	
7.40. CSDD_Accessecci	71 72
/ \$1	1/

	. CSDD_ReadExCsd	
7.43.	. CSDD_GetTupleFromCis	. 73
	. CSDD_ReadSdStatus	
7.45.	. CSDD_SetDriverStrength	. 75
7.46	. CSDD_ExecSetCurrentLimit	. 76
7.47	. CSDD_MmcSwitch	. 76
7.48.	. CSDD_MmcSetExtCsd	. 77
7.49.	. CSDD_MmcSetBootPartition	. 78
7.50.	. CSDD_MmcSetPartAccess	. 78
	. CSDD MmcSetBootAck	
7.52.	. CSDD MmcExecuteBoot	. 80
7.53.	. CSDD_MmcGetParitionBootSize	. 80
	. CSDD_GetInterfaceType	
	. CSDD_GetDeviceState	
	. CSDD_MemoryCardGetSecCount	
	. CSDD_SetDriverData	
	. CSDD_GetDriverData	
	. CSDD_SimpleInit	
	. CSDD_ResetHost	
	- CSDD_GetRca	
	. CSDD CQEnable	
	. CSDD_CQDisable	
	. CSDD_CQGetInitConfig	
	. CSDD_CQGetUnusedTaskId	
	. CSDD_CQStartExecuteTask	
	. CSDD_CQAttachRequest	
	. CSDD_CQExecuteDcmdRequest	
	. CSDD_CQGetDirectCmdConfig	
	. CSDD_CQSetDirectCmdConfig	
	. CSDD_CQSetIntCoalescingConfig	
	. CSDD_CQGetIntCoalescingConfig	
	. CSDD_CQGetIntCoalescingTimeoutBase	
	. CSDD_CQStartExecuteTasks	
	. CSDD_CQHalt	
	. CSDD_CQTaskDiscard	
	. CSDD_CQAllTasksDiscard	
	. CSDD_CQResetIntCoalCounters	
	. CSDD COSetResponseErrorMask	
	. CSDD_CQGetResponseErrorMask	
	. CSDD_GetBaseClk	
	. CSDD_WaitForRequest	
	. CSDD_setCPhyConfigIoDelay	
	. CSDD_GetCPhyConfigIoDelay	
	. CSDD_SetCPhyConfigLvsi	
	. CSDD_GetCPhyConfigLvsi	
	. CSDD_GetCPhyConfigDfiRd	
	. CSDD_GetCPhyConfigDfiRd	
	. CSDD_SetCPhyConfigOutputDelay	
	. CSDD_SetCPhyConfigOutputDetay	
	. CSDD_CPhyDllReset	
	. CSDD_CPhyDiffReset	
1.74.	CODD DUCT IIVEAUVIUUE	TOI

7.93.	CSDD_	_GetCPhyExtMode	101
7.94.	CSDD_	_SetCPhySdclkAdj	102
7.95.	CSDD	GetCPhvSdclkAdi	102

List	of	Fig	ures
		3	J — —

2 1	Structure of the CD Host controller driver	
7. I	. SHUCHIE OF THE STATIONS CONTIONER GILVER.	

# **List of Tables**

4.1.	Configuration options	10
5.1.	Configuration and Hardware Operation Information	12

# Chapter 1. Acronyms

API Application Programming Interface.

Core Driver Cadence Firmware component that provides IP programming abstraction.

CPS Cadence Platform Services. A set of basic platform specific access functions acting as hardware

abstraction layer for the core driver to operate.

IP Intelectual Property

SD Secure Digital

SDIO Secure Digital Input/Output

MMC Multi-Media Card

eMMC embedded Multi-Media Card

UHSI Ultra High Speed Phase I

SDMA Single-operation Direct Memory Address

ADMA Advanced-operation Direct Memory Address

PHY Physical layer

Chapter 2. Document Purpose		
This document is intended to serve as an overview and a reference for customers looking to use the Cadence SD Host Core Driver for the Cadence SD Host Core.		

# **Chapter 3. Description**

#### 3.1. General firmware info

The FW provided by Cadence is of 2 types:

- 1. Production Code: Code built to production standards, i.e. it is fully verified with positive and negative testing.
- 2. Reference Code: This is example code for the platform specific portions of the customers' code base. Reference code is only provided as an example to help the customer with his environment. Ideally code snippets from this will be looked at, and the customer will create his own versions of the reference code that is specific to his environment.

#### 3.2. Core driver features

Supported feautres:

- · Execution card command.
- Support PIO/SDMA/ADMA2/ADMA3 engines.
- Support for emmc boot.
- Support UHSI modes up to SDR104 including tuning procedure.
- Support eMMC high speed modes up to HS400ES.
- Programmable bus width.
- Support for PHY configuration.
- Support for eMMC command queuing

The Init function configures a number of parameters on creation of the driver instance, e.g. register base address, the size of descriptor lists, the callback functions

Provide event polling API for upper layer ISR - the driver's isr() function should be called in response to a hardware interrupt

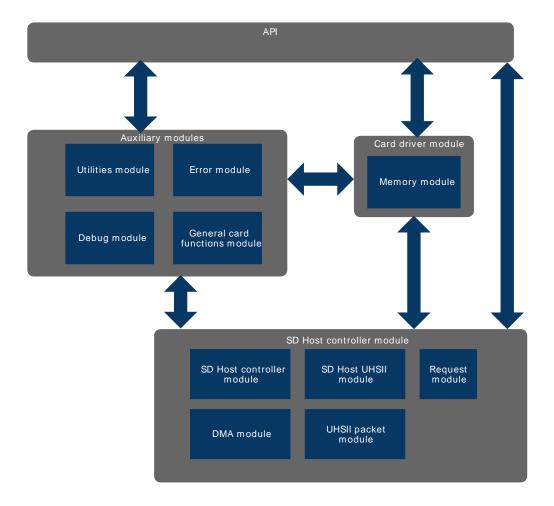
#### 3.2.1. SD Host driver structure

Figure presents driver structure. The driver can be divided into four blocks: SD Host controller module, auxiliary modules, memory card driver module, and user API module

- The SD Host module is the lowest and the most important lyaer and it consists of:
  - SD Host controller core module is responsible for initializing, configuring SD Host controller, initializing the
    newly inserted card, and managing other card drivers (e.g. memory card driver), executing commands on cards,
    handling interrupts,
  - Request module is responsible for preparing requests objects
  - DMA module is responsible for preparing, configuring and finishing DMA transfers
- The memory card driver module is responsible for transferring data to/from card and for configuring the memory card.

- The Auxiliary modules comprise of:
  - The debug module can be helpful during driver testing and debugging
  - The error module defines all error codes.
  - The general card function module implements such useful functions as read SDIO/SD/MMC card registers, change card state, read card status, reset card etc
- · API module shares user interface

Figure 3.1. Structure of the SD Host controller driver



### 3.3. Naming convensions

The SD Host Core Driver API will use the prefix CSDD\_ for public top-level names of functions and data objects/definitions.

### 3.4. System Usage

The SD Host Core Driver is supplied with reference code which illustrates the use of the core driver. It is provided as an example of how to use the driver API for basic operations. See the README file for further information.

# **Chapter 4. Core Driver Usage Model**

### 4.1. Description

In order to support multiple instances and provide the minimum name space pollution, the Core Driver is implemented as a structure that contains a function pointer table.

A public header is provided to define the API object structure and the data structures used. The file is contained in the include directory of the distribution as *csdd.h.* 

The API requires a private data pointer that provides the driver with instance information. It is critical that the upper software layer abides by the programming model.

Every API call apart from *probe* requires the private data address as the first parameter, to identify the driver instance and provide access to the internal state of that instance.

### 4.2. Probing the Hardware

The client code must obtain the object pointer to the core driver. It can be retrieved by issuing the *CSDD\_GetInstance()* function. This provides access to all of the API functions, but initially only *probe* may be called.

Before initialising the core driver, the client must first invoke the *probe* function. The *probe* function returns the dynamic memory requirements for the driver, depending on the configuration specified. The configuration information is passed to *probe* in an *CSDD\_Config* struct, although at this stage only those fields which affect the requirements need to be set, as indicated in the struct description. The client may repeat *probe* calls to customise configuration depending on available system resources.

The client code must then allocate the memory to the sizes returned by the probe function. .

#### 4.3. SD Host driver initialisation

After this stage, the client must reserve the necessary memory areas for the driver's private data and hardware configuration (if required). The CSDD\_Config struct should be filled out with the values for all initial configuration fields.

The driver can now be initialised with an *init* call, which will:

- initialise the driver instance
- configure the hardware as specified in the config parameter fields

e.g. *init* example, following on from *probe* example above:

```
CardInsertedCallback(void* pd, uint8_t slotIndex)
}
CardRemovedCallback(void* pd, uint8_t slotIndex)
}
AxiErrorCallback(void* pd, uint8_t axiError)
}
CSIH_Callbacks callbacks = {
   .cardInsertedCallback = CardInsertedCallback,
    .cardRemovedCallback = CardRemovedCallback,
    .axiErrorCallback = AxiErrorCallback
};
CSDD_SDIO_Host *privData = malloc(req.privDataSize);
cfg.descLogAddress = malloc(req.descSize);
cfg.descPhyAddress = config.descLogAddress;
cfg.idDescLogAddress = (uint32_t*)malloc(req.idDescSize);
cfg.idDescPhyAddress = cfg.idDescLogAddress;
if (sizeof(void*) > 4)
   config.dma64BitEn = 1;
else
   config.dma64BitEn = 0;
if (0 != (result = csdd0bj->init(privData, &cfg, &callbacks))) {
 printf("Error in csddObj->init: returned %d\n", result);
```

#### 4.4. Card initialisation

The memory card driver is loaded and the user is able to use the memory card driver. Next checking slots operations should be executed to check if a card is present in a slot and attach found cards.

```
// load memory card driver, it is necessary to use this driver
csddObj->memoryCardLoadDriver(privData);

// Check if there is a card in a slot
// if card is present then it will be initialized in this function
```

```
status = csddObj->checkSlots(privData);
if (status){
    // handle error ....
}

// function gets info about a device status
csddObj->getDeviceState(privData, slotIndex, &deviceState);

if(!deviceState.inserted) {
    //There is no card in slot
    //return 1;
}

if (deviceState.deviceType == CSDD_CARD_TYPE_MMC) {
    //mmc device found
}
if (deviceState.deviceType == CSDD_CARD_TYPE_SDMEM) {
    //sd device found
}
```

### 4.5. Access mode configuration

To change access mode user should use configure function.

### 4.6. Data transfer

Transfer data for all memory cards are executed by *memoryCardDataTransfer* and *memoryCardDataTransfer2* functions. These functions work on all memory devices (SD or eMMC).

### 4.6.1. Using ADMA with manually defined sub buffers

User can use sub buffers for two commands from API. There are: *execCardCommand* and *memoryCardDataTransfer2*. Sub buffer is a pair of values describing one buffer :an address and a buffer size. It can be used when one data transmission is split by a few buffers.

```
SDIO_SubBuffer subBuffers[2];
// define address of sub buffer 1
```

```
subBuffers[0].address = (uintptr_t)buffer1;
// define size of sub buffer 1
subBuffers[0].size = 512;
// define address of sub buffer 2
subBuffers[1].address = (uintptr_t)buffer2;
// define size of sub buffer 2
subBuffers[1].size = 1024;
// point data buffer to sub buffer array
pRequest->pDataBuffer = SubBuffers;
// set number of sub buffers
pRequest->SubBuffersCount = 2
// using sub bufers by execCardCommand function
csddObj->execCardCommand(privData, slotIndex, pRequest);
// using sub bufers by memoryCardDataTransfer2 function
csddObj->memoryCardDataTransfer2(privData, slotIndex, address, subBuffers,
     buffersSize, SDIO_TRANSFER_WRITE, 2);
```

### 4.7. Device specific functions and feaures

#### 4.7.1. eMMC devices

#### 4.7.1.1. Card access modes

Supported modes for eMMC devices.

- CSDD\_ACCESS\_MODE\_HS\_SDR
- CSDD\_ACCESS\_MODE\_HS\_DDR
- CSDD\_ACCESS\_MODE\_HS\_200
- CSDD\_ACCESS\_MODE\_HS\_400
- CSDD\_ACCESS\_MODE\_HS\_400\_ES

### 4.7.1.2. Command queuing

Command queuing is a part of eMMC 5.1 standard. By default it is disabled. To enable it cQEnable function must be called. To transfer data in CQ mode mode yu need to use another set of functions.

```
/* enabling CQ */
uint8_t status;
CSDD_CQInitConfig cQConfig;

cQConfig.sendStatBlckCount = 1;
cQConfig.sendStatIdleTimer = 0x1000;

status = sdHostDriver->cQEnable(sdHost, &cQConfig);
if (status){
    // handle error
}

/* executing data transfer in CQ mode*/
CSDD_CQRequest request;
```

```
CSDD_CQRequestData buffers;
memset(&request, 0, sizeof(request));
status = sdHostDriver->cQGetUnusedTaskId(sdHost, &request.taskId);
if (status){
    // handle error
buffers.buffPhyAddr = (uintptr_t)writeBuffer;
buffers.bufferSize = DataSize;
request.blockAddress = 0;
request.blockCount = 4;
request.buffers = &buffers;
request.numberOfBuffers = 1;
request.transferDirection = CSDD_TRANSFER_WRITE;
status = sdHostDriver->cQAttachRequest(sdHost, &request);
if (status){
    // handle error
status = sdHostDriver->cQStartExecuteTask(sdHost, request.taskId);
if (status){
    // handle error
while(request.cQReqStat == CSDD_CQ_REQ_STAT_PENDING){
    /*if interrupts are disabled then we need to call
    * interrupt handler manually in polling mode*/
    if (!withInt){
       bool handled;
        sdHostDriver->isr(sdHost, &handled);
    }
```

#### 4.7.1.3. eMMC Boot

There are a few functions in the SD host driver to configure and execute eMMC boot operation.

There are:

- mmcGetParitionBootSize get to know what is partiion size before program it
- mmcSetPartAccess select partion which will be accessed. After selection standard *memoryCardDataTransfer* function are used to transfer data to selected partition.
- mmcSetBootPartition set active boot partition for boot operation
- mmcExecuteBoot execute boot operation

#### 4.7.2. SD devices (UHSI and legacy modes)

#### 4.7.2.1. Card access modes

Card access modes for SD UHSI devices:

• CSDD\_ACCESS\_MODE\_SDR12

- CSDD\_ACCESS\_MODE\_SDR25
- CSDD\_ACCESS\_MODE\_SDR50
- CSDD ACCESS MODE DDR50
- CSDD\_ACCESS\_MODE\_SDR104

### 4.8. Interrupt mode

Driver can work with interrupts enabled or disabled. When user calls *start* function then interrupts are enabled and driver works in interrupt mode. If this function is not called the interrupts are disabled and driver works in polling mode. The most of communication with a card takes place inside the *execCardCommand* function. User should be aware how to use this function. When driver works in interrupt mode then user need only to check the status flag of *CSDD\_Request* parameter passed to *execCardCommand* function and wait until it is 0xFF. If driver works in polling mode user need to keep executing isr function untill status flag of a *CSDD\_Request* is not 0xFF. When execution card commands is made in other driver functions then polling is automatically made in these functions.

### 4.9. PHY configuration

For PHY configuration for SD6 and newer, combo PHY driver is recommended to be used. Please refer to CCP Core Driver user guide to get more information about combo PHY driver functionality. There are a few functions in Core Driver which are used together with combo PHY driver for PHY configuration. All of them contains CPhy in its name. For older SD host controller there is no Combo PHY so the previous PHY functions should be used: *writePhySet* and *readPhySet*. Please refer to reference code to get to know how to configure PHY.

### 4.10. Configuration of SD Host Controller Driver

The configurability of the CSDD driver helps to change CSDD driver options easily. All configuration options are defined in the CSDD\_Config.h file. Below there is a description of all driver options:

**Table 4.1. Configuration options** 

Configuration options	Description
SDIO_SDMA_SUPPORT	If the value is 0, then SDMA mode is disabled; if the value is 1, then SDMA mode is enabled
SDIO_ADMA1_SUPPORT	If the value is 0, then ADMA1 mode is disabled; if the value is 1, then ADMA1 mode is enabled
SDIO_ADMA2_SUPPORT	If the value is 0, then ADMA2 mode is disabled; if the value is 1, then ADMA2 mode is enabled
SDIO_ADMA3_SUPPORT	If the value is 0, then ADMA3 mode is disabled; if the value is 1, then ADMA3 mode is enabled
DEBOUNCING_TIME	This defines the debouncing time period.
COMMANDS_TIMEOUT	This is an iteration count, after which the timeout error will be reported if a command does not execute (mainly used in WaitForValue function).
ENABLE_CARD_INTERRUPT	Enables or disables, detecting a card interrupt (in interrupt mode). User would enable this option only if a procedure to handle card interrupt is implemented.
SYTEM_CLK_KHZ	It defines system clock in kHz. It is used as base clock if base clock in SRS16 register is 0

Configuration options	Description
MAX_DESCR_BUFF_SIZE	Buffer size for ADMA descriptors
MAX_COMMAND_DESCR_BUFF_SIZE	buffer size for ADMA 3 command descriptors
MAX_INTEGREATED_DESCR_BUFF_SIZE	buffer size for ADMA 3 integrated descriptors
SDIO_SLOT_COUNT	SDIO slot count in controller
MAX_SUPPORTED_DEVICE_COUNT	Maximum supported card/device drivers count. Default it is 2 SD and MMC.
USE_AUTO_CMD	Maximum supported card/device drivers count. Default it is 2 SD and MMC.
CHANGE_DATA_ENDIANITY_NODMA	This option can be used to change endianity of PIO transferred data form/to a card device.
POWER_UP_DELAY_US	This option defines delay in microseconds after power up before enabling clock.
SDIO_CFG_SUB_BUFFERS_COUNT	Number of sub-buffers used temporary by DMA module to create ADMA descriptors
SDIO_CFG_ENABLE_IO	Option enables support for IO cards. It should be disabled it was not tested yet
SDIO_CFG_RESET_COUNT	Configuration of how many times each reset operation shall be executed
SDIO_CFG_ENABLE_MMC	This option disables or enables support for MMC devices
SDIO_CFG_HOST_VER	Version of SD Host controller. It can be 3, 4 or 6 depending on which version of SD Host controller is used.

# 4.11. Platform depending configuration

The most important platform depending macros are located in CPS. But some extra macros are implemented in environment.h file. User can change this macros to adjust the Core Driver to own platform.

Endianess macros: CpuToLe32(a), LeToCpu32(a) macros are used during creation the DMA descriptors. If byte swapping is necessary it should be done in these macros.

GetByte macro is used to get one byte from 4 bytes word

# **Chapter 5. Configuration and Hardware Operation Information**

### 5.1. Introduction

The following definitions specify the driver operation environment that is defined by hardware configuration or client code.

These defines are located in the header file of the core driver.

**Table 5.1. Configuration and Hardware Operation Information** 

#define	value	description
CSDD_MAX_NUMBER_COMMAND		CommandField structure maximum array size.
CSDD_MAX_DEV_PER_SLOT	1U	Max devices per one slot.
CSDD_CQ_REQUEST_PTR	CSDD_CQRequest*	

# **Chapter 6. Dynamic Data Structures**

#### 6.1. Introduction

This section defines the data structures used by the driver to provide hardware information, modification and dynamic operation of the driver.

These data structures are defined in the header file of the core driver and utilized by the API.

### 6.2. CSDD\_SysReq\_s

Type: struct

#### **Fields**

pDataSize private data size

descSize ADMA descriptors buffer size.

idDescSize ADMA3 Integrated descriptors buffer size.

### 6.3. CSDD\_Config\_s

Type: struct

### **Description**

Structure defining all configuration parameters applied on driver start-up.

#### **Fields**

regBase base address of CSDD registers

descLogAddress logical address of ADMA2descriptors

descPhyAddress physical address of ADMA2descriptors

idDescLogAddress logical address of ADMA3 integrated descriptors

idDescPhyAddress physical address of ADMA3 integrated descriptors

dma64BitEn Enable DMA width 64bit.

# 6.4. CSDD\_RequestFlags\_s

Type: struct

### **Description**

Structure describes a parameters of SD request.

#### **Fields**

commandType Type of command.

dataPresent This field specifies if request will transfer the data.

1 - data is present, 0 - no data

responseType Response type.

dataTransferDirection This variable specifies the data direction transfer.

autoCMD12Enable if the flag has a value of 1, then AutoCMD12 is enabled; value of 0 means otherwise

(flag to be taken into consideration only in data transfer commands)

autoCMD23Enable 1 - enable Auto CMD23, 0 - disable Auto CMD23

hwResponseCheck 1 - use hardware response checking

appCmd 1 - APP\_CMD application-specific command

isInfinite 1 - means infinite transfer

### 6.5. CSDD\_CommandField\_s

Type: struct

### **Description**

Structure holds data transfer details.

#### **Fields**

argument Argument of command to execute.

requestFlags Request flags.

command Command to execute.

blockCount number of blocks to send or receive.

Field to be taken into consideration only in data transfer commands

blockLen size of block data in bytes to send or receive; field to be taken into consideration only in data

transfer commands

subBuffersCount Number of sub-buffers.

pDataBuffer data buffer or buffers for read/write data; field to be taken into consideration only in data

transfer commands.

If the SubBuffersCount parameter is 0 then it is just pointer to data. But if the

SubBuffersCount is more than 0 then it is pointer to array of sub buffers.

### 6.6. CSDD\_Request\_s

Type: struct

### **Description**

Structure describes a request which should be executed by host.

#### **Fields**

response Response pointer (used in SD layer)

responseTab Buffer for command response.

pBufferPos Current buffer position.

dataRemaining Number of bytes remaining in the transfer.

status Request status.

admaDescriptorTable ADMA descriptor table.

IdDescriptorTable ADMA3 integrated descriptor table.

pSdioHost Pointer to SDIO host object.

busyCheckFlags Internal field.

requestType Request type.

respSize Size of response packet in bytes.

respRegOffset Response register.

infiniteStatus

slotIndex slot index

subCommandRequest pointer to subcommand

commandCategory Indicate request is executed as a subcommand or Main command.

cmdCount Number of command in a request.

For noDMA, SDMA, ADMA1, ADMA2 must be 1 and for ADMA3 - 1 to

CSDD\_MAX\_NUMBER\_COMMAND

pCmd Array to hold set of commands.

### 6.7. CSDD\_SubBuffer\_s

Type: struct

### **Description**

structure contains info about one buffer.

Used to transfer group of buffers

#### **Fields**

address Address of sub buffer.

size Size in bytes of sub buffer.

### 6.8. CSDD DeviceInfo s

Type: struct

### **Description**

Structure contains information that will be used to recognize type of supported devices.

#### **Fields**

manufacturerCode Manufacturer code read from SDIO card CIS registers.

manufacturerInformation Manufacturer information(Part Number and/or Revision) read from SDIO card

CIS register.

deviceType Type of device (SDIO card, SD/MMC memory card or combo card)

pCardInterruptHandler Function pointer which should point to interrupt function which handle SDIO

card interrupt.

pCardInitialize Function pointer which should point to function which initialize the card device.

pCardDeinitialize Function pointer which should point to function which de-initialize the card

device.

## 6.9. CSDD\_PhyDelaySettings\_s

Type: struct

#### **Fields**

highSpeed PHY delay for SD High speed.

defaultSpeed PHY delay for SD default speed.

uhsiSdr12 PHY delay for SDR12 mode.

uhsiSdr25 PHY delay for SDR25 mode.

uhsiSdr50 PHY delay for SDR50 mode.

uhsiDdr50 PHY delay for DDR50 mode.

mmcLegacy PHY delay for eMMC legacy mode.

mmcSdr PHY delay for eMMC High speed SDR mode.

mmcDdr PHY delay for eMMC High speed DDR mode.

mmcHs400 PHY delay for eMMC High speed HS400 mode.

### 6.10. CSDD\_MemoryCardInfo\_s

Type: struct

#### **Fields**

blockSize block size

commandClasses card command classes

deviceSizeMB device size in MB

partialReadAllowed Defines whether partial block sizes can be used in block read commands.

partialWriteAlloed Defines whether partial block sizes can be used in block write commands.

writeBlkMisalign Defines if the data block to be written by one command can be spread over more than

one physical block of the memory device.

readBlkMisalign Defines if the data block to be read by one command can be spread over more than one

physical block of the memory device.

sectorSize The size of an erasable sector.

The content of this register is a 7-bit binary coded value, defining the number of write

blocks

eraseBlkEn The EraseBlkEn defines the granularity of the unit size of the data to be erased.

readBlkLen The maximum read data block length.

writeBlkLen The maximum write data block length.

### 6.11. CSDD\_DeviceState\_s

Type: struct

#### **Fields**

inserted is card physical located in slot

attached is card properly detected and initialized

deviceType device type

uhsSupported is Ultra High Speed I mode supported

### 6.12. CSDD\_CQInitConfig\_s

Type: struct

### **Description**

Command queuing initial configuration.

#### **Fields**

sendStatBlckCount Send Status Command Block Counter.

if 0 then the CQE does not send CMD13 during data transfer. The value is 1, 2, or N means, the CQE sends CMD13 is transferred during last, one before last, or (N-1) before

last block, respectively

sendStatIdleTimer time interval of polling device status (CMD13) when controller is idle

### 6.13. CSDD\_CQRequestData\_s

Type: struct

### **Description**

Request describing single task.

#### **Fields**

buffPhyAddr physical address of data buffer

bufferSize Size of buffer in bytes.

### 6.14. CSDD\_CQRequest\_s

Type: struct

### **Description**

Data transfer request.

#### **Fields**

blockCount Number of blocks to be read/written.

blockAddress Data block address.

taskId task ID - it must be unused

buffers it define one data buffer with data

numberOfBuffers number of buffers with data

contextId context ID

transferDirection Data transfer direction.

highPriorityEn Enable disable high priority.

queueBarrierEn Enable queue barrier.

forceProgEn When 1 data shall be forcefully programmed to nonvolatile storage instead of volatile

cache while cache is turned.

tagRequestEn Enable tag request.

intCoalEn If 1 Interrupt will be generated when interrupt coalescing conditions have been met.

If 0 then interrupt will be generated when task is finished.

reliableWriteEn Enable reliable write.

descDataBuffer pointer to virtual memory area where descriptors can be hold.

Virtual address. It is necessary if there is more than one data buffer is used.

descDataPhyAddr address of physical memory area where descriptors can be hold.

It is necessary if there is more than one data buffer is used.

descDataSize size of memory area where descriptors can be hold.

It is used by driver to verify if there is enough space to all transfer descriptors. It is

necessary if there is more than one data buffer is used.

cQReqStat Request status.

Only driver can modify it.

### 6.15. CSDD\_CQDcmdRequest\_s

Type: struct

### **Description**

Direct command request used to execute eMMC command by their index and argument.

It is not used to data transfer

#### **Fields**

cmdIdx The index of the command to be sent to device.

responseType response expected to be received from the device

argument of the command to be sent to the device

queueBarrierEn Enable queue barrier.

cmdTiming 1 - command may be sent to device during data activity or busy, 0 - command may not be sent

to device during data activity or busy

response command response get from device after command execution

cQReqStat Request status.

Only driver can modify it.

### 6.16. CSDD\_CQIntCoalescingCfg\_s

Type: struct

### **Description**

Command queuing interrupt coalescing configuration.

#### **Fields**

enable enable/disable Interrupt coalescing 1 - enable, 0 - disable

threshold counter threshold number of tasks completions which are required in order to generate an interrupt

timeout timeout value

# 6.17. CSDD\_SDIO\_SlotSettings\_s

Type: struct

#### **Fields**

DMA 64 bit enabled.

HostVer4\_En Host version 4 enabled.

# 6.18. CSDD\_SDIO\_CidRegister\_s

Type: struct

### **Description**

Structure defines CID register fields.

#### **Fields**

manufacturerId An 8-bit binary number that identifies the card manufacturer.

 ${\tt oemApplicationId} \qquad A \ 2\text{-character ASCII string that identifies the card OEM and/or the card contents}.$ 

productName Product name is a string, 5-character ASCII string.

productRevision The product revision is composed of two Binary Coded Decimal (BCD) digits.

productSn Product serial number.

manufacturingDate Manufacturing date (year and month)

#### 6.19. CSDD\_SDIO\_Device\_s

Type: struct

### **Description**

Structure contains information about inserted card and functions to handle them.

#### **Fields**

deviceType Type of device.

Types of devices are defined here Devices

DeviceCapacity Card capacity information.

Types of device capacities are define here Capacities

RCA Relative card address or NODE ID.

SpecVersNumb Specification Version Number.

SupportedBusWidths Card device supported bus width.

They are defined here BusWidths. This parameter is logic sum of all supported bus

widths

CommonCISAddress Address of card's common Card Information Structure (CIS)

IsSelected This variable defines if the card is selected or unselected.

pCardInterruptHandler Function pointer which should point to interrupt function which hanle card interrupt.

pCardDeinitialize Function pointer which should point to function which deinitialize the card device.

CardDriverData Private driver data.

pSlot Slot in which card is inserted.

UhsiSupported Flag is set if UHS-I mode is supported by the device.

CMD23Supported Flag is set if CMD23 commad is supported by the device.

CMD20Supported Flag is set if CMD20 commad is supported by the device.

cQDepth command queuing depth

### 6.20. CSDD\_SDIO\_Slot\_s

Type: struct

### **Description**

Structure contains information a SDIO Host slot.

#### **Fields**

RegOffset start address of the slot registers

DMABufferBoundary Size of buffer in the system memory which is used by DMA module.

pDevice Current selected device.

Devices These structure describes SD devices connected to the host.

BusWidth Current set bus width.

The bus widths are defined here BusWidths

pCurrentRequest Pointer to current executing SD request.

subCommandStatus

CardInserted 1 - card is inserted, 0 - there is no card in slot

UhsiSelected voltage is switched, host and sd card work in UHSI mode

Abort Request Abort current transaction.

IntSettings Settings of signaling the interrupts.

ErrorRecorvering Flag is set if error recovering is already executing.

pSdioHost pointer to the sdio host object

SlotNr slot number

DescriptorBuffer pointer to logical address of descriptor buffer

DescriptorDMAAddr pointer to physical address of descriptor buffer

IntegratedDescriptorBuffer

pointer to logical address of ADMA3 integrated descriptor buffer

IntegratedDescriptorDMAAddr

pointer to physical address of ADMA3 integrated descriptor buffer

ProgClockMode If this flag is set then programmable clock mode is enabled, if it is 0 then 10-

bit divider clock mode is enabled.

RetuningEnabled flag informs if re-tuning is currently enabled

AccessMode fields keep info about current card access mode (UHS-I)

RetuningRequest flags informs if host requests for re-tuning

DataCount data count in bytes which are transferred since last re-tuning procedure

DmaMode DMA mode.

AuxBuff extra buffer used for read data during initialization (256 = 512/2)

InterfaceType Interface type can be: - CSDD\_INTERFACE\_TYPE\_SD.

SlotSettings other slot settings

dmaModeSelected indicate the current DMA mode

NeedAttach flag is set when card is in slot but it is not attached by the driver

CQDcmdEnabled CQ: it informs if DCMD mode is enabled.

In DCMD mode the pointer CQCurrentReg[31] is always NULL

CQEnabled is command queuing enabled

CQHalted is command queuing halted

CQIntCoalescingEn is interrupt coalescing enabled

CQDescriptorBuffer pointer to logical address of task descriptor buffer

CQDescriptorDmaAddr pointer to physical address of task descriptor buffer

CQCurrentReq pointer to current request of each normal (not DCMD) task

CQCurrentDcmdReq used only if DCMD mode is enabled

CQDescSize task/transfer descriptor size in bytes

### 6.21. CSDD\_SDIO\_Host\_s

Type: struct

### **Description**

Structure contains information about inserted card and functions to handle them.

#### **Fields**

RegOffset start address of the host registers

Slots slots array which belong to the host

HostBusMode host bus mode (SPI SD, in the current version only SD is supported)

NumberOfSlots The host's slots count.

SpecVersNumb Specification Version Number.

pCardRemoved callback called when card removed interrupt occurs

pCardInserted callback called when card inserted interrupt occurs

pSetTuneVal function pointer which point to function which handle mmc tunning

axiErrorCallback called when AXI error occurs

drvData pointer to user driver data

intEn interrupts enabled

dma64BitEn DMA 64 bit enable.

cqSupported emmc command queueing is supported

hs400EsSupported HS 400ES supported.

hostCtrlVer Host Controller Version.

HostFixVer Fix Version Number: Number of the fix related to the Host Controller Version.

### 6.22. CSDD\_Callbacks\_s

Type: struct

### **Description**

Function pointers to event notification callbacks issued by driver functions when interrupt occurs.

Each call passes the drivers privateData pointer and slotIndex for instance identification if necessary.

#### **Fields**

cardInsertedCallback

cardRemovedCallback

axiErrorCallback

setTuneValCallback

### 6.23. CSDD\_CPhyConfigloDelay\_s

Type: struct

### **Description**

Controls the IO delay related timings - Combo PHY.

### **Fields**

rwCompensate

idelayVal

### 6.24. CSDD\_CPhyConfigLvsi\_s

Type: struct

### **Description**

Controls LVSI related timings - Combo PHY.

#### **Fields**

lvsiCnt

lvsiTcksel

### 6.25. CSDD\_CPhyConfigDfiRd\_s

Type: struct

### **Description**

Controls rddata and rdcmd parameters - Combo PHY.

#### **Fields**

rddataSwap

rddataEn

rdcmdEn

# 6.26. CSDD\_CPhyConfigOutputDelay\_s

Type: struct

### **Description**

Controls CMD DAT output delay related timings - Combo PHY.

#### **Fields**

wrdata1SdclkDly

wrdata0SdclkDly

wrcmd1SdclkDly

wrcmd0SdclkDly

wrdata1Dly

wrdata0Dly

wrcmd1Dly

wrcmd0Dly

# 6.27. CSDD\_CccrRegAddr

Type: enum

### **Description**

CCCR card control registers definitions.

#### **Values**

Value: = 0U

CSDD\_CCCR\_SD\_SPEC\_REV SD version number register.

Value: = 1U

CSDD\_CCCR\_IO\_ENABLE IO enable function register.

Value: = 2U

CSDD\_CCCR\_IO\_READY IO ready function register.

Value: = 3U

CSDD\_CCCR\_INT\_ENABLE interrupt enable register

Value: = 4U

CSDD\_CCCR\_INT\_PENDING interrupt pending register

Value: = 5U

CSDD\_CCCR\_ABORT IO Abort register.

It used to stop a function transfer.

Value:=6U

CSDD\_CCCR\_BUS\_CONTROL Bus interface control register.

Value: = 7U

CSDD\_CCCR\_CARD\_CAPABILITY

Card capability register.

Value: = 8U

CSDD\_CCCR\_CIS\_POINTER Pointer to card's common Card Information Structure (CIS)

Value: = 9U

CSDD\_CCCR\_BUS\_SUSPENDED Bus suspend register.

Value: = 12U

CSDD\_CCCR\_FUNCTION\_SELECT

Function select register.

Value: = 13U

CSDD\_CCCR\_EXEC\_FLAGS Exec flags register.

The bits of this register are used by the host to determine the current execution

status of all functions (1-7) and memory (0).

Value: = 14U

CSDD\_CCCR\_READY\_FLAGS Ready flags register.

The bits of this register tell the host the read or write busy status for functions

(1-7) and memory (0).

Value: = 15U

 ${\tt CSDD\_CCCR\_FN0\_BLOCK\_SIZE} \quad I/O \ block \ size \ for \ Function \ 0.$ 

Value: = 16U

CSDD\_CCCR\_POWER\_CONTROL Power control register.

Value: = 18U

CSDD\_CCCR\_HIGH\_SPEED Bus speed select.

Value: = 19U

CSDD\_CCCR\_UHSI\_SUPPORT UHS-I support info.

Value: = 20U

CSDD CCCR DRIVER STRENGTH

Driver Strength.

Value: = 21U

CSDD\_CCCR\_INT\_EXT Interrupt extension.

Value: = 22U

# 6.28. CSDD\_TupleCode

Type: enum

## **Description**

Tuple names definitions of SDIO card.

### **Values**

CSDD\_TUPLE\_CISTPL\_NULL NULL tuple.

Value: = 0U

CSDD\_TUPLE\_CISTPL\_CHECKSUM

Checksum control.

Value: = 16U

 ${\tt CSDD\_TUPLE\_CISTPL\_VERS\_1} \quad Level~1~version/product~information.$ 

Value: = 21U

CSDD\_TUPLE\_CISTPL\_ALTSTR Alternate language string tuple.

Value: = 22U

 ${\tt CSDD\_TUPLE\_CISTPL\_MANFID} \quad Manufacturer \ identification \ string \ tuple.$ 

Value: = 32U

CSDD\_TUPLE\_CISTPL\_FUNCID Function identification tuple.

Value: = 33U

CSDD\_TUPLE\_CISTPL\_SDIO\_STD

Additional information for functions built to support application specifications

for standard SDIO functions.

Value: = 145U

CSDD\_TUPLE\_CISTPL\_SDIO\_EXT

Reserved for future use with SDIO devices.

Value: = 146U

 ${\tt CSDD\_TUPLE\_CISTPL\_END} \qquad \quad \text{The End-of-chain Tuple}.$ 

Value: = 255U

# 6.29. CSDD\_CmdType

Type: enum

#### **Values**

CSDD\_CMD\_TYPE\_NORMAL normal command

Value: = 0U

CSDD\_CMD\_TYPE\_SUSPEND suspend command

Value: = 1U

CSDD\_CMD\_TYPE\_RESUME resume command

Value: = 2U

CSDD\_CMD\_TYPE\_ABORT abort command

Value: = 3U

CSDD\_CMD\_TYPE\_TRANS\_ABORT

abort command in UHS-II native protocol

Value: = 4U

CSDD\_CMD\_TYPE\_GO\_DORMANT go into dormant state command (UHS-II command type)

Value: = 5U

# 6.30. CSDD\_CmdCat

Type: enum

# **Description**

Command can be be MainCommand or SubCommand depending on the DAT line Busy during command execution.

### **Values**

CSDD\_CMD\_CAT\_MAIN Command is called as Main command if it contains a subcommand.

Value: = 0U

CSDD\_CMD\_CAT\_SUB Command is called as Sub command if it comes under a command.

Value: = 1U

CSDD\_CMD\_CAT\_NORMAL Normal Command.

Value: = 2U

# 6.31. CSDD\_ResponseType

#### Type: enum

### **Values**

 ${\tt CSDD\_RESPONSE\_NO\_RESP} \quad Value:=0U$ Value: = 1UCSDD\_RESPONSE\_R1 Value: = 2UCSDD\_RESPONSE\_R1B Value: = 3UCSDD\_RESPONSE\_R2 CSDD\_RESPONSE\_R3 Value: = 4UCSDD\_RESPONSE\_R4 Value: = 5UValue: = 6UCSDD\_RESPONSE\_R5 Value: = 7UCSDD\_RESPONSE\_R5B CSDD\_RESPONSE\_R6 Value: = 8UValue: = 9U CSDD\_RESPONSE\_R7

## 6.32. CSDD\_CardType

Type: enum

### **Values**

CSDD\_CARD\_TYPE\_NONE Value: = 0U

CSDD\_CARD\_TYPE\_SDIO Value: = 1U

CSDD\_CARD\_TYPE\_SDMEM Value: = 2U

CSDD\_CARD\_TYPE\_COMBO Value: = 3U

CSDD\_CARD\_TYPE\_MMC Value: = 4U

# 6.33. CSDD\_Capacity

Type: enum

#### **Values**

CSDD\_CAPACITY\_NORMAL Value: = 1U  $CSDD_CAPACITY_HIGH$  Value: = 2U

# 6.34. CSDD\_BusWidth

Type: enum

### **Values**

CSDD\_BUS\_WIDTH\_1 Value: = 1U

CSDD\_BUS\_WIDTH\_4 Value: = 4U

CSDD\_BUS\_WIDTH\_8 Value: = 8U

CSDD\_BUS\_WIDTH\_4\_DDR Value: = 5U

CSDD\_BUS\_WIDTH\_8\_DDR Value: = 6U

# 6.35. CSDD\_BusMode

Type: enum

### **Values**

CSDD\_BUS\_MODE\_SPI Value: = 1U CSDD\_BUS\_MODE\_SD Value: = 2U

# 6.36. CSDD\_InterfaceType

Type: enum

#### **Values**

CSDD\_INTERFACE\_TYPE\_SD Value: = 1U
CSDD\_INTERFACE\_TYPE\_UNKNOWN

Value: = 2U

# 6.37. CSDD\_RequestType

Type: enum

### **Values**

 ${\tt CSDD\_REQUEST\_TYPE\_SD} \quad SD \ layer \ request \ type \ (SD)$ 

Value: = 1U

# 6.38. CSDD\_ConfigCmd

Type: enum

### **Values**

CSDD\_CONFIG\_SET\_CLK set host clock frequency

Value:=1U

CSDD\_CONFIG\_SET\_BUS\_WIDTH

set host bus width

Value: = 2U

CSDD\_CONFIG\_SET\_DAT\_TIMEOUT

set timeout on DAT line.

Argument is timeout in microseconds

Value: = 3U

CSDD\_CONFIG\_DISABLE\_SIGNAL\_INTERRUPT

disable signal interrupts

Value: = 4U

CSDD\_CONFIG\_RESTORE\_SIGNAL\_INTERRUPT

restore signal interrupts

Value: = 5U

CSDD\_CONFIG\_SET\_DMA\_MODE set DMA mode

Value: = 6U

# 6.39. CSDD\_TransferDirection

Type: enum

### **Values**

CSDD\_TRANSFER\_READ Value: = 1U

 ${\tt CSDD\_TRANSFER\_WRITE} \quad Value := 0 U$ 

# 6.40. CSDD\_SpeedMode

Type: enum

#### **Values**

CSDD\_ACCESS\_MODE\_SDR12 access mode - SDR12 default (CLK: max 25MHz, DT: max 12MB/s)

Value: = 0U

CSDD\_ACCESS\_MODE\_SDR25 access mode - SDR15 default (CLK: max 50MHz, DT: max 25MB/s)

Value: = 1U

CSDD\_ACCESS\_MODE\_SDR50 access mode - SDR50 default (CLK: max 100MHz, DT: max 50MB/s)

Value: = 2U

CSDD\_ACCESS\_MODE\_SDR104 access mode - SDR104 default (CLK: max 208MHz, DT: max 104MB/s)

Value: = 3U

CSDD\_ACCESS\_MODE\_DDR50 access mode - DDR50 default (CLK: max 50MHz, DT: max 50MB/s)

Value: = 4U

CSDD\_ACCESS\_MODE\_MMC\_LEGACY

MMC access mode - legacy mode (CLK: max 26MHz, DT: max 26MB/s)

Value: = 6U

CSDD\_ACCESS\_MODE\_HS\_SDR MMC access mode - high speed SDR mode (CLK: max 26MHz, DT: max

26MB/s)

Value: = 7U

CSDD\_ACCESS\_MODE\_HS\_DDR MMC access mode - high speed DDR mode (CLK: max 52MHz, DT: max

104MB/s)

Value: = 8U

CSDD\_ACCESS\_MODE\_HS\_200 MMC access mode - HS200 mode (CLK: max 200MHz, DT: max 200MB/s)

Value: = 9U

CSDD ACCESS MODE HS 400 MMC access mode - HS400 mode (CLK: max 200MHz, DT: max 400MB/s)

Value: = 10U

CSDD\_ACCESS\_MODE\_HS\_400\_ES

MMC access mode - HS400 using Enhanced Strobe (CLK: max 200MHz, DT:

max 400MB/s)

Value: = 11U

# 6.41. CSDD\_DmaMode

Type: enum

#### **Values**

CSDD\_SDMA\_MODE Standard DMA mode.

Value: = 0U

CSDD\_ADMA1\_MODE Advanced DMA Mode Version 1.

Value: = 1U

CSDD\_ADMA2\_MODE Advanced DMA Mode Version 2.

Value: = 2U

CSDD\_ADMA3\_MODE Advanced DMA Mode Version 3.

Value: = 3U

CSDD\_AUTO\_MODE DMA mode is selected automatically.

Value: = 4U

CSDD\_NONEDMA\_MODE DMA is disabled.

Value: = 255U

# 6.42. CSDD\_ParitionAccess

Type: enum

# **Description**

Partition name to set access.

### **Values**

CSDD\_EMMC\_ACCCESS\_BOOT\_NONE

none partition

Value: = 0U

CSDD\_EMMC\_ACCCESS\_BOOT\_1 boot partition 1

Value: = 1U

CSDD\_EMMC\_ACCCESS\_BOOT\_2 boot partition 2

Value: = 2U

CSDD\_EMMC\_ACCCESS\_BOOT\_GENERAL\_PURP\_1

general purpose partition 1

Value: = 3U

CSDD\_EMMC\_ACCCESS\_BOOT\_GENERAL\_PURP\_2

general purpose partition 2

Value:=4U

CSDD\_EMMC\_ACCCESS\_BOOT\_GENERAL\_PURP\_3

general purpose partition 3

Value: = 5U

CSDD\_EMMC\_ACCCESS\_BOOT\_GENERAL\_PURP\_4

general purpose partition 4

Value: = 6U

CSDD\_EMMC\_ACCCESS\_BOOT\_RPMB

Replay-protected memory-block partition.

Value: = 7U

# 6.43. CSDD\_ParitionBoot

Type: enum

## **Description**

Partition to boot.

### **Values**

CSDD\_EMMC\_BOOT\_NONE none partition

Value: = 0U

CSDD\_EMMC\_BOOT\_1 set boot partition 1 for boot

Value: = 1U

CSDD\_EMMC\_BOOT\_2 set boot partition 2 for boot

Value: = 2U

CSDD\_EMMC\_BOOT\_USER set user partition for boot

Value: = 3U

# 6.44. CSDD\_MmcConfigCmd

Type: enum

# **Description**

Partition to boot.

### **Values**

CSDD\_MMC\_CARD\_CONF\_CARD\_LOCK

Lock device.

Value: = 4U

CSDD\_MMC\_CARD\_CONF\_CARD\_UNLOCK

Unlock device.

Value: = 0U

 ${\tt CSDD\_MMC\_CARD\_CONF\_SET\_PASSWORD}$ 

Set device password.

Value: = 1U

CSDD\_MMC\_CARD\_CONF\_RESET\_PASSWORD

Reset device password.

Value: = 2U

# 6.45. CSDD\_DriverStrengthType

Type: enum

## **Description**

Driver strength type.

### **Values**

CSDD\_SWITCH\_DRIVER\_STRENGTH\_TYPE\_A

Device driver strength A.

Value: = 1U

CSDD\_SWITCH\_DRIVER\_STRENGTH\_TYPE\_B

Device driver strength B.

Value: = 2U

CSDD\_SWITCH\_DRIVER\_STRENGTH\_TYPE\_C

Device driver strength C.

Value: = 3U

 ${\tt CSDD\_SWITCH\_DRIVER\_STRENGTH\_TYPE\_D}$ 

Device driver strength D.

Value:=4U

# 6.46. CSDD\_DriverCurrentLimit

Type: enum

## **Description**

SD card driver current limit.

#### **Values**

CSDD\_SDCARD\_SWITCH\_CURRENT\_LIMIT\_200

Card driver current limit - 200mA default.

Value: = 0U

CSDD\_SDCARD\_SWITCH\_CURRENT\_LIMIT\_400

Card driver current limit - 400mA.

Value: = 1U

CSDD\_SDCARD\_SWITCH\_CURRENT\_LIMIT\_600

Card driver current limit - 600mA.

Value: = 2U

CSDD\_SDCARD\_SWITCH\_CURRENT\_LIMIT\_800

Card driver current limit - 800mA.

Value: = 3U

# 6.47. CSDD\_EmmcCmdqTaskDescSize

Type: enum

## **Description**

Command queuing task descriptor size.

#### **Values**

CSDD\_CQ\_TASK\_DESC\_SIZE\_64BIT

Task descriptor size 64 bit.

Value: = 0U

CSDD\_CQ\_TASK\_DESC\_SIZE\_128BIT

Task descriptor size 128 bit.

Value: = 1U

# 6.48. CSDD\_CQReqStat

Type: enum

## **Description**

Command queuing request status.

### **Values**

CSDD\_CQ\_REQ\_STAT\_FINISHED

Task executed without errors.

Value: = 0U

CSDD\_CQ\_REQ\_STAT\_ATTACHED

Task is ready to execute.

Value: = 1U

CSDD\_CQ\_REQ\_STAT\_PENDING Task is currently executed.

Value: = 2U

CSDD\_CQ\_REQ\_STAT\_FAILED Task execution failed.

Value: = 3U

# 6.49. CSDD\_PhyDelay

Type: enum

# **Description**

PHY configuration delay type.

### **Values**

CSDD\_PHY\_DELAY\_INPUT\_HIGH\_SPEED

delay in the input path for High Speed work mode

Value: = 0U

CSDD\_PHY\_DELAY\_INPUT\_DEFAULT\_SPEED

delay in the input path for Default Speed work mode

Value: = 1U

CSDD\_PHY\_DELAY\_INPUT\_SDR12 delay in the input path for SDR12 work mode Value: = 2UCSDD\_PHY\_DELAY\_INPUT\_SDR25 delay in the input path for SDR25 work mode Value: = 3UCSDD\_PHY\_DELAY\_INPUT\_SDR50 delay in the input path for SDR50 work mode Value: = 4UCSDD\_PHY\_DELAY\_INPUT\_DDR50 delay in the input path for DDR50 work mode Value: = 5UCSDD\_PHY\_DELAY\_INPUT\_MMC\_LEGACY delay in the input path for eMMC legacy work mode Value: = 6UCSDD\_PHY\_DELAY\_INPUT\_MMC\_SDR delay in the input path for eMMC SDR work mode Value: = 7UCSDD\_PHY\_DELAY\_INPUT\_MMC\_DDR delay in the input path for eMMC DDR work mode Value: = 8UCSDD\_PHY\_DELAY\_DLL\_SDCLK Value of the delay introduced on the sdclk output for all modes except HS200, HS400 and HS400\_ES. Value: = 11U CSDD\_PHY\_DELAY\_DLL\_HS\_SDCLK Value of the delay introduced on the sdclk output for HS200, HS400 and

HS400\_ES speed mode.

Value: = 12U

CSDD\_PHY\_DELAY\_DLL\_DAT\_STROBE

Value of the delay introduced on the dat\_strobe input used in HS400 / HS400\_ES speed mode.

Value: = 13U

## 6.50. CSDD\_MEMORY\_CARD\_INFO

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct MEMORY\_CARD\_INFO\_s CSDD\_MEMORY\_CARD\_INFO

### 6.51. CSDD\_PMEMORY\_CARD\_INFO

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct MEMORY\_CARD\_INFO\_s \* CSDD\_PMEMORY\_CARD\_INFO

## 6.52. CSDD\_SysReq

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_SysReq\_s CSDD\_SysReq

# 6.53. CSDD\_Config

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD Config s CSDD Config

# 6.54. CSDD\_RequestFlags

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD RequestFlags s CSDD RequestFlags

## 6.55. CSDD\_CommandField

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CommandField\_s CSDD\_CommandField

### 6.56. CSDD\_Request

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_Request\_s CSDD\_Request

### 6.57. CSDD SubBuffer

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_SubBuffer\_s CSDD\_SubBuffer

### 6.58. CSDD\_DeviceInfo

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_DeviceInfo\_s CSDD\_DeviceInfo

# 6.59. CSDD\_PhyDelaySettings

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_PhyDelaySettings\_s CSDD\_PhyDelaySettings

# 6.60. CSDD\_MemoryCardInfo

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_MemoryCardInfo\_s CSDD\_MemoryCardInfo

### 6.61. CSDD\_DeviceState

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_DeviceState\_s CSDD\_DeviceState

### 6.62. CSDD\_CQInitConfig

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CQInitConfig\_s CSDD\_CQInitConfig

## 6.63. CSDD\_CQRequestData

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD CQRequestData s CSDD CQRequestData

# 6.64. CSDD\_CQRequest

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CQRequest\_s CSDD\_CQRequest

# 6.65. CSDD\_CQDcmdRequest

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CQDcmdRequest\_s CSDD\_CQDcmdRequest

## 6.66. CSDD\_CQIntCoalescingCfg

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CQIntCoalescingCfg\_s CSDD\_CQIntCoalescingCfg

## 6.67. CSDD\_SDIO\_SlotSettings

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

### **Function Declaration**

struct CSDD\_SDIO\_SlotSettings\_s CSDD\_SDIO\_SlotSettings

### 6.68. CSDD\_SDIO\_CidRegister

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_SDIO\_CidRegister\_s CSDD\_SDIO\_CidRegister

### 6.69. CSDD SDIO Device

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

### **Function Declaration**

struct CSDD\_SDIO\_Device\_s CSDD\_SDIO\_Device

## 6.70. CSDD\_SDIO\_Slot

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_SDIO\_Slot\_s CSDD\_SDIO\_Slot

### 6.71. CSDD SDIO Host

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_SDIO\_Host\_s CSDD\_SDIO\_Host

### 6.72. CSDD\_Callbacks

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_Callbacks\_s CSDD\_Callbacks

## 6.73. CSDD\_CPhyConfigloDelay

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CPhyConfigIoDelay\_s CSDD\_CPhyConfigIoDelay

# 6.74. CSDD\_CPhyConfigLvsi

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD CPhyConfigLvsi s CSDD CPhyConfigLvsi

# 6.75. CSDD\_CPhyConfigDfiRd

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CPhyConfigDfiRd\_s CSDD\_CPhyConfigDfiRd

# 6.76. CSDD\_CPhyConfigOutputDelay

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

struct CSDD\_CPhyConfigOutputDelay\_s CSDD\_CPhyConfigOutputDelay

### 6.77. CSDD CardInsertedCallback

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

void(\* CSDD\_CardInsertedCallback )(void \*pd, uint8\_t slotIndex)

## 6.78. CSDD CardRemovedCallback

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

void(\* CSDD\_CardRemovedCallback )(void \*pd, uint8\_t slotIndex)

## 6.79. CSDD\_CardInterruptHandlerCallback

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

uint8 t(\* CSDD CardInterruptHandlerCallback )(void \*pd, uint8 t slotIndex)

# 6.80. CSDD\_CardInitializeCallback

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

uint8\_t(\* CSDD\_CardInitializeCallback )(CSDD\_SDIO\_Host \*pd, uint8\_t slotIndex)

# 6.81. CSDD\_CardDeinitializeCallback

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

### **Function Declaration**

uint8\_t(\* CSDD\_CardDeinitializeCallback )(CSDD\_SDIO\_Host \*pd, uint8\_t
slotIndex)

# 6.82. CSDD\_AxiErrorCallback

Type: typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

### **Function Declaration**

void(\* CSDD\_AxiErrorCallback )(void \*pd, uint8\_t axiError)

## 6.83. CSDD\_SetTuneValCallback

**Type:** typedef

This is a callback event type. A function with matching prototype needs to be registered with the callbacks structure at init to enable event signaling.

#### **Function Declaration**

uint8\_t(\* CSDD\_SetTuneValCallback )(const CSDD\_SDIO\_Host \*pd, uint8\_t tune\_val)

# **Chapter 7. Driver Function API**

### 7.1. Introduction

Prototypes for the driver API functions.

The user application can link statically to the necessary API functions and call them directly.

## 7.2. CSDD\_Probe

### **Function Declaration**

```
uint32_t CSDD_Probe(registerBase, req);
uintptr_t registerBase
CSDD_SysReq *req
```

### **Parameter List**

# **Description**

#### **Return Value**

0 on success

ENOTSUP if configuration cannot be supported due to driver/hardware constraints

# 7.3. CSDD\_Init

### **Function Declaration**

```
uint32_t CSDD_Init(pD, config, callbacks);
CSDD_SDIO_Host *pD
CSDD_Config *config
CSDD_Callbacks *callbacks
```

```
pD [in]
private data
```

```
config [in]
startup configuration

callbacks [in]
pointer to callbacks functions
```

Function initializes all objects.

It must be called as the first function before calling other driver functions

### **Return Value**

0 on success or error code otherwise

## 7.4. CSDD\_Start

### **Function Declaration**

```
uint32_t CSDD_Start(pD);
CSDD_SDIO_Host *pD
```

### **Parameter List**

```
pD [in]
private data
```

# **Description**

Enable signaling interrupts.

### **Return Value**

0 on success or error code otherwise

# 7.5. CSDD\_Stop

### **Function Declaration**

```
uint32_t CSDD_Stop(pD);
CSDD_SDIO_Host *pD
```

```
pD [in]
private data
```

Disable signaling interrupts.

### **Return Value**

0 on success or error code otherwise

# 7.6. CSDD\_ExecCardCommand

### **Function Declaration**

```
uint32_t CSDD_ExecCardCommand(pD, slotIndex, request);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_Request *request
```

### **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

request [in]
request to execute
```

## **Description**

Function executes a request which is given as the request parameter.

### **Return Value**

0 on success or error code otherwise

# 7.7. CSDD\_DeviceDetach

### **Function Declaration**

```
uint32_t CSDD_DeviceDetach(pD, slotIndex);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

```
pD [in]
```

```
private data
slotIndex [in]
slot index
```

Function detaches card, meaning that all information about card is removed in this function.

### **Return Value**

0 on success or error code otherwise

## 7.8. CSDD\_DeviceAttach

#### **Function Declaration**

```
uint32_t CSDD_DeviceAttach(pD, slotIndex);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

#### **Parameter List**

```
pD [in]
private data
slotIndex [in]
slot index
```

# **Description**

Function initializes a newly inserted card, gathers information about it, and searches for card driver.

### **Return Value**

0 on success or error code otherwise

# 7.9. CSDD\_Abort

### **Function Declaration**

```
uint32_t CSDD_Abort(pD, slotIndex, isSynchronous);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint8_t isSynchronous
```

### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

isSynchronous [in]

abort type: synchronous or asynchronous

## Description

function aborts data transfer

### **Return Value**

0 on success or error code otherwise

## 7.10. CSDD\_StandBy

### **Function Declaration**

 $\verb|uint32_t CSDD_StandBy| (pD, slotIndex, wakeupCondition); \\$ 

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

uint8\_t wakeupCondition

### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

wakeupCondition [in]

conditions of wakeup from standby mode

## **Description**

sets slot of SD host controller to standby mode and waits for wakeup condition; in standby mode the clock is disabled

### **Return Value**

0 on success or error code otherwise

# 7.11. CSDD\_Configure

### **Function Declaration**

```
uint32_t CSDD_Configure(pD, slotIndex, cmd, data, sizeOfData);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_ConfigCmd cmd
void *data
uint8_t *sizeOfData
```

### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

cmd [in]

it describes what should be configured

data [in]

buffer with configuration data

sizeOfData [in]

size of data buffer in bytes

# **Description**

configures the SD Host controller

### **Return Value**

0 on success or error code otherwise

## 7.12. CSDD\_Isr

### **Function Declaration**

```
void CSDD_Isr(pD, handled);
CSDD_SDIO_Host *pD
bool *handled
```

### **Parameter List**

```
pD [in]

private data

handled [in]

informs if interrupt occurred
```

### **Description**

interrupt handler function, it should be called to handle SD host interrupts

# 7.13. CSDD\_ConfigureHighSpeed

### **Function Declaration**

```
uint32_t CSDD_ConfigureHighSpeed(pD, slotIndex, setHighSpeed);
CSDD_SDIO_Host *pD
uint8_t slotIndex
bool setHighSpeed
```

### **Parameter List**

## **Description**

switches a card and host to work either in high speed mode or in normal mode

### **Return Value**

0 on success or error code otherwise

# 7.14. CSDD\_CheckSlots

### **Function Declaration**

uint32\_t CSDD\_CheckSlots(pD);

```
CSDD_SDIO_Host *pD
```

#### **Parameter List**

```
pD [in]
private data
```

## **Description**

checks slots states; depending on the slots status, calls deviceAttach or deviceDettach, or does nothing if slot state remains unchanged

### **Return Value**

0 on success or error code otherwise

# 7.15. CSDD\_CheckInterrupt

#### **Function Declaration**

```
void CSDD_CheckInterrupt(pD, slotIndex, status);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t status
```

#### **Parameter List**

```
pD [in]
private data
slotIndex [in]
slot index
status [in]
```

# **Description**

# 7.16. CSDD\_ConfigureAccessMode

#### **Function Declaration**

```
uint32_t CSDD_ConfigureAccessMode(pD, slotIndex, accessMode);
CSDD_SDIO_Host *pD
```

```
uint8_t slotIndex
```

CSDD\_SpeedMode accessMode

#### **Parameter List**

```
pD [in]
```

private data

slotIndex [in]

slot index

accessMode [in]

access mode to set

## **Description**

Function configures card access mode.

### **Return Value**

0 on success or error code otherwise

## 7.17. CSDD\_Tuning

### **Function Declaration**

```
uint32_t CSDD_Tuning(pD, slotIndex);
```

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

## **Description**

function executes tuning operation on a card but only if it is needed

### **Return Value**

0 on success or error code otherwise

# 7.18. CSDD\_ClockGeneratorSelect

### **Function Declaration**

```
uint32_t CSDD_ClockGeneratorSelect(pD, slotIndex, progClkMode);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint8_t progClkMode
```

#### **Parameter List**

pD [in]
private data
slotIndex [in]
slot index

progClkMode [in]

parameter defines if programmable clock mode should be enabled. 1 programmable clock mode will be enabled; 0 10-bit divider clock mode is enabled

### **Description**

function executes tuning operation on a card but only if it is needed

### **Return Value**

0 on success or error code otherwise

# 7.19. CSDD\_PresetValueSwitch

#### **Function Declaration**

```
uint32_t CSDD_PresetValueSwitch(pD, slotIndex, enable);
CSDD_SDIO_Host *pD
uint8_t slotIndex
bool enable
```

```
pD [in]
private data
slotIndex [in]
slot index
```

enable [in]

enable/disable preset value switching

## **Description**

Function enables or disables preset value switching.

### **Return Value**

0 on success or error code otherwise

# 7.20. CSDD\_ConfigureDriverStrength

#### **Function Declaration**

```
uint32_t CSDD_ConfigureDriverStrength(pD, slotIndex, driverStrength);
```

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

CSDD\_DriverStrengthType driverStrength

#### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

driverStrength [in]

new driver strength

# Description

function configures driver strength of a card and the slot

### **Return Value**

0 on success or error code otherwise

# 7.21. CSDD\_MemoryCardLoadDriver

### **Function Declaration**

void CSDD\_MemoryCardLoadDriver(pD);

CSDD\_SDIO\_Host \*pD

### **Parameter List**

```
pD [in]
private data
```

## **Description**

Function loads driver for the card.

# 7.22. CSDD\_MemoryCardDataTransfer

### **Function Declaration**

```
uint32_t CSDD_MemoryCardDataTransfer(pD, slotIndex, address, buffer, size, direction);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t address
void *buffer
uint32_t size
```

#### **Parameter List**

CSDD\_TransferDirection direction

```
pD [in]
private data

slotIndex [in]
slot index

address [in]
address in card memory to/from which data will be transferred; address in blocks (512 bytes)

buffer [inout]
buffer with data to be written or to save data that was read

size [in]
size of buffer in bytes, Buffer size should be divisible by 512

direction [in]
```

# **Description**

Function transfers data to/from memory card, function operates on blocks (512 bytes);.

### **Return Value**

0 on success or error code otherwise

# 7.23. CSDD\_MemoryCardDataTransfer2

### **Function Declaration**

uint32\_t CSDD\_MemoryCardDataTransfer2(pD, slotIndex, address, buffer, size, direction, subBufferCount);

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

uint32\_t address

void \*buffer

uint32\_t size

CSDD\_TransferDirection direction

uint32\_t subBufferCount

### **Parameter List**

[in]

private data

slotIndex [in]

slot index

address [in]

memory card address to/from which data will be transferred; address in blocks (512 bytes);

buffer [inout]

buffer (or buffers when SubBufferCount > 0) with data to be written or to save data that was

read

size [in]

BufferSize size of buffer in bytes

direction [in]

parameter defines data transfer direction

subBufferCount [in]

If it is bigger than 0 it means that Buffer is pointer to CSDD\_SubBuffer array where are defined

buffers with data to transfer and data sizes of each buffer

Function transfers data to/from memory card, function operates on blocks (512 bytes)

### **Return Value**

0 on success or error code otherwise

# 7.24. CSDD\_MemoryCardConfigure

### **Function Declaration**

```
uint32_t CSDD_MemoryCardConfigure(pD, slotIndex, cmd, data, size);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_MmcConfigCmd cmd
uint8_t *data
uint8_t size
```

### **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

cmd [in]
this parameter defines what operation will be executed data [in]
buffer with data

size [in]
```

## **Description**

function executes configuration commands on memory card

size of data in bytes

### **Return Value**

0 on success or error code otherwise

# 7.25. CSDD\_MemoryCardDataErase

#### **Function Declaration**

uint32\_t CSDD\_MemoryCardDataErase(pD, slotIndex, startBlockAddress, blockCount);

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

uint32\_t startBlockAddress

uint32\_t blockCount

### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

startBlockAddress [in]

address of the first block to be erased

blockCount [in]

number of blocks to be erased.

### **Description**

Function erases block or blocks specified by startBlockAddress and blockCount parameteres.

### **Return Value**

0 on success or error code otherwise

# 7.26. CSDD\_MemCardPartialDataXfer

#### **Function Declaration**

uint32\_t CSDD\_MemCardPartialDataXfer(pD, slotIndex, address, buffer, size, direction);

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

uint32 t address

void \*buffer

uint32\_t size

CSDD\_TransferDirection direction

#### **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

address [in]
address in card memory to/from which data will be transferred; address in bytes

buffer [inout]
buffer with data to be written or to save data that was read

size [in]
size of buffer in bytes
```

# **Description**

Function transfers data to/from memory card (byte oriented)

size of buffer in bytes

#### **Return Value**

0 on success or error code otherwise

# ${\bf 7.27.~CSDD\_MemCardInfX} fer Start$

#### **Function Declaration**

```
uint32_t CSDD_MemCardInfXferStart(pD, slotIndex, address, buffer, size, direction);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t address
void *buffer
uint32_t size
CSDD_TransferDirection direction
```

pD [in]

private data

slotIndex [in]

slot index

address [in]

address in card memory to/from which data will be transferred; address in blocks (512 bytes)

buffer [inout]

buffer with data to be written or to save data that was read

size [in]

size of buffer in bytes

direction [in]

parameter defines transfer direction

# **Description**

Function transfers data in infinite mode to/from memory card.

Function operates on 512 data blocks. Data transfer can be continued by memCardInfXferContinue. Trnasmission must be finished by memCardInfXferFinish

#### **Return Value**

0 on success or error code otherwise

# 7.28. CSDD\_MemCardInfXferContinue

#### **Function Declaration**

```
uint32_t CSDD_MemCardInfXferContinue(pD, slotIndex, buffer, size, direction);
```

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

void \*buffer

uint32\_t size

CSDD\_TransferDirection direction

#### **Parameter List**

pD [in]

```
private data

slotIndex [in]
slot index

buffer [inout]
buffer with data to be written or to save data that was read

size [in]
size of buffer in bytes

direction [in]
```

parameter defines transfer direction

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.29. CSDD MemCardInfXferFinish

## **Function Declaration**

```
uint32_t CSDD_MemCardInfXferFinish(pD, slotIndex, direction);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_TransferDirection direction
```

## **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

direction [in]
parameter defines transfer direction
```

# **Description**

Function finishes data transfer in infinite mode.

## **Return Value**

0 on success or error code otherwise

# 7.30. CSDD\_MemCardDataXferNonBlock

## **Function Declaration**

```
рD
               [ in ]
               private data
slotIndex [in]
               slot index
address
               [ in ]
               address in card memory to/from which data will be transferred; address in blocks (512 bytes)
buffer
               [inout]
               buffer with data to be written or to save data that was read
size
               [ in ]
               size of buffer in bytes
direction [in]
               parameter defines transfer direction
request
               [out]
               current executing request
```

# **Description**

Function transfers data to/from memory card.

Function operates on 512 data blocks. Function does not wait for operation finish. Therefore it returns pointer to current request. User using MemoryCard\_FinishXferNonBlock function and request pointer can wait until operation finish and get the status of operation. Function needs AUTO\_CMD option enabled

#### **Return Value**

0 on success or error code otherwise

# 7.31. CSDD\_MemCardFinishXferNonBlock

## **Function Declaration**

```
uint32_t CSDD_MemCardFinishXferNonBlock(pD, pRequest);
CSDD_SDIO_Host *pD
CSDD_Request *pRequest
```

#### **Parameter List**

```
pD [in]
private data

pRequest [in]
request to wait for
```

# **Description**

Function waits until request finish and returns status of request execution.

## **Return Value**

0 on success or error code otherwise

# 7.32. CSDD\_PhySettingsSd3

## **Function Declaration**

```
uint32_t CSDD_PhySettingsSd3(pD, slotIndex, phyDelaySet);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_PhyDelaySettings *phyDelaySet
```

```
pD [in]
```

#### **Driver Function API**

private data

slotIndex [in]

slot index

phyDelaySet [in]

PHY delay settings

# **Description**

Function sets delay line in UHS-I PHY hardware module.

Function works for SD Host 3 Function is obsolete writePhySet function should be used to configure PHY delays.

## **Return Value**

0 on success or error code otherwise

# 7.33. CSDD\_PhySettingsSd4

## **Function Declaration**

```
uint32_t CSDD_PhySettingsSd4(pD, phyDelaySet);
CSDD_SDIO_Host *pD
CSDD_PhyDelaySettings *phyDelaySet
```

#### **Parameter List**

pD [in]

private data

phyDelaySet [in]

PHY delay settings

# Description

Function sets delay line in UHS-I PHY hardware module.

Function works for SD Host 4. Function is obsolete writePhySet function should be used to configure PHY delays.

#### **Return Value**

0 on success or error code otherwise

# 7.34. CSDD\_WritePhySet

## **Function Declaration**

uint32\_t CSDD\_WritePhySet(pD, slotIndex, phyDelayType, delayVal);

```
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_PhyDelay phyDelayType
uint8_t delayVal
```

pD [in]

private data

slotIndex [in]

slot index

phyDelayType [in]

it defines which PHY delay should be written

delayVal [in]

value to be written to selected PHY delay

# **Description**

Function configures one PHY delay line in UHS-I PHY hardware module.

#### **Return Value**

0 on success or error code otherwise

# 7.35. CSDD\_ReadPhySet

## **Function Declaration**

```
uint32_t CSDD_ReadPhySet(pD, slotIndex, phyDelayType, delayVal);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_PhyDelay phyDelayType
uint8_t *delayVal
```

## **Parameter List**

pD [in]

private data

slotIndex [in]

#### **Driver Function API**

slot index

phyDelayType [in]

it defines which PHY delay should be read:

delayVal [in]

read value of selected PHY delay

# **Description**

Function configures one PHY delay line in UHS-I PHY hardware module.

## **Return Value**

0 on success or error code otherwise

# 7.36. CSDD\_ReadCardStatus

## **Function Declaration**

```
uint32_t CSDD_ReadCardStatus(pD, slotIndex, cardStatus);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t *cardStatus
```

#### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

cardStatus [out]

pointer to memory where read card status shall be written

# **Description**

reads card status.

Function returns error if command executing error appears or card error bits are set

## **Return Value**

0 on success or error code otherwise

# 7.37. CSDD\_SelectCard

## **Function Declaration**

```
uint32_t CSDD_SelectCard(pD, slotIndex, rca);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint16_t rca
```

#### **Parameter List**

```
pD [in]
private data
slotIndex [in]
slot index
rca [in]
```

card address in selecting card case or 0 in deselecting card case

# **Description**

selects or deselects a card; if RCA parameter is 0, then card will be deselected, otherwise,a card of the RCA value will be selected

## **Return Value**

0 on success or error code otherwise

# 7.38. CSDD\_ResetCard

## **Function Declaration**

```
uint32_t CSDD_ResetCard(pD, slotIndex);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

```
pD [in]
private data
slotIndex [in]
slot index
```

# **Description**

resets a card using CMD0 command

#### **Return Value**

0 on success or error code otherwise

# 7.39. CSDD\_ExecCmd55Command

## **Function Declaration**

```
uint32_t CSDD_ExecCmd55Command(pD, slotIndex);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

## **Parameter List**

```
pD [in]
private data
slotIndex [in]
slot index
```

# **Description**

executes CMD55 command

## **Return Value**

0 on success or error code otherwise

# 7.40. CSDD\_AccessCccr

## **Function Declaration**

CSDD\_CccrRegAddr registerAddress

## **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

transferDirection [in]

parameter defines transfer direction

data [inout]

pointer to write/read data buffer

size [in]

size of Data buffer in bytes

registerAddress [in]

# **Description**

writes or reads the CCCR card registers; the CCCR is present in SDIO or combo cards only

## **Return Value**

0 on success or error code otherwise

# 7.41. CSDD\_ReadCsd

## **Function Declaration**

```
uint32_t CSDD_ReadCsd(pD, slotIndex, buffer[4]);
```

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

uint32\_t buffer[4]

#### **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

buffer [out]

content of CSD register 16 bytes

# **Description**

reads CSD register of the card

## **Return Value**

0 on success or error code otherwise

# 7.42. CSDD\_ReadExCsd

## **Function Declaration**

```
uint32_t CSDD_ReadExCsd(pD, slotIndex, buffer);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

uint8\_t \*buffer

## **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

buffer [out]

# **Description**

function reads Extended CSD register from the card

## **Return Value**

0 on success or error code otherwise

# 7.43. CSDD\_GetTupleFromCis

## **Function Declaration**

uint32\_t CSDD\_GetTupleFromCis(pD, slotIndex, tupleAddress, tupleCode, buffer, bufferSize);

```
CSDD_SDIO_Host *pD

uint8_t slotIndex

uint32_t tupleAddress

CSDD_TupleCode tupleCode

void *buffer

uint8_t bufferSize
```

pD [in]

private data

slotIndex [in]

slot index

tupleAddress [in]

start address of the CIS register

tupleCode [in]

code name of tuple

buffer [out]

buffer for read tuple

bufferSize [in]

size of buffer in bytes

# **Description**

function reads tuple from the CIS card register to buffer; CIS register is present only in SDIO or combo cards;

## **Return Value**

0 on success or error code otherwise

# 7.44. CSDD\_ReadSdStatus

## **Function Declaration**

```
uint32_t CSDD_ReadSdStatus(pD, slotIndex, buffer[64]);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

```
uint8_t buffer[64]
```

pD [in]

private data

slotIndex [in]

slot index

buffer [out]

card status

# **Description**

function reads SD card status

## **Return Value**

0 on success or error code otherwise

# 7.45. CSDD\_SetDriverStrength

## **Function Declaration**

 $\verb"uint32_t CSDD_SetDriverStrength" (pD, slotIndex, driverStrength");$ 

CSDD\_SDIO\_Host \*pD

uint8\_t slotIndex

CSDD\_DriverStrengthType driverStrength

## **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

driverStrength [in]

new driver strength value

# Description

Function configures driver strength of a card.

## **Return Value**

0 on success or error code otherwise

# 7.46. CSDD ExecSetCurrentLimit

#### **Function Declaration**

```
uint32_t CSDD_ExecSetCurrentLimit(pD, slotIndex, currentLimit);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_DriverCurrentLimit currentLimit
```

#### **Parameter List**

```
рD
                 [in]
                 private data
slotIndex
                 [ in ]
                 slot index
currentLimit [in]
```

# **Description**

Function sets a card current limit.

## **Return Value**

0 on success or error code otherwise

# 7.47. CSDD MmcSwitch

## **Function Declaration**

```
uint32_t CSDD_MmcSwitch(pD, slotIndex, argIndex, argValue);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint8_t argIndex
uint8 t argValue
```

```
[ in ]
рD
                private data
```

#### **Driver Function API**

# **Description**

Function executes mmc switch command to modify EXT\_CSD register.

## **Return Value**

0 on success or error code otherwise

# 7.48. CSDD\_MmcSetExtCsd

## **Function Declaration**

```
uint32_t CSDD_MmcSetExtCsd(pD, slotIndex, byteNr, newValue, mask);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint8_t byteNr
uint8_t newValue
uint8_t mask
```

```
pD [in]
private data

slotIndex [in]
slot index

byteNr [in]
index of EXT_CSD register field to be modified

newValue [in]
new value to be "or"
```

mask showing which part of byte should be masked

# **Description**

Function reads byte pointed by byteNr parameter.

Next it masks the value using ~mask, at the end function makes "or" operation with newValue. Such value is written to the EXT\_CSD register

#### **Return Value**

0 on success or error code otherwise

# 7.49. CSDD MmcSetBootPartition

## **Function Declaration**

```
uint32_t CSDD_MmcSetBootPartition(pD, slotIndex, partition);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_ParitionBoot partition
```

#### **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

partition [in]
partition to be active to boot
```

# Description

Function sets active partition to boot operation.

#### **Return Value**

0 on success or error code otherwise

# 7.50. CSDD\_MmcSetPartAccess

#### **Function Declaration**

```
uint32_t CSDD_MmcSetPartAccess(pD, slotIndex, partition);
CSDD_SDIO_Host *pD
```

```
uint8_t slotIndex
CSDD_ParitionAccess partition
```

```
pD [in]
private data

slotIndex [in]
slot index

partition [in]
partition to be active to access
```

# **Description**

Function sets active partition to access.

# **Return Value**

0 on success or error code otherwise

# 7.51. CSDD\_MmcSetBootAck

#### **Function Declaration**

```
uint32_t CSDD_MmcSetBootAck(pD, slotIndex, enableBootAck);
CSDD_SDIO_Host *pD
uint8_t slotIndex
bool enableBootAck
```

## **Parameter List**

```
pD [in]

private data

slotIndex [in]

slot index

enableBootAck [in]

enable/disable eMMC boot ACK
```

# **Description**

Function sets active partition to access.

## **Return Value**

0 on success or error code otherwise

# 7.52. CSDD\_MmcExecuteBoot

## **Function Declaration**

```
uint32_t CSDD_MmcExecuteBoot(pD, slotIndex, buffer, size);
CSDD_SDIO_Host *pD
uint8_t slotIndex
void *buffer
uint32_t size
```

## **Parameter List**

pD [in]

private data

slotIndex [in]

slot index

buffer [out]

buffer for read

size [in]

buffer size in bytes

# Description

Function executes boot operation.

It reads data from active boot partition to the buffer

## **Return Value**

0 on success or error code otherwise

# 7.53. CSDD\_MmcGetParitionBootSize

#### **Function Declaration**

```
uint32_t CSDD_MmcGetParitionBootSize(pD, slotIndex, bootSize);
CSDD_SDIO_Host *pD
uint8_t slotIndex
```

```
uint32_t *bootSize
```

```
pD [in]
```

private data

slotIndex [in]

slot index

bootSize [out]

size of boot partition

# **Description**

Function gets boot partition size.

## **Return Value**

0 on success or error code otherwise

# 7.54. CSDD\_GetInterfaceType

## **Function Declaration**

```
uint32_t CSDD_GetInterfaceType(pD, slotIndex, interfaceType);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_InterfaceType *interfaceType
```

## **Parameter List**

```
pD [in]
```

private data

slotIndex [in]

slot index

interfaceType [out]

interface type

# **Description**

function gets current device interface type (SD legacy)

## **Return Value**

0 on success or error code otherwise

# 7.55. CSDD\_GetDeviceState

## **Function Declaration**

```
uint32_t CSDD_GetDeviceState(pD, slotIndex, deviceState);
CSDD_SDIO_Host *pD
uint8_t slotIndex
CSDD_DeviceState *deviceState
```

#### **Parameter List**

```
pD [in]
```

private data

slotIndex [in]

slot index

deviceState [out]

device state and info

# **Description**

function gets current device state/info

#### **Return Value**

0 on success or error code otherwise

# ${\bf 7.56.~CSDD\_MemoryCardGetSecCount}$

## **Function Declaration**

```
uint32_t CSDD_MemoryCardGetSecCount(pD, slotIndex, sectorCount);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t *sectorCount
```

```
pD [in]
private data
```

```
slotIndex [in]
```

slot index

sectorCount [out]

sector count

# **Description**

Function gets sectors count.

## **Return Value**

0 on success or error code otherwise

# 7.57. CSDD\_SetDriverData

## **Function Declaration**

```
uint32_t CSDD_SetDriverData(pD, drvData);
CSDD_SDIO_Host *pD
void *drvData
```

## **Parameter List**

```
pD [in]
private data
drvData [in]
driver data
```

# **Description**

Function used to save pointer to driver data.

## **Return Value**

0 on success or error code otherwise

# 7.58. CSDD\_GetDriverData

## **Function Declaration**

```
uint32_t CSDD_GetDriverData(pD, *drvData);
CSDD_SDIO_Host *pD
const void **drvData
```

```
pD [in]
private data
drvData [out]
driver data
```

# **Description**

Function used get pointer to driver data saved by setDriverData function.

#### **Return Value**

0 on success or error code otherwise

# 7.59. CSDD\_SimpleInit

#### **Function Declaration**

```
uint32_t CSDD_SimpleInit(pD, slotIndex, clk);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t clk
```

## **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

clk [in]
clock frequency in hertz
```

# **Description**

Function makes very simple host initialization just enables clock and supply the power.

Function is useful for emmc boot operation

#### **Return Value**

0 on success or error code otherwise

# 7.60. CSDD\_ResetHost

## **Function Declaration**

```
uint32_t CSDD_ResetHost(pD);
CSDD_SDIO_Host *pD
```

# **Parameter List**

```
pD [in]
private data
```

# **Description**

Function resets SD Host controller.

## **Return Value**

0 on success or error code otherwise

# 7.61. CSDD\_GetRca

## **Function Declaration**

```
uint32_t CSDD_GetRca(pD, slotIndex, rca);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint16_t *rca
```

#### **Parameter List**

```
pD [in]
private data

slotIndex [in]
slot index

rca [out]
RCA address
```

# **Description**

Function gets RCA address of conneted device.

## **Return Value**

0 on success or error code otherwise

# 7.62. CSDD\_CQEnable

## **Function Declaration**

```
uint32_t CSDD_CQEnable(pD, cqConfig);
CSDD_SDIO_Host *pD
CSDD_CQInitConfig *cqConfig
```

#### **Parameter List**

```
pD [in]
private data

cqConfig [in]
Initial configuration.
```

# **Description**

Function enables command queuing and set initialize configuration.

## **Return Value**

0 on success or error code otherwise

# 7.63. CSDD\_CQDisable

#### **Function Declaration**

```
uint32_t CSDD_CQDisable(pD);
CSDD_SDIO_Host *pD
```

#### **Parameter List**

```
pD [in]
private data
```

# **Description**

Function disables command queuing.

## **Return Value**

0 on success or error code otherwise

# 7.64. CSDD\_CQGetInitConfig

## **Function Declaration**

uint32\_t CSDD\_CQGetInitConfig(pD, cqConfig);

```
CSDD_SDIO_Host *pD
CSDD_CQInitConfig *cqConfig
```

```
pD [in]
private data

cqConfig [out]
current command queue configuration
```

# **Description**

Function get command queuing initial configuration passed in in cQEnable function.

#### **Return Value**

0 on success or error code otherwise

# 7.65. CSDD\_CQGetUnusedTaskId

## **Function Declaration**

```
uint32_t CSDD_CQGetUnusedTaskId(pD, taskId);
CSDD_SDIO_Host *pD
uint8_t *taskId
```

#### **Parameter List**

```
pD [in]
private data
taskId [out]
unused task ID
```

# **Description**

Function searches and gets unused task ID.

## **Return Value**

0 on success or error code otherwise

# 7.66. CSDD\_CQStartExecuteTask

## **Function Declaration**

uint32\_t CSDD\_CQStartExecuteTask(pD, taskId);

```
CSDD_SDIO_Host *pD
uint8_t taskId
```

```
pD [in]

private data

taskId [in]

task ID which shall be executed
```

# **Description**

Function starts task execution.

Task must be attached before by cQAttachRequest function

## **Return Value**

0 on success or error code otherwise

# 7.67. CSDD\_CQAttachRequest

## **Function Declaration**

```
uint32_t CSDD_CQAttachRequest(pD, request);
CSDD_SDIO_Host *pD
CSDD_CQRequest *request
```

#### **Parameter List**

```
pD [in]

private data

request [in]

a request to be attached
```

# **Description**

Function attaches new request to a task.

Function create new descriptors. Function cannot be used to attach direct requests. Execution of request is not started by this function.

#### **Return Value**

0 on success or error code otherwise

# 7.68. CSDD\_CQExecuteDcmdRequest

## **Function Declaration**

```
uint32_t CSDD_CQExecuteDcmdRequest(pD, request);
CSDD_SDIO_Host *pD
CSDD_CQDcmdRequest *request
```

#### **Parameter List**

```
pD [in]

private data

request [in]

a direct request to be executed
```

# **Description**

Function attaches new request to the direct task.

Function create new descriptors. Function start of execution direct task. Function can be only to direct requests.

#### **Return Value**

0 on success or error code otherwise

# 7.69. CSDD\_CQGetDirectCmdConfig

#### **Function Declaration**

```
uint32_t CSDD_CQGetDirectCmdConfig(pD, enable);
CSDD_SDIO_Host *pD
uint8_t *enable
```

#### **Parameter List**

```
pD [in]

private data

enable [out]

it informs if direct command is enabled or disabled
```

# **Description**

Function gets current configuration of command queuing direct command.

## **Return Value**

0 on success or error code otherwise

# 7.70. CSDD\_CQSetDirectCmdConfig

#### **Function Declaration**

```
uint32_t CSDD_CQSetDirectCmdConfig(pD, enable);
CSDD_SDIO_Host *pD
uint8_t enable
```

#### **Parameter List**

```
pD [in]
private data

enable [out]
if it is then direct command will be enabled, if it is 0 then direct command will be disabled
```

# **Description**

Function sets new configuration of command queuing direct command.

#### **Return Value**

0 on success or error code otherwise

# 7.71. CSDD\_CQSetIntCoalescingConfig

## **Function Declaration**

```
uint32_t CSDD_CQSetIntCoalescingConfig(pD, config);
CSDD_SDIO_Host *pD
CSDD_CQIntCoalescingCfg *config
```

#### **Parameter List**

```
pD [in]
private data
```

# **Description**

Function sets new configuration of command queuing interrupt coalescing.

# 7.72. CSDD\_CQGetIntCoalescingConfig

## **Function Declaration**

```
uint32_t CSDD_CQGetIntCoalescingConfig(pD, config);
CSDD_SDIO_Host *pD
CSDD_CQIntCoalescingCfg *config
```

#### **Parameter List**

```
pD [in]

private data

config [out]

current interrupt coalescing configuration
```

# **Description**

Function gets current configuration of command queuing interrupt coalescing.

# **Return Value**

0 on success or error code otherwise

# 7.73. CSDD\_CQGetIntCoalescingTimeoutBase

#### **Function Declaration**

```
uint32_t CSDD_CQGetIntCoalescingTimeoutBase(pD, clockFreqKHz);
CSDD_SDIO_Host *pD
uint32_t *clockFreqKHz
```

## **Parameter List**

```
pD [in]
private data

clockFreqKHz [out]
interrupt coalescing timeout base clock frequency in KHz. It can be usefull to calculate interrupt coalescing timeout value
```

# **Description**

Function gets current configuration of command queuing interrupt coalescing.

## **Return Value**

0 on success or error code otherwise

# 7.74. CSDD\_CQStartExecuteTasks

## **Function Declaration**

```
uint32_t CSDD_CQStartExecuteTasks(pD, taskIds);
CSDD_SDIO_Host *pD
uint32_t taskIds
```

#### **Parameter List**

```
pD [in]
private data

taskIds [in]
task IDs OR'd combination of bit-flags selecting the tasks to be executed. Bit 0 - task ID 0, bit 1 task ID 1 ...
```

# **Description**

Function starts tasks execution.

Tasks must be attached before by cQAttachRequest function

#### **Return Value**

0 on success or error code otherwise

# 7.75. CSDD\_CQHalt

## **Function Declaration**

```
uint32_t CSDD_CQHalt(pD, set);
CSDD_SDIO_Host *pD
uint8_t set
```

```
pD [in]

private data

set [in]

1 - enter to halt state, 0 - exit from halt state
```

# **Description**

Function put command queueing to halt state or exit from halt state.

Behaviour depends on set parameter.

## **Return Value**

0 on success or error code otherwise

# 7.76. CSDD\_CQTaskDiscard

## **Function Declaration**

```
uint32_t CSDD_CQTaskDiscard(pD, taskId);
CSDD_SDIO_Host *pD
uint8_t taskId
```

#### **Parameter List**

```
pD [in]
private data
taskId [in]
task ID to discard
```

# **Description**

Function dicards one task.

## **Return Value**

0 on success or error code otherwise

# 7.77. CSDD\_CQAIITasksDiscard

## **Function Declaration**

```
uint32_t CSDD_CQAllTasksDiscard(pD);
CSDD_SDIO_Host *pD
```

# **Parameter List**

```
pD [in]
private data
```

# **Description**

Function dicards all tasks.

## **Return Value**

0 on success or error code otherwise

# 7.78. CSDD CQResetIntCoalCounters

#### **Function Declaration**

```
uint32_t CSDD_CQResetIntCoalCounters(pD);
CSDD_SDIO_Host *pD
```

## **Parameter List**

```
pD [in]
private data
```

# **Description**

Function resets interrupt coalescing timer and counter.

## **Return Value**

0 on success or error code otherwise

# 7.79. CSDD\_CQSetResponseErrorMask

## **Function Declaration**

```
uint32_t CSDD_CQSetResponseErrorMask(pD, errorMask);
CSDD_SDIO_Host *pD
uint32 t errorMask
```

#### **Parameter List**

```
pD [in]
private data
errorMask [in]
```

bit mask informs CQ engine which bits should be treated as error in command response

# **Description**

Function writes error mask for command response.

#### **Return Value**

0 on success or error code otherwise

# 7.80. CSDD\_CQGetResponseErrorMask

## **Function Declaration**

```
uint32_t CSDD_CQGetResponseErrorMask(pD, errorMask);
CSDD_SDIO_Host *pD
uint32_t *errorMask
```

#### **Parameter List**

```
pD [in]
private data
errorMask [out]
```

bit mask informs CQ engine which bits should be treated as error in command response

# **Description**

Function reads error mask for command response.

## **Return Value**

0 on success or error code otherwise

# 7.81. CSDD\_GetBaseClk

## **Function Declaration**

```
uint32_t CSDD_GetBaseClk(pD, slotIndex, frequencyKHz);
CSDD_SDIO_Host *pD
uint8_t slotIndex
uint32_t *frequencyKHz
```

#### **Parameter List**

pD [in]
private data
slotIndex [in]
slot index
frequencyKHz [out]

base clock

# **Description**

Function reads base clock.

#### **Return Value**

0 on success or error code otherwise

# 7.82. CSDD\_WaitForRequest

## **Function Declaration**

```
uint32_t CSDD_WaitForRequest(pD, pRequest);
CSDD_SDIO_Host *pD
CSDD_Request *pRequest
```

## **Parameter List**

```
pD [in]

private data

pRequest [in]

request to wait for
```

# **Description**

Function waits until request finish and returns status of request execution.

#### **Return Value**

0 on success or error code otherwise

# 7.83. CSDD\_SetCPhyConfigloDelay

## **Function Declaration**

```
uint32_t CSDD_SetCPhyConfigIoDelay(pD, ioDelay);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigIoDelay *ioDelay
```

```
pD [in]

private data

ioDelay [in]
```

#### configuration

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.84. CSDD\_GetCPhyConfigloDelay

## **Function Declaration**

```
uint32_t CSDD_GetCPhyConfigIoDelay(pD, ioDelay);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigIoDelay *ioDelay
```

## **Parameter List**

```
pD [in]
private data

ioDelay [out]
configuration
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.85. CSDD\_SetCPhyConfigLvsi

## **Function Declaration**

```
uint32_t CSDD_SetCPhyConfigLvsi(pD, lvsi);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigLvsi *lvsi
```

```
pD [ in ]
private data
```

```
lvsi [in]
configuration
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.86. CSDD\_GetCPhyConfigLvsi

## **Function Declaration**

```
uint32_t CSDD_GetCPhyConfigLvsi(pD, lvsi);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigLvsi *lvsi
```

## **Parameter List**

```
pD [in]
private data

lvsi [out]
configuration
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.87. CSDD\_SetCPhyConfigDfiRd

## **Function Declaration**

```
uint32_t CSDD_SetCPhyConfigDfiRd(pD, dfiRd);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigDfiRd *dfiRd
```

```
pD [in]
private data
```

```
dfiRd [in]
configuration
```

# **Description**

#### **Return Value**

0 on success or error code otherwise

# 7.88. CSDD\_GetCPhyConfigDfiRd

## **Function Declaration**

```
uint32_t CSDD_GetCPhyConfigDfiRd(pD, dfiRd);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigDfiRd *dfiRd
```

## **Parameter List**

```
pD [in]
private data

dfiRd [out]
configuration
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.89. CSDD\_SetCPhyConfigOutputDelay

# **Function Declaration**

```
uint32_t CSDD_SetCPhyConfigOutputDelay(pD, outputDelay);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigOutputDelay *outputDelay
```

```
pD [in]
private data
```

```
outputDelay [in]
```

configuration

# **Description**

#### **Return Value**

0 on success or error code otherwise

# 7.90. CSDD\_GetCPhyConfigOutputDelay

## **Function Declaration**

```
uint32_t CSDD_GetCPhyConfigOutputDelay(pD, outputDelay);
CSDD_SDIO_Host *pD
CSDD_CPhyConfigOutputDelay *outputDelay
```

## **Parameter List**

```
pD [in]
private data

outputDelay [out]
configuration
```

# **Description**

# **Return Value**

0 on success or error code otherwise

# 7.91. CSDD\_CPhyDIIReset

# **Function Declaration**

```
uint32_t CSDD_CPhyDllReset(pD, doReset);
CSDD_SDIO_Host *pD
bool doReset
```

```
pD [in]
private data
```

```
doReset [in]
enable/disable reset
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.92. CSDD\_SetCPhyExtMode

## **Function Declaration**

```
uint32_t CSDD_SetCPhyExtMode(pD, extendedWrMode, extendedRdMode);
CSDD_SDIO_Host *pD
bool extendedWrMode
bool extendedRdMode
```

## **Parameter List**

```
pD [in]
private data

extendedWrMode [in]

extendedRdMode [in]
```

# **Description**

#### **Return Value**

0 on success or error code otherwise

# 7.93. CSDD\_GetCPhyExtMode

#### **Function Declaration**

```
uint32_t CSDD_GetCPhyExtMode(pD, extendedWrMode, extendedRdMode);
CSDD_SDIO_Host *pD
bool *extendedWrMode
bool *extendedRdMode
```

```
pD [in]
private data

extendedWrMode [out]

extendedRdMode [out]
```

# **Description**

# **Return Value**

0 on success or error code otherwise

# 7.94. CSDD\_SetCPhySdclkAdj

## **Function Declaration**

```
uint32_t CSDD_SetCPhySdclkAdj(pD, sdclkAdj);
CSDD_SDIO_Host *pD
uint8_t sdclkAdj
```

#### **Parameter List**

```
pD [in]
private data
sdclkAdj [in]
configuration
```

# **Description**

## **Return Value**

0 on success or error code otherwise

# 7.95. CSDD\_GetCPhySdclkAdj

## **Function Declaration**

```
uint32_t CSDD_GetCPhySdclkAdj(pD, sdclkAdj);
CSDD_SDIO_Host *pD
```

uint8\_t \*sdclkAdj

# **Parameter List**

pD [in]

private data

sdclkAdj [out]

configuration

# **Description**

# **Return Value**

0 on success or error code otherwise