

A hybrid staggered/non-staggered formulation

For incompressible flows with block-structured mesh refinement

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Outlines

Introduction

Methodology

Method 1

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Method 3

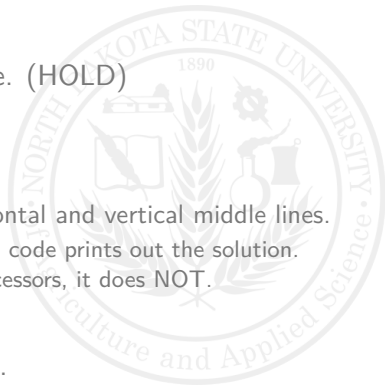
Results and Discussion



To-do List

For tracking progress and comments

- ☒ Debugging the code.
- ☒ Finish Wall Boundary Conditions feature. (HOLD)
- ☐ Benchmark the code.
 - ☐ Running 6 benchmark cases.
 - ☒ Fix L2-Norm.
 - ☐ Generate solution comparison at horizontal and vertical middle lines.
 - ▶ When running on one processor, the code prints out the solution.
When running on multiple MPI processors, it does NOT.
- ☐ Prepare Beamer for presentation.
- ☐ Present at APS DFD 2023 on Nov 19th.



Introduction

Feature list

This is *an important text*.

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Methodology I

The governing equations for incompressible fluid consist of Navier-Stokes (momentum) equation and the continuity equation such that, in general coordinate system:

$$\frac{\partial u_i}{\partial t} = -\frac{\partial}{\partial x_j} u_i u_j + \frac{1}{\text{Re}} \frac{\partial^2 u_i}{\partial x_i \partial x_j} - \frac{\partial P}{\partial x_i} \quad (1)$$

$$\frac{\partial u_i}{\partial x_i} = 0 \quad (2)$$

where: Re is the Reynolds number defined as:

$$\text{Re} = \frac{UL}{\nu} \quad (3)$$

Dimensionless Equations

Eqs. (1) and (2) are non-dimensionalized by a characteristic length L and velocity scale U .

Methodology II

Consider a two dimensional problem in Cartesian coordinate system, let us denote u and v so that they are velocity components in, respectively, x- and y-direction. Then the Navier-Stokes equation become:

$$\frac{\partial u}{\partial t} = - \left(\frac{\partial}{\partial x} uu + \frac{\partial}{\partial y} uv \right) + \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) - \frac{\partial P_x}{\partial x} \quad (4)$$

$$\frac{\partial v}{\partial t} = - \left(\frac{\partial}{\partial x} vu + \frac{\partial}{\partial y} vv \right) + \frac{1}{\text{Re}} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \frac{\partial P_y}{\partial y} \quad (5)$$

And the Continuity equation is as follow:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad (6)$$

Methodology III

From Kim and Moin:

The fractional step, or time-split method, is in general a method of approximation of the evolution equations based on decomposition of the operators they contain. In application to the Navier-Stokes governing equations, one can interpret the role of pressure in the momentum equation equations as a projection operator which projects an arbitrary vector field into a divergence-free velocity field.

$$\frac{\hat{u}_i - u_i^n}{\Delta t} = \frac{1}{2} [3H_i^n - H_i^{n-1}] + \frac{1}{2} \frac{1}{\text{Re}} \left[\frac{\delta^2}{\delta x_1^2} + \frac{\delta^2}{\delta x_2^2} + \frac{\delta^2}{\delta x_3^2} \right] (\hat{u}_i + u_i^n) \quad (7)$$

$$\frac{u_i^{n+1} - \hat{u}_i}{\Delta t} = -G(\phi^{n+1}) \quad (8)$$

Methodology IV

From Le and Moin:

The modification has been proved to saved 49% CPU time in comparison to the original KM scheme in a flow over backward-facing step benchmark test.

- ▶ Each time step is advanced in three sub-steps.
- ▶ Velocity field is advanced through a sub-step without the need to satisfy the continuity equation.
- ▶ The Poisson equation is used to project the predicted vector field into a divergence-free velocity field only at the final sub-step.
- ▶ Boundary conditions for the intermediate velocity field are derived using the method similar to that of LeVeque and Olinger.
- ▶ The method is implemented for a staggered grid.

Methodology V

$$\frac{u^k - u^{k-1}}{\Delta t} = \alpha_k L(u^{k-1}) + \beta_k L(u^k) - \gamma_k N(u^{k-1}) - \zeta_k N(u^{k-2}) - (\alpha_k + \beta_k) \frac{\delta P_x^k}{\delta x}$$

$$\frac{v^k - v^{k-1}}{\Delta t} = \alpha_k L(v^{k-1}) + \beta_k L(v^k) - \gamma_k N(v^{k-1}) - \zeta_k N(v^{k-2}) - (\alpha_k + \beta_k) \frac{\delta P_y^k}{\delta y}$$

where:

- ▶ $k = 1, 2, 3$ denote the sub-step ($k - 2$ is ignored for $k = 1$);
- ▶ u_i^0 and u_i^3 are the velocities at time step n and $n + 1$; and
- ▶ $\frac{\delta}{\delta x_i}$ is the finite difference operator.

Methodology VI

Equation dump:

$L(u_i)$ represents second-order finite difference approximation to the viscous terms, such that:

$$L(u_i) = \frac{1}{\text{Re}} \frac{\partial^2 u_i}{\partial x_j \partial x_j} \quad (9)$$

Meanwhile, $N(u_i)$ represents second-order finite difference approximation to the convective terms, such that:

$$N(u_i) = \frac{\partial}{\partial x_j} u_i u_j \quad (10)$$

From Eq.(1), at an arbitrary step n in which time $t_n + \Delta t$:

$$\frac{\partial u_i^n}{\partial t} = -\frac{\partial}{\partial x_j} u_i^n u_j^n + \frac{1}{\text{Re}} \frac{\partial^2 u_i^n}{\partial x_j \partial x_j} - \frac{\partial P^n}{\partial x_i} \quad (11)$$

Methodology VII

$$\frac{3u_i^n - 4u_i^{n-1} + u_i^{n-2}}{2\Delta t} = -N(u_i^n) + L(u_i^n) - \frac{\delta P^n}{\delta x_i} = \text{RHS}(u_i^n) \quad (12)$$

$$\frac{3u_i^n - 3u_i^{n-1} - u_i^{n-1} + u_i^{n-2}}{2\Delta t} = \text{RHS}(u_i^n) \quad (13)$$

$$\frac{3}{2\Delta t} (u_i^n - u_i^{n-1}) - \frac{1}{2\Delta t} (u_i^{n-1} - u_i^{n-2}) = \text{RHS}(u_i^n) \quad (14)$$

Define a function F such that:

$$F(u_i^n) = \text{RHS}(u_i^n) - \frac{3}{2\Delta t} (u_i^n - u_i^{n-1}) + \frac{1}{2\Delta t} (u_i^{n-1} - u_i^{n-2}) \quad (15)$$

Notice that:

$$F(u_i^n) = 0 \quad (16)$$

Methodology VIII

Consider an approximation \hat{u}_i such that:

$$\hat{u}_i = u_i^*(\mathbf{x}, t_n + \Delta t) \quad (17)$$

$$u_i^*(\mathbf{x}, t_n) = u_i(\mathbf{x}, t_n) \quad (18)$$

4th-order Runge-Kutta scheme with pseudo time τ :

1. *Start by assigning:*

$$u_i^*(\mathbf{x}, t_n) = u_i(\mathbf{x}, t_n) \quad (19)$$

2. *The following loop is repeated until:*

$$|u_i^*(\mathbf{x}, t_n) - \hat{u}_i| < \epsilon, \quad \epsilon \ll 1 \quad (20)$$

2.1 Let us use a notation \hat{u}_i^k , such that:

$$\hat{u}_i^1 = u_i^*(\mathbf{x}, t_n) \quad (21)$$

$$\hat{u}_i^4 = u_i^*(\mathbf{x}, t_n + \Delta t) \quad (22)$$

Methodology IX

2.2 Calculate $F(\hat{u}_i^k)$:

$$F(\hat{u}_i^k) = \text{RHS}(\hat{u}_i^k) - \frac{3}{2\Delta t} (\hat{u}_i^k - u_i^{n-1}) + \frac{1}{2\Delta t} (u_i^{n-1} - u_i^{n-2}) \quad (23)$$

2.3 Runge-Kutta advance:

$$\hat{u}_i^k = u_i^*(\mathbf{x}, t_n) + \alpha(\kappa \Delta t) F(\hat{u}_i^k) \quad k = 2, 3, 4 \quad (24)$$

(25)

Viscous Terms I

CDS2 Scheme

Now let us find the expression for the finite difference operators in Eq.(9) and Eq.(10).

First, consider the Viscous term (9) as follows:

$$L(u_i) = \frac{1}{\text{Re}} \frac{\partial^2 u_i}{\partial x_j \partial x_j} \quad (26)$$

For a 2 dimensional coordinate system, one has the expression such that:

In x-direction:

$$L_x(u) = \frac{1}{\text{Re}} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \quad (27)$$

In y-direction:

$$L_y(v) = \frac{1}{\text{Re}} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \quad (28)$$

Viscous Terms II

CDS2 Scheme

The second derivative at an arbitrary point (i,j) is approximated by the second central difference:

$$\frac{\partial^2 u_{i,j}}{\partial x^2} = \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{\Delta x^2} \quad (29)$$

$$\frac{\partial^2 u_{i,j}}{\partial y^2} = \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{\Delta y^2} \quad (30)$$

and:

$$\frac{\partial^2 v_{i,j}}{\partial x^2} = \frac{v_{i+1,j} - 2v_{i,j} + v_{i-1,j}}{\Delta x^2} \quad (31)$$

$$\frac{\partial^2 v_{i,j}}{\partial y^2} = \frac{v_{i,j+1} - 2v_{i,j} + v_{i,j-1}}{\Delta y^2} \quad (32)$$

Convective Terms I

QUICK Scheme

For inner nodes:

$$F = um [1/8 * (-U_{i+2} - 2U_{i+1} + 3U_i) + U_{i+1}] + up [1/8 * (-U_{i-1} - 2U_i + 3U_{i+1}) + U_i] \quad (33)$$

For begin node ($i = 1$):

$$F = um [1/8 * (-U_{i+2} - 2U_{i+1} + 3U_i) + U_{i+1}] + up [1/8 * (-U_i - 2U_i + 3U_{i+1}) + U_i] \quad (34)$$

For end node ($i = N$):

$$F = um [1/8 * (-U_{i+1} - 2U_{i+1} + 3U_i) + U_{i+1}] + up [1/8 * (-U_{i-1} - 2U_i + 3U_{i+1}) + U_i] \quad (35)$$

Methodology I

Benchmark Problems

2D Taylor-Green vortex is a classic benchmark problem which solution is a periodic array of vortices, that repeats itself in the x - and y -directions with a periodic length L :

$$u(x, y, t) = u_0 \sin(kx) \cos(ky) f(t) \quad (36)$$

$$v(x, y, t) = -u_0 \cos(kx) \sin(ky) f(t) \quad (37)$$

$$p = \frac{\rho u_0^2}{4} f(t)^2 [\cos(2kx) + \cos(2ky)] \quad (38)$$

$$f(t) = \exp(-2\nu k^2 t) \quad (39)$$

$$k = \frac{2\pi}{L} \quad (40)$$

Try it out!

Get the source of code from

<https://github.com/milk-white-way/AMRESSIF>

The code *itself* is licensed under a Creative Commons Attribution-NonCommercial 4.0 International License.

