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MIS HW #5

#10.15 Let A be an $m \times n$ matrix with columns a_1, a_2, \dots, a_n

Then $G = A^T A$ where $G_{ij} = a_i^T a_j$

$$G^T = (A^T A)^T = A^T (A^T)^T = A^T A = G$$

Then $G_{ij} = G_{ji}^T = G_{ji}$

$$\begin{aligned} \text{Let } \|a_i - a_j\|^2 &= (a_i - a_j)^T (a_i - a_j) \\ &= (a_i^T - a_j^T) (a_i - a_j) \\ &= a_i^T a_i - 2a_i^T a_j + a_j^T a_j \\ &= G_{ii} - 2G_{ij} + G_{jj} \end{aligned}$$

Taking the square root of both sides

$$\|a_i - a_j\| = \sqrt{G_{ii} - 2G_{ij} + G_{jj}}$$

#10.16 (a) $A = [a_1 \dots a_k]$
 $\mu = [\mu_1 \dots \mu_k] = \left[\frac{1^T a_1}{n}, \dots, \frac{1^T a_k}{n} \right]$

(b) $\tilde{A} = [a_1 - 1^T \mu_1 \dots a_k - 1^T \mu_k]$

(c) case 1: $i = j$

$$\sum = \frac{1}{N} \tilde{a}_i^T \tilde{a}_i = \frac{\hat{a}_i^T}{\sigma_{a_i}/N} \times \frac{\tilde{a}_i}{\sigma_{a_i}/N} \times \sigma_{a_i}^2 = (\bar{z}_{a_i} \times \bar{z}_{a_i}) \times \text{std } a_i^2 = \text{std}(a_i)^2$$

case 2: $i \neq j$

$$\sum = \frac{1}{N} \tilde{a}_i^T \tilde{a}_j = \frac{\hat{a}_i^T}{\sigma_{a_i}/N} \times \frac{\tilde{a}_j}{\sigma_{a_j}/N} \times \sigma_{a_i} \times \sigma_{a_j} = \rho_{ij} \times \text{std}(a_i) \times \text{std}(a_j)$$

(d)

$$Z = \begin{bmatrix} \frac{a_1 - 1^T \mu_1}{\text{std}(a_1)} & \dots & \frac{a_k - 1^T \mu_k}{\text{std}(a_k)} \end{bmatrix}$$

#10.36 (a) let $Ax = \begin{pmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

$$Ax = \begin{pmatrix} \sum_{i=1}^n a_{1i} x_i \\ \vdots \\ \sum_{i=1}^n a_{mi} x_i \end{pmatrix}$$

$$x^T Ax = (x_1 \dots x_n) \begin{pmatrix} \sum a_{1i} x_i \\ \vdots \\ \sum a_{mi} x_i \end{pmatrix}$$

$$= \sum a_{1i} x_i x_1 + \dots + \sum a_{mi} x_i x_n$$

$$= \sum_{i,j=1}^n a_{ji} x_i x_j$$

(b) $x^T A^T x = (Ax)^T x = \langle Ax, x \rangle = \langle x, Ax \rangle = x^T Ax$

(c) $x^T \left(\frac{A+A^T}{2} \right) x = \frac{x^T Ax}{2} + \frac{x^T A^T x}{2} = \frac{x^T Ax}{2} + \frac{x^T Ax}{2} = x^T Ax$

(d) $2x_1^2 - 3x_1x_2 - x_2^2 = 2x_1^2 - \frac{3}{2}x_1x_2 - \frac{3}{2}x_2x_1 - x_2^2$

$$= (x_1, x_2) \begin{pmatrix} 2 & -3/2 \\ -3/2 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x^T Ax$$

where $x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$ & $A = \begin{pmatrix} 2 & -3/2 \\ -3/2 & -1 \end{pmatrix}$

#10.42 Let $A = I + ab^T$

$$\begin{aligned} \text{Then } Ax &= (I + ab^T)x \\ &= \underset{\textcircled{1}}{I}x + \underset{\textcircled{2}}{ab^T}x \end{aligned}$$

① $Ix = x$ I is very sparse so this will take $n \times 1 = n$ flops

② $b^T x$: takes n mult. & $n-1$ add = $2n-1$ flops
 $a(c)$: takes n mult & $n-1$ add = $2n-1$ flops

Sum through we get n more flops
so the whole process takes
 $n + 2(2n-1) + n$ flops which
is $O(n)$

So if we distribute x and carry out calculations this will be done in linear time.

#11.3 (a) $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ $x = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $y = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\begin{aligned} AX &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad AY = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ AX &= AY \quad \text{but } x \neq y \end{aligned}$$

(b) $AX = AY \Leftrightarrow A^{-1}AX = A^{-1}AY \Leftrightarrow X = Y$

(c) example in (a) let $A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$ is A invertible

$\det(A) = 0$ so A is not invertible then
not left invertible

#11.9 (a) $(I+BA)x = 0 \Leftrightarrow x + B(Ax) = 0$
 $\Leftrightarrow x + By = 0 \Leftrightarrow Ax + AB_y = 0 \Leftrightarrow y + AB_y = 0$
 $\Leftrightarrow (I+AB)y = 0$

But $I+AB$ is invertible thus $y = Ax = 0$

Now $x + B(Ax) = 0 \Leftrightarrow x + B(0) = 0 \Leftrightarrow x = 0$
Hence the null space of $I+BA$ is $\{0\}$ and
Thus $I+BA$ is invertible

(b) $B(I+AB) = B + BAB = (I+BA)B$

$$B(I+AB) = (I+BA)B$$

$$B(I+AB)(I+AB)^{-1} = (I+BA)B(I+AB)^{-1}$$

$$B = (I+BA)B(I+AB)^{-1}$$

$$(I+BA)^{-1}B = (I+BA)^{-1}(I+BA)B(I+AB)^{-1}$$

$$(I+BA)^{-1}B = B(I+AB)^{-1}$$

#11.27 $n=500$

time 0.372s magnitude $= 3.24 \times 10^{-11}$

2.500^3 flops		$\text{Gflops} = 0.672 \text{ Gflops/s}$
0.372 s		
		10^9 flops

$n=1000$

time 0.603s magnitude $= 3.24 \times 10^{-11}$

2.1000^3 flops		$\text{Gflops} = 3.317 \text{ Gflops/s}$
0.603 s		
		10^9 flops

$n=2000$ time 0.890s magnitude 1.42×10^{-11}

2.2000^3 flops		$\text{Gflops} = 17.977 \text{ Gflops/s}$
0.890 s		
		10^9 flops

#12.13 (a) Let $x^{(k+1)} = x^{(k)}$

$$\text{Then } x^{(k+1)} = x^{(k)} - \mu A^T (Ax^{(k)} - b)$$

$$\Downarrow$$
$$x^{(k)} = x^{(k)} - \mu A^T (Ax^{(k)} - b)$$

$$\Downarrow$$
$$0 = -\mu A^T (Ax^{(k)} - b)$$

$$\Downarrow$$
$$0 = A^T (Ax^{(k)} - b)$$

Thus $(Ax^{(k)} - b)$ is minimized

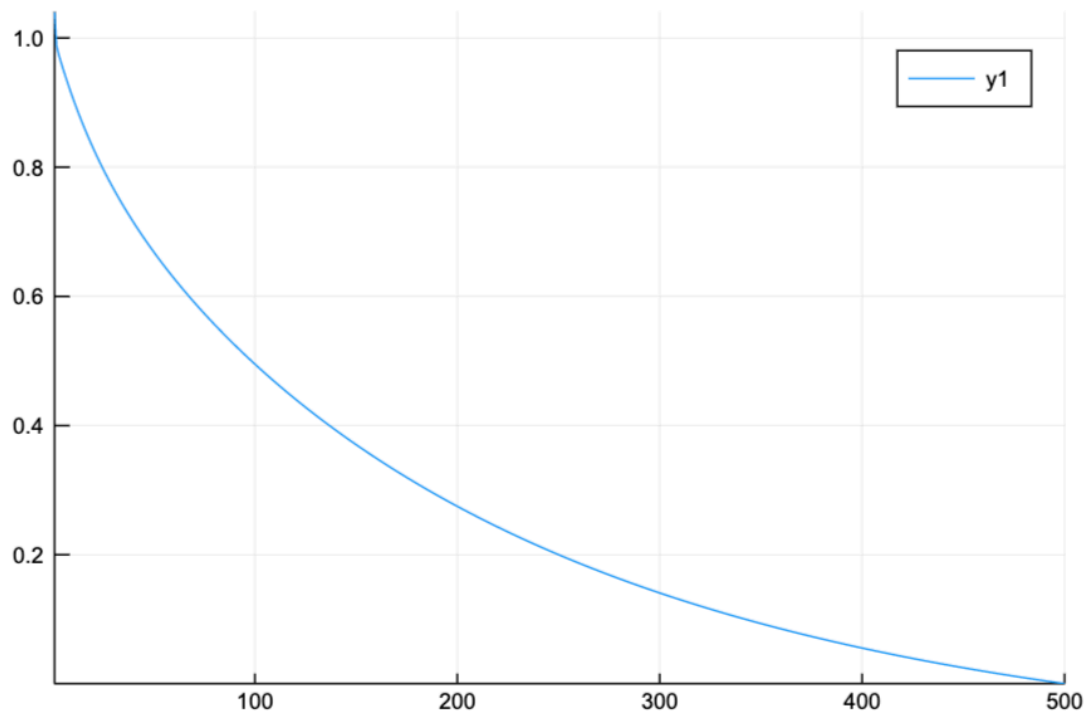
$$\text{So } x^{(k)} = \hat{x}$$

$$(b) \quad x^{(k+1)} = x^{(k)} - \mu A^T (Ax^{(k)} - b)$$
$$= x^{(k)} - \mu A^T A x^{(k)} + \mu A^T b$$
$$= (I - \mu A^T A) x^{(k)} + \mu A^T b$$

$$\Rightarrow x^{(k+1)} = F x^{(k)} + g$$

$$\text{where } F = (I - \mu A^T A) \text{ \& } g = \mu A^T b$$

(c)



As we can see after each iteration $Ax-b$ is converging to zero.