

#1 14.4

Prework: So, $\min \|X^T B - Y\| \Leftrightarrow \min \|Y - X^T B\|$,
which is the minimization of error E

$$Y = X^T B + E \quad E \in \mathbb{R} \leq Y - X^T B$$

$$\text{Therefore, } E(x) = (Y - X^T B)^T (Y - X^T B)$$

$$= (Y^T - (x^T B)^T)(Y - X^T B)$$

$$= (Y^T - (B^T x))(Y - X^T B)$$

$$= Y^T Y - Y^T x^T B - Y B^T X + B^T X X^T B$$

Note: $Y^T X B$ is a scalar
So, $Y^T X B = C = C^T = (Y^T X B)^T = B^T X^T Y$
Thus, $Y^T X B = B^T X^T Y$

We want to minimize $E(x)$ so

$$\frac{\partial E(x)}{\partial B} = -x^T Y + X X^T B = 0$$

$$\text{Then, } -x^T Y + X X^T B = 0$$

$$\Rightarrow X X^T B = X^T Y$$

$$\Rightarrow B = (X X^T)^{-1} X^T Y$$

#1 14.4a Y is the truth value for each of the variables in X for all samples N . The i^{th} row of Y is the truth for each of the variables in the i^{th} row of X , i.e. the actual response to i^{th} question for each of the N responses.

#1 14.4b Since, the rows of X are lin. indep. we can use the pseudo inverse
 $* X^+ = X(X X^T)^{-1}$ where $(X^+)^T = (X(X X^T)^{-1})^T = (X X^T)^{-T} X^T = (X^T X)^{-1} X^T = (X^T)^+$

From my prework I found that:

$$B = (X X^T)^{-1} X^T Y$$

Thus, by * we see that

$$\hat{B} = (X^T)^+ Y$$

#2 15.4 Here we want to minimize $\|A^{(1)}x - b\|^2 + \dots + \|A^{(k)}x - b\|^2$

$$\text{Let } F(x) = \sum_{i=0}^k \|A^{(i)}x - b\|^2$$

We want to minimize $F(x)$ with respect to x

$$\text{So, } \frac{\partial F(x)}{\partial x} = \sum_{i=1}^k 2 \langle A_j^{(k)}, A^{(k)}x - b \rangle = 0, \text{ where } A_j^{(k)} \text{ is the } j^{th} \text{ column of } A^{(k)}$$

$$\text{Then, } \sum_{i=1}^k \langle A_j^{(k)}, A^{(k)}x - b \rangle = 0$$

$$\Rightarrow (A^{(1)}x - b) + \dots + (A^{(k)}x - b) = 0$$

$$\Rightarrow (A^{(1)}x + \dots + A^{(k)}x) - kb = 0$$

$$\Rightarrow \sum_{i=1}^k (A^{(i)})x = kb$$

$$\text{Therefore, } x^{rob} = \left(\sum_{i=1}^k (A^{(i)}) \right)^{-1} kb$$

To verify that $x^{rob} = (A^{(1)})^{-1}b$ for $k=1$,
we set $k=1$ in the above equation and get:

$$x_1^{rob} = \left(\sum_{i=1}^1 (A^{(i)}) \right)^{-1} (1)b = (A^{(1)})^{-1}b$$

Thus, for $k=1$ $x^{rob} = (A^{(1)})^{-1}b$

#15.11a Let $A = 0_{m \times n}$ WLOG m > n, other case m=n & n>m

$$0^+ = \lim_{\lambda \rightarrow 0} 0_{m \times n}^T (0_{m \times n} 0_{m \times n}^T + \lambda I)^{-1} = \lim_{\lambda \rightarrow 0} 0_{m \times n} = 0_{m \times n}$$

#15.11 b Consider the first formula
 Since, the columns of A are lin. indep $(A^T A)^{-1}$ exists (#1)
 Thus, $A^+ = \lim_{\lambda \rightarrow 0} (A^T A + \lambda I)^{-1} A^T = (A^T A)^{-1} A^T$ which holds by (#1)
 So, the limit reduces to $A^+ = (A^T A)^{-1} A^T$

#15.11c Consider the second formula
 Since, the rows of A are lin. indep $(A A^T)^{-1}$ exists (#2)
 Thus, $A^+ = \lim_{\lambda \rightarrow 0} A^T (A A^T + \lambda I)^{-1} = A^T (A A^T)^{-1}$ which holds by (#2)
 So, the limit reduces to $A^+ = A^T (A A^T)^{-1}$

#4 16.11 Assume $Cx = d$ & let $y = x - a$

$$\text{Then, } C(y+a) = d$$

$$\begin{aligned} \Rightarrow Cy + Ca &= d \\ \Rightarrow -Cy &= Ca - d \\ \Rightarrow y &= C^+(Ca - d) \\ \Rightarrow x - a &= C^+(Ca - d) \\ \Rightarrow x &= a + C^+(Ca - d) \end{aligned}$$

Note: C^+ exists since the rows of C are lin. indep. and C^+ is the left pseudo inverse of C.

#5(1) Given that the columns of A are lin. indep.
 First, we can compute $A = QR$ using the Gram-Schmidt algorithm
 Then with Q & R, we can compute $A^+ = R^{-1} Q^T$
 So, we solve $x = A^+ b = R^{-1} Q^T b$

#5(2) First, compute $A = LL^T$ using Cholesky factorization
 where L is a lower triangular matrix.

Then, use forward substitution to solve $Lv = b$
 Finally, use backwards substitution to solve $L^T x = v$

#6 Let $E = \lambda I_n : n \times n$, $F = A^T : n \times m$, $G = I_m : m \times m$, & $H = A : n \times m$
 Consider $(A^T A + \lambda I_n)^{-1} = (\lambda I_n + A^T A)^{-1} = (\lambda I_n + A^T I_m A)^{-1} = (E + F G H)^{-1}$
 By matrix inversion lemma then

$$\begin{aligned} (E + F G H)^{-1} &= E^{-1} - E^{-1} F (G^{-1} + H E^{-1} F)^{-1} H E^{-1} \\ &= (\lambda I_n)^{-1} - (\lambda I_n)^{-1} A^T (I_m^{-1} + A(\lambda I_n)^{-1} A^T)^{-1} A (\lambda I_n)^{-1} \\ &= \lambda^{-1} I - \lambda^{-1} I A^T (I + \lambda^{-1} A A^T)^{-1} \lambda^{-1} A \\ &= (\lambda^{-1})^2 I (I - A^T (I + \lambda^{-1} A A^T)^{-1} A) \\ &\quad - J = (I + \lambda^{-1} A A^T)^{-1} \text{ takes } m^2 n + m^2 + m + m^3 \text{ flops to compute} \\ &= (\lambda^{-1})^2 I (I - A^T J A) \\ &\quad - K = (I - A^T J A) \text{ takes } m^2 n + m^2 n + n \text{ flops to compute} \\ &L = (\lambda^{-1})^2 I \text{ takes } m^3 + m^2 \text{ flops to compute} \end{aligned}$$

Then, $\hat{x} = L b$ takes $m^2 \cdot m$ flops to compute

Therefore, the total flops required is: $3m^2 + 3m^2 n + 2m^3 + n$

which is $\mathcal{O}(m^2 n + m^3)$

#7a Using $P_A(\lambda) = \det(\lambda I_n - A)$ (i.e. formal definition of characteristic polynomial)

$$\begin{aligned}
 P_C(\lambda) &= \det(\lambda I_n - C) = \det \begin{bmatrix} \lambda & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & \cdots & 0 & c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda & c_{n-2} \\ 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{bmatrix} \\
 &= \lambda \cdot \det \begin{bmatrix} \lambda & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & \cdots & 0 & c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda & c_{n-2} \\ 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{bmatrix} + (-1)^{1+n} \cdot c_0 \cdot \det \begin{bmatrix} -1 & \lambda & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda \\ 0 & 0 & \cdots & -1 \end{bmatrix} \\
 &= \lambda \cdot \det \begin{bmatrix} \lambda & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & \cdots & 0 & c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda & c_{n-2} \\ 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{bmatrix} + (-1)^{1+n} \cdot c_0 \cdot (-1)^{n-1} \\
 &= \lambda \cdot \det \begin{bmatrix} \lambda & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & \cdots & 0 & c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda & c_{n-2} \\ 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{bmatrix} + (-1)^{2n} c_0 \\
 &= \lambda \cdot \det \begin{bmatrix} \lambda & 0 & \cdots & 0 & c_0 \\ -1 & \lambda & \cdots & 0 & c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & \lambda & c_{n-2} \\ 0 & 0 & \cdots & -1 & \lambda + c_{n-1} \end{bmatrix} + c_0 \\
 &\vdots \\
 &= \lambda^n + \lambda^{n-1} c_{n-1} + \cdots + \lambda c_1 + c_0
 \end{aligned}$$

#7b Assume C has n distinct eigenvalues ($\lambda_1, \lambda_2, \dots, \lambda_n$)

$$\begin{aligned}
 \text{Then, } VC &= \begin{bmatrix} 1 & \lambda_1 & \lambda_1^2 & \cdots & \lambda_1^{n-1} \\ 1 & \lambda_2 & \lambda_2^2 & \cdots & \lambda_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \lambda_n & \lambda_n^2 & \cdots & \lambda_n^{n-1} \end{bmatrix} \begin{bmatrix} 0 & 0 & \cdots & 0 & -c_0 \\ 1 & 0 & \cdots & 0 & -c_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & -c_{n-2} \\ 0 & 0 & \cdots & 1 & -c_{n-1} \end{bmatrix} \\
 &= \begin{bmatrix} \lambda_1 & \lambda_1^2 & \cdots & \lambda_1^{n-1} & -p(\lambda_1) + \lambda_1^n \\ \lambda_2 & \lambda_2^2 & \cdots & \lambda_2^{n-1} & -p(\lambda_2) + \lambda_2^n \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \lambda_n & \lambda_n^2 & \cdots & \lambda_n^{n-1} & -p(\lambda_n) + \lambda_n^n \end{bmatrix} \text{ since: } -c_0 - c_1 \lambda_1 - \cdots - c_{n-1} \lambda_1^{n-1} - \lambda_1^n = 0 \\
 &\qquad\qquad\qquad \Rightarrow -c_0 - c_1 \lambda_2 - \cdots - c_{n-1} \lambda_2^{n-1} - \lambda_2^n + \lambda_2^n = \lambda_2^n \\
 &\qquad\qquad\qquad \Rightarrow -p(\lambda_2) + \lambda_2^n = 0 + \lambda_2^n = \lambda_2^n \\
 &= \begin{bmatrix} \lambda_1 & \lambda_1^2 & \cdots & \lambda_1^{n-1} & \lambda_1^n \\ \lambda_2 & \lambda_2^2 & \cdots & \lambda_2^{n-1} & \lambda_2^n \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \lambda_n & \lambda_n^2 & \cdots & \lambda_n^{n-1} & \lambda_n^n \end{bmatrix} \\
 &= \begin{bmatrix} \lambda_1 & & & & \\ & \lambda_2 & & & \\ & & \ddots & & \\ & & & \lambda_{n-1} & \\ & & & & \lambda_n \end{bmatrix} \begin{bmatrix} 1 & \lambda_1 & \lambda_1^2 & \cdots & \lambda_1^{n-1} \\ 1 & \lambda_2 & \lambda_2^2 & \cdots & \lambda_2^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \lambda_n & \lambda_n^2 & \cdots & \lambda_n^{n-1} \end{bmatrix} \\
 &= \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) \cdot V \\
 &= \Lambda V
 \end{aligned}$$

#8a Consider, $w = e^{2\pi i/n}$
 Note: $w^n = (e^{2\pi i/n})^n = e^{2\pi i} = 1$. So, $w^{j+n} = w^j w^n = w^j$

Using the primitive roots of unity of w
 The i th normalized eigenvector of C is

$$x^{(i)} = \begin{bmatrix} \frac{1}{\sqrt{n}} w^{0(i-1)} \\ \frac{1}{\sqrt{n}} w^{1(i-1)} \\ \vdots \\ \frac{1}{\sqrt{n}} w^{(n-1)(i-1)} \end{bmatrix}, \text{ and its corresponding eigenvalue is } \lambda_i$$

Therefore, the eigenmatrix of C is $V = [x^{(1)} \ x^{(2)} \ \dots \ x^{(n)}] = F^* = F^{-1}$

$$\text{and } \Lambda = \text{Diag}(\lambda_1, \lambda_2, \dots, \lambda_n) = \text{Diag}\left(\begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_n \end{bmatrix}\right) = \text{Diag}(x^{(1)} \ x^{(2)} \ \dots \ x^{(n)}) = \text{Diag}(F^*)$$

Thus,
 $C = V \Lambda V^{-1} = F^{-1} \Lambda (F^{-1})^{-1} = F^* \Lambda F$



#8b Suppose $C = F^* \Lambda F$

Then, I would solve $x = (F^* \Lambda F)^{-1} b = (F \Lambda^{-1} F^{-1}) b = (F \Lambda F^*) b$

Step 1: $x = F^* b$ takes $n \log n$ flops

Step 2: $y = \Lambda x$ takes $n \log n$ flops for $\Lambda \notin n$ flops for Λx

Step 3: $z = F y$ takes $n \log n$ flops

Total: takes $3n \log n + n$ flops

which is $O(n \log n)$

#9a Suppose $\nabla f(x) = 0$. Then, $A^T A \hat{x} = A^T b$

$$\begin{aligned} A^T A \hat{x} &= A^T A (V \Sigma^{-1} U^T b) = A^T (U \Sigma V^T) (V \Sigma^{-1} U^T) b \\ &= A^T (U \Sigma (V^T V) \Sigma^{-1} U^T) b = A^T (U \Sigma (I) \Sigma^{-1} U^T) b \\ &= A^T (U (\Sigma \Sigma^{-1}) U^T) b = A^T (U (I) U^T) b \\ &= A^T (U U^T) b = A^T (I) b \\ &= A^T b \end{aligned}$$

#9b Assume $x \neq \hat{x}$

$$\begin{aligned} \text{Then, } \|Ax - b\|^2 &= \|(Ax - A\hat{x}) + (A\hat{x} - b)\|^2 \\ &= \|(Ax - A\hat{x})\|^2 + \|(A\hat{x} - b)\|^2 + 2(Ax - A\hat{x})^T (A\hat{x} - b) \end{aligned}$$

Looking at the third term on the RHS

$$\begin{aligned} \text{Then, } (Ax - A\hat{x})^T (A\hat{x} - b) &= (A(x - \hat{x}))^T (A\hat{x} - b) \\ &= (x - \hat{x})^T A^T (A\hat{x} - b) \\ &= (x - \hat{x})^T (A^T A \hat{x} - A^T b) \\ &= (x - \hat{x})^T (0) \quad (\text{by #9a}) \\ &= 0 \end{aligned}$$

$$\text{So, } \|Ax - b\|^2 = \|(Ax - A\hat{x})\|^2 + \|(A\hat{x} - b)\|^2$$

Additionally, the first term on the RHS is non-negative.

Therefore, we have

$$\|Ax - b\|^2 \geq \|(A\hat{x} - b)\|^2$$

#10a

Part A

```
In [210]: a = np.random.rand(6, 3)
u, s, vh = np.linalg.svd(a, full_matrices=False)
q, r = np.linalg.qr(a)
list_r = [r]
list_q = [q]

for i in range(100000):
    q, r = np.linalg.qr(np.transpose(r))
    list_r.append(r)
    list_q.append(q)

print(a)
```

Starting matrix

$a = \begin{bmatrix} 0.68607795 & 0.801398 & 0.4805485 \\ 0.11252787 & 0.75508562 & 0.45226404 \\ 0.75385057 & 0.53701423 & 0.02117887 \\ 0.0853504 & 0.02602419 & 0.12403826 \\ 0.62733978 & 0.19914588 & 0.47546382 \\ 0.6633118 & 0.07862518 & 0.18284602 \end{bmatrix}$

```
In [213]: print(V)
print('\n')
print(np.transpose(vh))
```

$V \text{ algorithm vs SVD}$

$V = \begin{bmatrix} -0.68474985 & -0.72202029 & -0.09901686 \\ -0.61224018 & 0.64361845 & -0.45925728 \\ -0.39532216 & 0.25385425 & 0.88276747 \end{bmatrix}$

$V = \begin{bmatrix} -0.68474985 & -0.72202029 & -0.09901686 \\ -0.61224018 & 0.64361845 & -0.45925728 \\ -0.39532216 & 0.25385425 & 0.88276747 \end{bmatrix}$

```
In [214]: print(U)
print('\n')
print(u)
```

$U \text{ algorithm vs SVD}$

$U = \begin{bmatrix} 0.61850168 & -0.19841316 & -0.02806078 \\ 0.38609503 & -0.72379565 & 0.09857747 \\ 0.45879178 & 0.26927238 & -0.72180028 \\ 0.06635039 & 0.01865035 & 0.21253559 \\ 0.39755746 & 0.28430806 & 0.63490049 \\ 0.30893704 & 0.53203906 & 0.14223016 \end{bmatrix}$

$U = \begin{bmatrix} -0.61850168 & 0.19841316 & -0.02806078 \\ -0.38609503 & 0.72379565 & 0.09857747 \\ -0.45879178 & -0.26927238 & -0.72180028 \\ -0.06635039 & -0.01865035 & 0.21253559 \\ -0.39755746 & -0.28430806 & 0.63490049 \\ -0.30893704 & -0.53203906 & 0.14223016 \end{bmatrix}$

```
In [215]: print(list_r[99999])
print('\n')
print(s)
```

$\Sigma \text{ algorithm vs SVD}$

$\Sigma = \begin{bmatrix} 1.8600011e+000 & -9.88131292e-324 & 0.00000000e+000 \\ 0.00000000e+000 & -7.17811429e-001 & 0.00000000e+000 \\ 0.00000000e+000 & 0.00000000e+000 & 4.19195739e-001 \end{bmatrix}$

$\Sigma = [1.86000111 0.71781143 0.41919574]$

Based on the results of the test

I can conclude the hypothesis that

$Q_1 Q_3 \cdots Q_{2k+1} \cdots$ converges to V

$Q_0 Q_2 \cdots Q_{2k} \cdots$ converges to U

\notin

R_{2k} converges to Σ

Note that if λ is the eigenvalue for the eigenvector v then
 $(-\lambda)$ is the eigenvalue for the eigenvector $(-v)$.

#10b Prove $Q_1(R, R_0)$ is the QR factorization of $R^T R_0$.

$$Q_1(R, R_0) = (Q_1, R_1) R_0 = R_0^T R_0.$$

#10c ① Prove $(R, R_0) Q_1 = R_0 R_0^T$

$$\begin{aligned} (R, R_0) Q_1 &= R_0 (Q_1, R_1)^T Q_1 \\ &= R_0 R_1^T Q_1^T Q_1 \\ &= R_0 R_1^T (I) \\ &= R_0 R_1^T \end{aligned}$$

② Prove $R_1 R_1^T = R_2^T R_2$

$$\begin{aligned} R_1 R_1^T &= (Q_2 R_2)^T (Q_2 R_2) \\ &= R_2^T Q_2^T Q_2 R_2 \\ &= R_2^T (I) R_2 \\ &= R_2^T R_2 \end{aligned}$$

③ Prove $B_0 = R_0 R_0^T$ & $B_1 = R_2^T R_2$ have the same eigenvalues

In ② we showed that:

$$- R_i R_i^T = R_{i+1}^T R_{i+1}$$

Applying ② to $R_{i+1}^T R_{i+1}$, we see that:

$$- R_i R_i^T = R_{i+2}^T R_{i+2}$$

$$\text{So, } B_0 = R_0 R_0^T = R_2^T R_2 = B_1$$

Therefore, B_0 and B_1 are similar and that:

$$- B_1 = S^{-1} B_0 S, \text{ where } S \text{ is the change of basis matrix}$$

Then, the characteristic polynomial of B_1 is:

$$\begin{aligned} - P_{B_1}(\lambda) &= \det(B_1 - \lambda I) = \det(S^{-1} B_0 S - \lambda I) \\ &= \det(S^{-1}(B_0 - \lambda I)S) \\ &= \det(S^{-1}) \det(B_0 - \lambda I) \det(S) \\ &= \det(B_0 - \lambda I) = P_{B_0}(\lambda) \end{aligned}$$

Thus, since $B_0 \not\equiv B_1$ have the same characteristic
then they have the same eigenvalues.

#10d Prove $B_K = R_{2K} R_{2K}^T$ are the ...

In #10c I showed applying the QR factorization

to B_K an odd number of times (i.e. once) results
in $B_K = R_{K+1}, R_{K+1}^T = (B_{K+1})^T$.

Applying it an even number of times (i.e. twice)
results in $B_K = (B_{K+1})^T = B_{K+2}$

So, $B_K = B_t = R_t R_t^T$, where $t = 2n \notin n \in \mathbb{Z}^+$ (i.e. t is even)

Therefore, if we choose $t = 2K$, where $K \in \mathbb{Z}^+$

Thus, $B_K = R_{2K} R_{2K}^T$