CS350 Homework 3

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22.1-1

The out-degree of a vertex is just its adjacency list, so in $\Theta(V)$ time you can get the out-degree of every vertex. Finding the in-degree for every vertex would require looking for that vertex in every vertex's adjacency list. So the entire adjacency list must be visited, which would be $\Theta(V*E)$, where V is the total number of vertices, and E is the total number of edges.

22.1-3

```
Adjacency List [(1,[2,3]), (2,[4,5]), (3,[6,7])]
```

Adjacency Matrix

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|---|---|---|---|---|---|---|
| 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| 2 | 0 | 0 | 0 | 1 | 1 | 0 | 0 |
| 3 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 4 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 5 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 6 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

22.1-3

```
TRANSPOSE(ajd_list A)
1  new adj_list B
2  for each v in A
3   for each (v,x) in v
4    B.add(x,v)

TRANSPOSE(adj_matrix A)
1  new ajd_matrix B[A.width][A.height]
2  for i in A.width
3  for j in A.height
4  B[j][i] = A[i][j]
```

The running time of the list version of the transpose is $O(|V|^2)$, where V is the number of vertices. In the best case, with a completely disconnected graph, it would only take |V|.

The running time of the matrix version is $\Theta(|V|^2)$, because it copies the entire matrix which is width and height V.

22.1-6

Finding a universal sink has 3 parts: identifying the correct vertex, verifying that its in-degree is |V|-1, and verifying that its out-degree is 0.

In order to find a vertex with zero out-degree, the worst-case would be $|V|^2$, so immediately we know this is not where to start. We also know that determining a vertex's in-degree is $|V|^2$.

So as a shortcut, we'll start from an arbitrary row in the matrix, and when a 1 is found in column j, move to row i, where i = j. Then find the first 1, repeating this process until a row i is found with all zeros. This could potentially be the universal sink. The last step is to verify that in column j, where j = i, there are all 1s. While jumping from row to row, there were a few traversals within each row, for less than V rows. There was also the traversal of the sink row, which is length V. And lastly, there was the traversal of the V-length column. This is 3V, which is O(V).

This is clever, but it's not actually complete. This is because there are cases when this would be much worse than O(V). Here is the matrix to show a counterexample. Imagine a graph where all vertices are connected to each other, AND the sink, and the algorithm traverses every edge before reaching the sink. It would take $O(V^2)$.

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|---|---|---|---|---|---|---|
| 1 | 0 | 1 | 0 | 0 | 0 | 0 | 1 |
| 2 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |
| 3 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 4 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| 5 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |
| 6 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| 7 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

22.2-8

```
MAZESOLVE(G)
  new array visits[ G.edges.length ]
  new array status[ G.vertices.length]
  for each v in G.vertices
4
     status[v] = unvisited
  endfor
5
6
  new queue Q
7
  Q.enqueue(G.vertices[0])
  status[G.vertices[0]] = discovered
8
  while Q.notempty
9
10
     u = Q.dequeue
     for each v in u.adj_list
11
12
       if status[v] == unvisited
         ++visits[(u,v)]
13
14
         status[v] = discovered
         Q.enqueue(v)
15
       endif
16
17
     endfor
18
     status[u] = visited
19
     for each v in u.adj_list
20
       ++visits[(u,v)]
     endfor
21
22 endwhile
```

This algorithm should be setting each value of the 'visits' array to 2. That means each edge has been visited twice. The way this can solve a maze is by traversing the graph, you can find your way back out by following the vertices you've marked twice. Those are the ones that are visited.

22.3-8

Using adjacency-list representation, here is an example graph:

{ A : (B,C), B : (), C : (B) }

The depth-first search would produce a time table such as this:

| | A | В | С |
|---|---|---|---|
| d | 1 | 2 | 4 |
| V | 6 | 3 | 5 |

This includes a path $C \to B$, where d[B] < v[C].