HASHING NOTES

A hash function is a mathematical formula which, when applied to a key, produces an integer which can be used as an index for the key in the hash table.

TYPES -

- Division method
- Multiplication method
- Mid square method
- Folding method

DIVISION METHOD -

This method divides x by M and then uses the remainder obtained.

$h(x) = x \mod M$

It is always wise to choose M as an even number

Drawback: Consecutive keys map to consecutive hash values

Example:

Calculate the hash values of keys 1324 and 5642 (Use M as 97)

MULTIPLICATION METHOD -

It works in steps:

- 1. Choose A as 0 < A < 1
- 2. Multiply key k by A
- 3. Extract fractional part of kA
- 4. Multiply result of kA by size of hash table (m)

Knuth has suggested the best value to be used for A as 0.618033

Example:

Given a hash table of size 1000, map key 12345 to an appropriate location in the hash table

MID - SQUARE METHOD -

It works in steps:

- 1. Square the value of the key
- 2. Extract the middle r digits of the result obtained in 1.

Example:

Given a hash table of size 100 memory locations, map key 1234 and 5642 to an appropriate location in the hash table.

FOLDING METHOD -

It works in steps:

- 1. Divide key k value into number of parts, where each part has equal digits except the last part can have lesser digits.
- 2. Add all parts. The hash value is the one after ignoring the carry if any.

Example:

Given a hash table of size 100 memory locations, map key 5678, 321 and 34567 to an appropriate location in the hash table

COLLISION NOTES

COLLISION RESOLUTION TECHNIQUES -

- 1. Open Addressing
 - 1. Linear Probing
 - 2. Quadratic Probing
 - 3. Double Hashing
 - 4. Rehashing
- 2. Chaining

OPEN ADDRESSING -

1. LINEAR PROBING -

Function: $h(k, I) = [h'(k) + i] \mod m$

Where m is the size of the hash table, $h'(k) = k \mod m$ and I is the probe number

Drawback: Primary Clustering

Example:

Consider a hash table of size 10. Using Linear probing, insert the keys 72, 27, 36, 24, 63, 81, 92, 101 into the table.

1. QUADRATIC PROBING -

Function: $h(k, l) = [h'(k) + c1i + c2i] \mod m$

Where m is the size of the hash table, $h'(k) = k \mod m$ and I is the probe number which varies from 0 to m-1, c1 and c2 are constants other than 0.

Drawback: Successive probing explore only fraction of the table

Application: Widely used in Berkeley Fast File System to allocate free blocks

Example:

Consider a hash table of size 10. Using Linear probing, insert the keys 72, 27, 36, 24, 63, 81, 92, 101 into the table. Take c1 = 1 and c2 = 3

1. DOUBLE HASHING -

Function: $h(k, i) = [h1(k) + i*h2(k)] \mod m$

Where m is the size of the hash table, $h1(k) = k \mod m$, $h2(k) = k \mod m'$ and I is the probe number which varies from 0 to m-1, m' is a value less than m.

Advantage: Minimizes repeated collisions and the effects of clustering

Example:

Consider a hash table of size 10. Using Linear probing, insert the keys 72, 27, 36, 24, 63, 81, 92, 101 into the table. Take $h1 = k \mod 10$ and $h2 = k \mod 8$

1. REHASHING -

Hash table nearly full; collision increases; thereby degrading performance

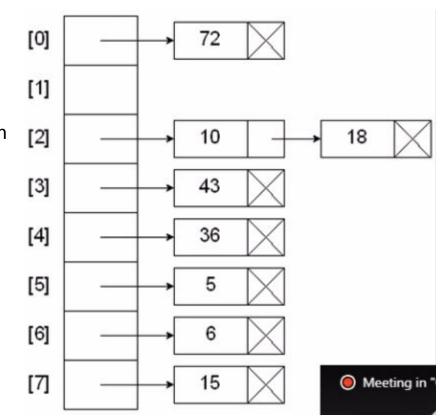
Create new hash table with double value

Move all values from old hash table to new one

Cons: Too expensive

CHAINING -

ADVANTAGES Number of key values
won't affect the
number of locations in
the hash table
DISADVANTAGES Overhead of storing
pointers
Poor cache
performance since
traversing the linked
list.



BUCKET HASHING -

- Divide M slots of hash table into B buckets
- So, each bucket has M / B slots
- Calculate position for key using hash function
- Slot free; allocate
- Else put the key in "Overflow bucket"
- Cons: If key not found in bucket; searching key in Overflow bucket is expensive

Ducket
1
Bucket
2
Bucket
3
Bucket
4

Bucket

APPLICATIONS -

- Database Indexing
- Compiler for Symbol table
- Driver's Licence
- Sparse Matrix