lab one + discussion week two

Is, cat, and wc

· Is: list directory contents

```
ls // Lists all files and directories in the present working directory
ls -a // Lists hidden files as well
ls -l // Lists files and directories with detailed information like permissions, size, owner, etc.
ls -R // Lists files in sub-directories as well
ls [path] // Lists files in the target directory
```

cat: reads data from the files and gives their content as output

```
cat filename // view a single file, it will show content of given filename cat file1 file2 // view multiple files, the content of file1 and file2. cat -n filename // view contents of a file preceding with line numbers. cat [filename-whose-contents-is-to-be-copied] > [destination-filename] // Copy the contents of one file to another file
```

- wc: find out number of lines, word count, byte and characters count in the files specified in the file arguments
- options
 - - 1, --lines Print the number of lines.
 - Fig. --words Print the number of words.
 - - m, --chars Print the number of characters.
 - - c, --bytes Print the number of bytes.
 - Fig. --max-line-length Print the length of the longest line.

piping

Name	Command	Description	Example
Redirect to a file	> *a_file	Take all output from standard out and place it into filename. Note using >> will append to the file, rather than overwrite it.	ls > *a_file
Read from a file	< *a_file	Copy all data from the file to the standard input of the program	echo < *a_file

Pipe

Take everything from standard out of program

1 and pass it to standard input of program 2

- if there is no pipe, where does a program dump output or take input from?
 - by default: connected to the terminal, 0 is to the standard inputer to the terminal (keyboard) and 1 is to the standard output from the terminal (console)
- what does cat test_lab1.py | wc do?
 - dumps the content of test1_lab1.py then counts the line/word/bytes of this dump

lab one overview

- three sub-components
 - read and execute the programs represented by the arguments
 - the execution ordering align with the arguments
 - create a pipe between two adjacent programs
 - connect argv[i] 's output to argv[i+1] 's input
- to check work
 - COMPARE program1 | program2 | program3 to ./pipe program1 program2 program3

read in command line arguments

```
int main(int argc, char *argv[]) {
  return 0;
}
```

- argc number of arguments passed in
- argv array of actual argument strings
 - argv[0] is the program we are running, the rest are the programs we want to pipe together

creating a new process

execlp api

```
int execlp(const char * file , const char * arg , ... /*(char*) NULL*/);
```

replaces the current process with a new process

- more convenient than execve, a wrapper function built on top
 - file path to new process
 - our executable file name
 - arg command line arguments of the new process, NULL terminated
 - arg[0] can be either the same as file, or different

fork api

pid_t fork(void)

- creates a new process (child process) by duplicating the calling process (parent process)
- child process has (almost) the same state as the parent process, including variables
- example

```
int i = 1, j = 2;
int res = fork();
// child: i = 1, j = 2, res = 0
// parent: i = 1, j = 2, res is pid > 0
```

- on success
 - return <0 means error
 - return 0 to the child process
 - return pid of the child process to the parent process
- distinguishing between child and parent process
 - 1. ==0 child process
 - 2. > parents process
 - 3. < fork() failed
- · execution order matters, by default it is non-deterministic

execution ordering

wait api: waiting for process to change state

```
wait(int *wstatus)
```

- blocks the calling process until any one of its child processes exits or a signal is received
- after wait() finished, the calling process continues its execution

- child process may terminate due to any of these
 - it calls exit();
 - it returns (an int) from main
 - it receives a signal (from the os or another process) whose default action is to terminate
 - wait() returns the pid of the child that terminates

```
pid_t waitpid(pid_t pid, int *wstatus, int options);
```

- "...until one of its children terminates" -> "...until child with this pid terminates"
- wait(&wstatus) = waitpid(-1, &wstatus, 0)

macro information about status

- to find information about status, we use WIF... macros
 - WIFEXITED(status) child exited normally
 - WEXITSTATUS(status) return code when child exits
 - wifsignaled(status) child exited because a signal was not caught
 - WTERMSIG(status) gives the number of the terminating signal
 - WIFSTOPPED(status) child is stopped
 - wstopsig(status) gives the number of the stop signal

pipe between adjacent programs

file descriptors

- in unix/linux, everything is a file
- powerful abstraction, only have to consider how to interact with "files"
 - be it a storage device, printer, monitor screen, etc.
- when interacting with them, make system call to kernel to request access to them
- system calls return file descriptors to the user process as a handle (reference) to the underlying file
- when a user process needs to perform i/o to the files, it needs to pass the file descriptor
 to the kernel via a system call, the kernel will access the file on process's behalf

standard file desciptors

Integer value	name	Symbol (<unistd.h>)</unistd.h>
0	Standard input	STDIN_FILENO
1	Standard output	STDOUT_FILENO
2	Standard error	STDERR_FILENO

redirection

- > set a prgram's stdout to be a specific fd of a file on the disk
- < set a program's stdin to be a specific fd of a file on disk
- connect argv[i]'s output to argv[i+1]'s input
 - Why it is not argv[i]'s stdout fd = argv[i+1]'s stdin fd
 - permission error of fds
 - programs across the pipe are not parallel
 - i.e. there is no real-time, async communication anyway
 - while waiting, the output has to be temporarily stored somewhere
 - need to create an in-memory buffer

pipe (|)

- in-memory buffer that connects two processes together
- instead of associating the fd for the standard output of the lhs program with an underlying device (i.e. terminal), the descriptor is pointed to an in-memory buffer provided by the kernel
- the other side of this same buffer is associated with the standard input of the rhs program, to consume the output of the lhs program

pipe system call

- pipe is for one-way communication only
 - use a pipe such that one process writes to the pipe, and the other process reads from the pipe
- the pipe can be used by either the parent or child process for reading and writing
 - one process can write to the pipe and another related process can read from it

• if a process tried to read before something is written to the pipe, the process is suspended until something is written

```
int pipe(int fds[2]);
```

- fds[0] will be the file descriptor for the read end of pipe.
- fds[1] will be the file descriptor for the write end of pipe.
- returns 0 on success, -1 on error.

- data written to the write end of the pipe is buffered by the kernel until it is read from the read end of the pipe
- call pipe before fork, if call it after then fork will create 2 pipes
 - if you call pipe in the parent process, so only 1 pipe, how the child is going to know what the pipefd∏ is, it cannot set the corresponding fds

io- redirection with dup2

both dup and dup2 can be used to redirecct a prev fd to target fd

```
#include <unistd.h>
int dup2(int target_fd, int prev_fd);
```

- dup() uses lowest-numbered unused file descriptor, uncontrollable.
- dup2() performs the same task as dup(), but it specifically redirects fd.
- if fd was previously open, it is *closed before being reused*; the close is performed silently (i.e., any errors during the close are not reported by dup2()).