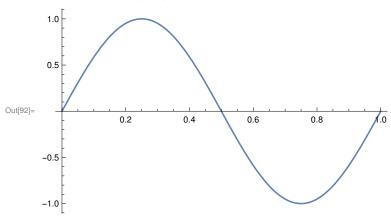
Implements Example 7.1 in Wachsmuth and Wachsmuth (2011), https://doi.org/10.1051/cocv/2010027

$$ln[89]:= a = -30; b = 30; \beta = 1/2;$$

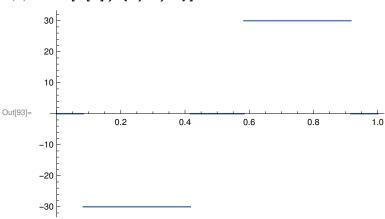
 $In[90]:= z[x_] := Sin[2 Pi x]$

 $ln[91]:= u[x_] := Piecewise[{{a, 1/12 < x < 5/12}, {b, 7/12 < x < 11/12}}, 0]$

 $In[92]:= Plot[z[x], \{x, 0, 1\}]$



In[93]:= Plot[u[x], {x, 0, 1}]



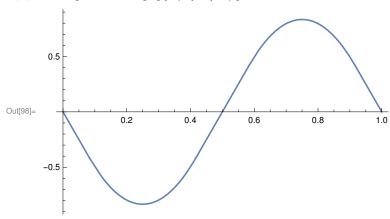
$$ln[94]:=$$
 state = DSolve[{-y''[x] == u[x], y[0] == 0, y[1] == 0}, y[x], x]

$$\text{Out} [94] = \left. \left\{ \left\{ y \left[\, X \, \right] \right. \right. \right. \rightarrow -5 \, X + \left. \left\{ \left\{ \begin{array}{l} 0 \\ \frac{5}{48} - \frac{5 \, X}{2} + 15 \, X^2 \\ -\frac{5}{2} + 10 \, X \\ -\frac{365}{48} + \frac{55 \, X}{2} - 15 \, X^2 \\ \frac{7}{12} < X \leq \frac{7}{12} \\ 5 \end{array} \right. \right\} \right\}$$

 $ln[96]:= statesol[x_] := y[x] /. state[[1]]$

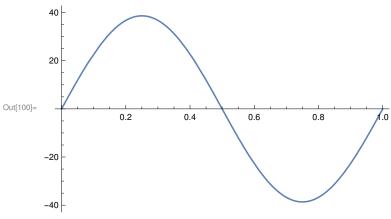
In[97]:= statesol[x]

In[98]:= Plot[statesol[x], {x, 0, 1}]



 $ln[99]:= yd[x_] := statesol[x] + 4 Pi Pi Sin[2 Pi x]$

 $ln[100]:= Plot[yd[x], \{x, 0, 1\}]$



Optimal objective function value