


Lecture 06. Logistic regression

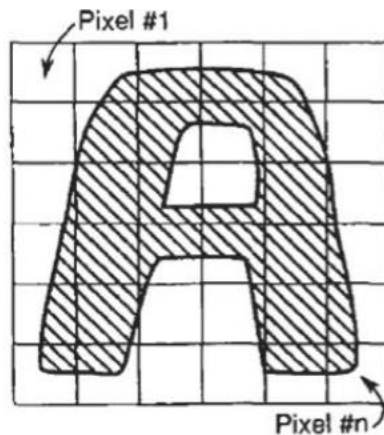
Xin Chen

Outline

- Generative classification and discriminative classification 
- The logistic regression model
- Understanding the objective model
- Gradient descent for parameter learning
- Multiclass logistic regression

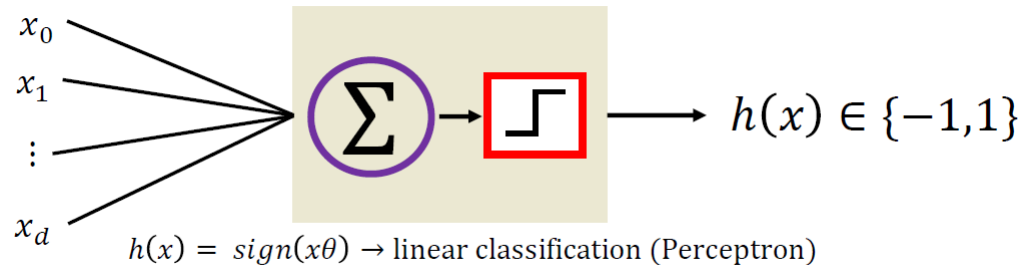
Classification

- Represent the data



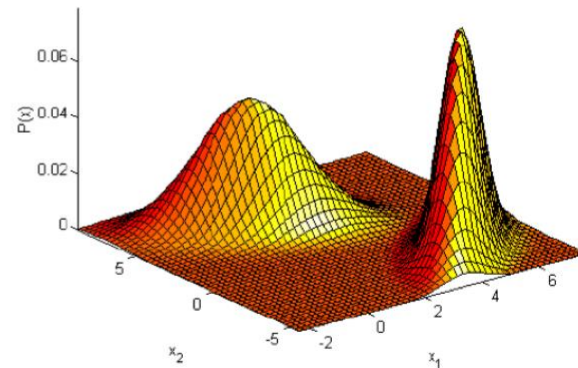
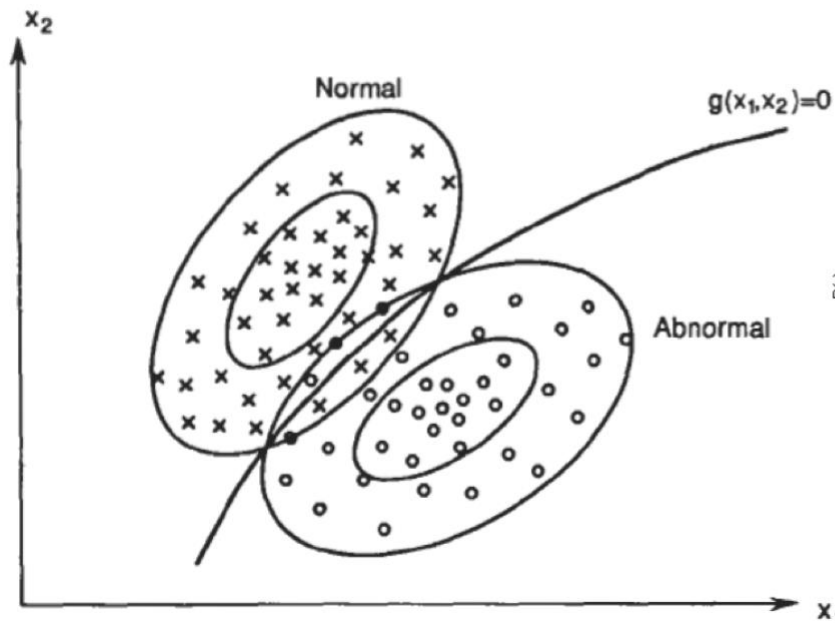
$$X = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$$

- A label is provided for each data point, $y \in \{-1, +1\}$
- Classifier:



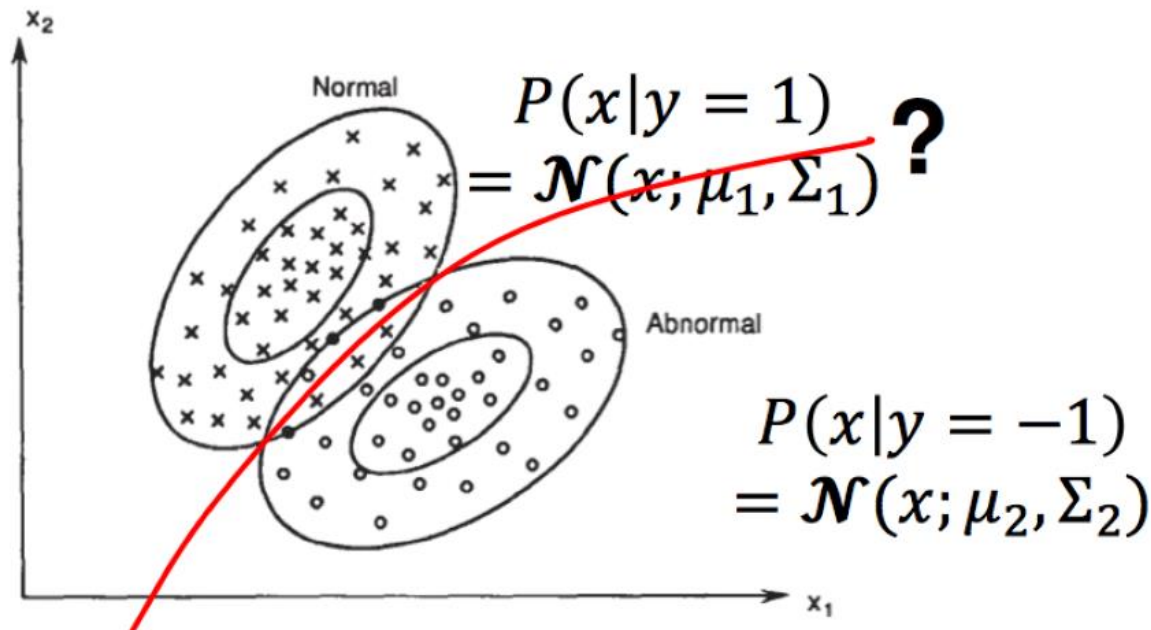
Decision making: dividing the feature space

- Distribution of sample from normal (positive class) and abnormal (negative class) issues.



How to determine the decision boundary?

- Given class conditional distribution: $P(x|y = 1), P(x|y = -1)$ and class prior: $P(y = -1), P(y = 1)$



Bayes Decision Rule

The diagram shows the equation for Bayes' theorem with red arrows pointing to specific parts: 'likelihood' points to $P(x|y)$, 'Prior' points to $P(y)$, 'posterior' points to $P(y|x)$, and 'normalization constant' points to $\sum_z P(x, y)$.

$$P(y|x) = \frac{P(x|y)P(y)}{P(x)} = \frac{P(x, y)}{\sum_z P(x, y)}$$

- Prior: $P(y)$
- Class conditional distribution: $P(x|y) = \mathcal{N}(x|u_y, \Sigma y)$
- Posterior: $P(y|x) = \frac{\mathcal{N}(x|u_y, \Sigma y)}{\sum p(y)\mathcal{N}(x|u_y, \Sigma y)}$

Bayes Decision Rule

- Learning: (1) Prior: $P(y)$ (2) Condition distribution: $P(x|y)$
- The poster probability of a test point $q_i(x) := P(y = i|x) = \frac{P(x|y)P(y)}{P(x)}$
- Bayes decision rule:
 - If $q_i(x) > q_j(x)$, then $y = i$, otherwise $y = j$
- Alternatively
 - If ratio $l(x) = \frac{P(x|y=i)}{P(x|y=j)} > \frac{P(y=j)}{P(y=i)}$, then $y = i$, otherwise $y = j$
 - Or look at the log-likelihood ratio $h(x) = -\ln(x) \frac{q_i(x)}{q_j(x)}$

What do people do in practice

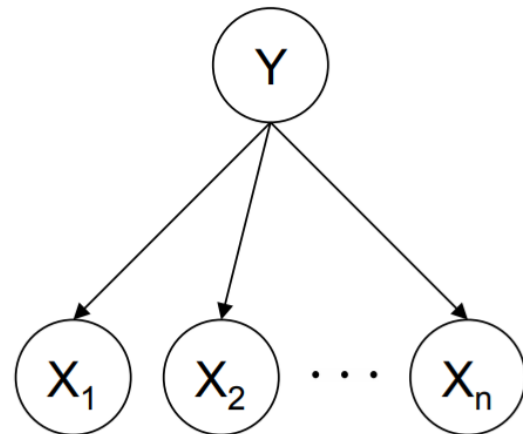
- Generative model
 - Model prior and likelihood explicitly
 - “Generative” means able to generate synthetic data points
 - Examples: Naive Bayes, Hidden Markov models
- Discriminative models
 - Directly estimate the posterior probabilities
 - No need to model underlying prior distributions
 - Examples: Logistic regression, SVM, Neural network

Generative Model: Naive Bayes

- Use Bayes decision rule for classification
- Assume $p(x|y = 1)$ is fully factorized: dimensions are independent.
- Or the variables corresponding to each dimension of the data are independent given the label

$$P(y|x) = \frac{P(x|y)P(y)}{P(x)}$$

$$P(x|y = 1) = \prod_{i=1}^d p(x_i|y = 1)$$



$$P(y|x) = \frac{P(x|y)P(y)}{P(x)}$$


Join probability model

$$\begin{aligned}
 P(x, y_{label=1}) &= P(x_1, \dots, x_d, y_{label=1}) = P(x_1 | x_2, \dots, x_d, y_{label=1}) P(x_2, \dots, x_d, y_{label=1}) \\
 &= P(x_1 | x_2, \dots, x_d, y_{label=1}) P(x_2 | x_3, \dots, x_d, y_{label=1}) P(x_3, \dots, x_d, y_{label=1}) \\
 &= \dots \\
 &= P(x_1 | x_2, \dots, x_d, y_{label=1}) P(x_2 | x_3, \dots, x_d, y_{label=1}) \dots P(x_{d-1} | x_d, y_{label=1}) P(x_d | y_{label=1}) P(y_{label=1})
 \end{aligned}$$

Discriminative models

- Directly estimate decision boundary: the posterior distribution $p(y|x)$ or $h(x) = -\ln(x) \frac{q_i(x)}{q_j(x)}$
 - Logistic regression, Neural networks
 - Do not estimate $p(x|y)$ and $p(y)$
- Why discriminative classifier?
 - Avoid difficult density estimation problem
 - Empirically achieve better classification results

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Gaussian Naive Bayes

$$\begin{aligned} P(y = 1|x) &= \frac{P(x|y=1)P(y=1)}{P(x)} = \frac{P(y=1)P(x|y=1)}{P(y=1)P(x|y=1) + P(y=-1)P(x|y=-1)} \\ &= \frac{1}{1 + \frac{P(y=-1)P(x|y=-1)}{P(y=1)P(x|y=1)}} \end{aligned}$$

$$P(x_i|y) \sim \mathcal{N}(u_{ki}, \sigma_i)$$

Class independent variance

$$P(x|y) = \prod_{i=1}^d p(x_i|y) = \prod_{i=1}^d \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2\sigma_i^2}(x_i - u_i)^2\right)$$

$$\text{Prior: } P(y = 1) = \pi_1$$

$$S = \frac{P(y=0)P(x|y=0)}{P(y=1)P(x|y=1)} = \frac{(1-\pi_1) \prod_{i=1}^d \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2\sigma_i^2}(x_i - u_{0i})^2\right)}{\pi_1 \prod_{i=1}^d \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2\sigma_i^2}(x_i - u_{1i})^2\right)}$$

$$\begin{aligned} \ln(S) &= \ln \frac{1-\pi_1}{\pi_1} + \sum_{i=1}^d \ln \left[\frac{1}{\sqrt{2\pi}\sigma_i} \exp \left(-\frac{1}{2\sigma_i^2} (x_i - u_{0i})^2 \right) \right] - \\ &\quad \sum_{i=1}^d \ln \left[\frac{1}{\sqrt{2\pi}\sigma_i} \exp \left(-\frac{1}{2\sigma_i^2} (x_i - u_{1i})^2 \right) \right] \\ &= \sum_{i=1}^d \left(\frac{u_{0i} - u_{1i}}{\sigma_i^2} x_i + \frac{u_{1i}^2 - u_{0i}^2}{2\sigma_i^2} \right) + \ln \frac{1-\pi_1}{\pi_1} \end{aligned}$$

$$P(y = 1|x) = \frac{1}{1 + \exp[\ln(s)]}$$

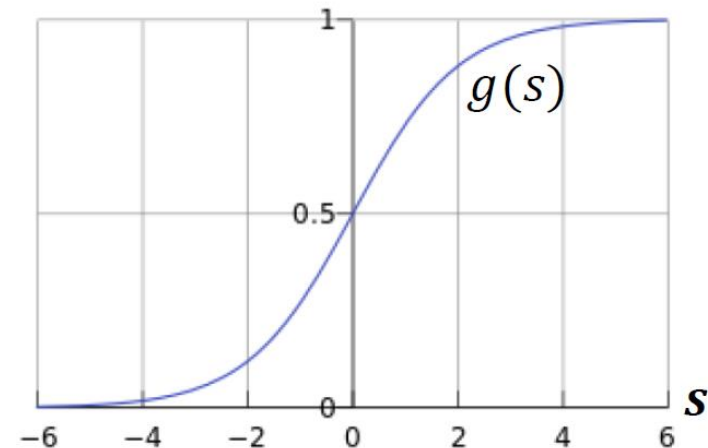
$$P(y = 1|x) = \frac{1}{1 + \exp[\sum_{i=1}^d (\frac{u_{0i} - u_{1i}}{\sigma_i^2} x_i + \frac{u_{1i}^2 - u_{0i}^2}{2\sigma_i^2}) + \ln \frac{1 - \pi_1}{\pi_1}]}$$

Let: $w_i = \frac{u_{0i} - u_{1i}}{\sigma_i^2}$, $w_0 = \ln \frac{1 - \pi_1}{\pi_1} + \sum_{i=1}^n \frac{u_{1i}^2 - u_{0i}^2}{2\sigma_i^2}$

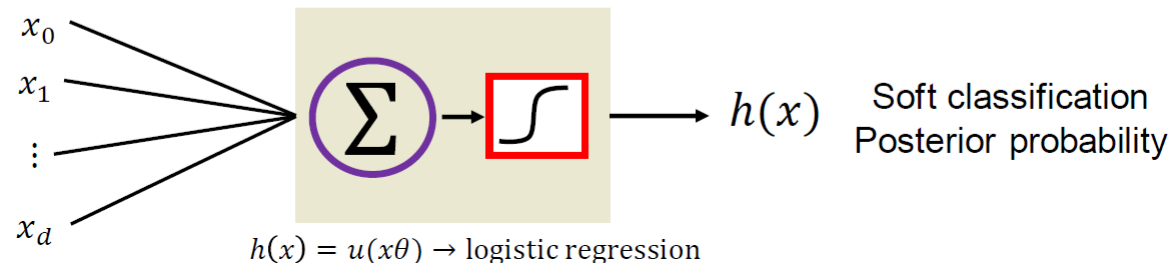
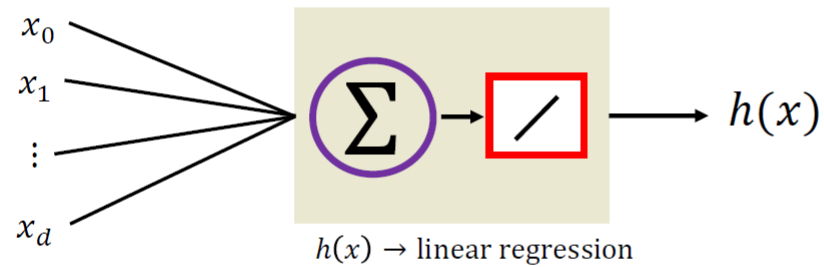
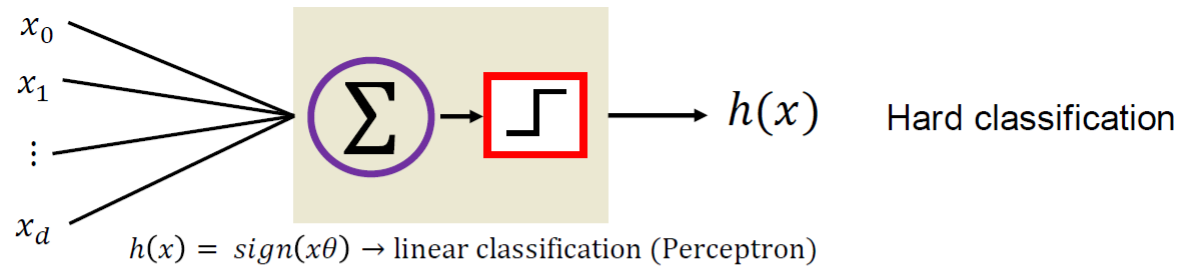
$$P(y = 1|x) = \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i x_i)}$$

Logistic function for posterior probability

- Let's use the following function:
$$g(s) = \frac{e^s}{1+e^s} = \frac{1}{1+e^{-s}} \text{ where } s = x\theta$$
- This is also called sigmoid function
- It's easier to use this function for optimization
- Logistic regression assumption: the form of $P(y = 0|x, \theta) = \frac{1}{1+\exp(-\sum \theta x_i)}$



$$s = x\theta = \sum_{i=0}^d x_i \theta_i$$



An example

- An example of predicting heart attacks
- Inputs: cholesterol level, age, weight, foot size, etc.
 - $g(s)$ is the probability of heart attack within a certain time
 - $s = x\theta$, is called risk score.

$$h_{\theta}(x) = p(y|x) = \begin{cases} g(s), & y = 1 \\ 1 - g(s), & y = 0 \end{cases}$$

Using posterior probability directly


$$h_{\theta}(x) = p(y|x) = \begin{cases} \frac{1}{1 + \exp(-x\theta)}, & y = 1 \\ \frac{\exp(-x\theta)}{1 + \exp(-x\theta)}, & y = 0 \end{cases}$$

We need to find parameters θ , let's set up log-likelihood for n data points:

$$l(\theta) = \log \prod_{i=1}^n p(y_i|x_i, \theta)$$

$$l(\theta) = \sum_{i=1}^n [\theta^T x_i^T (y_i - 1) - \log(1 + \exp(-x_i \theta))]$$

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Calculate gradient of $l(\theta)$

$$l(\theta) = \sum_{i=1}^n [\theta^T x_i^T (y_i - 1) - \log(1 + \exp(-x_i \theta))]$$

- Maximum conditional likelihood on data by calculate its gradient

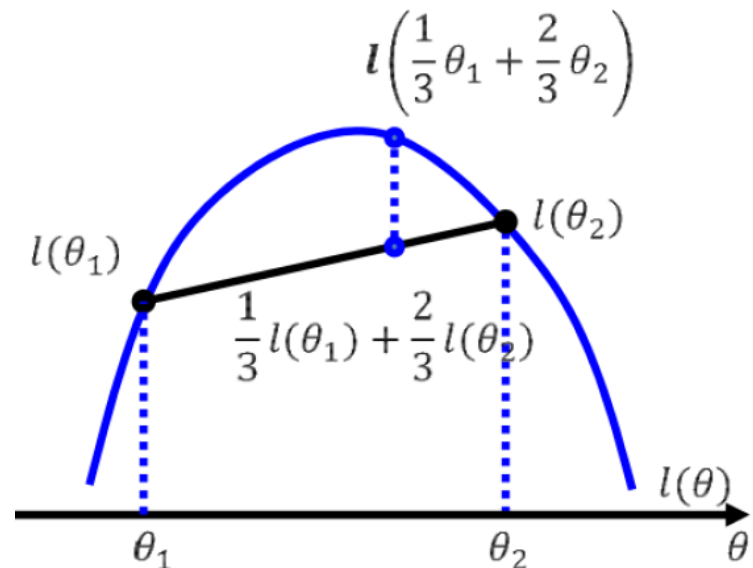
$$\frac{\partial l(\theta)}{\partial \theta} = \sum_i x_i^T (y_i - 1) + x_i^T \frac{\exp(-x_i \theta)}{1 + \exp(-x_i \theta)}$$

Logistic regression only models $P(y|x)$, so we only maximize $P(y|x)$, ignoring $P(x)$

The objective function


- Find θ such that the conditional likelihood of the labels is maximized.

$$\max l(\theta) = \log \prod_{i=1}^n p(y_i | x_i, \theta)$$



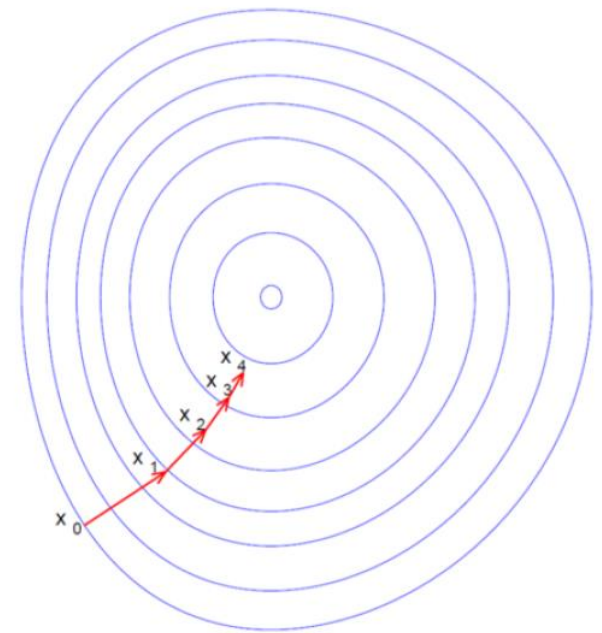
- Good news: $l(\theta)$ is concave function of θ , and there is a single global optimum.
- Bad news: no closed form solution (resort to numerical method)

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Gradient descent

- One way to solve an unconstrained optimization problem is gradient descent.
- Given an initial guess, we iteratively refine the guess by taking the direction of the negative gradient.
- Think about going down a hill by taking the steepest direction at each step.
- Update rule:
 - $x_{k+1} = x_k - \gamma_k \nabla f(x_k)$
 - γ_k is called the step size or learning rate.




Gradient descent algorithm

- Initialize parameter θ_0
- Do

$$\theta^{t+1} \leftarrow \theta^t + \eta \sum_i x_i^T (y_i - 1) + x_i^T \frac{\exp(-x_i \theta)}{1 + \exp(-x_i \theta)}$$

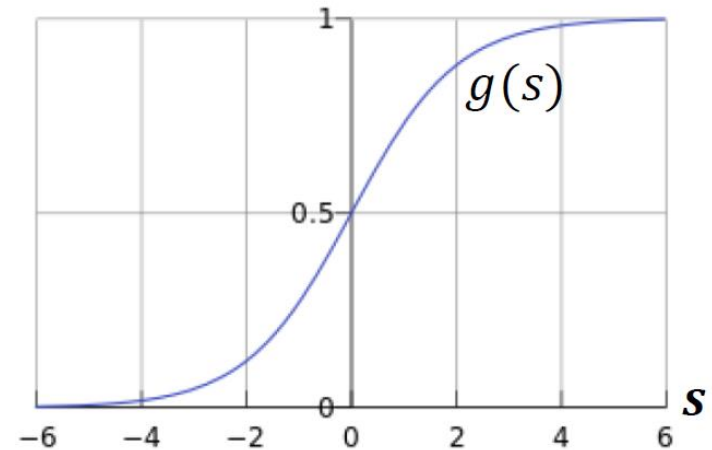
- While the $||\theta^{t+1} - \theta^t|| > \epsilon$

Outline

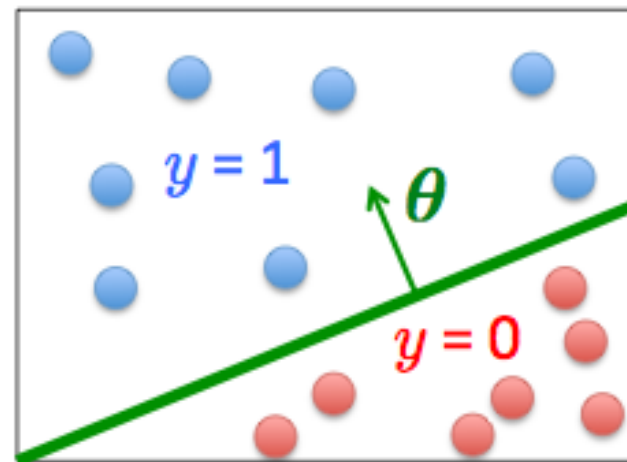
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Logistic regression

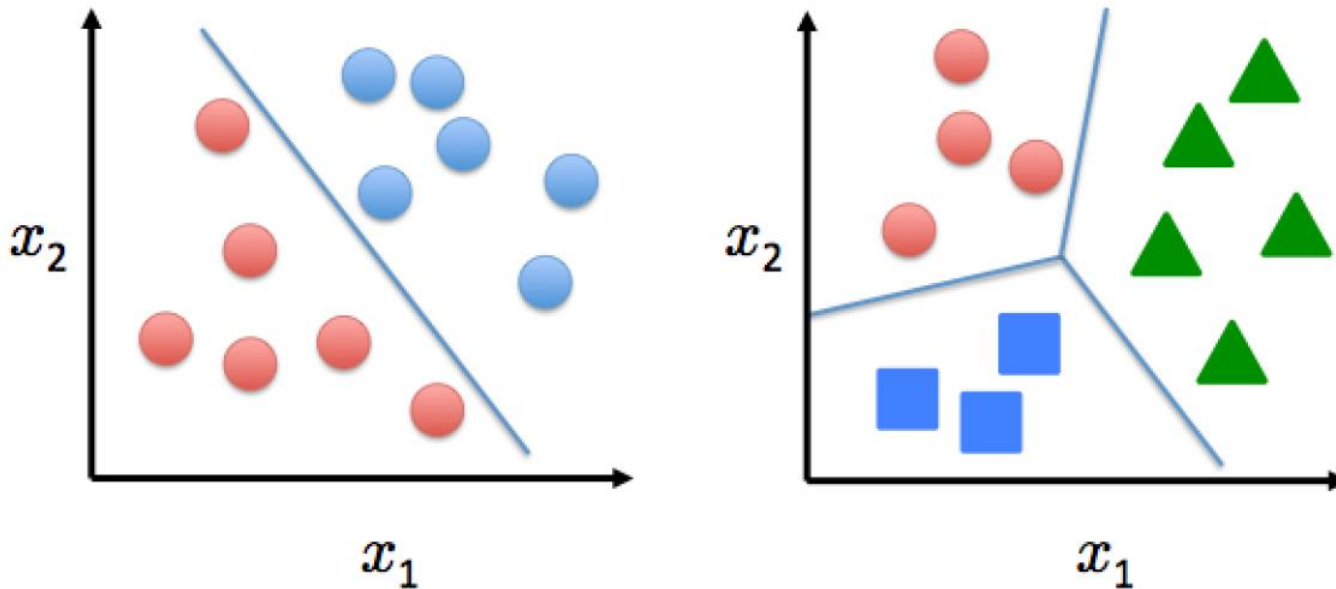
$$g(s) = \frac{e^s}{1+e^s} = \frac{1}{1+e^{-s}} \text{ where } s = x\theta$$



- Assume a threshold
 - Predict $y = 1$ if $g(s) > 0.5$
 - Predict $y = 0$ if $g(s) \leq 0.5$



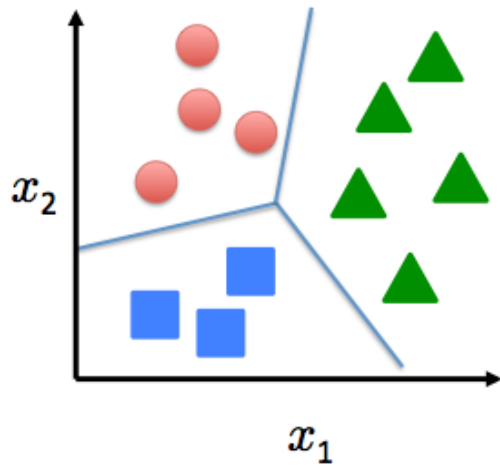
Multiclass Logistic regression



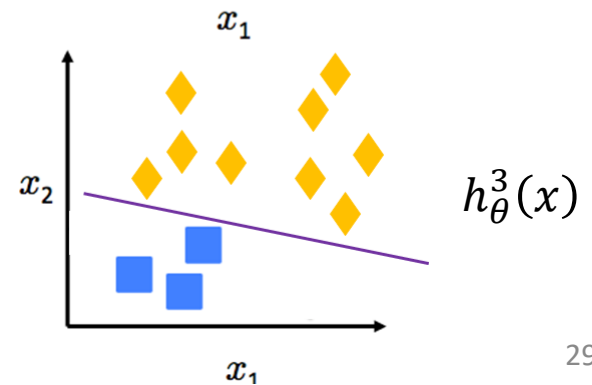
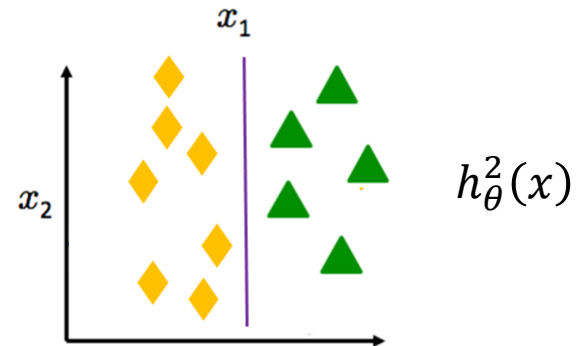
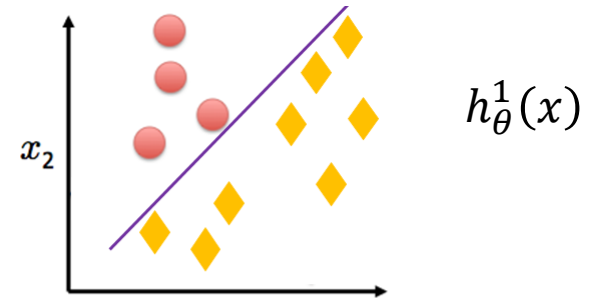
- Disease diagnosis: healthy / cold / flu / pneumonia
- Object classification: desk / chair / monitor / bookcase

One-vs-All (One-vs-Rest)

Multi-class classification:



$$h_{\theta}^{(i)}(x) = p(y = 1|x, \theta) \quad (i = 1, 2, 3)$$



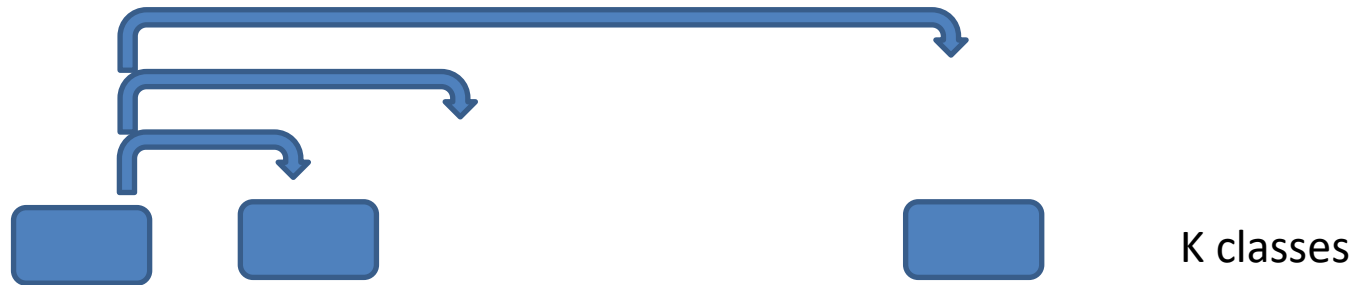
One-vs-All (One-vs-Rest)

Train a logistic regression $h_{\theta}^{(i)}(x)$ for each class i

To predict the label of a new input x , pick class i that maximizes:

$$\max_i h_{\theta}^{(i)}(x)$$

One-vs.-One



In total it has $\frac{K*(K-1)}{2}$ combinations

Train logistic regression $h_{\theta}^{(i)}(x)$, $\frac{K*(K-1)}{2}$ binary classifiers

To predict the label of a new input x , pick class i that maximizes: $\max_i h_{\theta}^{(i)}(x)$

Vote with a combined classifier

Generative and discriminative classifier

- Generative classifiers
 - Modeling the joint distribution $P(x, y)$
 - Usually via $P(x, y) = P(y)P(x|y)$
 - Example: Gaussian naive Bayes
- Discriminative classifiers
 - Modeling $P(y|x)$ or simply $f: x \rightarrow y$
 - Do not care about $P(x)$
 - Examples: logistic regression, support vector machine

Gaussian Naive Bayes vs Logistic regression

- How can we compare Gaussian naive Bayes with a logistic regression?
 - $P(x, y) = P(y)P(x|y)$ vs. $P(y|x)$

$$P(y = 1|x) = \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i x_i)}$$

$$\text{where: } w_i = \frac{u_{0i} - u_{1i}}{\sigma_i^2}, \quad w_0 = \ln \frac{1 - \pi_1}{\pi_1} + \sum_{i=1}^n \frac{u_{1i}^2 - u_{0i}^2}{2\sigma_i^2}$$

$$P(x_i|y) \sim \mathcal{N}(u_{ki}, \sigma_i)$$

Class independent variance

Gaussian Naive Bayes vs Logistic regression

- $P(y|x)$ of GNB is a subset of $P(y|x)$ of LR, with the assumption that GNB has independent variance.
- Given infinite training data:
 - We claim: LR \geq GNB
- For a general Gaussian Naive Bayes, none of them can encompass the other

Take-Home Messages

- Generative and Discriminative Classification
- The Logistic Regression Model
- Understanding the Objective Function
- Gradient Descent for Parameter Learning
- Multiclass Logistic Regression