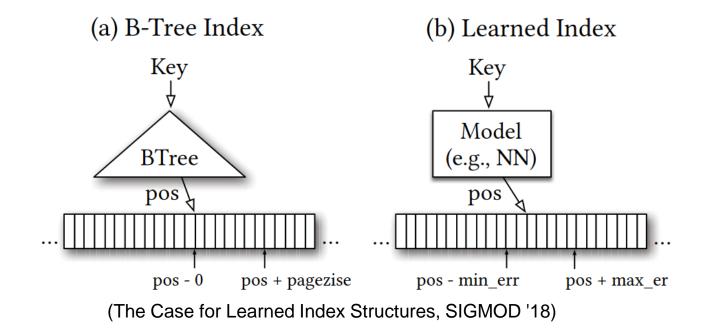
Can Learned Indexes be Built Efficiently? A Deep Dive into Sampling Trade-offs

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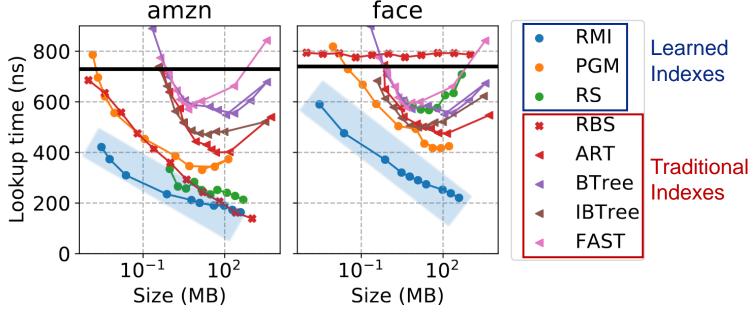




- Learned Index
 - Index structure employs machine learning techniques
 - View the index as a model that predicts the position of a key in a sorted array



- Learned Index
 - Space-efficient by effectively compressing data distribution through the model
 - Pareto optimal in terms of index size and lookup latency in read-only workloads
 - No alternative exists that has both a smaller size and lower latency



(Benchmarking Learned Indexes, VLDB '20)



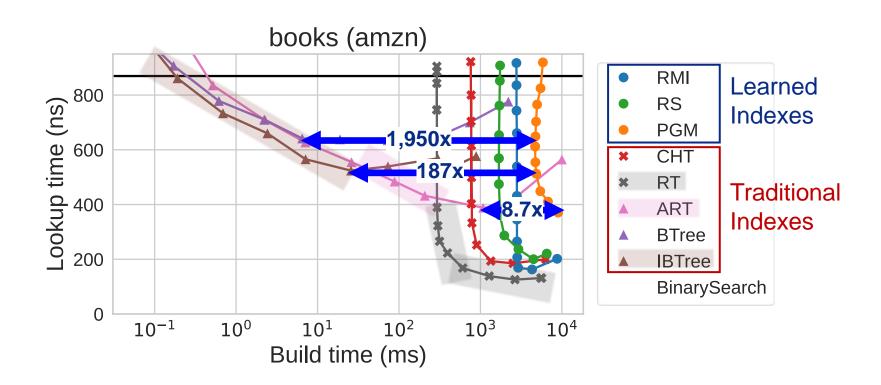
Limitation of Learned Index: Long Index Build Time



• Significantly (up to about 2,000x) slower than traditional indexes



- Not Pareto optimal (build-efficient) for build time and lookup latency
- Still, there are application (e.g., LSM-Tree) where the index build time is crucial







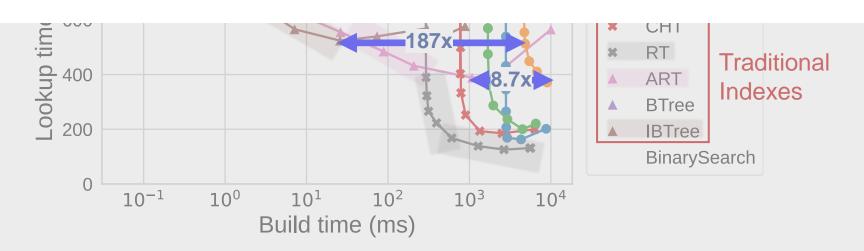


• Significantly (up to about 2,000x) slower than traditional indexes



Long build time has been identified as a high priority for future work in various papers:

RMI (SIGMOD `18), RadixSpline (aiDM `20), PGM-Index (VLDB `20), SOSD (VLDB `20), Critical-RMI (VLDB `22)



Primary Reason for Long Build Time

 $Index\ build\ time = Per - element\ overhead \times Number\ of\ elements$

- 1) Higher per-element training overhead
- 2) Complete traversal and training

- To Mitigate Per-element Overhead
 - Light-weight model: RadixSpline (aiDM `20), Bourbon (OSDI `20)
 - > It still shows longer build time than traditional indexes





Since the learned index uses the model,

Can't it learn efficiently even with less data?

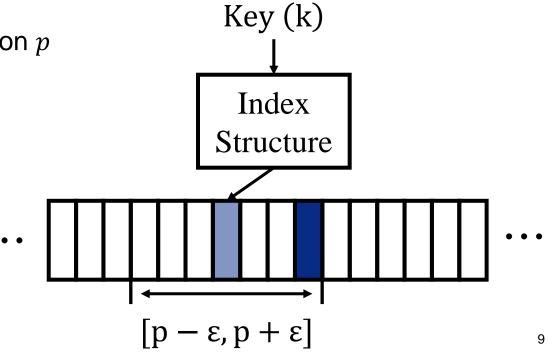
- Our Approach: Sampling
 - While sampling may seem simple and even naïve, it is indeed complex

Challenges

- 1. Absence of benchmark for sampling applied indexes
- 2. Losing the error-bound property due to sampling loss
- 3. Complex trade-offs in terms of model, index, and micro-architecture

2. Background

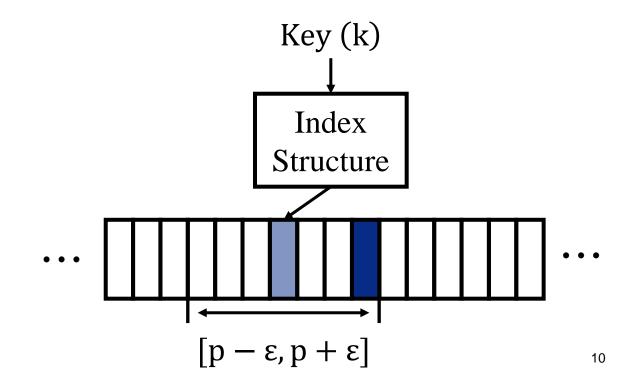
- Workload: Read-only In-memory
 - Practical beginning point of learned index
 - Dataset (D): Sorted array of unique integer keys without duplicates
 - Lookup: Find the position of a lookup key k in D
 - ① Prediction: Estimate the position of k as p
 - ② Correction: Find the exact position of k based on p



2. Background

- Workload: Read-only In-memory
 - Error-bound property
 - $\forall k \in D$, $Error(k) = |Pred(k) Pos(k)| \le \varepsilon (= error bound)$
 - k exists in correction range (= $[p \varepsilon, p + \varepsilon]$) \rightarrow binary search

- Important for robustness,
 - Especially where correction is expensive
 - E.g., Disk or remote I/O environments

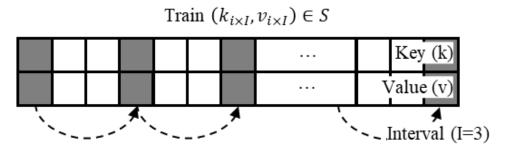


1. Unified Sampling Algorithm & Implementation



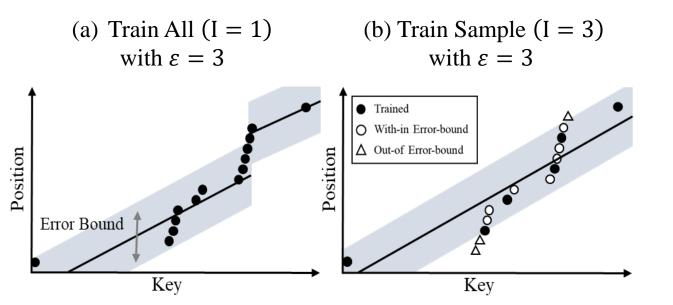
BASIL (Benchmark of Sampling Applied Learned Indexes)

- 1) Unified sampling algorithm
 - Systematic sampling: extract every I^{th} (I = sampling interval) key from the first key to the last key
 - Pros: Simple, universal, no decision/reordering cost
 - Cons: Not optimal (other methods, e.g., adaptive, should be explored)
- 2) Unified sampling implementation
 - All indexes access and train only sample key-value data from the entire dataset

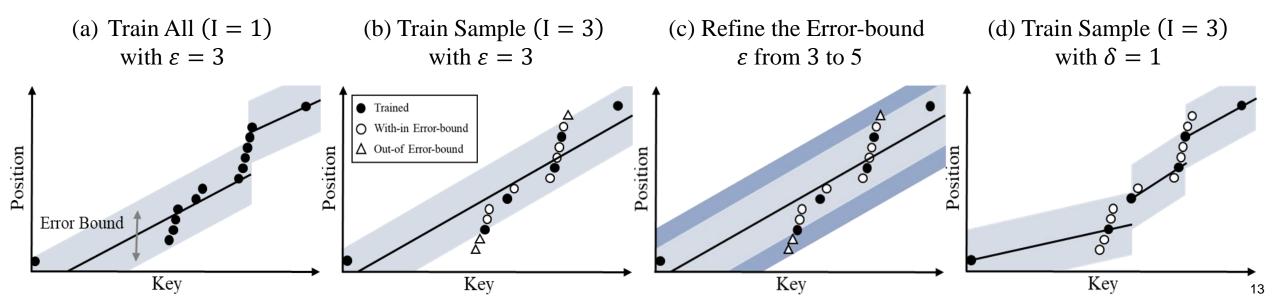


BASIL. Access I-th sample key-value in original dataset

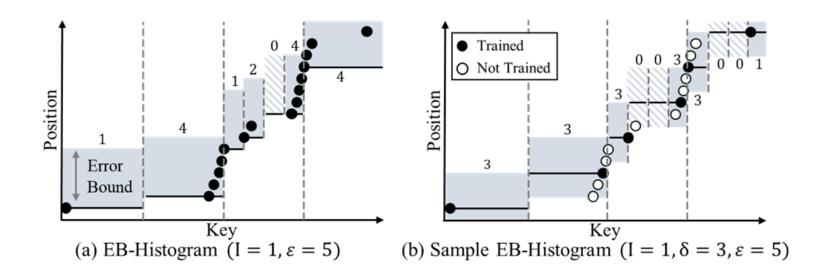
- EB-PLA (Error-bounded Piece-wise Linear Approximation)
 - Train all keys with error-bound $\varepsilon \to Error(k) \le \varepsilon$
 - Train the sample I^{th} keys with error-bound $\varepsilon \nrightarrow Error(k) \le \varepsilon$
 - Loss of the error-bound property, which is learning objective of the model



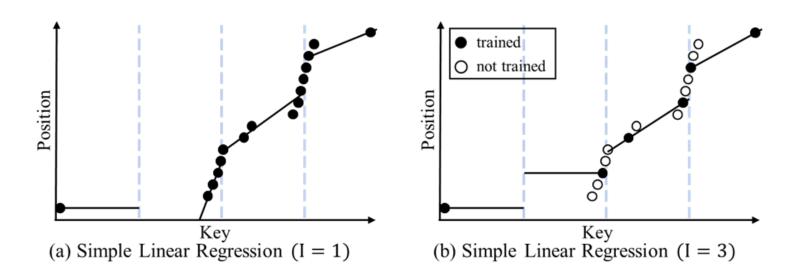
- Sample EB-PLA
 - Refine the error-bound due to sampling loss to $\varepsilon' (= \varepsilon + I 1) \rightarrow Error(k) \le \varepsilon'$
 - \triangleright Preserve the error-bound property, but cannot guarantee the desired error-bound (ε)
 - Replace the learning error-bound to $\delta (= \varepsilon I + 1) \rightarrow Error(k) \le \varepsilon$
 - \triangleright Preserve the error-bound (ε) by learning less data with a smaller and stricter error bound



- Sample EB-Histogram
 - Train all keys with the error-bound $\varepsilon \to k \in [p, p + \varepsilon]$
 - Train the sample I^{th} keys with smaller error-bound $\delta (=\varepsilon I + 1) \rightarrow k \in [p I + 1, p + \delta]$
 - \triangleright Preserve correction length $(\varepsilon + 1 = \delta + I)$

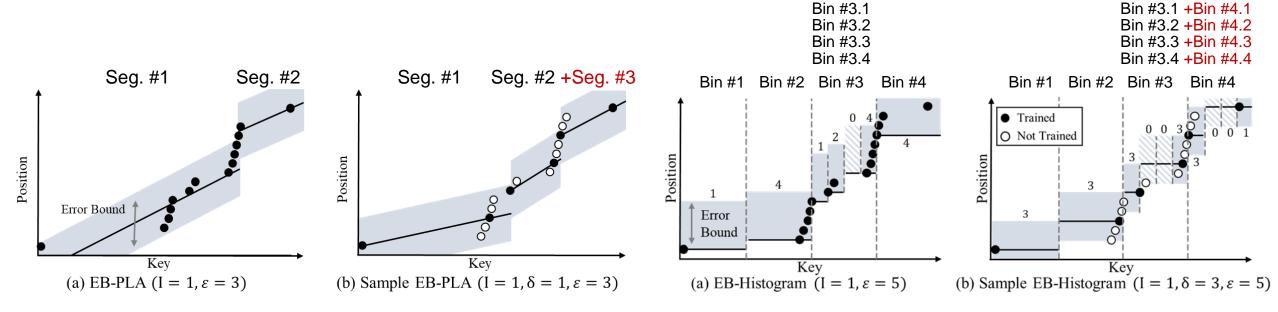


- Simple Linear Regression
 - The model itself cannot guarantee the error-bound regardless of sampling
 - > To guarantee error bounds, measuring the error of all data causes complete traversal
 - Train sample I^{th} keys \rightarrow Accuracy can decrease but the error-bound property doesn't change



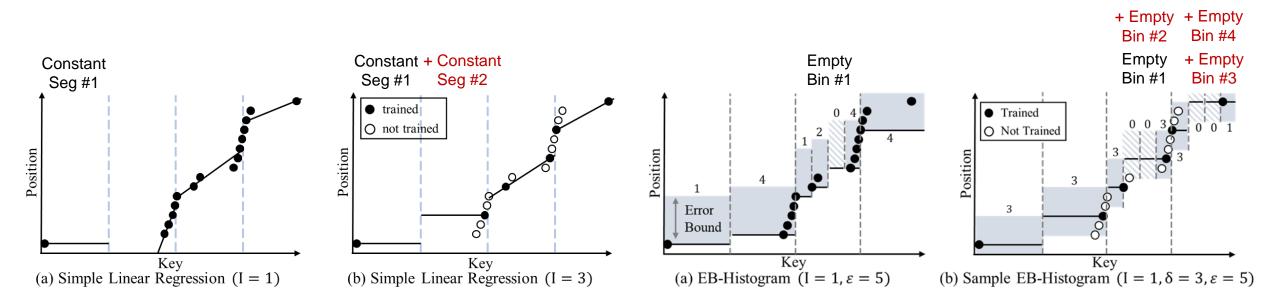
3. Internal Changes due to Sampling

- Depend on segmentation manner
 - 1) Dynamic segmentation (EB-PLA, EB-Histogram)
 - > Definition: Dynamically segment key ranges according to the distribution
 - > Trade-off: Decrease build time but aggressive sampling can increase # of segments (bins)



3. Internal Changes due to Sampling

- Depend on segmentation manner
 - 2) Fixed segmentation (Simple Linear Regression, EB-Histogram)
 - > Definition: Segment key ranges into a fixed number of segments
 - > Trade-off: Decrease build time but aggressive sampling can increase # of underfitting segments



4. Evaluation Setup



BASIL (Benchmark of Sampling Applied Learned Indexes)

- Applied sampling to 7 indexes, prefixed with "s"
 - 3 Learned, 2 Histogram, 3 Tree-based indexes

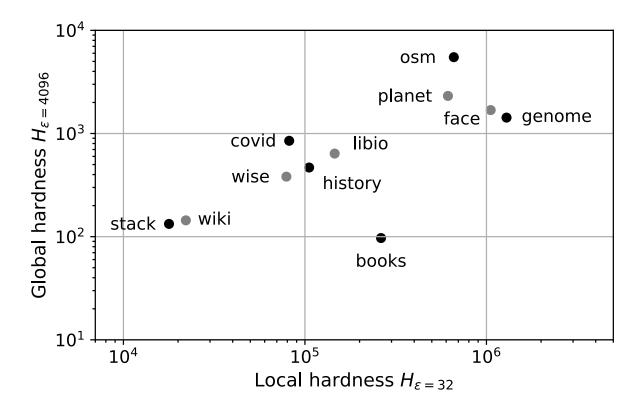
Туре	Index	Internal Model	Correction Search
Learned	sRMI	Simple Linear Regression	Exponential Search
Learned	sPGM / sRS	Sample EB-PLA	Binary Search
Histogram	sCHT	Sample EB-Histogram (Equal-width)	
Histogram	sRT	Sample Histogram (Equal-width)	
Tree-based	sART / sB+-Tree/ sIB-Tree	-	

4. Evaluation Setup



BASIL (Benchmark of Sampling Applied Learned Indexes)

- Datasets: 6 representative datasets with 200 million key-value pairs
- Workload: Lookup uniform random 10 million keys from the dataset.
- Environment: Intel(R) Xeon(R) Gold 6338 CPU 2.00 GHz, 48 MB L3 cache with 512 GB of main memory

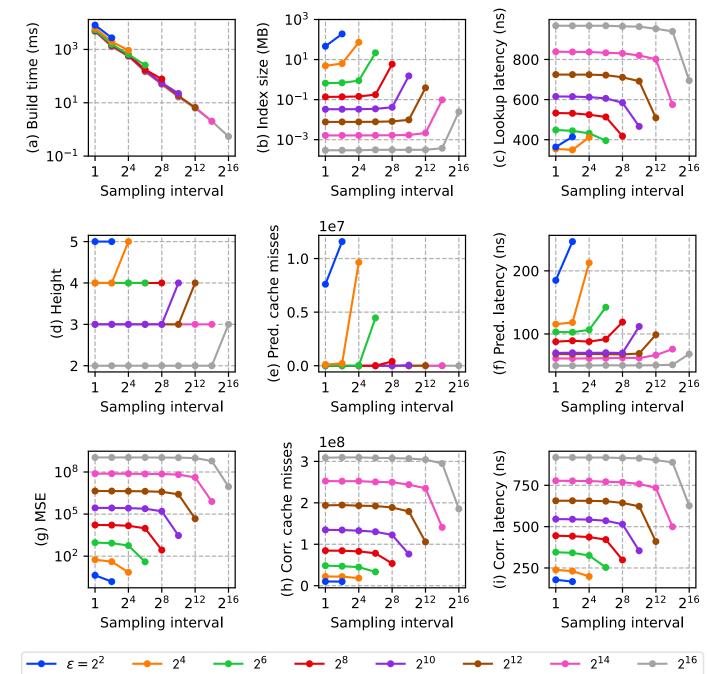


Dataset: History, Error bound ($\varepsilon \in [2^2, 2^{16}]$), Sampling interval ($I \in [2^0, \varepsilon (\leq 2^{16})]$)

5. Evaluation

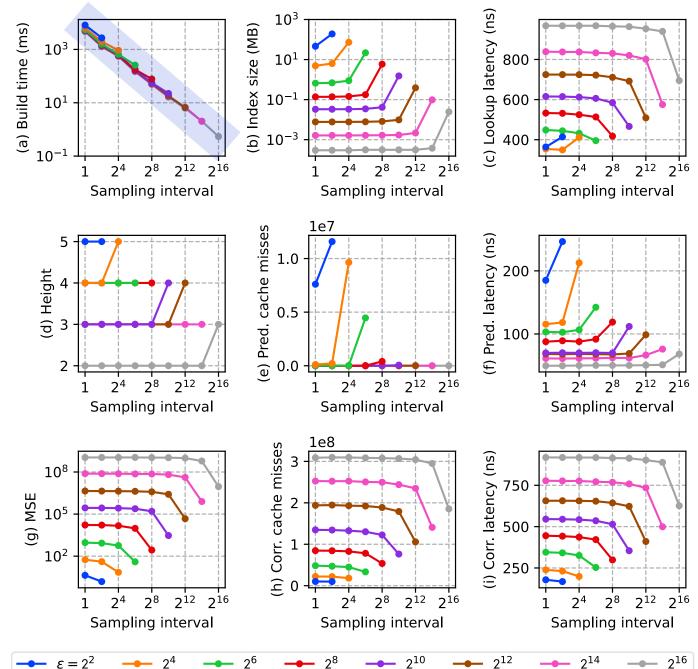
1. Sampling Trade-offs

- Index
 - sPGM
- Metrics
 - Index: (a) Build Time, (b) Size,
 (c) Latency, (f) Pred. latency,
 (i) Corr. latency
 - Model: (d) Height, (g) MSE (Accuracy)
 - Micro-architecture: (e) Pred.
 Cache Miss, (f) Corr. Cache
 Miss



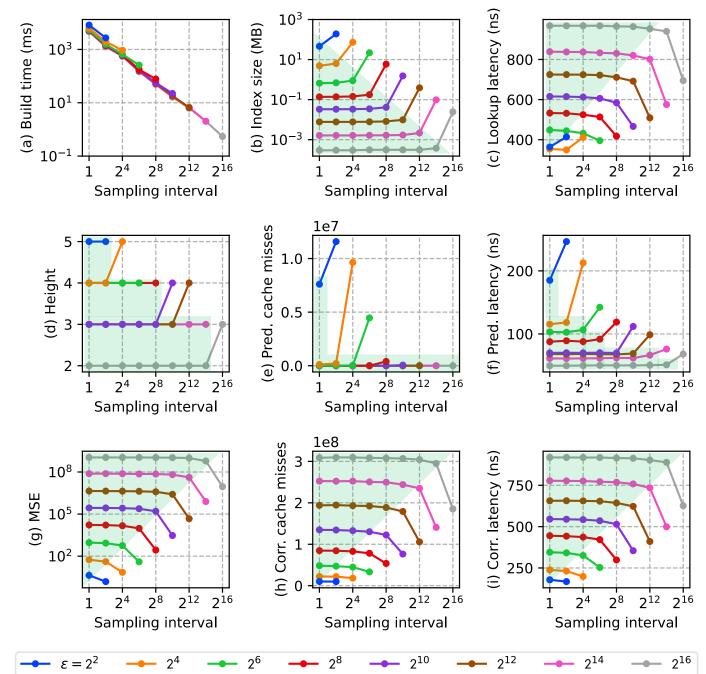
Dataset: History, Error bound ($\varepsilon \in [2^2, 2^{16}]$), Sampling interval ($I \in [2^0, \varepsilon (\leq 2^{16})]$)

- 1. Sampling Trade-offs
- When sampling interval (I) increases, (a) build time decreases by order of magnitude



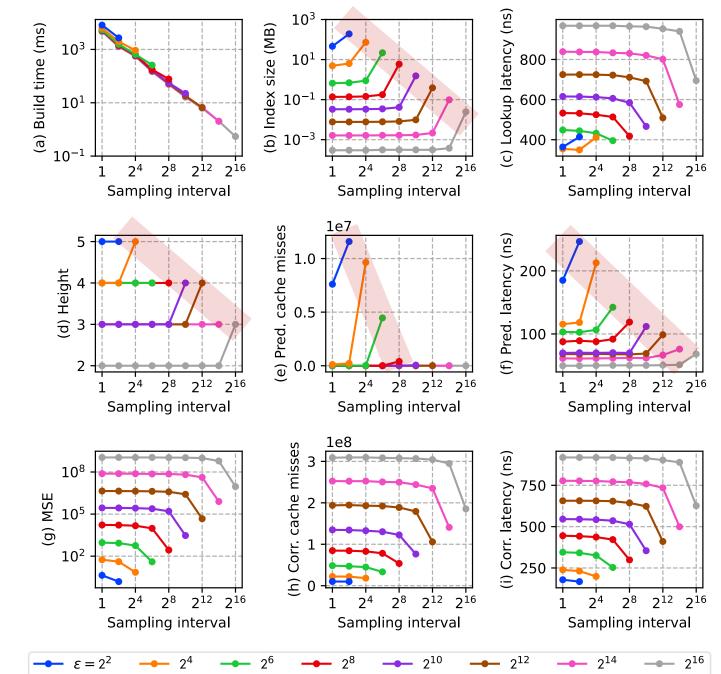
- 1. Sampling Trade-offs
- Each error-bound has
 a threshold interval (I_{TH})
 - mostly $\varepsilon = I^{TH}$

Until I_{TH},
 (b-i) the rest of metrics
 remain consistent



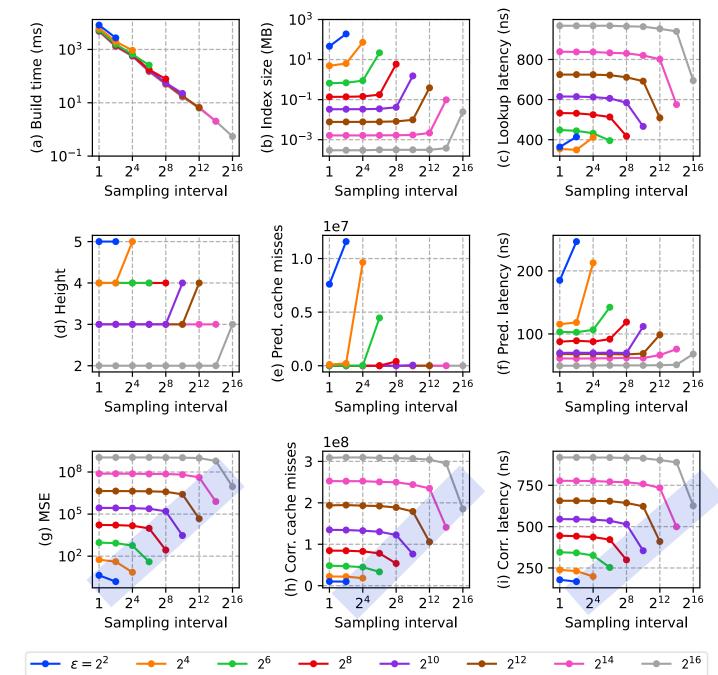
- 1. Sampling Trade-offs
- After I_{TH},
 - # of linear segments 1
 - \rightarrow (b) Size \uparrow
 - (d) Height 1
 - \rightarrow (e) Pred. cache miss \uparrow ,
 - (f) Pred. latency 1

Dataset: History, Error bound ($\varepsilon \in [2^2, 2^{16}]$), Sampling interval ($I \in [2^0, \varepsilon (\leq 2^{16})]$)



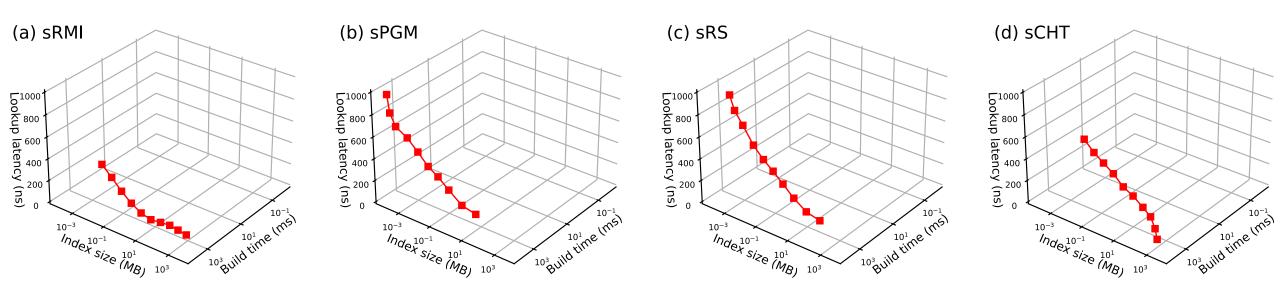
- 1. Sampling Trade-offs
- After I_{TH} ,
 - # of linear segments 1
 - \rightarrow (g) MSE \downarrow
 - → (h) Corr. cache miss ↓
 - (i) Corr. latency ↓

Dataset: History, Error bound ($\varepsilon \in [2^2, 2^{16}]$), Sampling interval ($I \in [2^0, \varepsilon (\leq 2^{16})]$)

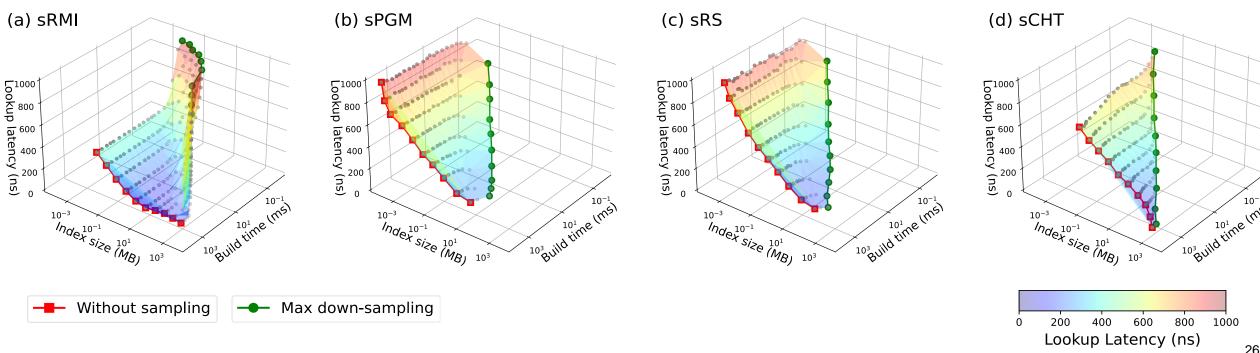


Without sampling

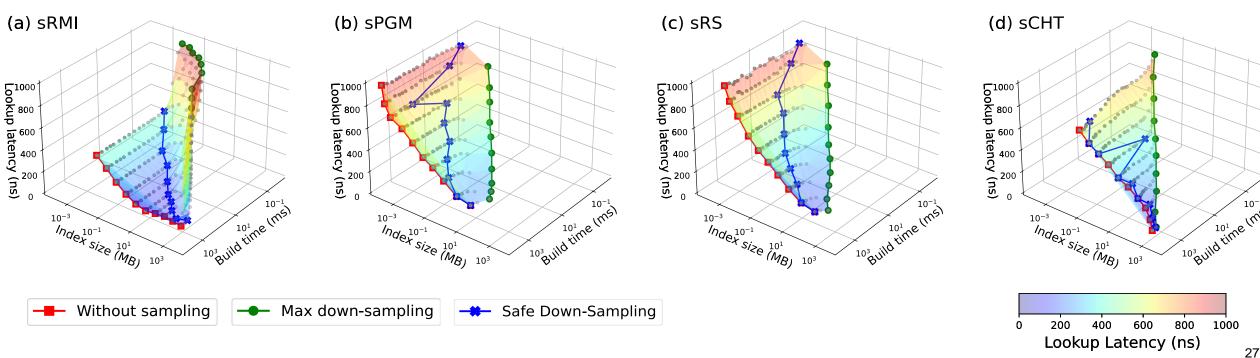
- 2. Design Space of Learned Indexes
 - Absence of trade-offs between build time, index size, and lookup latency
 - Incurs significant build times regardless of size and lookup



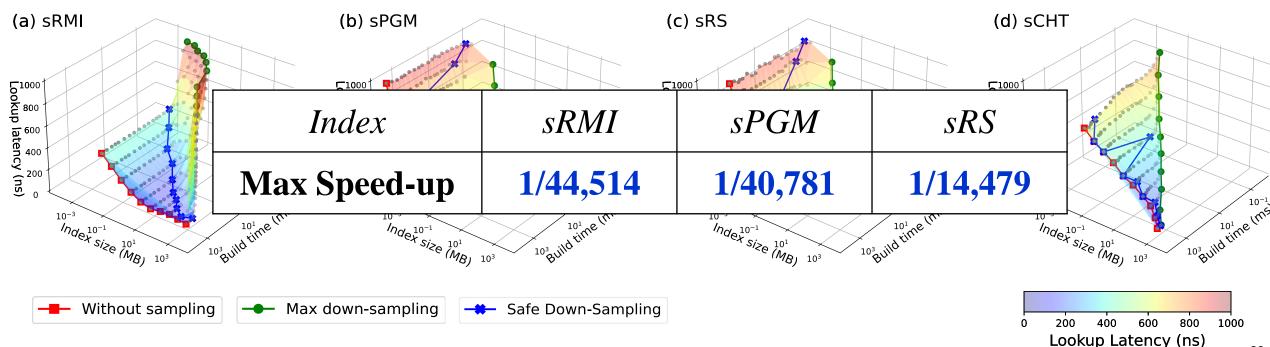
- 2. Design Space of Learned Indexes
 - Sampling introduces trade-offs between build-time, size, and lookup latency
 - Broadens design space of learned indexes from 2D to 3D



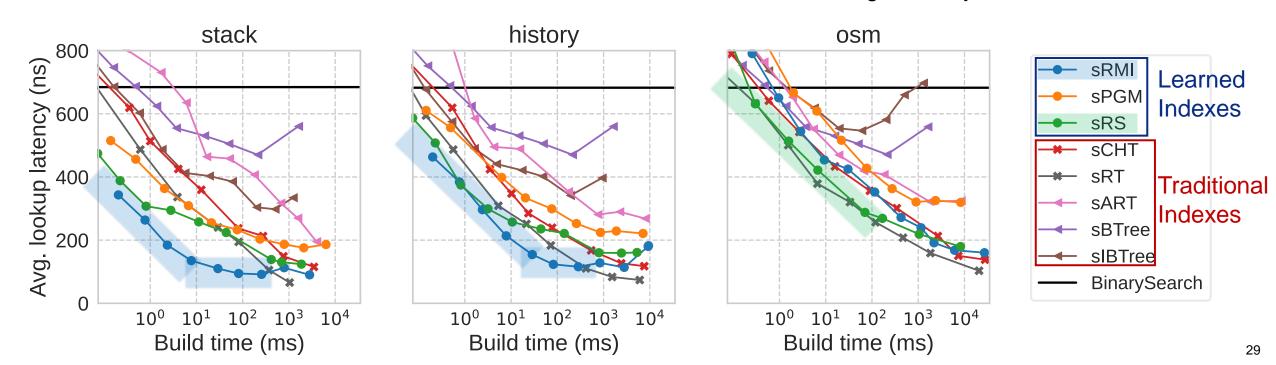
- 3. Build Speed-up
 - Question: How much can sampling reduce build time without significantly degrading index performance?
 - > Safe down-sampling where size and lookup latency increase by less than 5%



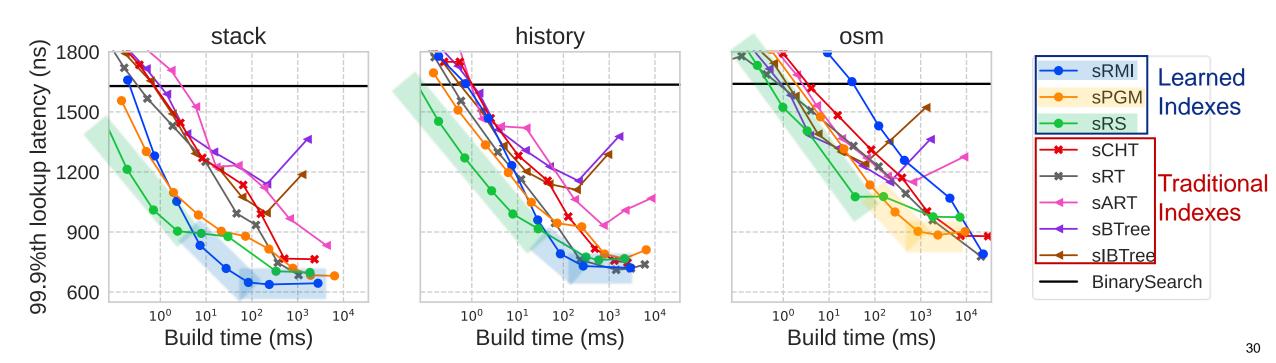
- 3. Build Speed-up
 - Question: How much can sampling reduce build time without significantly degrading index performance?
 - > Safe down-sampling where size and lookup latency increase by less than 5%



- 4. Pareto Optimal Analysis
 - Question: Can learned indexes be built more efficiently in terms of build time and lookup latency than traditional indexes through sampling?
 - Pareto optimal (build-efficient) in terms of build time and average lookup latency
 - > no alternative that has both shorter build time and lower average latency



- 4. Pareto Optimal Analysis
 - Question: Can learned indexes be built more efficiently in terms of build time and lookup latency than traditional indexes through sampling?
 - Pareto optimal (build-efficient) in terms of build time and tail lookup latency
 - no alternative that has both shorter build time and lower tail latency



6. Conclusion

- 1. Learned indexes are space-efficient, but long build time make them impractical.
- 2. Sampling has 3 challenges: 1) losing the error-bound property, 2) absence of benchmark, and 3) complex sampling trade-offs.
- 3. We propose 1) novel sample learning algorithms that preserve the error-bound, 2) new benchmark, BASIL, and 3) an analysis of sampling trade-offs.
- 4. We show that sampling can 1) expand the design space, 2) reduce build time without significant performance loss, and 3) build learned indexes efficiently.

Thank you