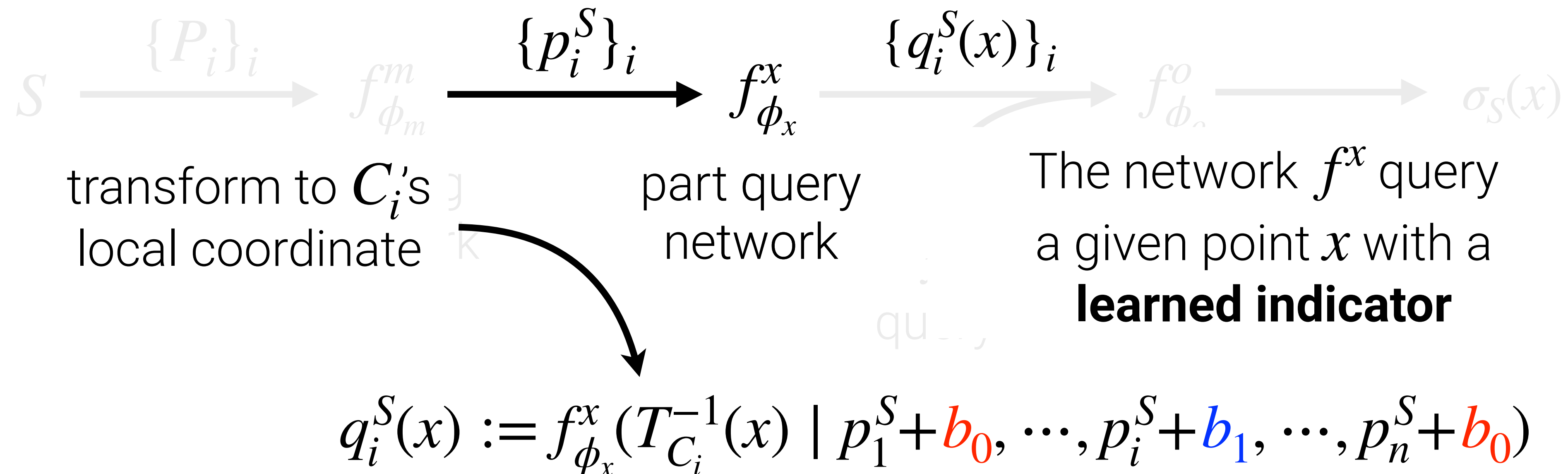


Method - Generalizable Shape Network

We approximate the object's occupancy $\sigma(x) \approx \sigma_S(x) := f_\theta(x \mid S)$ where f_θ is a neural network given shape parameters.



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