

Modular Probabilistic Models via Algebraic Effects

Minh Nguyen, Roly Perera, Meng Wang, Nicolas Wu



Modular Probabilistic Models

via Algebraic Effects

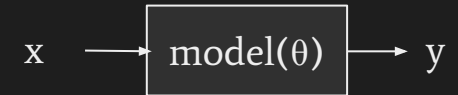
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Probabilistic model: a set of relationships between random variables

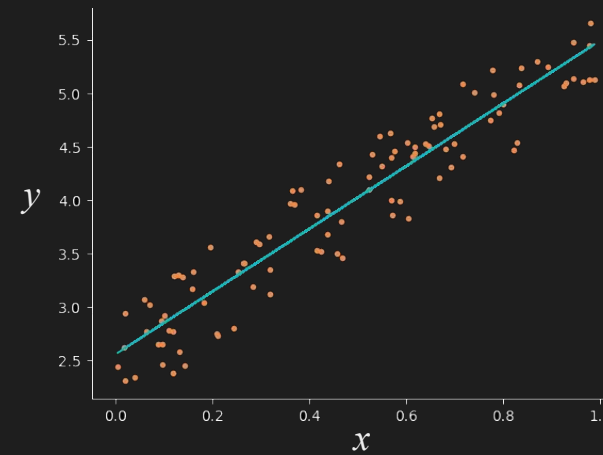


Probabilistic model: a set of relationships between random variables.



Linear regression

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parameters	$\left\{ \begin{array}{l} \mu \sim \text{Normal}(0, 3) \\ c \sim \text{Normal}(0, 2) \\ \sigma \sim \text{Uniform}(1, 3) \end{array} \right.$
output	$\{ y \sim \text{Normal}(\mu * x + c, \sigma)$



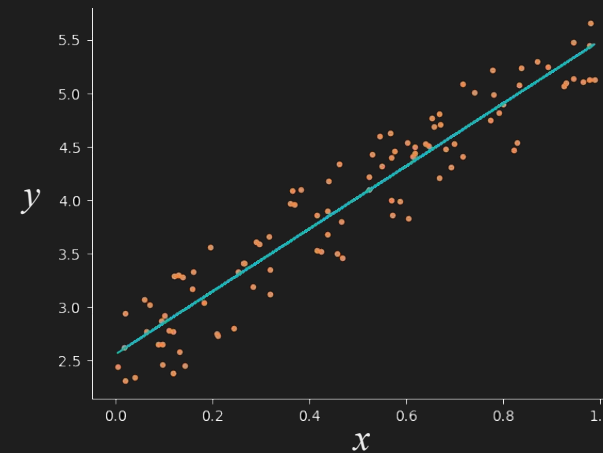
PPLs: Probabilistic models as programs

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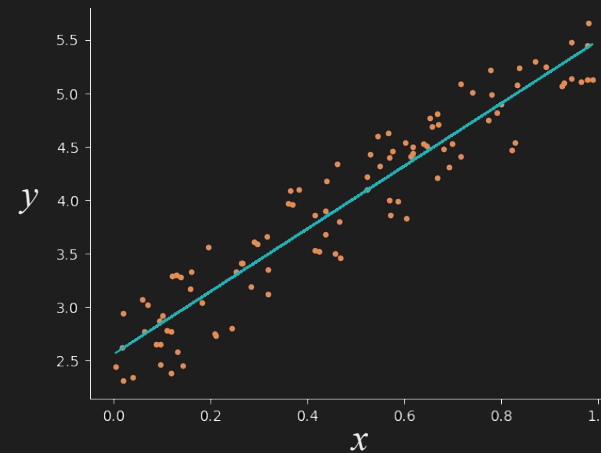
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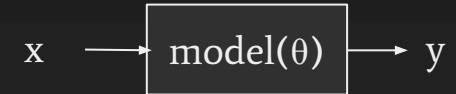
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What might linear regression look like as a **probabilistic program**?

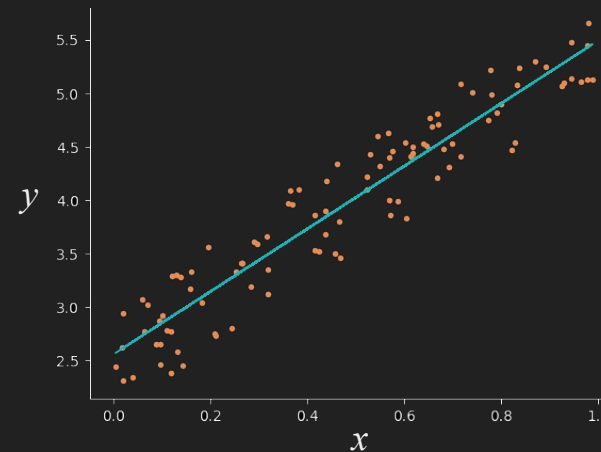
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What might linear regression look like as a **probabilistic program**?

[Monad Bayes]

A possible simulation

```

linRegr x μ c σ = do
  y ← sample (normal (μ * x + c) σ)
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```

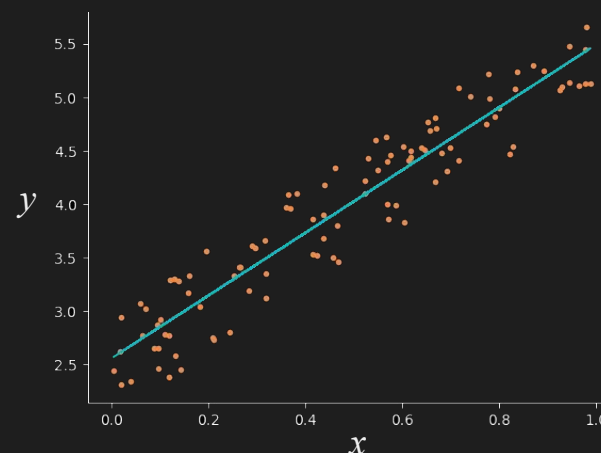
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```

A possible inference

```

linRegr x y = do
  μ ← sample (normal 0 3)
  c ← sample (normal 0 2)
  σ ← sample (uniform 0 3)
  observe (normal (μ * x + c) σ) y
  return (μ, c, σ)
  
```


PPLs: Probabilistic models as programs

[WebPPL]

A possible simulation

```
var linRegr = function(x, mu, c,  $\sigma$ ) {
  y = sample(Normal(mu * x + c,  $\sigma$ ), y)
  return y
}
```

A possible inference

```
var linRegr = function(x, y) {
  mu    = sample(Normal(0, 3))
  c     = sample(Normal(0, 2))
   $\sigma$  = sample(Uniform(0, 2))
  observe(Normal(mu * x + c,  $\sigma$ ), y)
  return (mu, c,  $\sigma$ )
}
```

[Anglican]

A possible simulation

```
(defquery linRegr [x, mu,  $\sigma$ , c]
  (let [y (sample(normal (c + (* mu) x))  $\sigma$ )]
    {:output y}))
```

A possible inference

```
(defquery linRegr [x mu-prior  $\sigma$ -prior c-prior y]
  (let [mu    (sample mu-prior)
        c     (sample c-prior)
         $\sigma$  (sample  $\sigma$ -prior)
        pred (fn [x] (normal (c + (map (* mu) x))  $\sigma$ ))]
    (observe (predictive x) y)
    {:mu mu : $\sigma$   $\sigma$  :predictor (pred x)}))
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PPLs: Probabilistic models as programs

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var linRegr = function(x, y) {
  mu    = sample(Normal(0, 3))
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  return (mu, c,  $\sigma$ )
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*How about just **one**
general-purpose model?*

Motivation 1: Multimodal models

Multimodal model: a model whose random variables can be specialised to `sample` or `observe` modes

ProbFX: a Haskell PPL supporting multimodal models

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Linear regression in ProbFX

```
linRegr :: Observables env ["μ", "c", "σ", "y"] Double
        => [Double] -> Model env [Double]

linRegr xs = do
  μ ← normal 0 3 #μ
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  σ ← uniform 1 3 #σ
  ys ← mapM (λx → normal (μ * x + c) σ #y) xs
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observable variable ←

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model environment

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Interacting with a **ProbFX** model

Motivation 1: Multimodal models

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```
do -- | Simulation
  let xs      = [0 .. 100]
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We observe μ, c, σ
 We sample y



Motivation 1: Multimodal models

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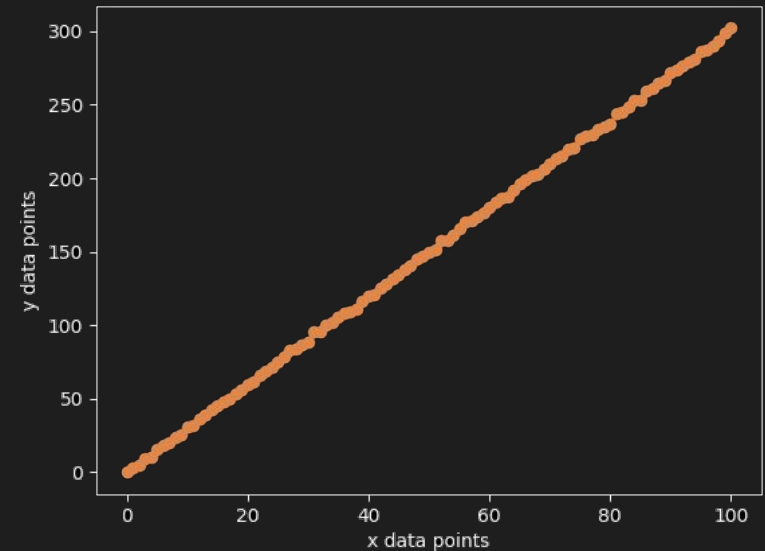
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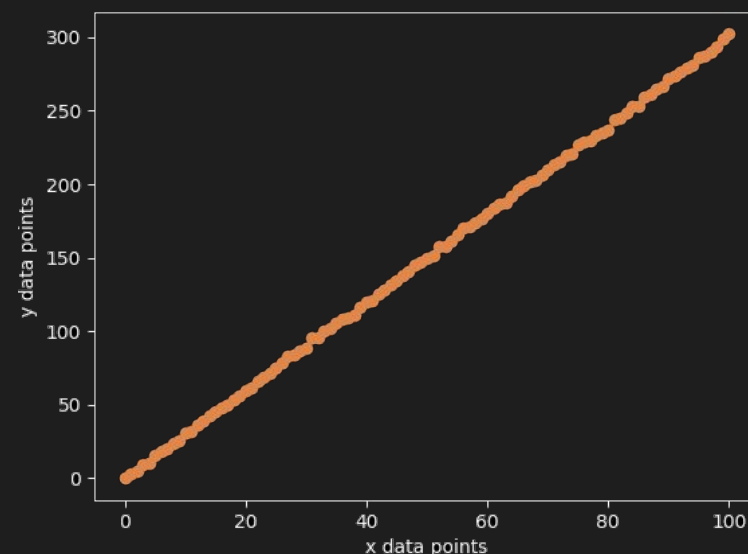
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  -- | Inference
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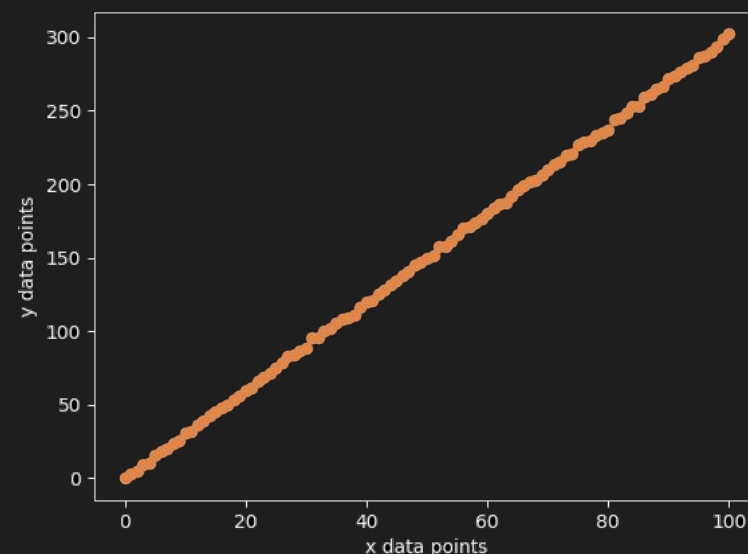
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  -- | Inference
  let envin    = (#μ := []) • (#c := []) • (#σ := []) • (#y := ys)
      (envouts, weights) ← lw 1000 (linRegr xs) envin
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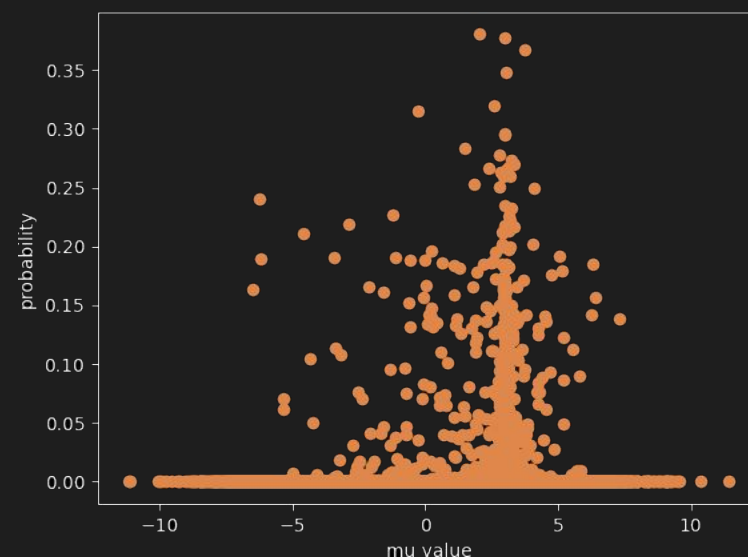
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(envouts, weights) ← lw 1000 (linRegr xs) envin
let μs = map (get #μ) envouts
return (μs, weights)
```



We observe μ, c, σ
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Motivation 2: Compositional models

Support for **multimodal models** already exists...

Supported model features	ProbFX	Gen	Turing	Stan	Pyro
Multimodal	●	●	●	●	●
Modular	●	●	●	○	●
Higher-order	●	◐	○	○	◐
Type-safe	●	○	○	●	○

- Full support
- ◐ Partial support
- No support

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- ◐ Partial support
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But models are generally not **first-class citizens**

[Turing]

```
@model function linRegr(x, mu, c, σ, y)
  y ~ Normal(mu * x + c, σ)
end
```

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But models are generally not **first-class citizens** or are not **statically typed**

[Turing]

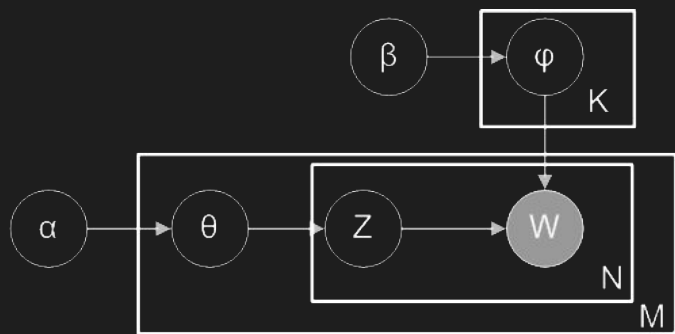
```
@model function linRegr(x, mu, c, σ, y)
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end
```

[Pyro]

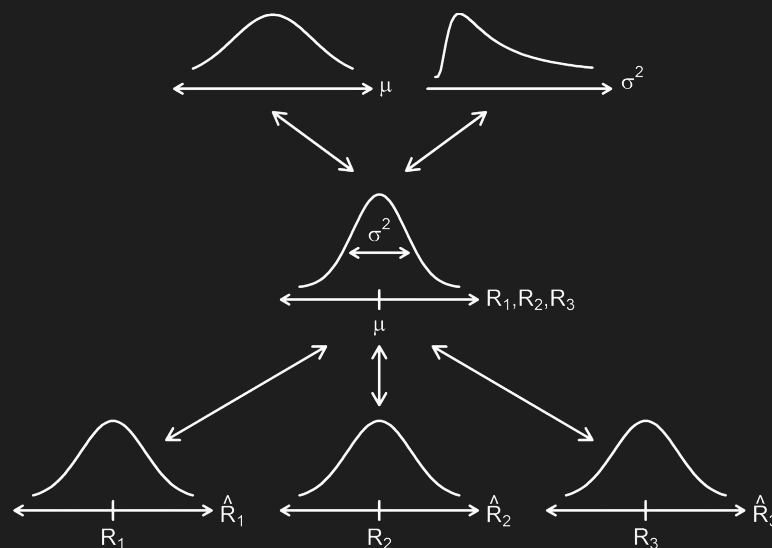
```
def linRegr(x, mu, c, σ):
  pyro.sample("y", dist.Normal(mu * x + c, σ))
  return y
```

```
pyro.condition(linRegr, {"hotdog" = True}) ??
```

*What about compositional,
higher-order models?*

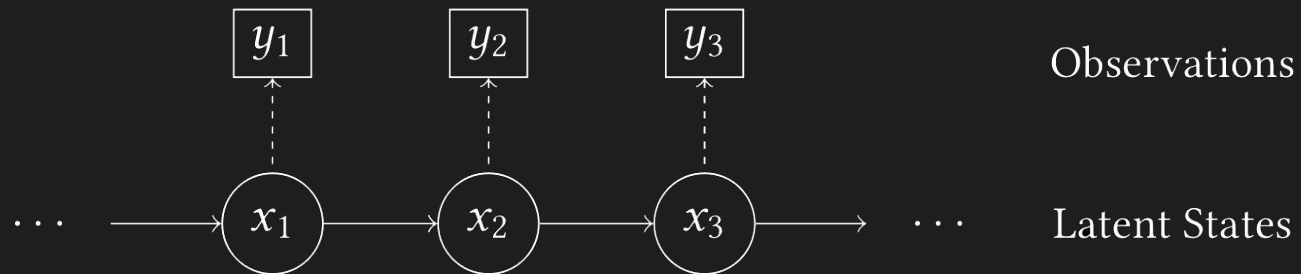


*What about **compositional, higher-order models?***



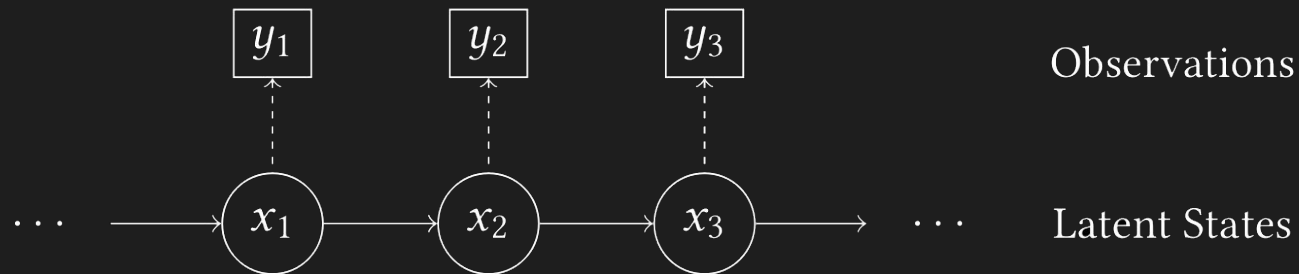
Motivation 2: Compositional models

Hidden Markov Model (HMM)



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Hidden Markov Model (HMM)

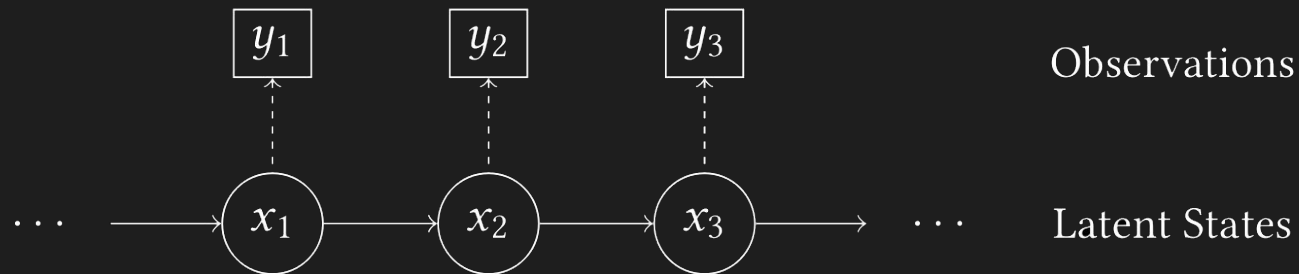


We can decompose this into two sub-models:

```
type TransModel env x    = x -> Model env x
type ObsModel   env x y = x -> Model env y
```

Motivation 2: Compositional models

Hidden Markov Model (HMM)



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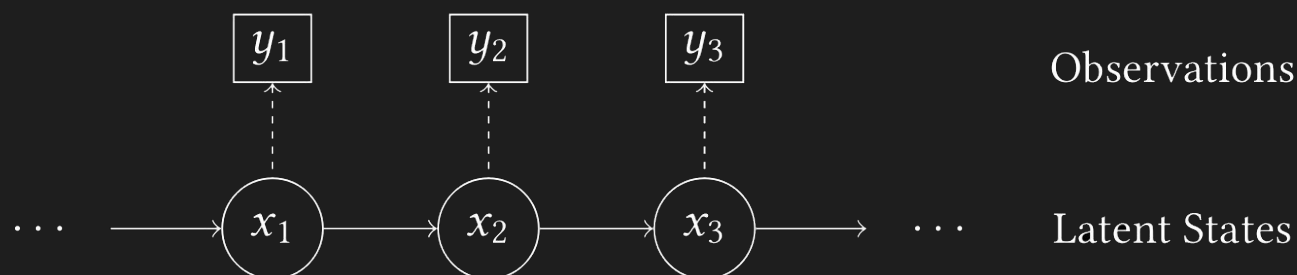
and then define a HMM as a higher-order model:

```
hmm :: TransModel env x -> ObsModel env x y -> Int -> x -> Model env x
```

```
hmm transModel obsModel n  $x_0$  = do
```

Motivation 2: Compositional models

Hidden Markov Model (HMM)



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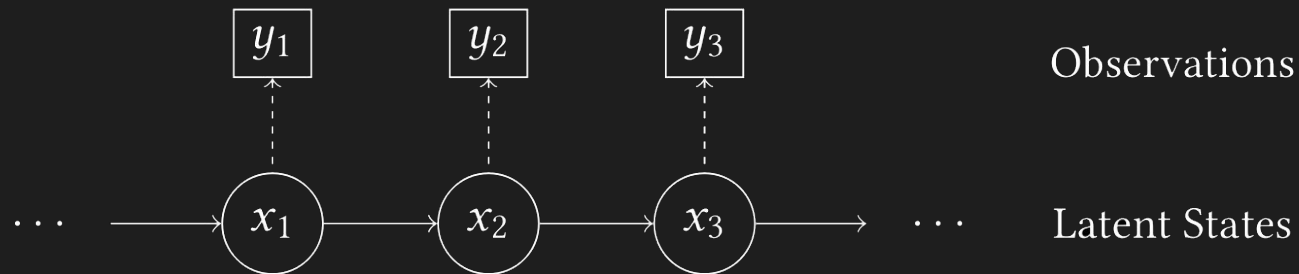
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```


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Hidden Markov Model (HMM)



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hmm transModel obsModel n x0 = do
  let hmmNode x = do x' <- transModel x
                     y' <- obsModel x'
                     return x'
  foldl (>=>) return (replicate n hmmNode) x0
```

```
(>=>) :: (a -> Model env b)
      -> (b -> Model env c)
      -> (a -> Model env c)
```

Modelling an Epidemic: the SIR model

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Setting: We assume a fixed total population of **S**usceptible, **I**nfected, and **R**ecovered individuals.

susceptible



infected



recovered



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The SIR model: During an epidemic, how do these populations vary over time (days)?

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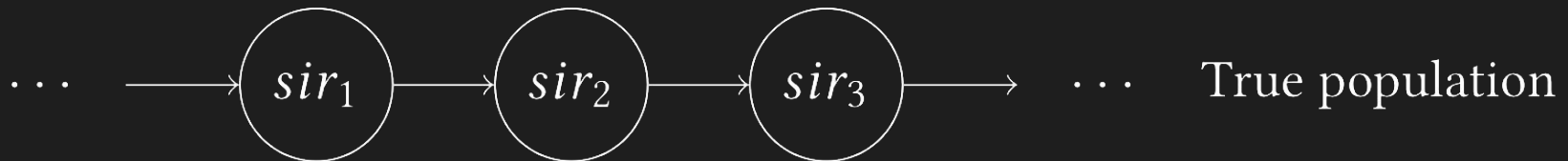


recovered



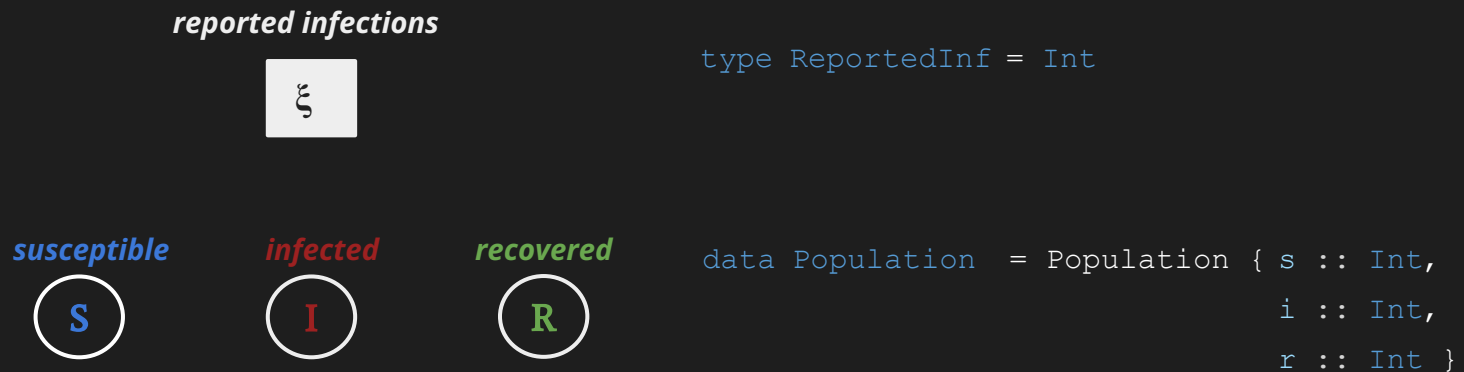
```
data Population = Population { s :: Int,
                                i :: Int,
                                r :: Int }
```

The SIR model: During an epidemic, how do these populations vary over time (days)?

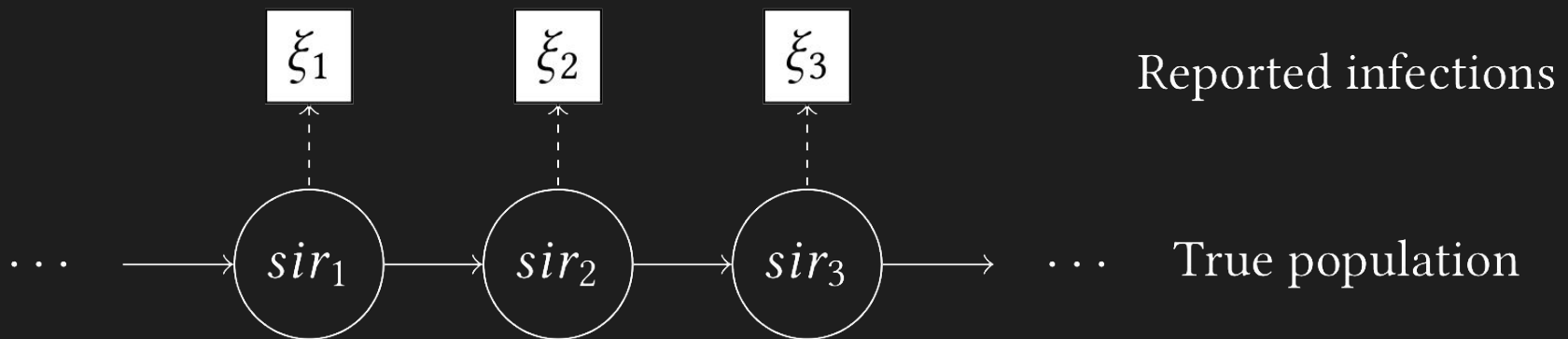


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The SIR model: During an epidemic, how do these populations vary over time (days)?



Modelling an Epidemic: the SIR model

SIR observation model

reported infections



```
type ReportedInf = Int
```

susceptible



infected



recovered

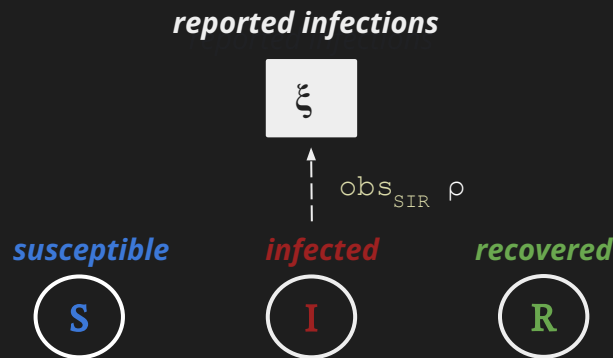


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data Population = Population { s :: Int,  
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```
type ObsModel env x y = x -> Model env y
```

Modelling an Epidemic: the SIR model

SIR observation model



```
type ReportedInf = Int
```

```
data Population = Population { s :: Int,
                                i :: Int,
                                r :: Int }
```

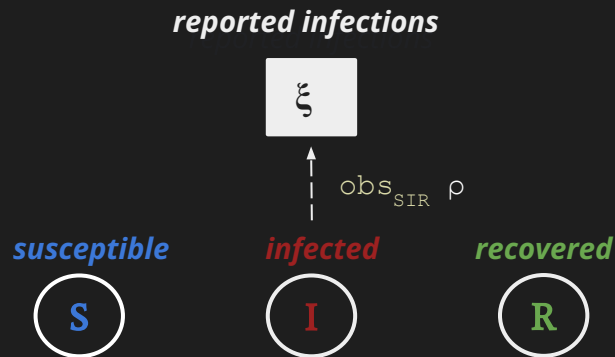
```
type ObsModel env x y = x -> Model env y
```

```
obsSIR :: Observable env "ξ" Int => Double -> ObsModel env Population ReportedInf
```

```
obsSIR ρ (Population _ i _) = poisson (ρ * i) ξ
```


Modelling an Epidemic: the SIR model

SIR transition model



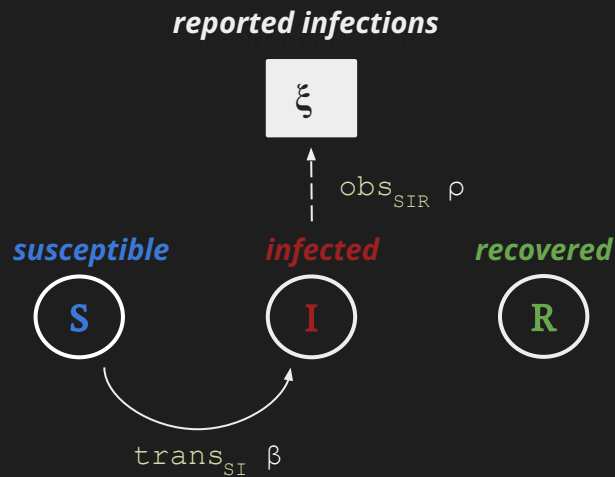
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type ReportedInf = Int
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data Population = Population { s :: Int,
                               i :: Int,
                               r :: Int }
```

```
type TransModel env x = x -> Model env x
```

Modelling an Epidemic: the SIR model

SIR transition model



```
type ReportedInf = Int
```

```
data Population = Population { s :: Int,
                               i :: Int,
                               r :: Int }
```

```
type TransModel env x = x -> Model env x
```

```
transSI :: Double -> TransModel env Population
```

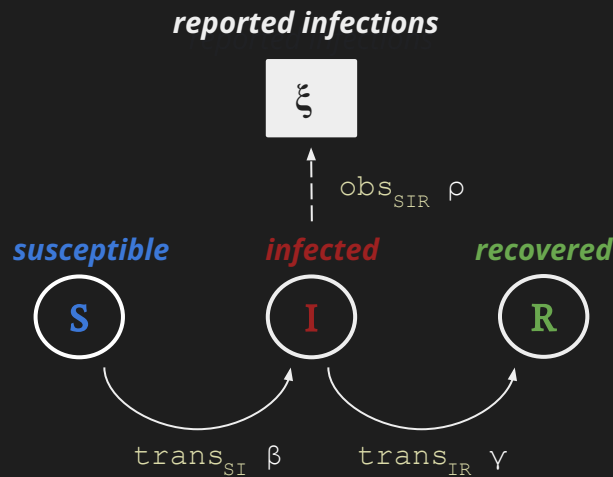
```
transSI  $\beta$  (Population s i r) = do
```

```
   $\delta_{SI} \leftarrow \text{binomial}' s (1.0 - \exp (-\beta * i / s + i + r))$ 
```

```
  return $ Population (s -  $\delta_{SI}$ ) (i +  $\delta_{SI}$ ) r
```

Modelling an Epidemic: the SIR model

SIR transition model



```
type ReportedInf = Int
```

```
data Population = Population { s :: Int,
                                i :: Int,
                                r :: Int }
```

```
type TransModel env x = x -> Model env x
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```
transSI :: Double -> TransModel env Population
```

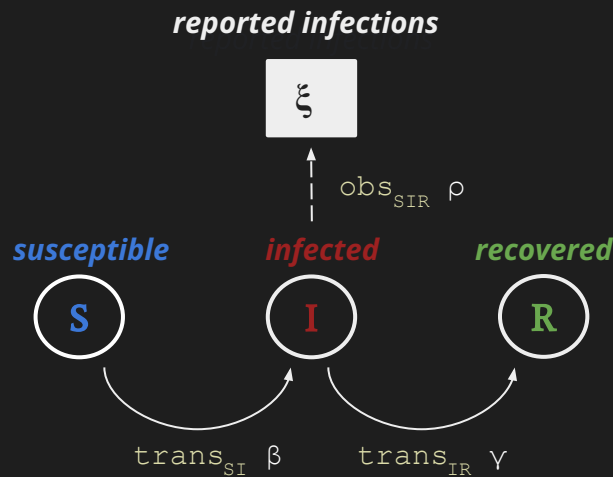
```
transSI β (Population s i r) = do
  δSI ← binomial' s (1.0 - exp (-β * i / s + i + r))
  return $ Population (s - δSI) (i + δSI) r
```

```
transIR :: Double -> TransModel env Population
```

```
transIR γ (Population s i r) = do
  δIR ← binomial' i (1.0 - exp (-γ))
  return $ Population s (i - δIR) (r + δIR)
```

Modelling an Epidemic: the SIR model

SIR transition model



```
type ReportedInf = Int
```

```
data Population = Population { s :: Int,
                               i :: Int,
                               r :: Int }
```

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type TransModel env x = x -> Model env x
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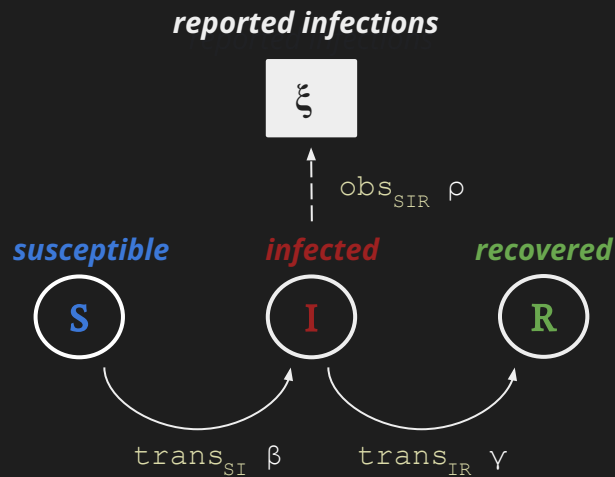
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transIR γ (Population s i r) = do
  δIR ← binomial' i (1.0 - exp (-γ))
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```

```
transSIR :: Double
          -> Double
          -> TransModel env Population
transSIR β γ = transSI β >=> transIR γ
```

Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



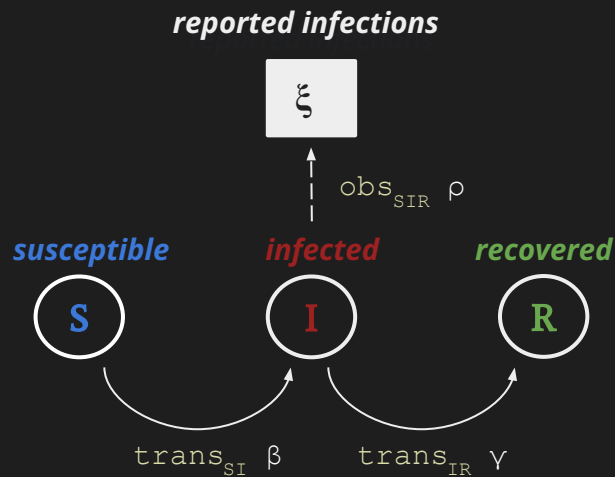
```
hmm :: TransModel env x -> ObsModel env x y -> Int -> x -> Model env x
```

```
obsSIR ρ (Population _ i _)
  = poisson (ρ * i) #ξ
```

```
transSIR β γ
  = transSI β ==> transIR γ
```

Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



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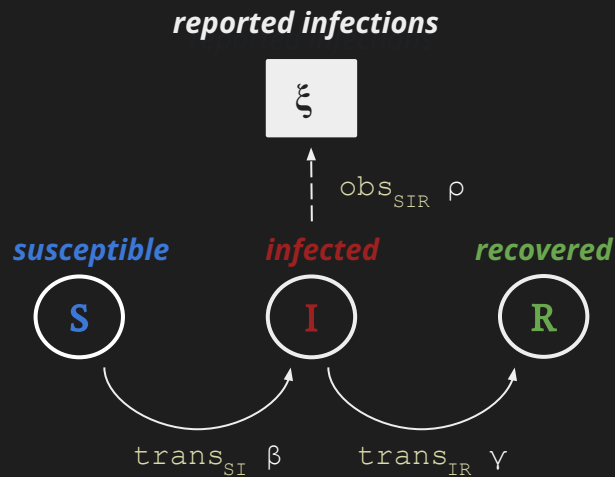
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sirModel = hmm (transSIR β γ) (obsSIR ρ)
```

Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



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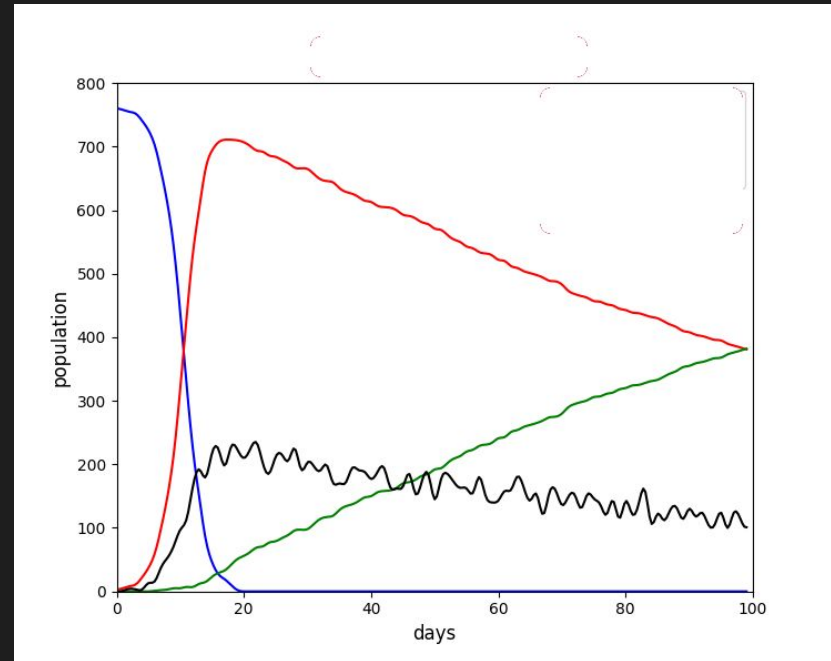
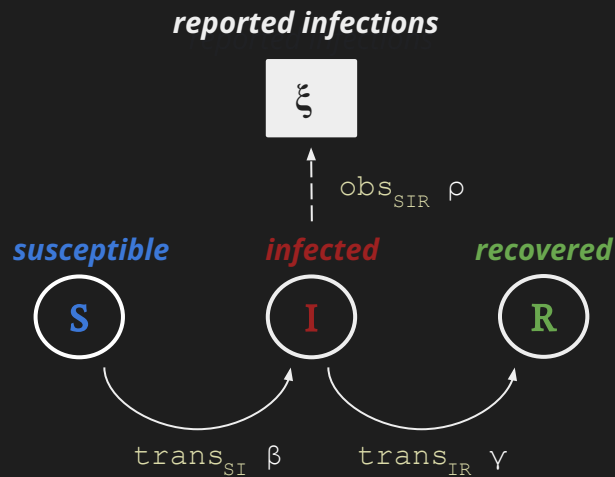
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```
sirModel = hmm (transSIR β γ) (obsSIR ρ)
              100 (Population {s = 762, i = 1, r = 0})
```

Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



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hmm :: TransModel env x -> ObsModel env x y -> Int -> x -> Model env x
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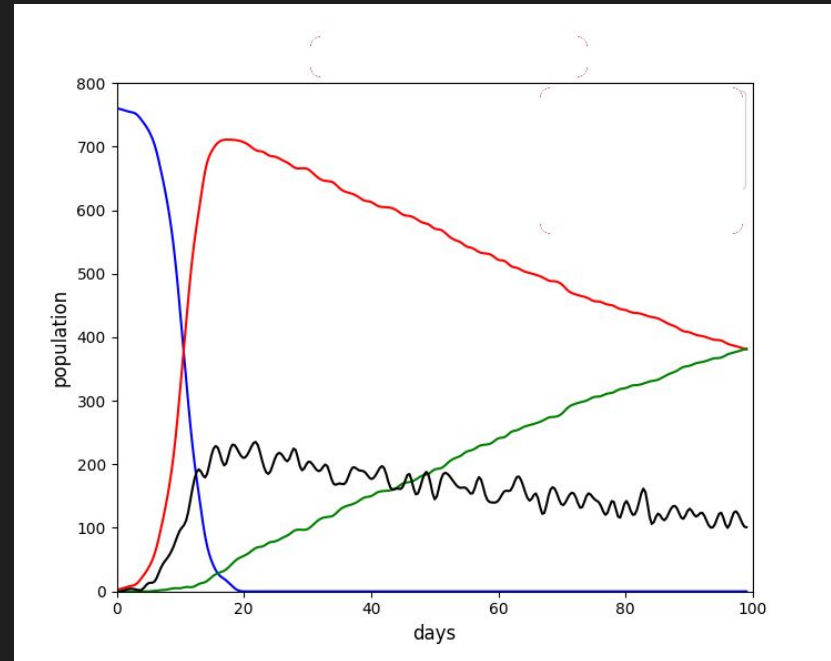
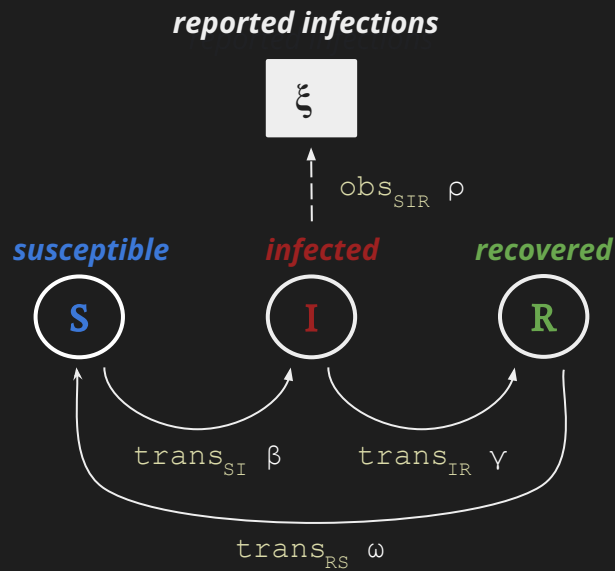
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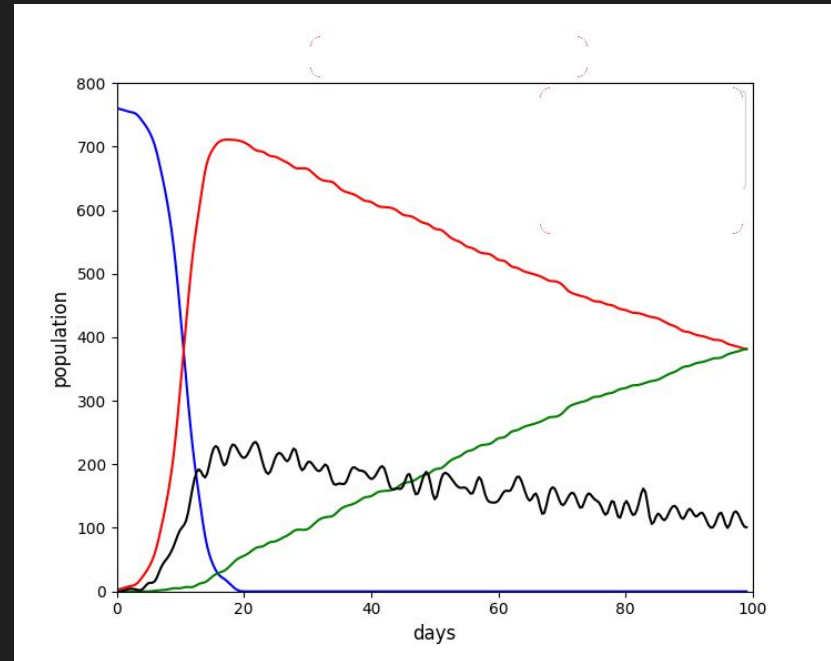
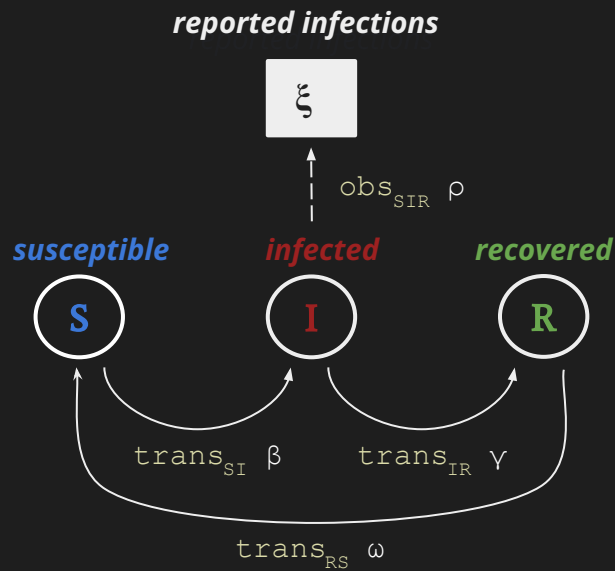
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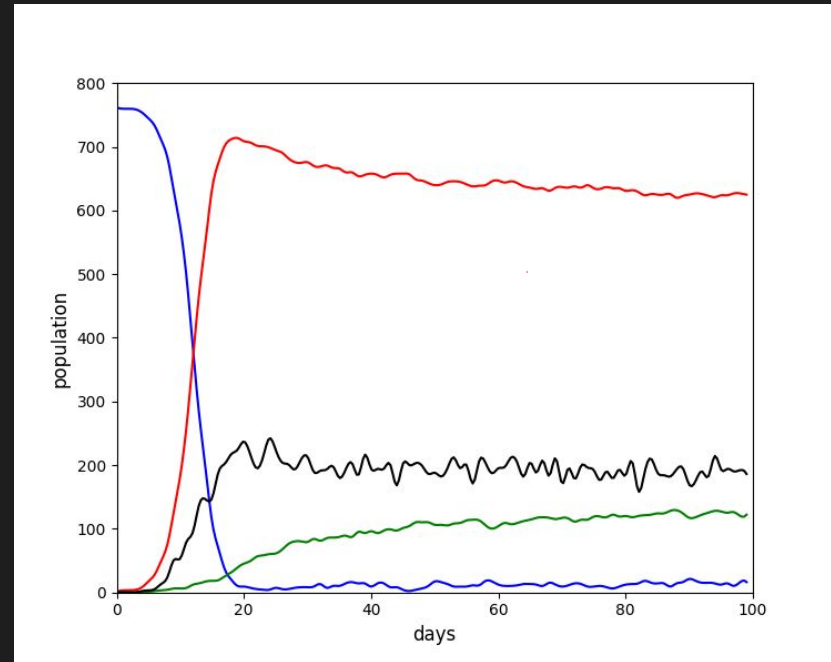
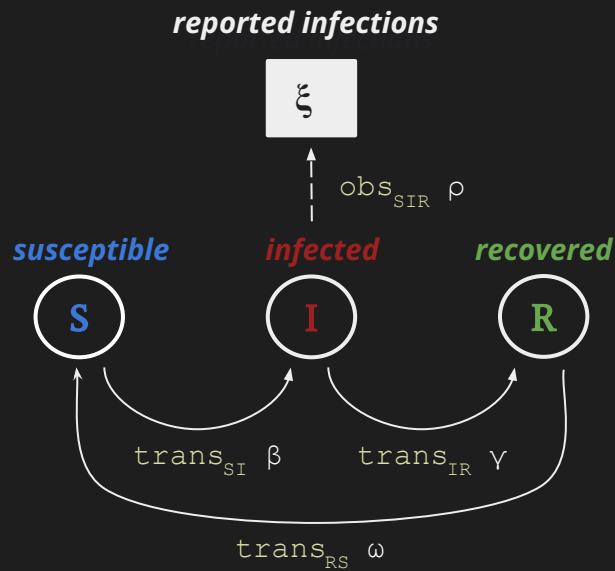
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obsSIR ρ (Population _ i _)
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```

```
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```

```
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Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



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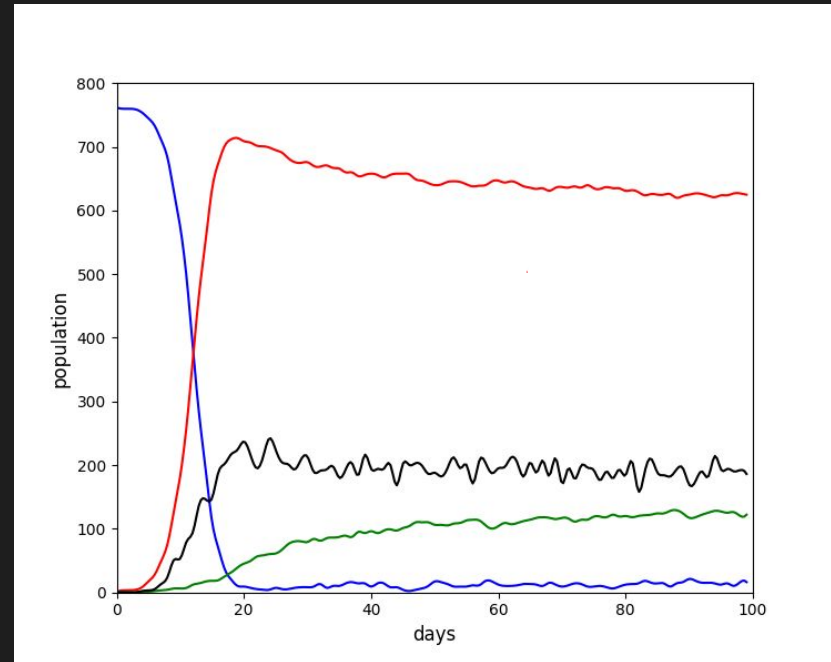
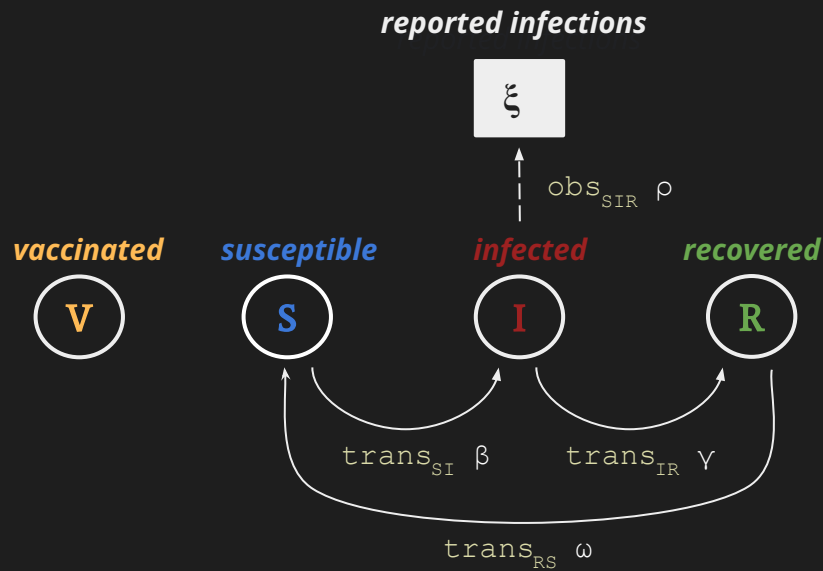
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SIR as a Hidden Markov Model



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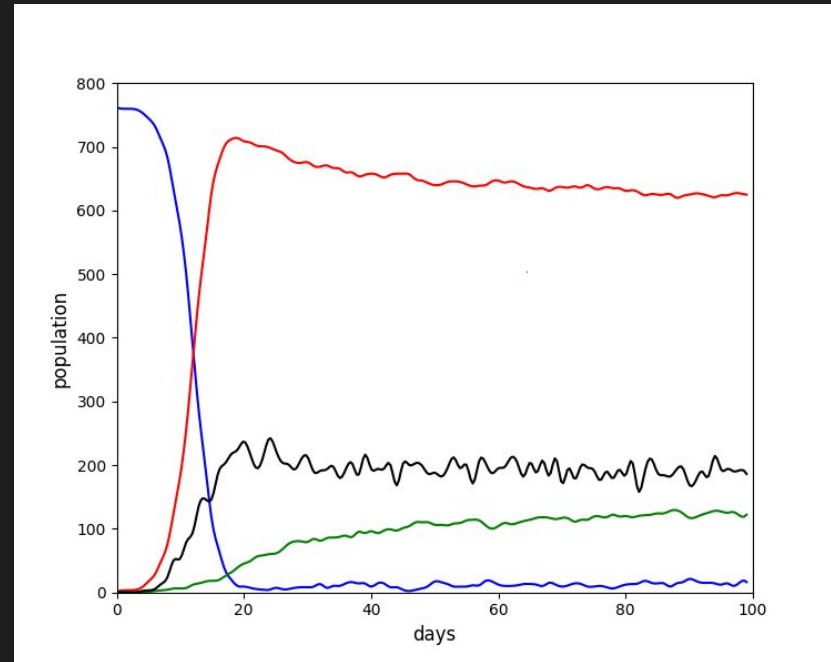
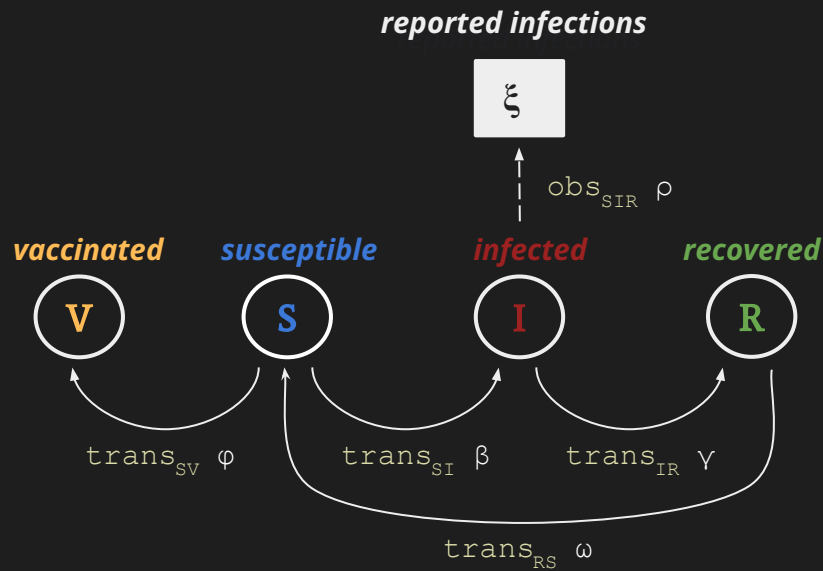
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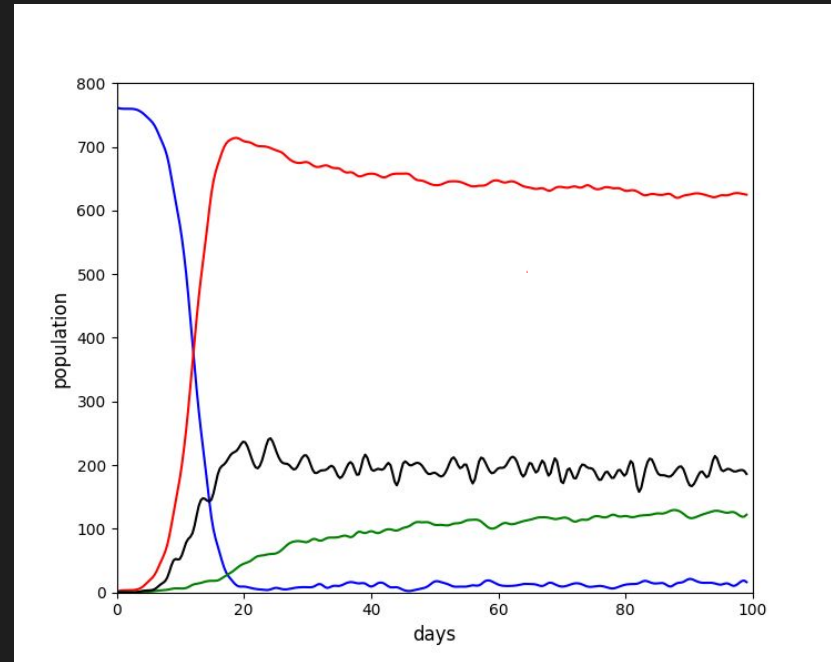
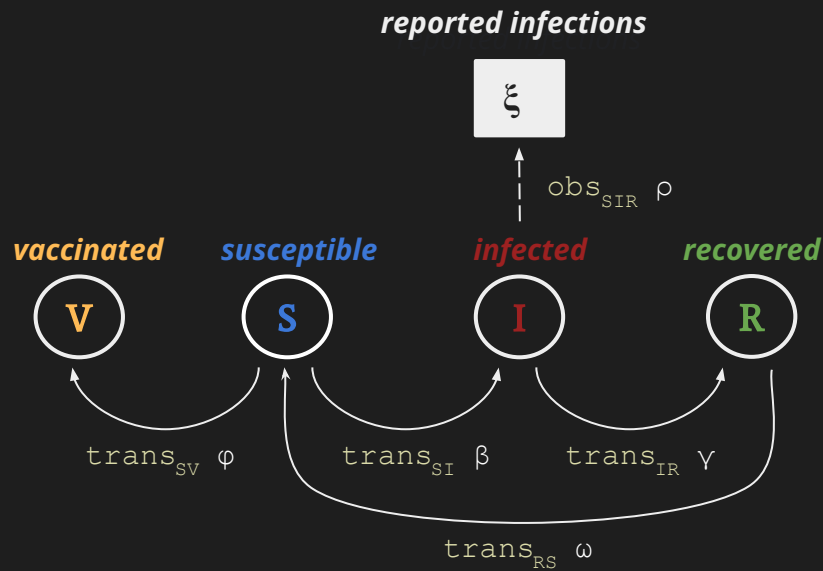
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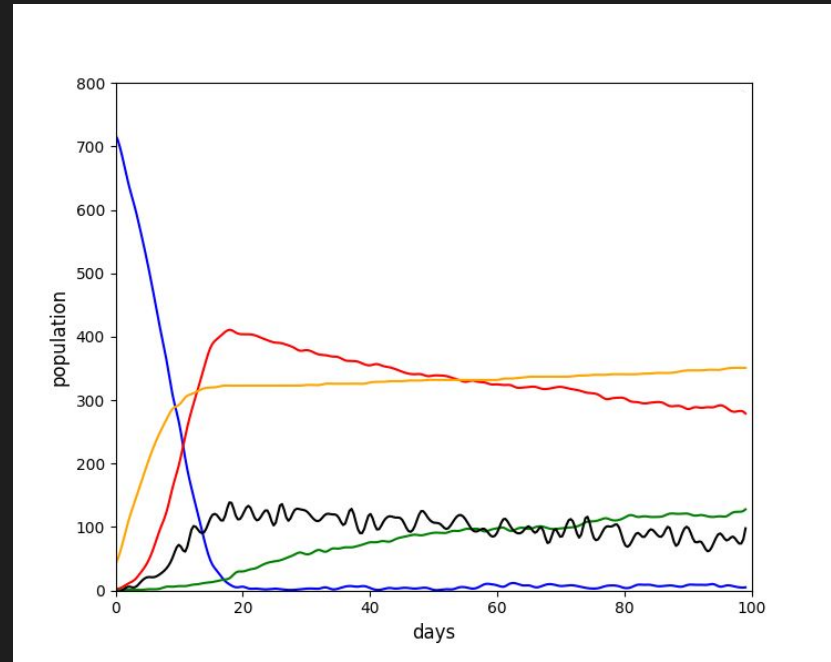
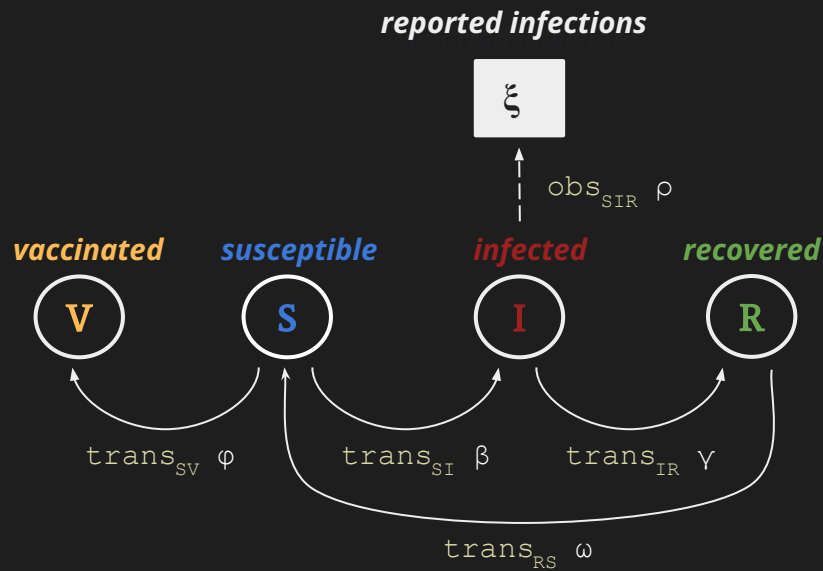
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  = poisson (ρ * i) #ξ
```

```
transSIR β γ ω φ  
  = transSI β ==> transIR γ  
    ==> transRS ω  
    ==> transSV φ
```

```
sirModel = hmm (transSIR β γ ω φ) (obsSIR ρ)  
              100 (Population {s = 762, i = 1, r = 0, v = 0})
```

Modelling an Epidemic: the SIR model

SIR as a Hidden Markov Model



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hmm :: TransModel env x -> ObsModel env x y -> Int -> x -> Model env x
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obsSIR ρ (Population _ i _ _)  
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              100 (Population {s = 762, i = 1, r = 0, v = 0})
```



`[github.com/min-nguyen/prob-fx]`

Models

```
type Model env es a = (Member Dist es, Member (ObsReader env) es) => Prog es a
```

Primitive distributions

Reading observable variables

Effect signature

Smart constructors for primitive distributions

```
coinFlip :: (Observable env "p" Double,
            Observable env "y" Bool)
          => Model env es Bool
```

```
coinFlip = do
  p <- uniform 0 1 #p
  y <- bernoulli p #y
  return y
```

desugars to



```
coinFlip = do
  maybe_p <- call (Ask #p)
  p <- call (Uniform 0 1 maybe_p)
  maybe_y <- call (Ask #y)
  y <- call (Bernoulli p maybe_y)
  return y
```

handles to



```
(#p := [])
(#y := [True])
```

```
coinFlip = do
  p <- call (Sample (Uniform 0 1))
  y <- call (Observe (Bernoulli p) True)
  return y
```

Model environments

```
data Env env where
  ENil    :: Env '[]
  ECons   :: [a] -> Env env -> Env ((x := a) : env)

data Assign x a = x := a

-- For example:
(#μ := [3.0]) • (#c := [0.0]) • (#σ := [1.0]) • (#y := []) • nil
  :: Env ["μ" := Double, "c" := Double , "σ" := Double, "y" := Double]
```

Observable variables

```
data ObsVar (x :: Symbol) where
  ObsVar :: KnownSymbol x => ObsVar x

-- For example:
#foo :: ObsVar "foo"
```