

A Theory of Changes for Higher-Order Languages

A Theory of Changes: (1) Formalizing change structures

Definition: Change Structure

A change structure for V is the tuple $\mathbf{V} = (V, \Delta, \oplus, \ominus)$ where ...

- V is a set called the base set
- Δv is the change set for a specified value $v \in V$
- Updating a base value $v_{\text{old}} \in V$ with a change $dv \in \Delta v_{\text{old}}$:
$$v_{\text{new}} = v_{\text{old}} \oplus dv$$
- Computing the change between two values $v_{\text{old}} \in V$ and $v_{\text{new}} \in V$:
$$dv = v_{\text{new}} \ominus v_{\text{old}}$$

A Theory of Changes: (1) Formalizing change structures

Example: Naturals

Base set: \mathbb{N} Change set: Δv $\oplus = +$ $\ominus = -$

Given some natural $v_{\text{old}} \in \mathbb{N}$, a change $dv \in \Delta v_{\text{old}}$ describes the difference between v_{old} and another natural v_{new} .

- Updating a base value v with a change dv :
$$v_{\text{new}} = v_{\text{old}} \oplus dv$$
$$v_{\text{new}} = v_{\text{old}} + dv$$

If $\Delta v = \mathbb{Z}$, then the following is possible (and invalid):

$$3 \oplus -5$$
$$= 3 + (-5)$$
$$= -2 \notin \mathbb{N}$$
- Computing the change between two values v_{old} and v_{new} :
$$dv = v_{\text{new}} \ominus v_{\text{old}}$$
$$dv = v_{\text{new}} - v_{\text{old}}$$

If $\Delta v = \mathbb{N}$, then the following is possible (and invalid):

$$3 \ominus 5$$
$$= 3 - 5$$
$$= -2 \notin \mathbb{N}$$

A Theory of Changes: (1) Formalizing change structures

Example: Naturals

Base set: \mathbb{N} Change set: Δv $\oplus = +$ $\ominus = -$

Given some natural $v \in \mathbb{N}$, a change $dv \in \Delta v$ describes the difference between v and another natural v_{new} .

Solution: Introduce dependent types

For a natural v , we set $\Delta v = \{ dv \mid v + dv \geq 0 \}$; \ominus and \oplus are then always defined.

Conditions for change structures:

- For each base value $v \in \mathbb{N}$, there exists a specific set of changes Δv for v .
- Given $v_{\text{new}}, v_{\text{old}} \in \mathbb{N}$: $v_{\text{new}} \ominus v_{\text{old}} \in \Delta v_{\text{old}}$
- Given $v \in \mathbb{N}, dv \in \Delta v$: $v \oplus dv \in \mathbb{N}$

A Theory of Changes: (2) Nil Changes & Derivatives

Definition: Nil Changes

$$\mathbf{0}_v = v \ominus v$$

$$v \oplus \mathbf{0}_v = v$$

Definition: Derivatives

The derivative \mathbf{f}' of a function \mathbf{f} computes the change of $\mathbf{f} \mathbf{a}$ when \mathbf{a} is updated to $\mathbf{a} \oplus \mathbf{da}$.

$$\mathbf{f} \quad :: \mathbf{A} \rightarrow \mathbf{B}$$

$$\mathbf{f}' \quad :: \mathbf{A} \rightarrow \Delta \mathbf{A} \rightarrow \Delta \mathbf{B}$$

$$\mathbf{f}' \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a}$$

or equivalently:

$$\underline{\mathbf{f} \mathbf{a}} \oplus \underline{\mathbf{f}' \mathbf{a} \mathbf{da}} = \underline{\mathbf{f} (\mathbf{a} \oplus \mathbf{da})}$$

↑
Original
output

↑
Output
change

↑
Updated
input

A Theory of Changes: (2) Nil Changes & Derivatives

Corollary: The derivative of a function applied to an input 'a' and its nil change '0_a' produces a nil output change '0_(f a)'

$$\mathbf{f'}\ \mathbf{a}\ \mathbf{0}_a = \mathbf{0}_{(f\ a)}$$

$$\mathbf{f}\ \mathbf{a} \oplus \mathbf{f'}\ \mathbf{a}\ \mathbf{0}_a = \mathbf{f}\ \mathbf{a}$$

A Theory of Changes: (3) Function Changes

Recall (Derivatives):

A derivative \mathbf{f}' of a function \mathbf{f} computes the change of $\mathbf{f} \mathbf{a}$ when:

- \mathbf{a} is updated to $\mathbf{a} \oplus \mathbf{da}$.

$$\mathbf{f}' \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a}$$

$$\mathbf{f}' :: \mathbf{A} \rightarrow \Delta \mathbf{A} \rightarrow \Delta \mathbf{B}$$

Incrementalization Theorem (Function Changes):

A function change \mathbf{df} of a function \mathbf{f} computes the change of $\mathbf{f} \mathbf{a}$ when:

- \mathbf{a} is updated to $\mathbf{a} \oplus \mathbf{da}$
- \mathbf{f} is updated to $\mathbf{f} \oplus \mathbf{df}$

$$\mathbf{df} \mathbf{a} \mathbf{da} = \underbrace{(\mathbf{f} \oplus \mathbf{df}) (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a}}$$

$$\mathbf{df} :: \mathbf{A} \rightarrow \Delta \mathbf{A} \rightarrow \Delta \mathbf{B}$$



We need to avoid computing this directly

A Theory of Changes: (3) Function Changes

Relating Derivatives With Function Changes:

Recall the incrementalization theorem:

$$\mathbf{df} \mathbf{a} \mathbf{da} = (\mathbf{f} \oplus \mathbf{df}) (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a} \quad (\text{Incrementalization Theorem})$$

When \mathbf{df} is the nil change for \mathbf{f} (i.e. $\mathbf{f} \oplus \mathbf{df} = \mathbf{f}$ or $\mathbf{df} = \mathbf{0}_f$), this theorem becomes:

$$\mathbf{df} \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a} \quad (\text{Incrementalization Theorem when } \mathbf{df} = \mathbf{0}_f)$$

This looks exactly the same as the definition for derivatives of a function!

$$\mathbf{f}' \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a} \quad (\text{Definition: Derivatives})$$

Conclusion:

The nil change to a function, $\mathbf{0}_f$, is exactly the same as its derivative, \mathbf{f}' .

$$\mathbf{0}_f = \mathbf{f}' \quad (\text{Theorem: Nil Changes are Derivatives})$$

Incrementing λ -Calculi

We want to define a computation *Derive* which computes the derivatives of functions.

We could implement this using the definition for derivatives ...

$$\mathbf{f}' \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a}$$

... but this is no faster than recomputation.

Therefore, we must define *Derive* as a source-to-source transformation that guarantees that:

$\llbracket \text{Derive}(\mathbf{f}) \rrbracket$ represents the derivative of $\llbracket \mathbf{f} \rrbracket$

$$\text{Derive}(\mathbf{f}) \mathbf{a} \mathbf{da} = \mathbf{f} (\mathbf{a} \oplus \mathbf{da}) \ominus \mathbf{f} \mathbf{a}$$

Incrementing λ -Calculi - Plugins

Incremental λ -Calculi is a simply-typed λ -Calculi parameterized by *plugins* provided by a user.

A plugin should define:

- The base types
- The change representation for each base type
- The primitive constants
- The incremental version/derivatives of each primitive constant

What we can define right now, is the incrementalization of features that are universal amongst all possible instances of plugin implementations.

- Function types
- Abstractions
- Application
- Variable References

Incrementing λ -Calculi - Differentiation

Defining $\mathcal{D}erive(f)$

- We require that if $\Gamma \vdash t : \tau$, then $\mathcal{D}erive(t)$ represents the change in t in terms of changes to the values of its free variables.

$\mathcal{D}erive(u)$

1. If $u = x$

$$\mathcal{D}erive(x) = dx \text{ (that is, the change of } x\text{)}$$

2. If $u = \lambda x. t$

$$\mathcal{D}erive(\lambda x. t) = \lambda x. \lambda dx. \mathcal{D}erive(t)$$

3. If $u = s t$

$$\mathcal{D}erive(s t) = \mathcal{D}erive(s) t \mathcal{D}erive(t)$$

4. If $u = c$

$$\mathcal{D}erive(c) = 0_c$$

$$\frac{\Gamma \vdash t : \tau}{\Gamma, \Delta\Gamma \vdash \mathcal{D}erive(t) : \Delta\tau} \mathcal{D}erive$$

Incrementing λ -Calculi - Proving Desired Behaviour of Derive

Desired behaviour of *Derive*: $f (a \oplus da) \cong (f a) \oplus (\text{Derive}(f) a da)$

Given a standard denotational semantics $\llbracket - \rrbracket$ for simply typed λ -calculus, we define a non-standard denotational semantics $\llbracket - \rrbracket^\Delta$

We aim to prove that $\llbracket t \rrbracket^\Delta$ is the derivative of $\llbracket t \rrbracket$

Incrementing λ -Calculi - Proving Desired Behaviour of Derive

Change Semantics

$$\llbracket t \rrbracket \rho$$
$$\begin{aligned}\llbracket c \rrbracket \rho &= \dots \\ \llbracket \lambda x. t \rrbracket \rho &= \lambda v. \llbracket t \rrbracket (\rho, x = v) \\ \llbracket s t \rrbracket \rho &= (\llbracket s \rrbracket \rho) (\llbracket t \rrbracket \rho) \\ \llbracket x \rrbracket \rho &= \text{lookup } x \text{ in } \rho\end{aligned}$$

(Standard Evaluation)

$$\frac{\llbracket t \rrbracket^\Delta \rho}{d\rho}$$
$$\begin{aligned}\llbracket c \rrbracket^\Delta \rho \, d\rho &= \dots \\ \llbracket \lambda x. t \rrbracket^\Delta \rho \, d\rho &= \lambda v \, dv. \llbracket t \rrbracket^\Delta (\rho, x = v) (d\rho, dx = dv) \\ \llbracket s t \rrbracket^\Delta \rho \, d\rho &= (\llbracket s \rrbracket^\Delta \rho \, d\rho) (\llbracket t \rrbracket^\Delta \rho \, d\rho) \\ \llbracket x \rrbracket^\Delta \rho \, d\rho &= \text{lookup } dx \text{ in } d\rho\end{aligned}$$

(Differential Evaluation)

Incrementing λ -Calculi - Proving Desired Behaviour of Derive

Aim: Proving the behaviours of $\llbracket \text{Derive}(t) \rrbracket$ and $\llbracket t \rrbracket^\Delta$ are consistent

Theorem: (Correctness of differentiation)

Let $f : \sigma \rightarrow \tau$ be a closed term of function type.

For every closed base term $s : \sigma$ and closed change term $ds : \Delta\sigma$ such that there exists a change $dv \in \Delta_\sigma \llbracket s \rrbracket$ which erases to ds , we have that:

$$f (s \oplus ds) \cong (f s) \oplus (\text{Derive}(f) s ds)$$

Recall: $f (a \oplus da) \cong (f a) \oplus (\text{Derive}(f) a da)$