# **MINA KHAN**

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413-210-0830



#### **EDUCATION**

Bachelor of Arts: Mount Holyoke College (MHC), South Hadley, MA

Expected May 2015

Majors: Mathematics, Computer Science and Physics

GPA: 4.00

<u>Scholarships:</u> The Google Anita Borg Memorial Scholarship ('14), Grace Hopper Scholarship Grant ('14) <u>Academic Awards and Honors:</u> Sigma Pi Sigma-Physics Honors Society (2014); Sarah Williston Prize for Highest ranked students *(2013)*; Sarah Williston Scholar- top 15% of class (2013); Bennett Prize for Excellence in Physics *(2012)*; Mildred L Sanderson Prize for Excellence in Mathematics *(2012)*.

<u>Courses:</u> Operating Systems; Artificial Intelligence; Machine Learning; Software Design; Web Programming; Computer Systems; Computational Theory; Abstract Algebra; Real and Complex Analysis; Electronics; Advanced Quantum; Statistical Mechanics; Differential Equations; Data Structures.

#### **SKILLS AND EXPERTISE**

- **Programming Skills:** Java; Python; JavaScript; HTML; CSS; Google App Engine (Spark: match, mentor, code); WearScript.js for Google Glass; Node.js; PostgreSQL; Arduino Integrated Development Environment; MATLAB; Sage; Fortran; C++; Linux.
- **Leadership Experience:** Head of Literaty Pakistan USA Chapter (*Sept 2012-May 2014*); Youngest Secretary General for Five College Model United Nations VI (*2012-13*).

### **PROJECTS**

- **CookUps:** Food recipe search engine that suggests recipes based on ingredients Sept 2014- present
- Just-in-time learning using Google Glass

August 2014- present

- Advisor: Professor Pattie Maes and Scott Greenwald at MIT Media Lab
- Develop applications on Google Glass, Mobile and Web for contextual learning and augmented memory
- Gröbner Bases for Polynomial Systems in Robotics

June - August 2014

- Advisor: Professor Russ Tedrake at MIT Computer Science and Artificial Intelligence Laboratory
- Efficiently solve equations of motion of robots using Gröbner bases
- Presentation: Gröbner Bases for Polynomial Systems in Robotics (August 2014)
- Swarm Robotics: Remotely Controlled Multi-Robot Formations

Sept 2013- June 2014

- Advisor: Professor Audrey St. John at Mount Holyoke College
- Create a leader-follower model of robots using iRobot Create, Arduino robots and rigid graph theory
- Presentations: <u>Leader Follower Control Using Directed Graphs</u> (*May '14*); <u>Leader Follower Control of Multi-Robot Formations</u> (New England Undergraduate Computing Symposium: *March 2014*)
- Ferromagnetic Nanorings and Nanowires

May 2012-May 2014

- Advisor: Professor Kathy Aidala at Mount Holyoke College
- Investigate ferromagnetic nanostructures for magnetic memory using Atomic Force Microscopy
- Publication: <u>A Multi-level Single-bit Data Storage Device</u> (Journal of Applied Physics: *March 2014*); Presentation: <u>Multi-level Single-bit Data Storage Device</u> (Magnetism & Magnetic Materials: *Nov '13*)
- Analyze Joule Heating using Defense Meteorological Satellite Program data June-August 2013
- Advisor: Dr. Barbara Emery and Dr. Astrid Maute at National Center for Atmospheric Research
- Analyze data using MATLAB and Fortran code to estimate Joule heating
- Presentation: Calculate Joule Heating using DMSP data (American Geophysical Union: Dec 2013)

#### **TEACHING EXPERIENCE**

• **Udacity:** Course Manager

May '14-present