

# Численные методы решения систем нелинейных уравнений

## Дз №7

### Вариант 5 Доскоч Роман 3 курс 13 группа

```
In [1]: import numpy as np
from numpy import array
import matplotlib.pyplot as plt
from matplotlib.pyplot import plot
from numpy import meshgrid
import random
import math
```

$$\begin{cases} 6(x-5)^2 + 9y - 5 = 0 \\ (x-10)^2 + (y+4)^2 - 21^2 = 0 \end{cases}$$

Найдем центр параболы

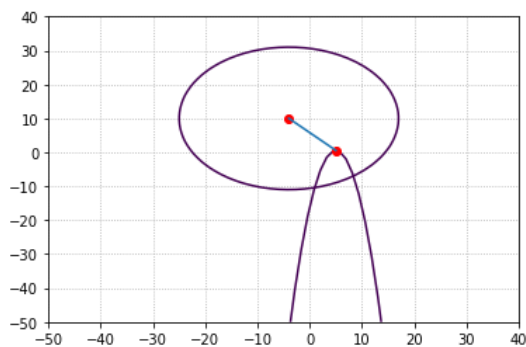
$$\begin{aligned} dy &= (-6(x-5)^2 - 5/9)' = 0 \\ &- 12(x-5)/9 = 0 \\ x &= 5 \quad y = \frac{5}{9} \end{aligned}$$

так как центр окружности находится в точке  $O(-4, 10)$ , а центр параболы в точке  $O'(5, \frac{5}{9})$  расстояние между точками  $\sqrt{(5+4)^2 + (5/9-10)^2} = 13.0459775 < 21$

Значит, корней всего 2 и будут они вблизи вершины параболы.

```
In [2]: f1 = lambda x,y: 6*(x - 5)**2 + 9*y - 5
f2 = lambda x,y: (x - 10)**2 + (y + 4)**2 - 21**2
```

```
In [3]: x, y = meshgrid(np.linspace(-20,40,50), np.linspace(-50,30,50))
plt.contour(x,y,f1(x,y),[0])
plt.contour(y,x,f2(x,y),[0])
plot(-4, 10, 'ro', 5, 5/9, 'ro', [-4,5], [10,5/9])
plt.grid(ls=':')
```



```
In [4]: #метод крамера для решения 2-матрицы
def Cramer(X,f):
    a1, a2, a3, a4 = X[0][0], X[0][1], X[1][0], X[1][1]
    b1, b2 = f[0], f[1]
    y = (a3*b1 - a1*b2)/(a3*a2 - a1*a4)
    x = (b2 - a4*y)/a3
    return array([x,y])
```

### Метод ньютона

```
In [5]: def solver(x_, y_, iterations=3):
        x_curr = array([x_, y_])
        path_X, path_Y = [], []
        for i in range(iterations):
            x, y = x_curr[0], x_curr[1]
            J = [[12*(x-5), 9],
                 [2*(x-10), 2*(y+4)]]
            x_curr += Cramer(J, [-f1(x, y), -f2(x, y)])

            path_X.append(x)
            path_Y.append(y)

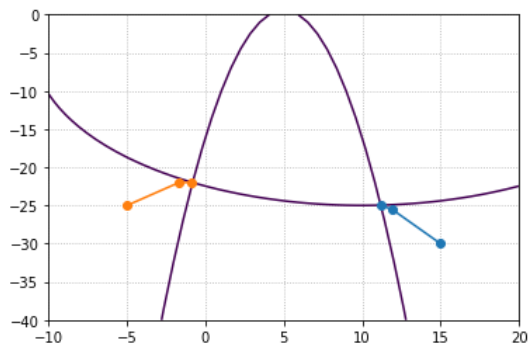
        return x_curr, path_X, path_Y
```

```
In [6]: x, y = meshgrid(np.linspace(-10, 20, 50), np.linspace(-40, 0, 50))
        plt.contour(x, y, f1(x, y), [0])
        plt.contour(x, y, f2(x, y), [0])
        plt.grid(ls=':')

        r1, path_X, path_Y = solver(15.0, -30.0)
        plot(path_X, path_Y, '-o')
        r2, path_X, path_Y = solver(-5.0, -25.0)
        plot(path_X, path_Y, '-o')

        print(f'(x1, y1) = {[r1[0], r1[1]]}')
        print(f'(x2, y2) = {[r2[0], r2[1]]}')
        print(f'f1(x1, y1) = {f1(r1[0], r1[1])} = 0')
        print(f'f2(x2, y2) = {f2(r2[0], r2[1])} = 0')
```

```
(x1, y1) = [11.18748904356222, -24.966454635154953]
(x2, y2) = [-0.8168988581780426, -21.999943891219807]
f1(x1, y1) = 0.01203226882051922 ≈ 0
f2(x2, y2) = 0.00328099511466462 ≈ 0
```



### Дискретный метод Ньютона

```
In [7]: def discrete_solver(x_, y_, h=.001, iterations=3):
        x_curr = array([x_, y_])
        path_X, path_Y = [], []
        for i in range(iterations):
            x, y = x_curr[0], x_curr[1]
            J = [(f1(x+h, y) - f1(x, y))/h, (f1(x, y+h) - f1(x, y))/h],
                 [(f2(x+h, y) - f2(x, y))/h, (f2(x, y+h) - f2(x, y))/h]
            x_curr += Cramer(J, [-f1(x, y), -f2(x, y)])

            path_X.append(x)
            path_Y.append(y)

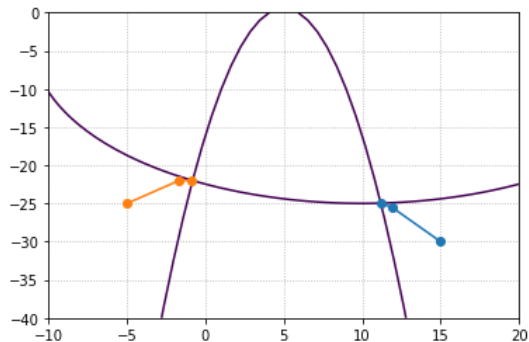
        return x_curr, path_X, path_Y
```

```
In [8]: x,y = meshgrid(np.linspace(-10,20, 50), np.linspace(-40,0, 50))
plt.contour(x,y,f1(x,y),[0])
plt.contour(x,y,f2(x,y),[0])
plt.grid(ls=':')

dr1, path_X, path_Y = discrete_solver(15.0,-30.0)
plot(path_X,path_Y,'-o')
dr2, path_X, path_Y = discrete_solver(-5.0,-25.0)
plot(path_X,path_Y,'-o')

print(f'(x1,y1)={dr1[0],dr1[1]}')
print(f'(x2,y2)={dr2[0],dr2[1]}')
print(f'f1(x1,y1) = {f1(dr1[0],dr1[1])} ≈ 0')
print(f'f2(x2,y2) = {f2(dr2[0],dr2[1])} ≈ 0')
```

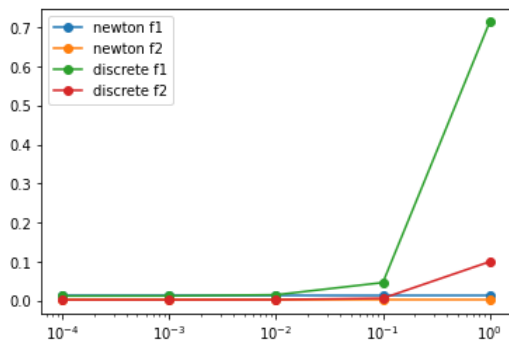
```
(x1,y1)=[11.187493192480334, -24.966455162664637]
(x2,y2)=[-0.8168936297634727, -21.999945663730106]
f1(x1,y1) = 0.0123355779611245 ≈ 0
f2(x2,y2) = 0.0032316948538095858 ≈ 0
```



```
In [9]: start_point = (15.0,-30.0)
H = [ .0001, .001, .01, .1, 1]

discrete = [[f1(*solver(*start_point)[0]),
              f2(*solver(*start_point)[0]),
              f1(*discrete_solver(*start_point, h)[0]),
              f2(*discrete_solver(*start_point, h)[0])] for h in H]

pl = plot(H, discrete, '-o')
plt.legend(iter(pl), ('newton f1','newton f2','discrete f1','discrete f2'));
plt.xscale('log',base=10)
```



Вывод: точность дискретного метода зависит от  $h$  (дельты), хотя если выбрать достаточно маленькую  $h$  то ответ будет не хуже настоящего.