ClassifierExperiment_new

March 13, 2016

```
In [1]: %load_ext autoreload
        %autoreload 2
        %matplotlib inline
        import numpy as np
        from libs import experiment
        from pandas import DataFrame
        from bpati import signals
        from libs.datafiles import *
        from libs.classifiers import *
        from libs import common, features
        from libs.arff import *
        from datetime import datetime
        datafiles = DataFiles(2)
        generics, smags, sangles = datafiles.get_smag()
        fn_sag_mode_events = common.get_precise_cycle_fault_signature()
Cfgmap loadad! (/mnt/qnap/BPATI_2014/2014.cmap)
Lazy Loading new-style data with 252454 minutes
No event data read 'eventdata'
PMUData SHA: b053a1359ab9e9ce1e6c43d6ca6cd9efa519d11e
In [2]: def experimental_classifier_plot(df, classifier, xline=True, filename='', xlim=None):
            ce, results, start_i, v_ss,_,_ = classifier.scan_df(df)
            experimental_plot(df, results, classifier.signal, classifier.smags, xline, xlim, filename=f
        def experimental_plot(df, results, signal, smags, xline, xlim, filename=''):
            if results == None or all([isnan(r) for r in results]):
                print 'No signals'
                return
            result_diff_i = []
            for idx, _class in enumerate(results):
                if len(result_diff_i) == 0 or idx == len(results) - 1:
                    result_diff_i.append(idx)
                    continue
                if results[idx-1] == _class: continue
                result_diff_i.append(idx)
            phase_a, phase_b, phase_c = smags
            dt = df['DateTime'].iloc[0]
            pyplot.figure(figsize=(12, 4), dpi=100)
```

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#pyplot.subplot(211)
    #pyplot.title('%s\nStarting At: %s\nOrange: SLG, Yellow: LtL, Blue: 3P, Purple: N/A' % (sig
    pyplot.xlabel('Cycles')
    pyplot.ylabel('Voltage (kV)\nA,B,C Phases in Red,Green,Blue')
   pyplot.plot(df.index, df[phase_a], 'g', label = 'A')
   pyplot.plot(df.index, df[phase_b], 'r--', label = 'B')
   pyplot.plot(df.index, df[phase_c], 'k:', label = 'C')
    pyplot.legend(loc='best', title='Phases')
    if xlim is not None: pyplot.xlim((xlim[0], xlim[1]))
    if xline:
        for idx in xrng: pyplot.axvline(idx, c='r', linestyle='--')
    base = df.index[0]
    for idx, start_span in enumerate(result_diff_i[:-1]):
        #if start_span > 38: continue
        if (results[start_span] == 0): color = {'color':'orange', 'alpha':.5}
        elif (results[start_span] == 1): color = {'color':'yellow', 'alpha':.5}
        elif (results[start_span] == 2): color = {'color':'blue', 'alpha':.5}
        elif (np.isnan(results[start_span])): color = {'color':'purple', 'alpha':.5}
        else: continue
        pyplot.axvspan(base + start_span, base + result_diff_i[idx+1], **color)
    if filename != '': pyplot.savefig(filename, format='pdf', bbox_inches='tight')
    pyplot.show()
   pyplot.close()
class BaseClassifyingExperimenter(object):
    class __Classification:
        def __init__(self):
            self.classification = []
            self.steady_states = []
            self.first_steady_state = {}
            self.updated_steady_state = []
        def first_update(self, experimenter, start_idx, start_i):
            self.first_steady_state[start_idx] = [experimenter.signaldata[mag] for mag in exper
            self.classification += [-1]*(start_i - start_idx)
            self.updated_steady_state += [False]*(start_i - start_idx)
            self.steady_states += [None]*(start_i - start_idx)
        def add(self, _class, ss, isupdated):
            self.classification.append(_class)
            self.steady_states.append(ss)
            self.updated_steady_state.append(isupdated)
        def __len__(self):
            return len(self.classification)
    def __init__(self, signal, smags, sangles, classifier_pickle):
        self.signal = signal
        self.smags = smags[signal]
        self.is2014data = common.check_2014_data(signal)
```

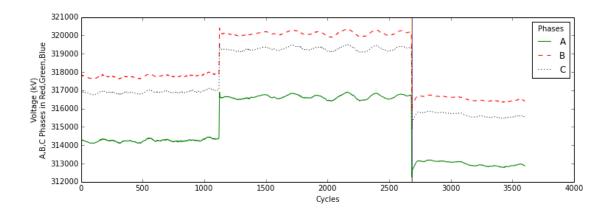
```
if not self.is2014data: self.sangles = sangles[signal.replace('Mag', 'Ang')]
    else: self.sangles = sangles[signal.replace('MAG', 'ANG')]
    self.nominal = signals.nominalvoltage(signal)
    self.signaldata = None
    self.datapoint = None
    self.first_signal_data = None
    self.classifier = EventClassifier.LoadPickle(classifier_pickle)
    self.last_datapoint_scan_datetime = None
    pass
# the function is to convert 2014 -> 2013 format
def convert_2014_data_(self, scan_df):
    df = {col: common.convert_2014_smag(scan_df[col].values) for col in self.smags}
    df.update({col: common.convert_2014_angs(scan_df[col].values) for col in self.sangles})
    df.update({'DateTime': scan_df['DateTime'].values})
    return DataFrame(data=df, index=scan_df.index.values)
#the function return the tuple: success, normal_voltages, starting point and ending point
def steady_state_(self, arr, extent = 10):
    assert self.signaldata is not None or len(arr) > extent, 'Scan window is too narrow'
    for starti in range(0, len(arr) - extent):
        window = arr[starti:starti + extent]
        #print 'check nan or window <=25', any(isnan(window)) or any(window <= 25)</pre>
        #print 'come heh', any(isnan(window)), any(window <= 25)</pre>
        if any(isnan(window)) or any(window <= 25): continue
        if self.is_steady_state_(window, True): return True, starti, starti + extent
    return False, starti, len(arr)
def is_steady_state_(self, voltages, edge_test):
    sagthresh=.9
    edgethresh=.01
    outofservice_threshold = 0.8
    w_mean, w_min = mean(voltages), min(voltages)
    edgemin = (1.0 - edgethresh) * w_mean
    edgemax = (1.0 + edgethresh) * w_mean
    return w_min > sagthresh*w_mean and w_mean >= outofservice_threshold * self.nominal and
            (not edge_test or (voltages[0] > edgemin and voltages[-1] > edgemin))
def update_first_window_(self, df, steady_states, base_idx, starti, extent_data_point = 1):
    self.signaldata = {key: array(df[key].loc[v_ss[1]+base_idx:v_ss[2]+base_idx-1])
                           for key, v_ss in zip(self.smags, steady_states)}
    self.signaldata.update({key: array(df[key].loc[v_ss[1]+base_idx:v_ss[2]+base_idx-1])
                            for key, v_ss in zip(self.sangles, steady_states)})
    self.datapoint = {key: array(df[key].loc[starti-extent_data_point:starti-1])
                          for key in self.signaldata}
def update_data_window(self, df, idx):
    for key in self.signaldata:
        self.signaldata[key] = append(delete(self.signaldata[key], 0), df[key][idx])
```

```
def reused_first_window_(self, dt):
    limitted_n_cycle_from_lastpoint = 2
    in_out_date = self.last_datapoint_scan_datetime is not None and \
            0 <= (dt - self.last_datapoint_scan_datetime).total_seconds() < 0.02 * limitted
    return in_out_date
def compute_starting_point_(self, df, base_idx):
    if self.reused_first_window_(df['DateTime'][base_idx]): return base_idx
    if any([col not in df for col in self.smags+self.sangles]): return -1
    # no scan before
    v_ss_info = [self.steady_state_(df[s].loc[base_idx:].values) for s in self.smags]
    starti = base_idx + max([v_ss[2] for v_ss in v_ss_info])
    if all([v_ss[0] for v_ss in v_ss_info]):
        self.update_first_window_(df, v_ss_info, base_idx, starti)
    return starti
def get_exporting_event_(self, df, idx, verbose=False):
    for s in self.signaldata:
       self.datapoint[s] = append(delete(self.datapoint[s], 0), df[s][idx])
       print '\tDatapoint'
       for k in self.datapoint: print '\t\t', k, self.datapoint[k]
    return ExportingEvent(self.signal, self.smags, self.sangles, self.datapoint, self.signa
# the function is a combination of logics to determine that the moment of time is appropria
# in this experiment, I would let the movement forward if the voltage is not less than 90%
# the sag threshod is equal to the one used in steady_state_
def is_safe_to_slide_(self, predict, v_a, v_b, v_c, verbose):
    ss_flags = [self.is_steady_state_(append(delete(self.signaldata[s], 0), v), False)
                    for v, s in zip([v_a, v_b, v_c], self.smags)]
    if verbose:
       print '\tSteady state flags:'
       for s, f in zip(self.smags, ss_flags): print '\t\t', s, f
    # if the last outcome is noFault, or is steady_state check is ok
    return predict == 3.0 and all(ss_flags)
def is_valid_ss_window_(self, dt):
    return True
# the function is an iteration if scan that should start at start_idx and break
#if ss window is out date time or until reach to end
def __scan_df_(self, df, start_idx, classification, verbose):
   start_i = self.compute_starting_point_(df, start_idx)
    if verbose: print 'Staring point: ', start_i
    if self.signaldata is None : return -1
    classification.first_update(self, start_idx, start_i)
    idx = start_i
    for idx in df.index[df.index >= start_i]:
       if not self.is_valid_ss_window_(df['DateTime'][idx]): break
```

```
if verbose:
           print 'At cycle', idx
            print '\tSteady state phase A', ss_a
            print '\tSteady state phase B', ss_b
            print '\tSteady state phase C', ss_c
        ee = self.get_exporting_event_(df, idx, verbose)
        self.last_datapoint_scan_datetime = df['DateTime'][idx]
        if ee.error:
            if verbose: print '\tSkip since the signal is unvailable'
            classification.add(nan, (ss_a, ss_b, ss_c), False)
            #print idx, len(results)
            continue
        # all success for ss computation
        x = {field.split()[0]: lambda_fn(ee)
                  for field, lambda_fn
                  in defaultfields if field.split()[0] in self.classifier.features()}
        if verbose:
           print '\tComputed features:'
            for k in x: print '\t\t', k, x[k]
        outcome_predict = self.classifier.predict_instance(x)
        update_ss = False
        # check to move
        if self.is_safe_to_slide_(outcome_predict, # recently predict outcome, test to bypa
                                      df[self.smags[0]][idx], # v_a
                                      df[self.smags[1]][idx], # v_b
                                      df[self.smags[2]][idx],
                                      verbose = verbose): # v_c
            if verbose: print '\tUpdating steady state', idx
            self.update_data_window(df, idx)
            update_ss = True
        else:
            if verbose: print '\tSkipping updating steady state', idx
        classification.add(outcome_predict, (ss_a, ss_b, ss_c), update_ss)
        if verbose: print '\tPrediction outcome:', outcome_predict
    return idx
# return a tuple as
    self: the object experiment which contains up to date signal data
    results: the predict outcome
    start_i: the start index of dataframe in which corespondents to the first predict outc
def scan_df(self, df, verbose = False):
    if self.is2014data:
        df = self.convert_2014_data_(df)
    df = df[self.smags + self.sangles + ['DateTime']]
    start_idx = df.index.values[0]
    result = self.__Classification()
    while(len(result.classification) < df.shape[0]):</pre>
        idx = self.__scan_df_(df, start_idx, result, verbose)
        if idx == -1: return None, None, None, None
```

ss_a, ss_b, ss_c = [mean(self.signaldata[s]) for s in self.smags]

```
start_idx = idx
                return result.classification, result.steady_states, result.first_steady_state, result.
        class ClassifyingExperimenter(BaseClassifyingExperimenter):
            pass
        class ConfigurableClassifyingExperimenter(BaseClassifyingExperimenter):
            def __init__(self, signal, smags, sangles, classifier_pickle):
                super(ConfigurableClassifyingExperimenter, self).__init__(signal, smags, sangles, class
                self.last_ss_scan_datetime = None
            def reused_first_window_(self, dt):
                return self.is_valid_ss_window_(dt)
            def update_data_window(self, df, idx):
                super(ConfigurableClassifyingExperimenter, self).update_data_window(df, idx)
                self.last_ss_scan_datetime = df['DateTime'][idx]
            def update_first_window_(self, df, steady_states, base_idx, starti):
                super(ConfigurableClassifyingExperimenter, self) update_first_window_(df, steady_states
                self.last_ss_scan_datetime = df['DateTime'][starti-1]
            # test the scan should be within datetime of steady state
            def is_valid_ss_window_(self, dt):
                limitted_n_cycle_from_ss = 3
                in_out_date = self.last_ss_scan_datetime is not None and \
                        0 <= (dt - self.last_ss_scan_datetime).total_seconds() < 0.02 * limitted_n_cycl
                return in_out_date
        class ContinuousClassifyingExperimenter(BaseClassifyingExperimenter):
            #the function return the tuple: success, normal_voltages, starting point and ending point
            def steady_state_(self, arr):
                return super(ContinuousClassifyingExperimenter, self).steady_state_(arr, 30)
            def is_safe_to_slide_(self, predict, v_a, v_b, v_c, verbose):
               return True
In [3]: signal = '' # signal name
        classifier = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pic
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[:]
       results, _, _, _ = classifier.scan_df(df, False)
        experimental_plot(df, results, classifier.signal, classifier.smags, False, None, '')
       print len(results)
```



3600

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In [4]: # test function
        signal = '' # signal name
        classifier = ClassifyingExperimenter(signal, smags, sangles, 'txt/EventClassifier_20160101.pick
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)
        results, v_ss, first_ss, updated_ss = classifier.scan_df(df, False)
        assert all([x == -1 \text{ for } x \text{ in results}[0:10]]), 'first ten cycles are equal to 10'
        assert all([x != -1 for x in results[10:]]), 'The ss window should not reset'
        assert len(results) == 3600 and len(updated_ss) == 3600, 'Failed to reach the end of window'
        assert len(classifier.signaldata[smags[signal][0]]) == 10, 'Over flow signal data'
        assert len(classifier.datapoint[smags[signal][0]]) == 1, 'Over flow signal data'
        # Test of resuing ss window
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 31), 0, 60)
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert results[0] != -1, 'Failed to reuse the window steady state'
        # Test of resuing ss window
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[1000:2000]
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert len(results) == 1000, 'Failed to reach the end of window'
        assert results[0] == -1, 'Begining of scan'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[2002:3002]
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert results[0] == -1, 'Failed since reusing the window steady state'
        assert len(results) == 1000, 'Failed to reach the end of window'
        # Test of not resuing ss window
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[1000:2000]
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert len(results) == 1000, 'Failed to reach the end of window'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[2011:3011]
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert results[0] == -1, 'Failed to reuse the window steady state'
        assert len(results) == 1000, 'Failed to reach the end of window'
```

```
print 'Pass'
Pass
In [5]: # test function
        signal = '' # signal name
        classifier = ClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pickle')
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)
        results, v_ss, first_ss, updated = classifier.scan_df(df, False)
        assert len(results) == 3600, 'Failed to reach the end of window'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 31), 0, 60)
        results, v_ss, first_ss, updated = classifier.scan_df(df, False)
        assert results[0] != -1, 'Failed to reuse the window steady state'
        print 'Pass'
Pass
In [6]: #test function
        signal = '' # signal name
        classifier = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pic
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)
        results, v_ss, _, _ = classifier.scan_df(df, False)
        assert all([x == -1 \text{ for } x \text{ in results}[2684:2684+10]]), 'start of reset scan should equal to -1'
        assert all([x == -1 \text{ for } x \text{ in results}[0:10]]), 'start of scan should equal to -1'
        assert all([x != -1 \text{ for } x \text{ in results}[10:2684]]), 'The other should not be -1'
        assert all([x != -1 \text{ for } x \text{ in results}[2684+10:]]), 'The other should not be -1'
        #test function
        signal = '' # signal name
        classifier = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pic
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 2, 30), 0, 60)[:]
        results, v_ss, first_ss, updated = classifier.scan_df(df, False)
        assert results is None, 'No data'
        assert v_ss is None, 'No data'
        assert first_ss is None, 'No data'
        assert updated is None, 'No data'
        print 'PASS'
PASS
In [7]: #test function
        signal = '' # signal name
        experimenter = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.p
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 56), 0, 1*60)[1950:1985]
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        #experimental_plot(df, classification, signal, smags[signal], False, filename='', xlim=None)
        assert len(classification) == 35, 'Data failed'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 56), 0, 1*60)[1985:]
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        #experimental_plot(df, classification, signal, smags[signal], False, filename='', xlim=None)
```

```
classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        #experimental_plot(df, classification, signal, smags[signal], False, filename='', xlim=None)
        assert classification[0] == -1, 'reestablish ss window'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 56), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        #experimental_plot(df, classification, signal, smags[signal], False, filename='', xlim=None)
        assert classification[0] == -1, 'reestablish ss window'
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 57), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        assert classification[0] != -1, 'reuse ss window'
        print 'PASS'
PASS
In [8]: signal = '' # signal name
        experimenter = ContinuousClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pic
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 56), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        assert len(classification) == 3600, 'Failed since not reaching end of window'
        assert len([x for x in classification if x == -1]) == 30, 'Failed since not reaching end of win
        assert len([x for x in classification if x \ge 0]) == 3600-30, 'Failed since not reaching end of
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 57), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        assert len(classification) == 3600, 'Failed since not reaching end of window'
        assert len([x \text{ for } x \text{ in classification if } x == -1]) == 0, 'Failed since not reaching end of wind
        assert len([x \text{ for } x \text{ in classification if } x >= 0]) == 3600, 'Failed since not reaching end of wi
        print 'PASS'
PASS
In [9]: signal = '' # signal name
        experimenter = ContinuousClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pic
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 3, 58), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        assert len(classification) == 3600, 'Failed since not reaching end of window'
        assert len([x \text{ for } x \text{ in classification if } x == -1]) == 30, 'Failed since not reaching end of win
        assert all([np.isnan(x) for x in classification[1500:1559]]), 'Failed since not reaching end of
        experimenter = ClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.pickle')
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 3, 58), 0, 1*60)
        classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(
        assert len(classification) == 3600, 'Failed since not reaching end of window'
        assert len([x for x in classification[0:10] if x == -1]) == 10, 'Failed since not reaching end
        assert all([np.isnan(x) for x in classification[1500:1559]]), 'Failed since not reaching end of
        experimenter = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/J48Classifier.p
        df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 3, 58), 0, 1*60)
```

assert classification[0] == -1, 'reestablish ss window'

df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 23, 56), 0, 1*60)[3000:]

```
assert len(classification) == 3600, 'Failed since not reaching end of window'
       assert len([x for x in classification[0:10] if x == -1]) == 10, 'Failed since not reaching end
        assert all([np.isnan(x) for x in classification[1500:1503]]), 'Failed since not reaching end of
        assert all([x == -1 for x in classification[1503:1559]]), 'Failed since not reaching end of win
       print 'PASS'
PASS
In [10]: signal = '' # signal name
         experimenter = ConfigurableClassifyingExperimenter(signal, smags, sangles, 'txt/one_vs_one_cla
         df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 0, 22), 0, 1*60)
         classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df
         assert len(classification) == 3600, 'Failed since not reaching end of window'
         df = datafiles.pmudata.dataframe(datetime(2014, 10, 5, 0, 23), 0, 1*60)
         classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df
         assert len(classification) == 3600, 'Failed since not reaching end of window'
         assert len(steady_states) == 3600, 'Failed since not reaching end of window'
         assert len([x for x in classification if x == -1]) == len([x for x in steady_states if x is No.
        print 'PASS'
PASS
```

classification, steady_states, first_steady_state, updated_steady_state = experimenter.scan_df(

In []: