## 0.6 Graphical models

## 0.6.1 Gibbs' Sampling from an discrete undirected model

```
Algorithm 35: Gibbs' sampling from undirected model
Input : Potential functions \{\phi_c[\mathcal{S}_c]\}_{c=1}^C
Output: Samples \{\mathbf{x}_t\}_1^T
begin
     // Initialize first sample in chain
    \mathbf{x}_0 = \mathbf{x}^{(0)}
     // For each time sample
     for t=1 to T do
          \mathbf{x}_t = \mathbf{x}_{t-1}
          // For each dimension
          for d=1 to d do
               // For each possible value
               for k=1 to K do
                   \lambda_k = 1
                    x_{td} = k
                    for c such that d \in \mathcal{S}_c do
                        \lambda_k = \lambda_k \phi_c [\mathcal{S}_c]
                    end
              \lambda = \lambda / \sum_{k=1}^{K} \lambda_k
               // Draw from categorical distribution
               x_{td} = \mathsf{DrawFromCategorical}[\boldsymbol{\lambda}]
          \mathbf{end}
     end
end
```

It is normal to discard the first few thousand entries so that the initial conditions are forgotten. Then entries are chosen that are spaced apart to avoid correlation between the samples.