



Gitee: https://gitee.com/MindSpore/toolkits/tree/master/troubleshooter

网络迁移_ (migrator)

pth权重迁移

ckpt校验

数据保存/比较

网络正向自动输出比较

从PyTorch网络迁移到MindSpore网络时,两者的ckpt文件的编码不同,无法直接加载,需要权重转换。

MindSpore的API实现细节上与PyTorch不同,权重名称与PyTorch有差异(例如norm层中的weight和gamma等)。

为提高网络迁移易用性, troubleshooter提供了完备的权重转换工具。

网络结构完全一致,权重自动转换

import troubleshooter as ts

2023-01-04 14:50:57,529 - troubleshooter.log - WARNING - [*User Attention*] The PTH has been converted to the checkpoint of MindSpore. Please check whether the conversion result is correct. The saved path is: ./convert_resnet.ckpt

The list of conversion result

Parameter name of pth
Parameter name of converted ckpt
Whether the name is converted
Parameter shape of pth

Parameter name of pth	Parameter name of converted ckpt	Whether the name is converted	Parameter shape of pth
conv1.weight	conv1.weight	False	torch.Size([64, 3, 7, 7])
bn1.weight	bn1.gamma	True	torch.Size([64])
bn1.bias	bn1.beta	True	torch.Size([64])
bn1.running_mean	bn1.moving_mean	True	torch.Size([64])
bn1.running_var	bn1.moving_variance	True	torch.Size([64])
bn1.num_batches_tracked	bn1.num_batches_tracked	False	torch.Size([])
layer1.0.conv1.weight	layer1.0.conv1.weight	False	torch.Size([64, 64, 1, 1])
layer1.0.bn1.weight	layer1.0.bn1.gamma	True	torch.Size([64])
layer1.0.bn1.bias	layer1.0.bn1.beta	True	torch.Size([64])
layer1.0.bn1.running_mean	layer1.0.bn1.moving_mean	True	torch.Size([64])
layer1.0.bn1.running_var	layer1.0.bn1.moving_variance	True	torch.Size([64])
layer1.0.bn1.num_batches_tracked	layer1.0.bn1.num_batches_tracked	False	torch.Size([])
layer1.0.conv2.weight	layer1.0.conv2.weight	False	torch.Size([64, 64, 3, 3])
layer1.0.bn2.weight	layer1.0.bn2.gamma	True	torch.Size([64])
layer1.0.bn2.bias	layer1.0.bn2.beta	True	torch.Size([64])
layer1.0.bn2.running_mean	layer1.0.bn2.moving_mean	True	torch.Size([64])
layer1.0.bn2.running_var	layer1.0.bn2.moving_variance	True	torch.Size([64])
layer1.0.bn2.num_batches_tracked	layer1.0.bn2.num_batches_tracked	False	torch.Size([])
layer1.0.conv3.weight	layer1.0.conv3.weight	False	torch.Size([256, 64, 1, 1]
layer1.0.bn3.weight	layer1.0.bn3.gamma	True	torch.Size([256])

网络结构有一定差异,需要定制权重名称前缀

```
import troubleshooter as ts
# pytorch的resnet50网络
torch net = resnet50(num classes=10)
pth path="./resnet.pth"
# weight name prefix: 需要添加的权重前缀
ts.migrator.get weight map(pt model=torch net,
                          weight map save path="/tmp/torch net map.json",
                          weight_name_prefix='uvp'
                          print map=True)
# 调用转换接口
ts.migrator.convert_weight(weight_map_path="/tmp/torch_net_map.json",
                          pt file path="/tmp/torch net.pth",
                          ms file save path='/tmp/convert_resnet.ckpt')
```

获得根据默认规则转换后的map,之后执行自定义函数,

进行自定义的修改。

网络结构有一定差异,需要对权重名称做复杂的定制转换

```
import troubleshooter as ts

def custorm_weight_name(weight_name_map):
    prefix='.custorm.'
    custorm_name_map = {}
    for key, value in weight_name_map.items():
        index = value.find(".")
        value = value[0:index] + prefix + value[index+1:]
        print(key, ":", value)
        custorm_name_map[key] = str(value)
    return custorm_name_map
```

```
# pytorch的resnet50网络
torch net = resnet50(num classes=10)
pth path="./resnet.pth"
custom name func: 可封装定制函数,例如: custorm_weight_name, 完成映射关系的定制
ts.migrator.get weight map(pt model=torch net,
                         weight_map_save_path="/tmp/torch_net_map.json",
                          custom name func=custorm weight name,
                          print map=True)
# 调用转换接口
ts.migrator.convert weight(weight map path="/tmp/torch net map.json",
                         pt file path="/tmp/torch net.pth",
                         ms file save path='/tmp/convert resnet.ckpt')
```

执行结果:根据定制所有参数名称增加一个层custorm ,例如:features.Linear_mm.weight 参数名称将转换为features.custorm.Linear_mm.weight

转换后的ckpt与MindSpore比较校验

将网络生产的ckpt与转换的ckpt (用权重转换工具从pth转换过来的ckpt) 进行对

+				+
!	The list	t of comparison results		. !
Parameter name of input ckpt	Parameter name of converted ckpt	Whether shape are equal	Parameter shape of input ckpt	Parameter shape of converted ckpt
	conv1.weight	True	(64, 3, 7, 7)	(64, 3, 7, 7)
bn1.moving_mean	bn1.moving_mean	True	(64,)	(64,)
bn1.moving_variance	bn1.moving_variance	True	(64,)	(64,)
bn1.gamma	bn1.gamma	True	(64,)	(64,)
bn1.beta	bn1.beta	True	(64,)	(64,)
layer1.0.conv1.weight	layer1.0.conv1.weight	True	(64, 64, 1, 1)	(64, 64, 1, 1)
layer1.0.bn1.moving_mean	layer1.0.bn1.moving_mean	True	(64,)	(64,)
layer1.0.bn1.moving variance	layer1.0.bn1.moving variance	True	(64,)	(64,)
layer1.0.bn1.gamma	layer1.0.bn1.gamma	True	(64,)	(64,)
layer1.0.bn1.beta	layer1.0.bn1.beta	True	(64,)	(64,)
layer1.0.conv2.weight	layer1.0.conv2.weight	True	(64, 64, 3, 3)	(64, 64, 3, 3)
layer1.0.bn2.moving_mean	layer1.0.bn2.moving_mean	True	(64,)	(64,)
layer1.0.bn2.moving_variance	layer1.0.bn2.moving_variance	True	(64,)	(64,)
layer1.0.bn2.gamma	layer1.0.bn2.gamma	True	(64,)	(64,)
layer1.0.bn2.beta	layer1.0.bn2.beta	True	(64,)	(64,)
layer1.0.conv3.weight	layer1.0.conv3.weight	True	(256, 64, 1, 1)	(256, 64, 1, 1)
layer1.0.bn3.moving_mean	layer1.0.bn3.moving_mean	True	(256,)	(256,)
layer1.0.bn3.moving_variance	layer1.0.bn3.moving_variance	True	(256,)	(256,)
layer1.0.bn3.gamma	layer1.0.bn3.gamma	True	(256,)	(256,)
layer1.0.bn3.beta	layer1.0.bn3.beta	True	(256,)	(256,)
laver1.0.downsample.0.weight	laver1.0.downsample.0.weight	j True	(256, 64, 1, 1)	(256, 64, 1, 1)

ts.migrator.compare_pth_and_ckpt(weight_map_path, pth_path, ms_path)

在网络迁移精度问题排查时,需要对网络中的数据进行保存。

原始方案:

- 1. 静态图中在网络中使用print (实际调用ops.Print()算子),对tensor进行打印 难以对大量数据进行输出,难以保存供后续对比使用。
- 2. 使用TensorSummary接口保存到summary文件 必须和SummaryRecord或SummaryCollector—起使用,学习成本 高。

troubleshooter提供了支持MindSpore和PyTorch统一的数据保存接口 **ts.save**

可以将tensor存储数据为numpy,方便后续统一比较。(适配2.0正式版)

易用性:

- 1. 支持PyTorch和MindSpore (pynative/图模式),自动识别数据类型。
- 2. 支持保存tensor, list[tensor]/tuple[tensor]/dict[str, tensor]
- 3. 支持自动编号功能,多个迭代文件不覆盖。

接口定义

```
ts.save(file:str, data:Union(Tensor, list[Tensor], tuple[Tensor], dict[str, Tensor], auto_id=True, suffix=None))
```

- file: 文件名路径。当 file 为 None 或 '' 时,文件名会自动设置为 tensor_(shape),文件路径为当前路径。
- data: 数据,支持保存 Tensor (包括 mindspore.Tensor 和 pytorch.tensor),以及 Tensor 构成的 list/tuple/dict。当为 list/tuple 类型时,会按照顺序添加编号;当为 dict 类型时,文件名中会添加 key。
- auto_id: 自动编号,默认值为 True 。当为 True 时,保存时会自动为文件添加全局编号,编号从0开始。
- suffix: 文件名后缀,默认值为 None。

文件保存格式

存储的文件名称为 {id}_name_{idx/key}_{suffix}.npy

MindSpore

```
import os
import shutil
import troubleshooter as ts
import mindspore as ms
from mindspore import nn, Tensor
class NetWorkSave(nn.Cell):
    def init (self, file):
        super(NetWorkSave, self). init ()
        self.file = file
   def construct(self, x):
        ts.save(self.file, x)
        return x
x1 = Tensor(-0.5962, ms.float32)
x2 = Tensor(0.4985, ms.float32)
try:
    shutil.rmtree("/tmp/save/")
except FileNotFoundError:
    pass
os.makedirs("/tmp/save/")
net = NetWorkSave('/tmp/save/ms tensor')
```

```
x1 = Tensor(-0.5962, ms.float32)
x2 = Tensor(0.4985, ms.float32)
try:
   shutil.rmtree("/tmp/save/")
except FileNotFoundError:
   pass
os.makedirs("/tmp/save/")
net = NetWorkSave('/tmp/save/ms tensor')
# 支持自动编号
out1 = net(x1)
                          支持自动编号
# /tmp/save/0 ms tensor.npy
out2 = net(x2)
# /tmp/save/1_ms_tensor.npy 支持tensor/list/dict多种数据格式
out3 = net([x1, x2])
# /tmp/save/2 ms tensor 0.npy
# /tmp/save/2 ms tensor 1.npy
out4 = net({"x1": x1, "x2":x2})
# /tmp/save/3 ms tensor x1.npy
# /tmp/save/3 ms tensor x2.npy
```

file = '/tmp/save/torch tensor'

PyTorch

```
import os
                                                       ts.save(file, x1)
import shutil
                                                       # /tmp/save/0 torch tensor.npy
                                                       ts.save(file, x2)
import troubleshooter as ts
                                                       # /tmp/save/1_torch_tensor.npy
import torch
x1 = torch.tensor([-0.5962, 0.3123], dtype=torch.float32)
                                                       ts.save(None, {"x1":x1, "x2":x2}, suffix="torch")
x2 = torch.tensor([[0.4985], [0.4323]], dtype=torch.float32)
                                                      # ./2_tensor_(2,)_x1_torch.npy
                                                      # ./2 tensor (2, 1) x2 torch.npy
try:
   shutil.rmtree("/tmp/save/")
except FileNotFoundError:
                                                       当file为空时, 会为文件自动命名为
   pass
os.makedirs("/tmp/save/")
                                                      tensor {data.shape}
```

数据比对接口

进行网络迁移精度问题排查等场景,需要获取网络中的tensor值进行比较。

一般我们将tensor保存成npy进行手工比较,此功能提供了批量对比两个目录下名称可以映射的npy值的接口。

数据比对接口

直接映射

ta

```
import troubleshooter as ts
 ta = "/mnt/d/06_project/troubleshooter/troubleshooter/tests/diff_handler/ta"
 tb = "/mnt/d/06_project/troubleshooter/troubleshooter/tests/diff_handler/tb"
 # 比较ta与tb目录下名称可以映射的npy文件的值
 ts.migrator.compare npy dir(ta, tb)
The orig dir: /tmp/troubleshooter_ta/
The target dir: /tmp/troubleshooter_tb/
                                        The list of comparison results
              target array name | results of comparison | match ratio | cosine similarity
                                                                                   (mean, max, min)
orig array name
                 data1.npy
   data1.npy
                                                   100.00
                                                                1.00000
                                     True
   data2.npy
                 data2.npy
                                    False
                                                   83.33
                                                                0.99924
                                                                            ['0.013382',
                                                                                      '0.080290', '0.000000']
          tb
                     allclose结果
                                      allclose的正确率
                                                       余弦相似度
                                                                               差异值的指标
                                      allclose成功数/总数量
```

数据比对接口

两个目录下名称不能完全映射,需要手工调整

```
import troubleshooter as ts
ta = "/mnt/d/06 project/troubleshooter/troubleshooter/tests/diff handler/ta"
tb = "/mnt/d/06_project/troubleshooter/troubleshooter/tests/diff_handler/tb"
# 可以通过如下接口获取名称映射列表,对npy文件名称映射进行调整
name_list = ts.migrator.get_filename_map_list(ta, tb)
# 通过自定定义一个函数进行list的修改, 例如: custom fun (name list)
name_list = custom_fun(name_list)
# 将调整后的名称传入比较接口
ts.migrator.compare_npy_dir(name_map_list=name_list)
```

name_list为经过自动映射的列表,类型为list[tuple(str, str)],例如[(a.npy, a.npy), (b.npy, b.npy),...]。可以通过调整name_list进行自定义映射和比较。

网络正向结果自动比对

比较MindSpore和PyTorch网络输出是否一致

从PyTorch在迁移到MindSpore过程中,可能存在网络输出精度不一致的情况。需要比较MindSpore和PyTorch网络输出结果是否一致。

此功能实现控制随机性(结果可复现),使用相同数据或自动生成随机数据,多轮对比MindSpore和PyTorch的输出结果。

网络正向结果自动比对

比较MindSpore和PyTorch网络输出是否

接口参数

参数	类型	说明
ms_net	mindspore.nn.Cell	mindspore模型实例
pt_net	torch.nn.Module	torch模型实例
input_data	单输入: Union(tuple[torch.tensor], tuple[mindspore.Tensor], tuple[numpy.ndarray], tuple[str]); 多输入: list[Union(tuple[torch.tensor], tuple[mindspore.Tensor], tuple[numpy.ndarray], tuple[str])]	模型输入。模型输入支持 torch.Tensor, mindspore.Tensor, np.ndarray 以及 str,每个 tuple 中包含一个模型输入;当用户想要同时验证 多组数据时,请使用一个列表存放所有输入。
auto_input_data	单输入: tuple[tuple[numpy.shape, numpy.dtype]]; 多输入: {'input': tuple[tuple[numpy.shape, numpy.dtype]], 'num':int}	默认为 None ,为了方便用户快速验证。用户可以不输入 input_data ,而是输入 auto_input_data ,auto_input_data 每一个元素为模型输入的 shape ,如果需要使用多次测试,可以传入一个字典,字典的键为 'input' 和 'num' ,分别表示每次的输入以及输入个数

网络正向结果自动比对

比较MindSpore和PyTorch网络输出是否

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可以参考troubleshooter/tests/diff_handler/test_netdifffinder.py中的使用方法,或者下面的使用方法:

```
pt_net = ConstTorch()
ms_net = ConstMS()
diff_finder = ts.migrator.NetDifferenceFinder(
    pt_net=pt_net,
    ms_net=ms_net,
    auto_input=(((1, 12), np.float32), ))
diff_finder.compare()
```

输出结果:

Saved MindSpore output data at: /Volumes/Samsung_T5/实习/mindspore实习/网络输出结果进行精度比对/toolkits/data/output/MindSpore/result.npy
Saved PyTorch output data at: /Volumes/Samsung_T5/实习/mindspore实习/网络输出结果进行精度比对/toolkits/data/output/PyTorch/result.npy

The comparison results of Net					
pt data	ms data	results of comparison	match ratio	cosine similarity	(mean, max, min)
test0-result	test0-result	False	0.00	0.99600	['0.400000', '0.400000', '0.400000']

在线异常建议

故障分析_ (proposer)

离线报错分析

简洁调用栈

自动生成报错处理建议(在线分析)

结果展示:

```
MindSpore FAR(Failure Analysis Report)
    项目
             描述
 版本信息:
             r1.9
              Graph Mode
              CPU
              静态图的控制流(例如:if...else...)语法要求不同分支返回值的shape相同,不相同时会报错。
示例错误代码:
              > def construct(self, x, a, b):
                   if a > b:
                      return self.relu(x)
                   else:
                      # shape: (*)->()
                      return self.reducesum(x)
                          ^~~~~返回值shape与if分支不一致
              检查不同分支的返回结果的shape,如果不相同,请修改至相同shape
 处理建议:
 相关案例:
              1. 编译时报错Shape Join Failed案例:
              https://www.mindspore.cn/docs/zh-CN/r1.9/fag/network_compilation.html
              2.静态图语法:
              https://www.mindspore.cn/docs/zh-CN/r1.9/note/static_graph_syntax_support.html
    ID:
              compiler_id_9
```

自动生成报错处理建议(在线分析)

return self.reducesum(x) # shape:(), dype: Float32

使用方法1 使用装饰器@ts.proposal()

```
import numpy as np
                                                 # 通过装饰器,装饰在执行函数前
import mindspore
from mindspore import ops, Tensor, nn
                                                 @ts.proposal()
import troubleshooter as ts
                                                 def main():
                                                     input x = Tensor(np.random.rand(2, 3, 4, 5).astype(np.float32))
                                                     input a = Tensor(2, mindspore.float32)
class Net(nn.Cell):
                                                     input b = Tensor(6, mindspore.float32)
   def init (self):
                                                     net = Net()
       super(). init ()
                                                     out = net(input x, input a, input b)
       self.relu = ops.ReLU()
       self.reducesum = ops.ReduceSum()
   def construct(self, x, a, b):
       if a > b:
           return self.relu(x) # shape: (2, 3, 4, 5), dtype:Float32
       else:
```

自动生成报错处理建议(在线分析)

使用方法2 使用with ts.proposal()

```
import numpy as np
                                      # 诵讨with 来实现片段代码分析
import mindspore
                                      with ts.proposal():
from mindspore import ops, Tensor, nn
                                           input x = Tensor(np.random.rand(2, 3, 4, 5).astype(np.float32))
import troubleshooter as ts
                                           input a = Tensor(2, mindspore.float32)
                                           input b = Tensor(6, mindspore.float32)
class Net(nn.Cell):
                                           net = Net()
   def init (self):
                                           out = net(input x, input a, input b)
      super(). init ()
       self.relu = ops.ReLU()
       self.reducesum = ops.ReduceSum()
   def construct(self, x, a, b):
      if a > b:
          return self.relu(x) # shape: (2, 3, 4, 5), dtype:Float32
       else:
          return self.reducesum(x) # shape:(), dype: Float32
```

已生成的报错自动分析(离线分析)

import troubleshooter as ts

将MindSpore的报错信息,从第一个Traceback (most recent call last): 到最后一行打印的信息,全部拷贝到字符串中,使用raise抛出,即可被proposal捕获并分析。

```
@ts.proposal()
def main():
    error = """
    Traceback (most recent call last):
      File "/mnt/d/06_project/trouble-shooter/examples/proposal_demo_1.py", line 25, in <module>
        out = net(input x, input a, input b)
      File "/root/envs/lib/python3.7/site-packages/mindspore/nn/cell.py", line 596, in call
        out = self.compile and run(*args)
      File "/root/envs/lib/python3.7/site-packages/mindspore/nn/cell.py", line 985, in compile and run
        self.compile(*inputs)
      File "/root/envs/lib/python3.7/site-packages/mindspore/nn/cell.py", line 957, in compile
        jit config dict=self. jit config dict)
      File "/root/envs/lib/python3.7/site-packages/mindspore/common/api.py", line 1131, in compile
        result = self. graph executor.compile(obj, args list, phase, self. use vm mode())
    ValueError: Cannot join the return values of different branches, perhaps you need to make them equal.
    Shape Join Failed: shape1 = (2, 3, 4, 5), shape2 = ().
    For more details, please refer to https://www.mindspore.cn/search?inputValue=Shape%20Join%20Failed
    - C++ Call Stack: (For framework developers)
   mindspore/ccsrc/pipeline/jit/static analysis/static analysis.cc:850 ProcessEvalResults
    ....
    raise ValueError(error)
```

显示简洁异常调用栈(删除部分框架栈信息)

部分框架内部栈信息会影响用户阅读调用栈,此功能以黑名单方式过滤掉部分栈信息,使 网络调用株式 Traceback (most recent call last):

```
[TroubleShooter-Clear Stack] Python Traceback (most recent call last):
Traceback (most recent call last):
 File "/mnt/d/06_project/trouble-shooter/tests/bak/tracker/bak/test_lenet.py", line 52, in test_lent
   out = net(x)
 File "/mnt/d/06_project/trouble-shooter/tests/bak/tracker/bak/test_lenet.py", line 39, in construct
   x = self.fc1(x)
 File "/root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/nn/layer/basic.py", line 555, in construct
   x = self.matmul(x, self.weight)
 File "/root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/ops/primitive.py", line 794, in _run_op
    output = _pynative_executor.real_run_op(obj, op_name, args)
 File "/root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/ops/operations/math_ops.py", line 1473, in check_shape
    raise ValueError(f"For '{cls_name}', the input dimensions must be equal, but got 'x1_col': {x1_col} "
ValueError: For 'MatMul', the input dimensions must be equal, but got 'x1_col': 144 and 'x2_row': 400. And 'x' shape [1, 144](transp
```

File "/root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/ops/primitive.py", line 494, in __check__
fn(*(x[track] for x in args))

File "/root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/ops/operations/math_ops.py", line 1473, in check_shape
raise ValueError(f"For '{cls_name}', the input dimensions must be equal, but got 'x1_col': {x1_col} "

ValueError: For 'MatMul', the input dimensions must be equal, but got 'x1_col': 144 and 'x2_row': 400. And 'x' shape [1, 144](transp

开启后

显示简洁异常调用栈(删除部分框架栈信息)

如何使用

配置print_clear_stack=True参数 (默认False)

```
@ts.proposal(print_clear_stack=True)
def test_lent():
    context.set_context(mode=context.PYNATIVE_MODE, device_target="CPU")
    x = np.arange(1 * 24 * 24).reshape(1, 1, 24, 24)
    x = Tensor(x, ms.float32)
    net = LeNet5()
    out = net(x)
```

跟踪调试 (tracker)

网络运行信息

获取INF/NAN值抛出点

黑白名单过滤追踪信息

跟踪API报错详细执行过程

跟踪调试

在网络问题定位中,例如算子shape报错/结果出现nan值等场景时,通常需要进行pdb调试、查看调用栈等手段。

troubleshooter提供了跟踪网络执行的tracking功能,可以跟踪实际执行过程,打印丰富的执行信息。(当前仅对pynative模式和图模式下的 Python阶段有效)

网络运行信息(结构、shape)

效果

```
========= Starting Training ==========
19:51:02.074695 call
                                 def construct(self, x):
                                     x = self.transpose(x, (0, 3, 1, 2))
19:51:02.075004 line
19:51:02.192380 line
19:51:02.230425 line
19:51:02.273478 line
19:51:02.286534 line
19:51:02.299206 line
19:51:02.303392 line
19:51:02.305934 line
19:51:02.306866 line
19:51:02.382671 line
19:51:02.411025 line
19:51:02.427581 line
19:51:02.435671 line
19:51:02.436213 return
```

网络运行信息(结构、shape) 使用方式:

import mindspore.nn as nn from mindspore import ops from mindspore.common.initializer import Normal import troubleshooter as ts class LeNet5(nn.Cell): def __init__(self, num_class=10, num_channel=1, include_top=True): super(LeNet5, self).__init__() self.conv1 = nn.Conv2d(num_channel, 6, 5, pad_mode='valid') self.conv2 = nn.Conv2d(6, 16, 5, pad_mode='valid') self.relu = nn.ReLU() self.max_pool2d = nn.MaxPool2d(kernel_size=2, stride=2) self.include_top = include_top self.transpose = ops.Transpose() if self.include_top: self.flatten = nn.Flatten()

self.fc1 = nn.Dense(16 * 5 * 5, 120, weight init=Normal(0.02))

self.fc3 = nn.Dense(84, num class, weight init=Normal(0.02))

self.fc2 = nn.Dense(120, 84, weight init=Normal(0.02))

1. 使用装饰器 @ts.tracking()

```
# 跟踪construct函数执行
@ts.tracking()
def construct(self, x):
   x = self.transpose(x, (0, 3, 1, 2))
   x = self.conv1(x)
   x = self.relu(x)
   x = self.max pool2d(x)
   x = self.conv2(x)
   x = self.relu(x)
   x = self.max pool2d(x)
   if not self.include top:
        return x
   x = self.flatten(x)
   x = self.relu(self.fc1(x))
   x = self.relu(self.fc2(x))
   x = self.fc3(x)
    return x
```

2. 使用with

```
ts. tracking() x):
   x = self.transpose(x, (0, 3, 1, 2))
   x = self.conv1(x)
   x = self.relu(x)
   x = self.max pool2d(x)
   x = self.conv2(x)
   x = self.relu(x)
   # 使用with 仅打印部分输出
   with ts.tracking():
       x = self.max pool2d(x)
       if not self.include top:
           return x
       x = self.flatten(x)
       x = self.relu(self.fc1(x))
       x = self.relu(self.fc2(x))
       x = self.fc3(x)
   return x
```

获取INF/NAN值抛出点

效果展示

x = self.sqrt(y) 出现 nan, 给出 "User Warning 'nan' is detected"报错。

进程工作中 沿出化和。

获取INF/NAN值抛出点 使用方法:

使用ts.tracking的 "check_keyword"参数

- check_keyword: 用于设置需要检查的值
- check_mode: 用于设置检查模式,1:检查到值即退出并打印用户告警日志(默认),2:检查到值不退出,仅打印用户告警日志

```
import mindspore
import numpy as np
from mindspore import nn, ops, Tensor
import troubleshooter as ts
mindspore.set_context(mode=mindspore.PYNATIVE_MODE)
class Net(nn.Cell):
   def init (self):
       super(). init ()
       self.sqrt = ops.Sqrt()
        self.matmul = ops.MatMul()
   def construct(self, input x):
       y = self.matmul(input x, input x)
       x = self.sqrt(y)
       return x
```

```
# 配置检查值
@ts.tracking(check_mode=1, check_keyword='nan')
def nan_func():
    input_x = Tensor(np.array([[0.0, -1.0], [4.0, 3.0]]))
    k = 3.0
    net = Net()
    print(net(input_x))
nan_func()
```

按照路径黑白名单过滤跟踪信息

结果展示:

配置路径白名单,仅跟踪'layer/conv.py'文件中的代码

按照路径黑白名单过滤跟踪信息

方法1: 使用ts.tracking的"path_wl"白名单参数

```
import mindspore
import numpy as np
from mindspore import nn, ops, Tensor
import troubleshooter as ts
mindspore.set context(mode=mindspore.PYNATIVE MODE)
# 使用path wl白名单,仅打印白名单文件中的代码跟踪
@ts.tracking(level=1, path_wl=['layer/conv.py'])
def main():
   conv = nn.Conv2d(3, 2, 3, pad_mode='valid', weight_init="ones")
   relu = nn.ReLU()
   seq = nn.SequentialCell([conv, relu])
   x = Tensor(np.ones([1, 3, 4, 4]), dtype=mindspore.float32)
```

按照路径黑白名单过滤跟踪信息

方法2: 使用ts.tracking的"path_bl"黑名单参数

```
# 黑名单与level 可同时使用,先通过level过滤,再通过黑名单过滤@ts.tracking(level=2, color=False, path_bl=['layer/activation.py'])
def main():
    context.set_context(mode=context.PYNATIVE_MODE)
    conv = nn.Conv2d(3, 2, 3, pad_mode='valid', weight_init="ones")
    relu = nn.ReLU()
    seq = nn.SequentialCell([conv, relu])
    x = Tensor(np.ones([1, 3, 4, 4]), dtype=mindspore.float32)
    output = seq(x)
    print(output)
```

跟踪API报错的详细执行过程

当API报错时,我们仅能看到有限的堆栈信息,有时需要了解API的调用流程和参数传递&变化过程,以定位报错的原因,此场景下,可以应用tracking功能进行错误跟踪。

跟踪可以通过level参数控制跟踪信息

- •level=1(默认) 仅跟踪用户脚本中的construct函数
- •level=2 跟踪用户脚本以及MindSpore主要的Python执行代码
- •level=3 跟踪用户脚本以及MindSpore的全部Python执行代码
- •level=4 跟踪用户脚本、MindSpore、Python库以及第三方包的所有Python执行代码

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跟踪API报错的详细执行过程

案例

3)结合代码和跟踪信息可知,self.weight是根据dense的参数in_channels和out_channels决定的,定位到问题原因。

```
18:11:51.547729 line 46 fn(self, *args, **kwargs)

Source path:... /root/miniconda3/envs/miaoym/lib/python3.7/site-packages/mindspore/nn/layer/basic.py
Starting var:.. self = REPR FAILED

Starting var:.. in_channels = 5

Starting var:.. but_ohannels = 4

Starting var:.. weight_init = 'normal'

Starting var:.. bias_init = 'zeros'

Starting var:.. has_bias = True

Starting var:.. activation = None

Starting var:.. __class__ = <class 'mindspore.nn.layer.basic.Dense'>
```

Next:

反向精度定位

API级别精度自动比对

静态图API级别数据保存

• • •

欢迎加入我们,共同提高MindSpore易用性!

Gitee:

https://gitee.com/MindSpore/toolkits/tree/master/troubleshooter

Thank you!