

Mindy Tieu

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EDUCATION

Olin College of Engineering, Needham MA

Bachelor's in Mechanical Engineering Candidate, May 2017. GPA 3.5

- Previous courses: Principles of Modern Biology, Mechanics of Solids and Structures, Thermodynamics, User Oriented Collaborative Design, Dynamics, Modeling and Control.

Sophia University, Tokyo, Japan

Study Abroad Semester, September 2015- January 2016.

- American Association of Teachers of Japanese Bridging Scholarship 2015 Recipient.

EXPERIENCE

MA Space Grant Research Engineer, Needham MA

June 2015 - Aug 2015

- Managed and lead team of six student researchers working on four different projects.
- Conducted Finite Element Analysis of an orthodontic pacifier designed by Dr. Tesini.
- Designed, fabricated, and tested perching landing gear for implementation on drones.

Snot Bot Research Engineer, Needham MA

Sept 2014 - Dec 2014

- Implemented autonomous quad-copter drones in whale research with Ocean Alliance.
- Field tested and acquired data from drone and whale simulated interactions.

Design Nature Course Assistant, Needham MA

Sept 2014 - Dec 2014

- Assisted professors in the modification and execution of a design course for first years at Olin.
- Provided in class assistance to students, held office hours and tutorials on SolidWorks and mechanical design, and managed class materials and design stockroom.

Santos Family Foundation Researcher, Needham MA

June 2014 - Aug 2014

- Devised a Senior Capstone Program in Engineering (SCOPE) project that bridged the Santos mission for automotive safety with the needs and values of a team of Olin seniors.
- Implemented design frameworks and handled co-designs and expert interviews.

Robot X Research Engineer, Needham MA

Jan 2014 - May 2014

- Designed and fabricated sensor mounts on Robot X, an intelligent maritime vehicle shared by Olin and MIT.
- Developed advanced composite fabrication skills for marine applications through CAD modeling and machine shop use.

PRESENTATIONS AND PUBLICATIONS

Autonomous Aerial Vehicles for Remote Sample Collection in Difficult Conditions

- Paper published to IEEE International Conference on Technologies for Practical Robot Applications, 11-12 May 2015, Woburn, MA.
- Poster Presented at Northeast Robotics Colloquium, 11 Sept 2014, Brown University, RI.

Demonstrations of Bio-Inspired Perching Landing Gear for UAVs

- Paper published to SPIE Smart Materials Conference 9797 on Bioinspiration, Biomimetics, and Bioreplication VI in Nevada March 2016.

SKILLS

Experienced in: SolidWorks, MATLAB, LabVIEW, HTML, CSS, LaTeX, Photoshop, InDesign, FEA

Trained on: Mill, Lathe, Laser Cutter, Composites, Horizontal and Vertical Band Saws, Drill Press, MakerBot Replicator 2x, Stratasys

Interests: Videogames, running, fencing, paper crafts, foreign language (Japanese and Russian)