

--!: {field: []}: (😊) <- **Field Functions Library: Produce and Execute Field Plans** ->
muse/docs/lib/field.md

--(: field: *Fields are rectangular solids defined by a range (a situation pair with fields keyed properties)*. -> field, _field

--:+ *Fields are made up of plots, each plot at least small enough to deal with turtle inventory limitations.*

--:# **Execution train runs from field.make to field.plot to field.plan to execute the plan**

--:: field.make(commands: fieldCommands, faced: ^:) -> *Load field files; return their field.plot calls* -> report: ":" &:

--:> fieldCommands: *For CLI -> :[fieldOpName: ":" , ranger: ":" , firstPlot: #?: , lastPlot: #:??]*

--:+ *The second entry, ranger in fieldCommands is a string which may simply be a name for a range, (a kind of place).*

--:+ *If so, the range name gets the range's features dictionary and the field file name to load (keyed as features.fields).*

--:+ *It could also be a string specifying the name of a farm and a farm field name in that farm (separated by a colon).*

--:+ *If so, the farm name specifies the farm's range and so the farm range's features dictionary.*

--:+ *The fields entry in that dictionary is itself a dictionary, keyed by the farm's field name to specify its range name.*

--:+ *With the proper range name in hand, either directly as above, or from the farm, the field file to load is specified.*

--:: field.plot(commands: field.plotSpan, fieldsOp: (😊, fieldOpName: ":" , plots: #:, offset: xyz?) -> Plots -> report: ":" &: &!

--:+ *Called by field files. Calls fieldsOp from field file (which calls field.plan).*

--:> field.plotSpan: *{} spans all plots; if only first, default plots after first -> :[_:, _: , first: #?: , last: #:??]*

--:: field.plan(planName: ":" , fielding: fieldParameters, offset: xyz?) -> *Run plan, default offset {0,0,0}.*
-> report: ":" &: &!

--:+ *Loads and executes the prototype plan (which calls field.paths) for each (odd, even, or last) level of a plot.*

--:> fieldParameters: *bounds (and materials to fill and replace)* -> :[bounds, fieldParameters.fills?, fieldParameters.removeables??]

--:> fieldParameters.fills: *Group or list of craft items for fill material* -> group|craft[]

--:> fieldParameters.removeables: *Material replaced by fill* -> group|craft[]

--:> craft: *Minecraft item detail.name without minecraft: prefix* -> ":"

--:: field.extents(:bounds:, :strides:, faced: ":"?) -> *Plots placed* -> field.count, field.count , eP, eP, striding, ^:, ^:

--:+ Returns nplots:[fieldOp #:], slots:[fieldOp]: #:, strides: eP, run: eP,
 striding, turn: ^:, back: ^:
 --+ Extents for **stride** (shorter) and **run** (longer) virtual axes for each **opName** in the **strides** entries unless **faced**.

--:> field.count: _dictionary keyed by 'opName' for number of elements in field for that operation_ ->[fieldOp]: #`

--:> strides: dictionary keyed by **opName** for the distance along the stride axis for a striding -> [fieldOp]: #:

--:> striding: dictionary keyed by **opName** of vectors incrementing game coordinate positions for **turn**
 -> [fieldOp]: xyz

--:> eP: pair of coordinates for extents -> :[xyz, xyz]

--:> fieldOp: Operation name in the set for a particular kind of field -> ":"

--:# **Path generator: flying ox plow paths through given three dimensional rectangular bounds.**
 --:+ Ox plow paths minimize travel to plow a field. Flying oxen (aka turtles) do that in three dimensions.

--:: field.paths(bounds: xyz[]) -> Called by plan prototype file to generate plans for plot. -> **paths**,
 yDelta: #:, xzEdge: facing

--:> paths: _Flying ox traverse of three dimensional rectangular solid -> {start: ":"[], odd: ":"[], even: ":"[], last: ":"[]}
 --+ Returns paths, vertical traverse (**yDelta**: #:), and orientation of longest horizontal edge for bounded block.

--:# **Cut, fill, till, and traverse points defining rectangular volumes** using **field.plan** to optimize traversal.

--:: field.cut(places: :[nearPlace: ":" , farPlace: ":"]) -> Quarry out blocks from one place to the other. -> ":" &:
 --:- cut point point -> Quarry out blocks bound by named points (defining a rectangular solid).

--:: field.fill(parameters: :[nearPlace: ":" , farPlace: ":" , fill: ":" , target: ":" ?]) -> Fill, Till, Replace. -> ":" &:
 --:< Filling and target may be one of the turtle categories or a Minecraft detail name without prefix **minecraft**:

--:- fill point point filling ?target -> Layer fill bounds by points; optionally swaps out only target blocks.

--:: field.till(parameters: :[nearPlace: ":" , farPlace: ":" , seed: ":"]) -> Till the seed from one place to the other. -> ":" &:

--:< Seed may be one of the turtle categories or a Minecraft detail name without the prefix
"minecraft:"

--:- till point point seed -> *Till the seed bounds by named points (defining a rectangular solid).*

--:: field.fence(parameters: :[ranger: ":" , fencing: ":" ?]) -> *Put fencing using Layer plan.* -> ":"

--:- fence range [item] -> *Put item or available wooden fence from one point to another in range.*