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# **Computational Economics Lecture 3: Introduction to Dynamics**

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# Outline

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1. **Motivation**
2. **States/Markov Chains**
3. **Distributions**
4. **Simulation**
5. **Assignment**
6. **Appendix**

## Motivation

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- Many economics models are naturally dynamics (at least with  $t$  and  $t + 1$ )
- So numerically, we need to know how changes happen over time
  - A state  $S_t$  transit to a state  $S_{t+1}$
  - A distribution  $D_t$  transit to a distribution  $D_{t+1}$
- Some transitions are exogenous, either non-stochastic or stochastic
  - Non-stochastic: Deterministic rules, i.e.,  $x_{t+1} = x_t + 1$
  - Stochastic: i.e., Markov Chains, often used: AR(1)
- Some transitions are endogenous: i.e.,  $x_{t+1} = x_t + z_t$ , where  $z_t$  is a control
- Finally, we often need to simulate decisions and distributions over time
- Today, we will cover them all briefly

## States/Markov Chains

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- State space is the basics: Chapter 24. Linear State Space Models
- Let  $S$  be a finite set with  $n$  elements  $\{x_1, \dots, x_n\}$
- The set  $S$  is called the *state space* and  $x_1, \dots, x_n$  are the *state values*
- Markov chains are one of the most useful classes of stochastic processes:
  - simple, flexible, and supported by many elegant theoretical results
  - valuable for building intuition about random dynamic models
  - central to quantitative modeling in their own right
- Finite Markov Chains: Chapter 23. Finite Markov Chains
- Continuous State Markov Chains: Chapter 18. Continuous State Markov Chains
- Review some of the theory of Markov chains
- Introduce some of the high-quality routines for working with Markov chains

## Finite Markov Chains

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- A Markov chain  $\{X_t\}$  on  $S$  is a sequence of random variables on  $S$  with *Markov property*
- This means that, for any date  $t$  and any state  $y \in S$ ,

$$\mathbb{P}\{X_{t+1} = y \mid X_t\} = \mathbb{P}\{X_{t+1} = y \mid X_t, X_{t-1}, \dots\}$$

*\*Knowing the current state is enough to know probabilities for future states*

- The dynamics of a Markov chain are fully determined by the set of values

$$P(x, y) := \mathbb{P}\{X_{t+1} = y \mid X_t = x\} \quad (x, y \in S)$$

- We can view  $P$  as a stochastic matrix where

$$P_{ij} = P(x_i, x_j) \quad 1 \leq i, j \leq n$$

- Finally, to generate a Markov chain  $\{X_t\}$ , we just need  $S$ ,  $P$ , and initial draw  $X_0$

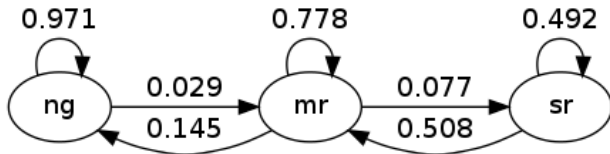
## Finite Markov Chains: Simple Example

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- The stochastic matrix of economic conditions: (Monthly Frequency)

$$P = \begin{pmatrix} 0.971 & 0.029 & 0 \\ 0.145 & 0.778 & 0.077 \\ 0 & 0.508 & 0.492 \end{pmatrix}$$

where states are: “normal growth”, “mild recession”, “severe recession”



## Finite Markov Chains: AR(1) with (Tauchen, 1986)

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- It is convenient to replace a continuous AR(1) with a discrete Markov chains
- Discrete approximations to AR(1) processes of the form

$$y_{t+1} = \rho y_t + u_{t+1}, \text{ where } u_t \text{ is assumed to be i.i.d. and follow } N(0, \sigma_u^2)$$

- The variance of the stationary probability distribution of  $\{y_t\}$  is

$$\sigma_y^2 = \frac{\sigma_u^2}{1 - \rho^2}$$

- Tauchen's method is the most used for approximating this continuous state process with a finite state Markov chain; Other methods are also used, i.e., Rouwenhorst (95)
- Let's write our own Tauchen method!
- Step 1: Choose discretization objects:
  - $n$ , the number of states for the discrete approximation
  - $m$ , an integer that parameterizes the width of the state space
- Step 2: Choose state space  $S = \{x_0, \dots, x_{n-1}\} \subset \mathbb{R}$ 
  - $x_0 = -m \sigma_y$
  - $x_{n-1} = m \sigma_y$
  - $x_{i+1} = x_i + s$  where step  $s = (x_{n-1} - x_0)/(n - 1)$

## Finite Markov Chains: AR(1) with (Tauchen, 1986)

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- Step 3: Choose a stochastic  $n \times n$  matrix  $P$  (most important part)
  - Let  $F$  be the cumulative distribution function of the normal distribution  $N(0, \sigma_u^2)$
  - The values  $P(x_i, x_j)$  are computed to approximate the AR(1) process
  - If  $j = 0$ , then set

$$P(x_i, x_j) = P(x_i, x_0) = F(x_0 - \rho x_i + s/2)$$

- If  $j = n - 1$ , then set

$$P(x_i, x_j) = P(x_i, x_{n-1}) = 1 - F(x_{n-1} - \rho x_i - s/2)$$

- Otherwise, set

$$P(x_i, x_j) = F(x_j - \rho x_i + s/2) - F(x_j - \rho x_i - s/2)$$

- With both  $S$  and  $P$  in hand, we successfully replaced a continuous AR(1)!
- So, how good is our approximation? [Will find out in the assignment]
- How about other methods, say Rouwenhorst, 1995? [Will find out in the assignment]



## Finite Markov Chains: AR(1) Extension - Uncertainty Shocks

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- A very popular second-moment shock is uncertainty shock (Bloom, 2009)
- Basically, a shock to the second moment  $\sigma_u$  in the above AR(1) process
- How to construct an uncertainty shock? i.e.,  $\hat{\sigma}_u > \sigma_u$
- One answer is to manipulate the stochastic  $n \times n$  matrix  $\hat{P}$ 
  - Step 1&2: The same progress as in normal AR(1)
  - Step 3-1: use  $\hat{F}$  as the cumulative distribution function of the normal distribution  $N(0, \hat{\sigma}_u^2)$
  - Step 3-2: construct  $P(x_i, x_j)$  with the same three cases
- When you hit the firms with uncertainty shock, force them to use the new matrix  $\hat{P}$
- So, how good is this approximation? [Will find out in the assignment]
- How about other methods, say "change state space  $S$ "? [Will find out in the assignment]

## Continuous State Markov Chains: Simple Introduction

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- Continuous state Markov chains is a more general case of what we just studied
- The best usage is to use on "nonlinear distributions" in economic models
- We focus on the "Density Case" where state  $S$  is a bounded interval  $(a, b)$
- Formally, a stochastic kernel on  $S$  is a function  $p: S \times S \rightarrow \mathbb{R}$  with the property that:
  1.  $p(x, y) \geq 0$  for all  $x, y \in S$
  2.  $\int p(x, y)dy = 1$  for all  $x \in S$
- For example, let  $S = \mathbb{R}$  and consider the particular stochastic kernel  $p_w$  defined by

$$p_w(x, y) := \frac{1}{\sqrt{2\pi}} \exp \left\{ -\frac{(y - x)^2}{2} \right\}$$

- This is the (normally distributed) random walk

$$X_{t+1} = X_t + \xi_{t+1} \quad \text{where} \quad \{\xi_t\} \stackrel{\text{iid}}{\sim} N(0, 1)$$

- Applications: See QuantEcon 18.2.6. example of usage for the stochastic growth model

## Distributions

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- Now we formally talk about transition of distributions  $D_t$  to  $D_{t+1}$
- Different from the very simple distributions in Continuous State Markov Chains
- We want to have distributions that are both nonlinear and endogenous
- See Chapter 25. Wealth Distribution Dynamics for an example of households' wealth
- Why do we want distribution dynamics in the model?
  - modeling heterogeneous firms or households
  - measures of inequality (households) or misallocation (firms) of the economy
  - how distribution matters for the economy, etc...
- Finally, the transition of distribution is just a collection of transitions between states
- We will play with simple one- and two-dimension distributions

## Distributions: One-dimension: Model

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- Let's start with QuantEcon 25.3. A Model of Wealth Dynamics
- This and the next pages describe the economic model
- The model we will study is

$$w_{t+1} = (1 + r_{t+1})s(w_t) + y_{t+1}$$

- $w_t$  is wealth at time  $t$  for a given household,
  - $r_t$  is the rate of return of financial assets,
  - $y_t$  is current non-financial (e.g., labor) income and
  - $s(w_t)$  is current wealth net of consumption
- Letting  $\{z_t\}$  be a correlated state process of the form

$$z_{t+1} = az_t + b + \sigma_z \epsilon_{t+1}$$

## Distributions: Model

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- We'll assume that

$$1 + r_t = c_r \exp(z_t) + \exp(\mu_r + \sigma_r \xi_t)$$

$$y_t = c_y \exp(z_t) + \exp(\mu_y + \sigma_y \zeta_t)$$

- Here  $\{(\epsilon_t, \xi_t, \zeta_t)\}$  is IID and standard normal in  $\mathbb{R}^3$ .
- The value of  $c_r$  is close to zero since the return on assets does not exhibit large trends.
- When we simulate a population of households, assume all shocks are idiosyncratic (i.e., specific to individual households and independent across them).
- Regarding the savings function  $s$ , our default model will be

$$s(w) = s_0 w \cdot \mathbf{1}\{w \geq \hat{w}\}, \quad \text{where } s_0 \text{ is a positive constant.}$$

- Thus, for  $w < \hat{w}$ , the household saves nothing.
- For  $w \geq \bar{w}$ , the household saves a fraction  $s_0$  of their wealth.

## Distributions: Implementation

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```
function wealth_dynamics_model(; # all named arguments
    w_hat = 1.0, # savings parameter
    s_0 = 0.75, # savings parameter
    c_y = 1.0, # labor income parameter
    mu_y = 1.0, # labor income parameter
    sigma_y = 0.2, # labor income parameter
    c_r = 0.05, # rate of return parameter
    mu_r = 0.1, # rate of return parameter
    sigma_r = 0.5, # rate of return parameter
    a = 0.5, # aggregate shock parameter
    b = 0.0, # aggregate shock parameter
    sigma_z = 0.1)

    z_mean = b / (1 - a)
    z_var = sigma_z^2 / (1 - a^2)
    exp_z_mean = exp(z_mean + z_var / 2)
    R_mean = c_r * exp_z_mean + exp(mu_r + sigma_r^2 / 2)
    y_mean = c_y * exp_z_mean + exp(mu_y + sigma_y^2 / 2)
    alpha = R_mean * s_0

    # Distributions
    z_stationary_dist = Normal(z_mean, sqrt(z_var))

    @assert alpha <= 1 # check stability condition that wealth does not diverge
    return (; w_hat, s_0, c_y, mu_y, sigma_y, c_r, mu_r, sigma_r, a, b, sigma_z,
        z_mean, z_var, z_stationary_dist, exp_z_mean, R_mean, y_mean, alpha)
end
```

```
wealth_dynamics_model (generic function with 1 method)
```

## Distributions: Simulation

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```
function simulate_wealth_dynamics(w_0, z_0, T, params)
    (; w_hat, s_0, c_y, mu_y, sigma_y, c_r, mu_r, sigma_r, a, b, sigma_z) = params # ur
    w = zeros(T + 1)
    z = zeros(T + 1)
    w[1] = w_0
    z[1] = z_0

    for t in 2:(T + 1)
        z[t] = a * z[t - 1] + b + sigma_z * randn()
        y = c_y * exp(z[t]) + exp(mu_y + sigma_y * randn())
        w[t] = y # income goes to next periods wealth
        if w[t - 1] >= w_hat # if above minimum wealth level, add savings
            R = c_r * exp(z[t]) + exp(mu_r + sigma_r * randn())
            w[t] += R * s_0 * w[t - 1]
        end
    end
    return w, z
end
```

simulate\_wealth\_dynamics (generic function with 1 method)

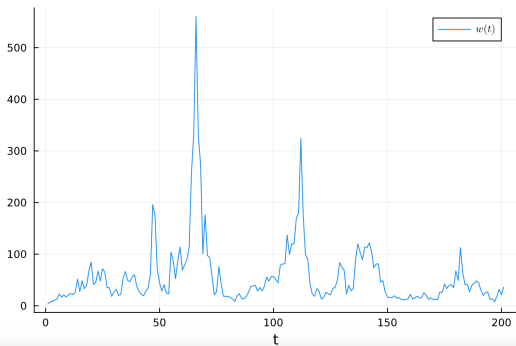
## Distributions: Results in One-dimension

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Let's look at the wealth dynamics of an individual household.

```
p = wealth_dynamics_model() # all defaults
y_0 = p.y_mean
z_0 = rand(p.z_stationary_dist)
T = 200
w, z = simulate_wealth_dynamics(y_0, z_0, T, p)

plot(w, caption = "Wealth simulation", xlabel = "t", label = L"w(t)")
```





## Distributions: Results in One-dimension

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- Assuming the distribution is stationary (is it?), we could:
- Plot the stationary distribution in one-dimension
- Generate the statistics of the stationary distribution in one-dimension
- Also, we could calculate the inequality measures like the Gini index
- [Will find out in the assignment]

## Distributions: Extension in Two-dimension

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- However, remember that  $z_{t+1}$  is a persistent AR(1) process
- Actually the distribution is in two dimensions  $D_t(z_t, w_t)$  instead of  $D_t(w_t)$
- Plot the stationary distribution in two-dimension  $(z, w)$
- Generate the statistics of the stationary distribution in two-dimension
- Also, we could calculate the inequality measures like the Gini index
- [Will find out in the assignment]

# Simulation

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- Finally, let's talk about simulation of distributions
- We have already seen stochastic simulation through random number generators

```
function simulate_wealth_dynamics(w_0, z_0, T, params)
    (; w_hat, s_0, c_y, mu_y, sigma_y, c_r, mu_r, sigma_r, a, b, sigma_z) = params # ur
    w = zeros(T + 1)
    z = zeros(T + 1)
    w[1] = w_0
    z[1] = z_0

    for t in 2:(T + 1)
        z[t] = a * z[t - 1] + b + sigma_z * randn()
        y = c_y * exp(z[t]) + exp(mu_y + sigma_y * randn())
        w[t] = y # income goes to next periods wealth
        if w[t - 1] >= w_hat # if above minimum wealth level, add savings
            R = c_r * exp(z[t]) + exp(mu_r + sigma_r * randn())
            w[t] += R * s_0 * w[t - 1]
        end
    end
    return w, z
end
```

simulate\_wealth\_dynamics (generic function with 1 method)

- Could we simulate stochastic progress without stochastic simulation?
- Yes, we can! Eric Young, 2010 provides a fantastic non-stochastic simulation method!

## Simulation: Stochastic

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- First, let's redo the stochastic simulation to be using discrete grids
- To make your life easier, we kill two stochastic progress  $\{(\xi_t = 0, \zeta_t = 0)\}$
- For  $z$  state, use the Tauchen method: let's choose 11 states
- For  $w$  state, choose 100 grid points from  $w_{low} = 0$  to  $w_{cap} = 200$  (0,2,4,6,...,200)
- You can modify  $w_{t+1} = (1 + r_{t+1})s(w_t) + y_{t+1}$  to enforce artificially  $w_{t+1} \leq 200$
- How about the  $w_t$  that is between grid points, i.e.,  $w_t = 2.5 \in [2, 4]$ ?
- Use interpolation that you learned in the last lecture to assign mass onto 2 and 4
- So, how good is our approximation? [Will find out in the assignment]

## Simulation: Non-Stochastic

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- Now, let's finally do the non-stochastic simulation (Young, 2010)
- We use exactly the same Tauchen grids and wealth grids as above
- But from time  $t$  to  $t + 1$ , we do not use random number generators!
- Instead, we could generate a distribution of possible  $w_{t+1}$  given  $(z_t, w_t)$
- For instance, for a grid point today,  $z_t = z_i$  and  $w_t = w_p$
- There is a  $w_{t+1}$  value  $w(z_j, w_p) \in [w_k, w_{k+1}]$  if  $z_{t+1} = z_j$  with  $p(z_i, z_j)$
- We could just assign the mass on  $w_k$  and  $w_{k+1}$  by distance from  $w(z_j, w_p)$

$$D[z_j, w_k] \quad + = \quad D[z_i, w_p] * p(z_i, z_j) * \frac{w_{k+1} - w(z_j, w_t)}{w_{k+1} - w_k}$$

$$D[z_j, w_{k+1}] \quad + = \quad D[z_i, w_p] * p(z_i, z_j) * \frac{w(z_j, w_t) - w_k}{w_{k+1} - w_k}$$

- Brilliant! So, how good is our approximation? [Will find out in the assignment]

# Assignment 1

- Individual assignment, but you can discuss with classmates
- Make presentable slides of your results (maybe some codes if you wish)
- Push codes and slides of the results to your GitHub (shared with me)
- Everyone will have 8 minutes to present the results on **Feb.12th (DDL)**
- You will be graded depending on:
  - If you could deliver the correct results (40)
  - How clean and organized are your codes written (30)
  - How well you could deliver your results in a presentation (30)

## Task 1: AR(1) on Page 7&8

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- Suggested Parameters:  $\{\rho = 0.9, \sigma_u = 0.1, n = 11, m = 3\}$   
(Choose your own if not working)
- All the outputs of tasks below is a plot!
- Task 1-1:  
Solve Tauchen (86) approximation and simulate the stationary distribution  $D^T(y)$
- Task 1-2:  
Compare  $D^T(y)$  to true distribution  $D(y)$  (Continuous State Markov Chains)
- Task 1-3:  
Solve Rouwenhorst (95) approximation and simulate the stationary distribution  $D^R(y)$
- Task 1-4:  
Compare  $D^R(y)$  to true distribution  $D(y)$  (Continuous State Markov Chains)



## Task 2: AR(1) Extension of Uncertainty Shocks on Page 9

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- Suggested Parameters:  $\{\rho = 0.9, \sigma_u = 0.1, n = 11, m = 3, \hat{\sigma}_u = 0.2\}$  | Method: Tauchen (86)
- Task 2-1:  
Solve the stochastic matrix  $\hat{P}$  of the uncertainty shock
- Task 2-2:  
Simulate 1000 individuals indexed by  $i$  for 21 periods  $t = 0, 1, \dots, 20$ , starting with  $y_{i,0} = 0$  that receive an uncertainty shock only at time  $t = 11$ . Plot the time path of  $y_{i,t}$  of all 1000 individuals over  $t$ .
- Task 2-3: [Bonus]  
How about other methods, say "change state space  $S$ "? For instance, an uncertainty shock pushes individuals to have larger upper bounds and smaller lower bounds.

### Task 3: Distributions on Page 17&18

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- Same economic parameters as in the codes
- Simulate  $N=10,000$  individuals with a random start until the distribution is stationary
- Task 3-1:  
Plot the stationary distribution in one-dimension
- Task 3-2:  
Simulate and plot the stationary distribution in two-dimension
- Task 3-3:  
Generate the statistics of the stationary distribution in two-dimension: i.e.,  $\text{Corr}(z,w)$

## Task 4: Distributions on Page 20&21

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- Same economic parameters as in the codes
- Simulate  $N=10,000$  individuals with a random start until the distribution is stationary
- For  $z$  state, use the Tauchen method: let's choose 5 states
- For  $w$  state, choose 50 grid points from  $w_{low} = 0$  to  $w_{cap} = 200$  (0,4,8,...,200)
- Task 4-1:  
Compare the stochastic simulation using discrete grids to the original stochastic simulation in Task 3. Plot the stationary distribution in one- and two-dimension.
- Task 4-2:  
Compare the non-stochastic simulation to the stochastic simulation using discrete grids. Plot the stationary distribution in one- and two-dimension.
- Task 4-3:  
Compare the computing time for all three simulations for  $T=1,000$  period

# Appendix

## REFERENCES

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