

PhD Macro Core Part I:  
Lecture 8 – Dynamic Programming IV

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# Today

- Practical stochastic dynamic programming
- Numerical integration to help compute expectations
- Using interpolations & approximations to solve the stochastic optimal growth model

## Goal: Solve the Stochastic Growth Model

- Let's solve the Bellman equation

$$v(k, z) = \max_{k'} \{u(f(k, z) - k') + \beta \mathbb{E}[v(k', z') | z]\}$$

with the usual specification

$$f(k, z) = zk^{\alpha} + (1 - \delta)k$$

$$u(c) = \frac{c^{1-\sigma} - 1}{1 - \sigma}$$

- And let's suppose that  $z'$  is an AR(1) in logs ( $\mu = 0$ )

$$\log z' = \rho_z \log z + \varepsilon, \quad \varepsilon \sim \text{IID } N(0, \sigma_z^2)$$

## Steps: Value Function Iteration

- Step 1: Create grids for both states and transition matrix for  $z$

$$k_{\min} < \dots < k_i < \dots < k_{\max}, \quad i = 1, \dots, n$$

$$z_{\min} < \dots < z_j < \dots < z_{\max}, \quad j = 1, \dots, m; \quad \text{an } m \times m \text{ matrix } P_z$$

- Step 2: Create  $n \times m$  matrices for value function  $v(k, z)$  and policy function  $k'(k, z)$
- Step 3: Make an initial guess of value function  $v_0(k, z)$
- Step 4: For each pair today  $(z_j, k')$ , calculate the expected value  $\mathbb{E}[v(k', z') \mid z_j]$
- Step 5: Given  $\mathbb{E}[v(k', z') \mid z_j]$  for any  $k'$ , find  $k'_1(k_i, z_j)$  for each pair  $(k_i, z_j)$  and  $v_0(k, z)$
- Step 6: Calculate  $v_1(k, z) \Rightarrow$  Now we are done with one iteration! Repeat until convergence!

## How to Decide the Grids of $z$ : Tauchen (1986)

- $z'$  is an AR(1) in logs ( $\mu = 0$ )

$$\log z' = \rho_z \log z + \varepsilon, \quad \varepsilon \sim \text{IID } N(0, \sigma_z^2)$$

- Conditional on  $z$ ,  $\log z'$  is normally distributed with mean  $\rho_z \log z$  and standard deviation  $\sigma_z$
- Decisions to make: number of points  $m$ , grid range  $(\log z_m - \log z_1)$ , probability matrix  $P_z$

$$\log z_1 < \dots < \log z_j < \dots < \log z_m, \quad j = 1, \dots, m; \quad \text{an } m \times m \text{ matrix } P_z$$

- Choose  $\log z_1 = -\tau\sigma_z/\sqrt{1-\rho_z^2}$  and  $\log z_m = +\tau\sigma_z/\sqrt{1-\rho_z^2}$  where  $\tau$  is a number
- We can then denote distance  $w \equiv \log z_2 - \log z_1 = \log z_j - \log z_{j-1}$

## How to Decide the Grids of $z$ : Tauchen (1986)

- For any  $j$  between 2 and  $m - 1$ :

$$p_{i,j} = \text{Prob} [\log z_j - w/2 \leq \rho_z \log z_i + \varepsilon \leq \log z_j + w/2]$$

- If  $j = 1$  then set

$$p_{i,1} = \text{Prob} [\rho_z \log z_i + \varepsilon \leq \log z_1 + w/2]$$

- And if  $j = m$  set

$$p_{i,m} = 1 - \text{Prob} [\log z_m - w/2 \leq \rho_z \log z_i + \varepsilon]$$

- Equivalently, ( $\Phi$  is the standard normal c.d.f.)

$$p_{ij} = \begin{cases} \Phi \left( \frac{\log z_1 + w/2 - \rho_z \log z}{\sigma_z} \right) & \text{for } j = 1 \\ \Phi \left( \frac{\log z_m - w/2 - \rho_z \log z}{\sigma_z} \right) - \Phi \left( \frac{\log z_1 + w/2 - \rho_z \log z}{\sigma_z} \right) & \text{for } 1 < j < n \\ 1 - \Phi \left( \frac{\log z_m - w/2 - \rho_z \log z}{\sigma_z} \right) & \text{for } j = n \end{cases}$$

## How to Decide the Grids of $z$ : Tauchen (1986)

- For any  $(i, j)$  pair, we have now:

$$p_{ij} = \text{Prob}(z' = \log z_j \mid z = \log z_i)$$

- Now, computing the conditional expectation no longer involves an integral since

$$\mathbb{E}[v(k', z') \mid z_i] = \sum_{j=1}^m p_{ij} v(k', z')$$

- The most difficult step 5 is nailed!

## VFI with Discrete Choices of $k'$

- Almost the same as Lecture 6 without stochastic component  $z$
- But everything is two dimensional now: value function and policy function
- Just more effort of the computer!



## VFI with Discrete Choices of $k'$ : S1-S4

- Step 1: Create grids for both states and transition matrix for  $z$

$$k_{\min} < \dots < k_i < \dots < k_{\max}, \quad i = 1, \dots, n$$

$$z_{\min} < \dots < z_j < \dots < z_{\max}, \quad j = 1, \dots, m; \quad \text{an } m \times m \text{ matrix } P_z$$

- Step 2: Create  $n \times m$  matrices for value function  $v(k, z)$  and policy function  $k'(k, z)$
- Step 3: Make an initial guess of value function  $v_0(k, z) = 0$
- Step 4: For each pair today  $(z_i, k')$ , calculate the expected value

$$\mathbb{E}[v_0(k', z') \mid z_i] = \sum_{j=1}^m p_{ij} v_0(k', z')$$

## VFI with Discrete Choices of $k'$ : S5

- Let  $c_{ijp}$  denote consumption if current productivity is  $z = z_i$ , capital is  $k = k_j$  and capital chosen for next period is  $k' = k_p$

$$c_{ijp} = z_i f(k_j) - k_p, \quad i, j = 1, \dots, n$$

We will need to be careful to respect the feasibility constraints

$$0 \leq k_p \leq f(k_j), \quad i, j = 1, \dots, n$$

- Let  $u_{ijp}$  denote the flow utility associated with  $c_{ijp}$

$$u_{ijp} = u(c_{ijp}), \quad i = 1, \dots, m; j, p = 1, \dots, n$$

- So  $u$  is an  $m \times n \times n$  matrix

## VFI with Discrete Choices of $k'$ : S5

- In this notation, our Bellman equation can be written

$$v_{ij} = \max_p [u_{ijp} + \beta \mathbb{E}[v_{i'p}]]$$

- Associated with this is the policy function

$$k'_{ij} = g_{ij} = \operatorname{argmax}_p [u_{ijp} + \beta \mathbb{E}[v_{i'p}]]$$

## VFI with Discrete Choices of $k'$ : S6

- Start with an initial guess  $v_{ij}^0$  and then calculate

$$v_{ij}^1 = Tv_{ij}^0 = \max_p [u_{ijp} + \beta \mathbb{E}[v_{i'j}^0]]$$

and compute the error

$$\|Tv^0 - v^0\| = \max_i [|Tv_i^0 - v_i^0|]$$

- If this error is less than some pre-specified tolerance  $\varepsilon > 0$ , stop. Otherwise, update to

$$v_{ij}^2 = Tv_{ij}^1$$

until the error is small enough

## VFI with Discrete Choices of $k'$ : Performance

- To achieve a high-accuracy solution, discrete choices of  $k'$  need a huge grid on  $k$
- Say,  $k_{min} = k_1 = 0.01$  and  $k_{max} = k_{10000} = 100.00$
- If your productivity grid points are 10
- Then  $u_{ijp}$  is a  $10 \times 10000 \times 10000$  matrix with  $10^9$  elements!
- Evaluation of the below step will be extremely costly

$$v_{ij}^1 = Tv_{ij}^0 = \max_p [u_{ijp} + \beta \mathbb{E}[v_{i'j}^0]]$$

- Can we improve on it? Certainly, we can!

## VFI with Continuous Choices of $k'$ : Setup

- The reason that we need so many grid points (nodes) of  $k$  is because of accuracy need
- If true  $k'(k_j, z_i) = 0.521$ , but the nearest nodes are  $k_- = 0.515$  and  $k_+ = 0.530$
- Then, we would choose  $\hat{k}'(k_j, z_i) = k_- = 0.515$ ,  $error = \hat{k}'/k' - 1 = 1.16\%$ ! (huge)
- To reduce the error to  $10e^{-7}$ , we need 15,000 nodes in between  $k_- = 0.515$  and  $k_+ = 0.530$
- So, ideally, we want to choose true  $k'(k_j, z_i) = 0.521$ , but we do not know  $v(0.521, z_i)$ , any  $i$
- To achieve this, we need interpolation

## VFI with Continuous Choices of $k'$ : Interpolation

- Interpolation: a type of estimation, a method of constructing (finding) new data points based on the range of a discrete set of known data points.
- We will do linear interpolation for today (simple)
- Given  $z_i$ ,  $v(k_-, z_i)$  and  $v(k_+, z_i)$  are known, now we want to know  $v(k', z_i)$  for any  $k' \in [k_-, k_+]$
- We construct an interpolation function

$$\text{Interp}(v(k, z_i)) = v(k_j, z_i) + (v(k_{j+1}, z_i) - v(k_j, z_i)) \frac{k' - k_j}{k_{j+1} - k_j}$$

for any  $k_j$  from  $k_{\min}$  to  $k_{\max}-1$

## VFI with Continuous Choices of $k'$ : Only Change is in S5

- In this notation, our Bellman equation can be written

$$v_{ij} = \max_p [u_{ijp} + \beta \text{Interp}(\mathbb{E}[v_{i'p}])]$$

- Associated with this is the policy function

$$k'_{ij} = g_{ij} = \operatorname{argmax}_p [u_{ijp} + \beta \text{Interp}(\mathbb{E}[v_{i'p}])]$$

- In practice, instead of choosing  $k_{min} = k_1 = 0.01$  and  $k_{max} = k_{10000} = 100.00$
- You can now choose  $k_{min} = k_1 = 0.01$  and  $k_{max} = k_{30} = 100.00$  (30 instead of 10,000 nodes)



## VFI in Stochastic Growth: Practice

- Next homework: Solve the same model with different methods
- Compute speed, error, etc