PhD Macro Core Part I: Lecture 3 – Neoclassical Growth I

Min Fang University of Florida

Fall 2024

Today

- Setup the Neoclassical Growth Model
- Social Planner's Problem (From Sequential to Recursive)
- Simplified Solution with Guess and Verify
- General Solutions: VFI & PFI

Setup the Neoclassical Growth Model

- Discrete time t = 0, 1, 2, ...
- Aggregate output Y_t is produced with physical capital K_t and labor L_t

$$Y_t = F(K_t, A_t L_t)$$

with labor-augmenting productivity A_t

• Physical capital depreciates at rate δ

$$K_{t+1} = (1 - \delta)K_t + I_t, \quad 0 < \delta < 1, \quad K_0 > 0$$

Goods may be either consumed or invested

$$C_t + I_t = Y_t$$

• Gives the sequence of resource constraints, one for each date

$$C_t + K_{t+1} = F(K_t, L_t) + (1 - \delta)K_t, \quad K_0 > 0$$

Aggregate Production Function

Each input has a positive marginal product

$$F_K(K,L) > 0, \quad F_L(K,L) > 0$$

• Each input suffers from diminishing returns

$$F_{KK}(K,L) < 0, \quad F_{LL}(K,L) < 0$$

• Constant returns to scale, i.e., if both inputs scaled by a common factor c > 0, then

$$F(cK, cL) = cF(K, L)$$

Some analysis is simplified by assuming the Inada conditions

$$F_K(0,L) = F_L(K,0) = \infty$$

$$F_K(\infty,L) = F_L(K,\infty) = 0$$

and that both inputs are essential, i.e., F(0, L) = F(K, 0) = 0

Efficiency Labor Unit Format

In efficiency units

$$y \equiv \frac{Y}{AL}, \quad k \equiv \frac{K}{AL}, \dots$$
 etc

• Using constant returns to scale

$$y = \frac{Y}{AL} = \frac{F(K, AL)}{AL} = F\left(\frac{K}{AL}, 1\right) = F(k, 1)$$

• Suppose constant $L_t = L$ and $A_t = A$, the resource constraint is simply

$$c_t + k_{t+1} = F(k, 1) + (1 - \delta)k_t \equiv f(k_t), \quad k_0 > 0$$

• Since all households are representative, it is the same to solve per household problem

Optimal Growth: Pareto Optimal Allocations

- The optimal growth satisfies the FWT, so it is Pareto optimal
- **Definition:** An allocation $\{c_t, k_t, l_t\}_{t=0}^{\infty}$ is feasible if for all $t \ge 0$

$$F(k_t, l_t) = c_t + k_{t+1} - (1 - \delta)k_t$$
$$c_t \ge 0, k_t \ge 0, 0 \le l_t \le 1$$
$$k_0 \le \bar{k}_0$$

• **Definition:** An allocation $\{c_t, k_t, l_t\}_{t=0}^{\infty}$ is Pareto efficient if it is feasible and there is no other feasible allocation $\{\hat{c}_t, \hat{k}_t, \hat{l}_t\}_{t=0}^{\infty}$ such that

$$\sum_{t=0}^{\infty} \beta^{t} U\left(\hat{c}_{t}\right) > \sum_{t=0}^{\infty} \beta^{t} U\left(c_{t}\right)$$

• Therefore, we can just focus on the social planner's problem; also, we know the optimal $l_t = 1$

Social Planner's Problem: Sequential Formulation

• Social planner chooses stream $c_t \ge 0$ to maximize

$$\sum_{t=0}^{\infty} \beta^{t} u\left(c_{t}\right)$$

subject to a sequence of resource constraints

$$c_t + k_{t+1} = f(k_t), \quad k_0 > 0$$

- Infinite horizon keeps model 'stationary', no life-cycle effects
- Can be decentralized, focus on planner's problem for simplicity

Social Planner's Problem: FOCs

• Lagrangian with multiplier $\lambda_t \ge 0$ for each resource constraint

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^{t} u\left(c_{t}\right) + \sum_{t=0}^{\infty} \lambda_{t} \left[f\left(k_{t}\right) - c_{t} - k_{t+1}\right]$$

Key first order conditions

$$c_{t}: \quad \beta^{t}u'(c_{t}) - \lambda_{t} = 0$$

$$k_{t+1}: \quad -\lambda_{t} + \lambda_{t+1}f'(k_{t+1}) = 0$$

$$\lambda_{t}: \quad f(k_{t}) - c_{t} - k_{t+1} = 0$$

These are held on every date

Consumption Euler Equation

Eliminating the Lagrange multipliers

$$u'(c_t) = \beta u'(c_{t+1}) [f'(k_{t+1}) + 1 - \delta]$$

• Same as last class if we recognize that the 'return on capital' is

$$R_{t+1} = f'\left(k_{t+1}\right)$$

- Planner equates marginal rate of substitution (MRS) between t and t+1 with marginal rate of transformation (MRT)
- MRS between t and t + 1

$$\frac{u'\left(c_{t}\right)}{\beta u'\left(c_{t+1}\right)}$$

• MRT between t and t+1

$$f'(k_{t+1})$$

From Sequential Formulation to Recursive Formulation

• We could rewrite the sequential formulation as

$$v(k_{0}) = \max \sum_{t=0}^{\infty} \beta^{t} u(f(k_{t}) - k_{t+1})$$

$$= \max \left\{ u(f(k_{0}) - k_{1}) + \beta \sum_{t=1}^{\infty} \beta^{t-1} u(f(k_{t}) - k_{t+1}) \right\}$$

$$= \max \left\{ u(f(k_{0}) - k_{1}) + \beta \left[\max \sum_{t=1}^{\infty} \beta^{t-1} u(f(k_{t}) - k_{t+1}) \right] \right\}$$

• Eventually, we have

$$v\left(k_{0}\right) = \max_{\substack{0 \leqslant k_{1} \leqslant f\left(k_{0}\right) \\ k_{0} \text{ given}}} \left\{u\left(f\left(k_{0}\right) - k_{1}\right) + \beta v\left(k_{1}\right)\right\}$$

Solve Recursive Formulation: An Example

• The recursive problem is not straightforward to solve since we do not know v(k')

$$v(k) = \max_{0 \le k' \le f(k)} \left\{ u\left(f(k) - k'\right) + \beta v\left(k'\right) \right\}$$

- We will show in the future that it derives the same Euler equations
- Today, we will guess and verify in a simplified example w/

$$u(c) = ln(c), \quad \delta = 1, \quad f(k) = k^{\alpha}$$

the functional equation becomes

$$v(k) = \max_{0 \le k' \le k^{\alpha}} \left\{ \ln \left(k^{\alpha} - k' \right) + \beta v \left(k' \right) \right\}$$

Let us guess

$$v(k) = A + B \ln(k)$$

where A and B are unknown coefficients to be determined.

- The method consists of three steps:
- Step 1: Solve the maximization problem on the right-hand side, given the guess for v, i.e., solve

$$\max_{0 \leqslant k' \leqslant k^{\alpha}} \left\{ \ln \left(k^{a} - k' \right) + \beta \left(A + B \ln \left(k' \right) \right) \right\}$$

where the FOC yields

$$\frac{1}{k^{\alpha} - k'} = \frac{\beta B}{k'}$$

$$k' = \frac{\beta B k^{\alpha}}{1 + \beta B}$$
(3.3)

• Step 2: Evaluate the right-hand side at the optimal solution $k' = \frac{\beta B k^{\alpha}}{1+\beta B}$. This yields

RHS =
$$\ln (k^a - k') + \beta (A + B \ln (k'))$$

= $\ln \left(\frac{k^{\alpha}}{1 + \beta B}\right) + \beta A + \beta B \ln \left(\frac{\beta B k^{\alpha}}{1 + \beta B}\right)$
= $-\ln(1 + \beta B) + \alpha \ln(k) + \beta A + \beta B \ln \left(\frac{\beta B}{1 + \beta B}\right) + \alpha \beta B \ln(k)$

- In order for our guess to solve the functional equation, the left-hand side of the functional equation, which we have guessed to equal LHS = $A + B \ln(k)$ must equal the right-hand side, which we just found, for all possible values of k.
- If we can find coefficients A, B for which this is true, we have found a solution to the functional equation.

• Step 3: Equating LHS and RHS yields

$$A + B \ln(k) = -\ln(1 + \beta B) + \alpha \ln(k) + \beta A + \beta B \ln\left(\frac{\beta B}{1 + \beta B}\right) + \alpha \beta B \ln(k)$$

$$(B - \alpha(1 + \beta B)) \ln(k) = -A - \ln(1 + \beta B) + \beta A + \beta B \ln\left(\frac{\beta B}{1 + \beta B}\right)$$
(3.4)

• But this equation has to hold for every capital stock k. The right-hand side of (3.4) does not depend on k, but the left-hand side does. Hence, the right-hand side is a constant.

$$B = \frac{\alpha}{1 - \alpha \beta}$$

$$0 = -A - \ln(1 + \beta B) + \beta A + \beta B \ln\left(\frac{\beta B}{1 + \beta B}\right)$$

$$= -A - \ln\left(\frac{1}{1 - \alpha \beta}\right) + \beta A + \frac{\alpha \beta}{1 - \alpha \beta} \ln(\alpha \beta)$$

• Solving this mess for A yields

$$A = \frac{1}{1 - \beta} \left[\frac{\alpha \beta}{1 - \alpha \beta} \ln(\alpha \beta) + \ln(1 - \alpha \beta) \right]$$

• We can also determine the optimal policy function k' = g(k) by plugging in $B = \frac{\alpha}{1 - \alpha\beta}$ into (3.3):

$$g(k) = \frac{\beta B k^{\alpha}}{1 + \beta B}$$
$$= \alpha \beta k^{\alpha}$$

• Hence, our guess was correct: the function $v^*(k) = A + B \ln(k)$, with A, B as determined above, solves the functional equation, with associated policy function $g(k) = \alpha \beta k^{\alpha}$.

Value Function Iteration: Analytical Approach

- Guess and verify will not work in most cases; we need more general methods
- It is still "guess", but we do not just "verify"; we improve on our naive initial guess
- Consider instead the following iterative procedure for our previous example
 - 1. Guess an arbitrary function $v_0(k)$. For concreteness let's take $v_0(k) = 0$ for all
 - 2. Proceed by solving

$$v_1(k) = \max_{0 \le k' \le k\alpha} \{ \ln (k^{\alpha} - k') + \beta v_0(k') \}$$

Note that we can solve the maximization problem on the right-hand side since we know v_0 (since we have guessed it). In particular, since $v_0(k') = 0$ for all k' we have as optimal solution

$$k' = g_1(k) = 0$$
 for all k

Plugging this back in, we get

$$v_1(k) = \ln(k^{\alpha} - 0) + \beta v_0(0) = \ln k^{\alpha} = \alpha \ln k$$

Value Function Iteration: Analytical Approach

- Consider instead the following iterative procedure for our previous example
 - 3. Now we can solve

$$v_2(k) = \max_{0 \le k' \le k^{\alpha}} \{ \ln(k^{\alpha} - k') + \beta v_1(k') \}$$

4. Since we know v_1 and so forth. By iterating on the recursion

$$v_{n+1}(k) = \max_{0 \leqslant k' \leqslant k^{\alpha}} \left\{ \ln \left(k^{\alpha} - k' \right) + \beta v_n \left(k' \right) \right\}$$

- We obtain a sequence of value functions $\{v_n\}_{n=0}^{\infty}$ and policy functions $\{g_n\}_{n=1}^{\infty}$.
- Hopefully, these sequences will converge to the solution v^* and associated policy g^* .

Euler Equation Approach (Policy Function Iteration)

• The infinite horizon case: The problem was to solve

$$v\left(\bar{k}_{0}\right) = \max_{\left\{k_{t+1}\right\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^{t} u\left(f\left(k_{t}\right) - k_{t+1}\right)$$

$$0 \leqslant k_{t+1} \leqslant f\left(k_{t}\right)$$

$$k_{0} = \bar{k}_{0} > 0 \text{ given}$$

The first-order conditions constitute the necessary conditions for an optimal

$$\beta u' (f(k_{t+1}) - k_{t+2}) f'(k_{t+1}) = u' (f(k_t) - k_{t+1}) \quad \text{for all } t = 0, \dots, t, \dots$$
(3.8)

- However, we have no terminal condition since there is no terminal time period
- The transversality condition (TVC) substitutes for the missing terminal condition

Euler Equation Approach: The Transversality Condition

Let us first state and then interpret the TVC

$$\lim_{t \to \infty} \underbrace{\beta^t u' \left(f \left(k_t \right) - k_{t+1} \right) f' \left(k_t \right)}_{t \to \infty} \underbrace{k_t}_{t \to \infty} = 0$$
value in discounted total
utility terms of one more = 0
unit of capital stock

• Often one can find an alternative statement of the TVC in the literature:

$$\lim_{t\to\infty}\lambda_t k_{t+1}=0$$

where λ_t is the Lagrange multiplier on the constraint

$$c_t + k_{t+1} = f(k_t)$$

hence, the TVC becomes

$$\lim_{t\to\infty}\beta^{t}u'\left(f\left(k_{t}\right)-k_{t+1}\right)k_{t+1}=0$$

Euler Equation Approach: Analytical Approach

- Take TVC as given, solve the simple example u(c) = ln(c), $\delta = 1$, $f(k) = k^{\alpha}$
- Define $z_t = k_{t+1}/f(k_t) = k'/k^{\alpha}$ as the saving rate, the TVC becomes

$$\lim_{t \to \infty} \beta^{t} u' \left(f \left(k_{t} \right) - k_{t+1} \right) f' \left(k_{t} \right) k_{t}$$

$$= \lim_{t \to \infty} \frac{\alpha \beta^{t} k_{t}^{\alpha}}{k_{t}^{\alpha} - k_{t+1}} = \lim_{t \to \infty} \frac{\alpha \beta^{t}}{1 - \frac{k_{t+1}}{k_{t}^{\alpha}}}$$

$$= \lim_{t \to \infty} \frac{\alpha \beta^{t}}{1 - z_{t}}$$

• Repeat the first-order difference equation derived from the Euler equations

$$z_{t+1} = 1 + \alpha \beta - \frac{\alpha \beta}{z_t}$$

Euler Equation Approach: Analytical Approach

- Guess and verify: Only one guess for z_0 yields a sequence that does not violate the TVC or the non-negativity constraint on capital or consumption.
 - 1. $z_0 < \alpha \beta$. In finite time $z_t < 0$, violating the nonnegativity constraint on capital
 - 2. $z_0 > \alpha \beta$. Then from Figure 3 we see that $\lim_{t\to\infty} z_t = 1$. (Note that, in fact, every $z_0 > 1$ violates the nonnegativity of consumption and hence is not admissible as a starting value). We will argue that all these paths violate the TVC.
 - 3. $z_0 = \alpha \beta$. Then $z_t = \alpha \beta$ for all t > 0. For this path (which obviously satisfies the Euler equations) we have that

$$\lim_{t\to\infty}\frac{\alpha\beta^t}{1-z_t}=\lim_{t\to\infty}\frac{\alpha\beta^t}{1-\alpha\beta}=0$$

• The Euler approach directly solves the policy function $z_t = z_0$ or $k' = g(k) = \alpha \beta k^{\alpha}$

References

- [DK] Dirk Krueger, Macroeconomic Theory (2015)
 - Chapter 2: A Simple Dynamic Economy
- Please refer to the book for all other proofs
- Please refer to the book for the finite case of the Euler approach