Ming-Yu Liu

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Objectives: Seeking a research scientist position in an industrial artificial intelligence research lab or product development department
Research interest: Computer vision, deep unsupervised learning, deep reinforcement learning
Expertise: Computer vision, deep learning, and machine learning

Education

- **University of Maryland College Park, Maryland** **College Park, MD, USA**
  Electrical and Computer Engineering, Ph.D. *2006 – 2012*
  Dissertation: Discrete optimization methods for segmentation and matching
  Adviser: Rama Chellappa
- **National Chiao Tung University** **Hsinchu, Taiwan**
  Electrical Engineering, B.A. *1999 – 2003*

Professional Experiences

- **Mitsubishi Electric Research Laboratories (MERL)** **Cambridge, MA, USA**
  Principal Research Scientist *2012 – present*
  - Conducted fundamental and applied research in computer vision and deep learning.
  - Applied fields: autonomous driving, factory automation, social infrastructure monitoring, and satellite image analysis
  - Computer vision expertise: object detection, semantic segmentation and labeling, pose estimation, image classification, domain adaptation, depth super-resolution
  - Deep learning expertise: deep convolutional neural nets, deep generative adversarial nets, attention mechanism and recurrent neural nets, recursive context propagation nets
  - Published 10 high impact scientific papers
  - Earned 5 US patents
  - Product launched: MELFA-3D vision system
- **Intel** **Taipei, Taiwan**
  Software Engineering Intern *2005 – 2006*
  Intel X-Scale ARM-based embedded system software development for smart TV applications
- **Army** **Taiwan**
  Paratrooper Platoon Leader, Military Rank: Second Lieutenant *2003 – 2005*

Earned Patents

- US 8,428,363: Method for segmenting images using superpixels and entropy rate clustering
- US 8,983,177: Method for increasing resolutions of depth images
- US 8,908,913: Voting-based pose estimation for 3D sensors
- US 9,195,904: Method for detecting objects in stereo images
- US 9,280,827: Method for determining object poses using Weighted Features

Awards

- Best paper honorable mention by Robotics: Science and System Conference RSS, 2015
- R&D 100 Award by R&D magazine, 2014
- University of Maryland College Park, Fellowship, 2011

Publications

- **Gaussian Conditional Random Field Network for Semantic Segmentation**
  R. Vemulapalli, O. Tuzel, Ming-Yu Liu, R. Chellappa, CVPR 2016
- **Deep Gaussian Conditional Random Field Network: A Model-based Deep Network for Denoising**
  R. Vemulapalli, O. Tuzel, Ming-Yu Liu, CVPR 2016
- **Learning to Remove Multipath Distortions in Time-of-Flight Range Images for a Robotic Arm Setup**
  K. Son, Ming-Yu Liu, Y. Taguchi, ICRA 2016
- **Unsupervised Network Pretraining via Encoding Human Design**
  Ming-Yu Liu, Arun Mallya, Oncel Tuzel, Xi Chen, WACV 2016
- **Layered Interpretation of Street View Images**
  Ming-Yu Liu, S. Lin, S. Ramalingam, O. Tuzel, RSS 2015 (**Best paper honorable mention**)
- **Recursive Context Propagation Network for Semantic Scene Labeling**
  A. Sharma, O. Tuzel, Ming-Yu Liu, NIPS 2014
- **Learning to Rankd 3D Features**
  O. Tuzel, Ming-Yu Liu, Y. Taguchi, A. Raghunathan, ECCV 2014
- **Joint Geodesic Upsampling of Depth Images**
  Ming-Yu Liu, O. Tuzel, Y. Taguchi, CVPR 2013
- **Cluster Analysis via Maximizing a Submodular Function subject to a Matroid Constraint**
  Ming-Yu Liu, O. Tuzel, S. Ramalingam, R. Chellappa, TPAMI 2014
- **Model-Based Vehicle Pose Estimation and Tracking in Videos Using Random Forests**
  M. Hödlmoser, B. Micusik, M. Pollefeys, Ming-Yu Liu, M. Kampel, 3DV 2013
- **Fast Object Detection and Pose Estimation in Heavy Clutter for Robotic Bin-Picking**
  Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, Y. Taguchi, T. Marks, R. Chellappa, IJRR 2012
- **Voting-Based Pose Estimation for Robotic Assembly Using a 3D Sensor**
  C. Choi, Y. Taguchi, O. Tuzel, Ming-Yu Liu, S. Ramalingam, ICRA 2012
- **A Grassmann Manifold-based Domain Adaptation Approach**
  J. Zheng, Ming-Yu Liu, R. Chellappa, P. Phillips, ICPR 2012
- **Classification and Pose Estimation of Vehicles in Videos by 3D Modeling**
  M. Hödlmoser, B. Micusik, Ming-Yu Liu, M. Pollefeys, M. Kampel, 3DV 2012
- **Entropy Rate Superpixel Segmentation**
  Ming-Yu Liu, O. Tuzel, S. Ramalingam, R. Chellappa, CVPR 2011
- **Fast Directional Chamfer Matching**
  Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, R. Chellappa, CVPR 2010
- **Pose Estimation in Heavy Clutter using a Multi-Flash Camera**
  Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, R. Chellappa, A. Agrawal, H. Okuda, ICRA 2010

Services

- **Reviewer**: IEEE TIP, IEEE SPL, CVIU
- **Technical committee**: CVPR, ICCV, ECCV, NIPS, ICRA, AAAI

Programming Skills

Programming Languages: C++, Python, Matlab
Libraries: Caffe, OpenCV, EIGEN, OpenGL, Coin-OR, GUROBI
Opensource Code:

- Fast directional chamfer matching algorithm
- Entropy rate superpixel segmentation algorithm
- Joint geodesic depth upsampling algorithm

References

- Upon request