

In general the variances of transform

Coefficients can be computed as follows:

Let  $\underline{u}$  be the image vector.

$$\underline{M}_u = E[\underline{u}]$$

$$R_u = E[(\underline{u} - \underline{M}_u)(\underline{u} - \underline{M}_u)^T]$$

$$\text{Let } \underline{v} = \underline{A} \underline{u} \quad \text{transform}$$

$$\underline{M}_v = E[\underline{v}]$$

$$= \underline{A} E[\underline{u}] = \underline{A} \underline{M}_u$$

$$R_v = E[(\underline{v} - \underline{M}_v)(\underline{v} - \underline{M}_v)^T]$$

$$= E[(\underline{A}\underline{u} - \underline{A}\underline{M}_u)(\underline{A}\underline{u} - \underline{A}\underline{M}_u)^T]$$

$$= \underline{A} R_u \underline{A}^T$$

The transform coefficient variances are

given by the diagonal elements of  $R_v$

$$\sigma_v^2(k) = [R_v]_{k,k} = [\underline{A} R_u \underline{A}^T]_{k,k}$$

from Parseval's th

$$\sum_{k=0}^{N-1} |v(k)|^2 = \sum_{k=0}^{N-1} |u(n)|^2$$

$$\sum E |v(k)|^2 = \sum E [u(n)]^2$$

~~for~~ for 2-D separable transform

$$V(k, l) = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} u(m, n) a(k, m) a(l, n)$$

$$E [V(k, l)] = \mu_v(k, l) = \sum \sum a(k, m) a(l, n) \mu_u(m, n)$$

$$\sigma_v^2(k, l) = E [ |V(k, l) - \mu_v(k, l)|^2 ]$$

$$= E \left\{ \left[ \sum \sum (u(m, n) a(k, m) a(l, n) - \mu_u(m, n) a(k, m) a(l, n)) \right]^2 \right\}$$

$$= \sum_{m, n} \sum_{m', n'} a(k, m) a(l, n) \gamma(m, n; m', n') a^*(k, m') a^*(l, n')$$

Simpler Computation for separable ~~if~~

$$\gamma(m, m; n, n) = \gamma_1(m, m) \gamma_2(n, n)$$

$$\sigma_v^2(k, l) = \sigma_1^2(k) \sigma_2^2(l)$$

$$= [AR_1A^*]^T_{k,k} [AR_2A^*]_{l,l}$$

$$R_1 = \{ \gamma_1(m, m) \} \quad R_2 = \{ \gamma_2(n, n) \}$$

for stationary  $\gamma$ -f.

$$\sigma_v^2(k, l) = \sum_m \sum_{m'} \sum_n \sum_{n'} a(k, m) a(l, n)$$

$$\gamma(m-m', n-n') a^*(k, m) a^*(l, m')$$

→ for DFT, DST, DCT

Can be Computed in  $O(N^2 \log N)$

operations