Ming-Yu Liu

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Objectives: Seeking a research scientist position in an industrial artificial intelligence research lab or product development department

Research interest: Computer vision, deep unsupervised learning, deep reinforcement learning

Expertise: Computer vision, deep learning, and machine learning

Education

• University of Maryland College Park, Maryland

College Park, MD, USA

2006 - 2012

Electrical and Computer Engineering, Ph.D.

Dissertation: Discrete optimization methods for segmentation and matching

Adviser: Rama Chellappa

• National Chiao Tung University

Electrical Engineering, B.A.

Principal Research Scientist

Hsinchu, Taiwan

1999 - 2003

Professional Experiences

• Mitsubishi Electric Research Laboratories (MERL)

Cambridge, MA, USA

2012 - present

- Conducted fundamental and applied research in computer vision and deep learning.

- Applied fields: autonomous driving, factory automation, social infrastructure monitoring, and satellite image analysis
- Computer vision expertise: object detection, semantic segmentation and labeling, pose estimation, image classification, domain adaptation, depth super-resolution
- Deep learning expertise: deep convolutional neural nets, deep generative adversarial nets, attention mechanism and recurrent neural nets, recursive context propagation nets
- Published 10 high impact scientific papers
- Earned 5 US patents
- Product launched: MELFA-3D vision system

• Intel Taipei, Taiwan

Software Engineering Intern

2005 - 2006

Intel X-Scale ARM-based embedded system software development for smart TV applications

• Army Taiwan

Paratrooper Platoon Leader, Military Rank: Second Lieutenant

2003 - 2005

Earned Patents

- US 8,428,363: Method for segmenting images using superpixels and entropy rate clustering
- US 8,983,177: Method for increasing resolutions of depth images
- US 8,908,913: Voting-based pose estimation for 3D sensors
- US 9,195,904: Method for detecting objects in stereo images
- US 9,280,827: Method for determining object poses using Weighted Features

Awards

- Best paper honorable mention by Robotics: Science and System Conference RSS, 2015
- R&D 100 Award by R&D magazine, 2014
- University of Maryland College Park, Fellowship, 2011

Publications

• Coupled Generative Adversarial Networks

Ming-Yu Liu, O. Tuzel, arXiv:1606.07536

• Gaussian Conditional Random Field Network for Semantic Segmentation

R. Vemulapalli, O. Tuzel, Ming-Yu Liu, R. Chellappa, CVPR 2016

- Deep Gaussian Conditional Random Field Network: A Model-based Deep Network for Denoising R. Vemulapalli, O. Tuzel, Ming-Yu Liu, CVPR 2016
- Learning to Remove Multipath Distortions in Time-of-Flight Range Images for a Robotic Arm Setup K. Son, Ming-Yu Liu, Y. Taguchi, ICRA 2016
- Unsupervised Network Pretraining via Encoding Human Design Ming-Yu Liu, Arun Mallya, Oncel Tuzel, Xi Chen, WACV 2016
- Layered Interpretation of Street View Images

Ming-Yu Liu, S. Lin, S. Ramalingam, O. Tuzel, RSS 2015 (Best paper honorable mention)

 Recursive Context Propagation Network for Semantic Scene Labeling A. Sharma, O. Tuzel, Ming-Yu Liu, NIPS 2014

• Learning to Rankd 3D Features

O. Tuzel, Ming-Yu Liu, Y. Taguchi, A. Raghunathan, ECCV 2014

• Joint Geodesic Upsampling of Depth Images Ming-Yu Liu, O. Tuzel, Y. Taguchi, CVPR 2013

- Cluster Analysis via Maximizing a Submodular Function subject to a Matroid Constraint Ming-Yu Liu, O. Tuzel, S. Ramalingam, R. Chellappa, TPAMI 2014
- Model-Based Vehicle Pose Estimation and Tracking in Videos Using Random Forests M. Hödlmoser, B. Micusik, M. Pollefeys, Ming-Yu Liu, M. Kampel, 3DV 2013
- Fast Object Detection and Pose Estimation in Heavy Clutter for Robotic Bin-Picking Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, Y. Taguchi, T. Marks, R. Chellappa, IJRR 2012
- Voting-Based Pose Estimation for Robotic Assembly Using a 3D Sensor C. Choi, Y. Taguchi, O. Tuzel, Ming-Yu Liu, S. Ramalingam, ICRA 2012
- A Grassmann Manifold-based Domain Adaptation Approach
 J. Zheng, Ming-Yu Liu, R. Chellappa, P. Phillips, ICPR 2012
- Classification and Pose Estimation of Vehicles in Videos by 3D Modeling M. Hödlmoser, B. Micusik, Ming-Yu Liu, M. Pollefeys, M. Kampel, 3DV 2012
- Entropy Rate Superpixel Segmentation

Ming-Yu Liu, O. Tuzel, S. Ramalingam, R. Chellappa, CVPR 2011

• Fast Directional Chamfer Matching

Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, R. Chellappa, CVPR 2010

Pose Estimation in Heavy Clutter using a Multi-Flash Camera

Ming-Yu Liu, O. Tuzel, A. Veeraraghavan, R. Chellappa, A. Agrawal, H. Okuda, ICRA 2010

Services

- Reviewer: IEEE TIP, IEEE SPL, CVIU
- Technical committee: CVPR, ICCV, ECCV, NIPS, ICRA, AAAI

Programming Skills

Programming Languages: C++, Python, Matlab

Libraries: Caffe, OpenCV, EIGEN, OpenGL, Coin-OR, GUROBI

Opensource Code:

- Fast directional chamfer matching algorithm
- Entropy rate superpixel segmentation algorithm
- Joint geodesic depth upsampling algorithm

References

Upon request