

Online Optimization, Learning, and Games (O2LG)

Lesson 1: Introduction to Game Theory

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Why game theory?



- **Game theory** is the study of *strategic decision-making*.
- Provide a **framework** for understanding **how agents interact** with each other in **competitive and cooperative environments**.
- **Model** a wide variety of **real-world situations**, e.g., traffics, economics, sports, etc.
- **Design algorithms** that are **robust** to adversarial behavior.

Example: Traffic Congestion

2021→2022 INRIX Global Traffic Scorecard

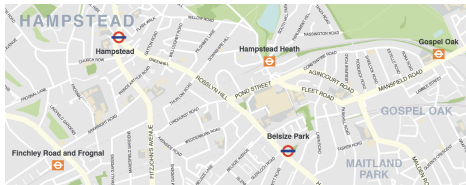
- **London** is the **most congested** city in the world.
- **148 → 156 hours** lost per driver to **delay**.
- **Congestion cost** of **£5.1 (1% GDP) → £5.7 billion**.
- **£212 (2022) fuel surcharge** per driver.

How to deal with traffic congestion?



Traffic Congestion in London

Example: Traffic Congestion



Greater London map

London

- Population (2023): ≈ 10 million.
- 21.6 million daily trips^a (2021)
- 831 stations & 107,000 roads^b

^aTravel in London Report 15

^bGreater London map

How to model traffic congestion?

- Consider a network of roads with each road of a limited capacity.
- The *vehicles choose which roads* to travel from one station to another on the network. But if *too many vehicles* choose the *same road*, then the *road will become congested*.
- **Model as a congestion game**: player = vehicle; player's action = which road to take; player's payoff = travel time. **Goal of each player**: minimize their travel time.

A very large game!

Why learning?



- **Learning** is the ability to *improve performance* over time *by experience*.
- **Key component** of many online optimization and game-playing algorithms.
- **Online optimization + Learning:** *Adapt to changes* in the environment.

Example: Traffic Congestion (cont.)



Traffic Congestion

Learning can be used to deal with traffic congestion:

- **Predictive traffic modeling:** predict *traffic patterns*
⇒ improve traffic flow and optimize routing decisions
★ **Online learning:** adapt to changes in traffic patterns.
- **Dynamic routing:** provide drivers with *real-time routing information* that takes into account *traffic conditions*
⇒ avoid congested areas and find the fastest routes.
- **Parking optimization:** optimize *parking availability/pricing*
⇒ find parking more easily and reduce congestion.
- **Smart traffic lights:** *control traffic lights* in real time
⇒ reduce congestion and improve traffic safety.

Questions we'll try to answer

1 How should we model player interactions?

- Types of situations (e.g. traffic congestion),
- Types of players (e.g. vehicles),
- Types of interactions (e.g. competition),...

2 What is a desired operational state ?

- Different goals (e.g., reduce congestion),
- Types of states (equilibrium, optimum),...

3 How to compute it?

- Calculation (simple, well-understanding),
- Implementation (simple, easy to control),
- Learning (complex).

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1 Motivation

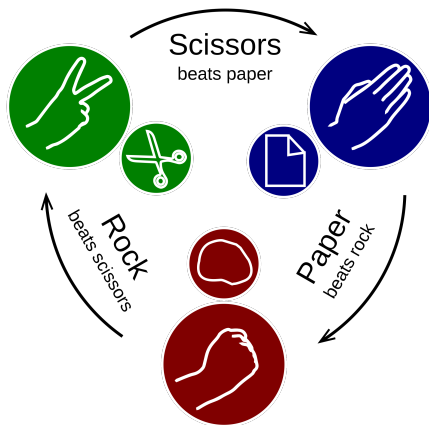
2 Basics of Game Theory

- Introduction

- Strategic dominance

- Best responses and Nash equilibrium

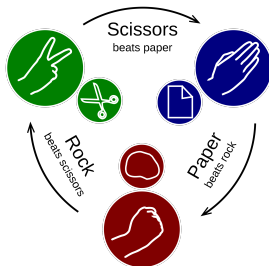
Introduction: Let's play a game



How to model this game **mathematically**?

How to model the rock-paper-scissors game?

- **Players:** $\mathcal{N} = \{1, 2\}$
- **Actions** associated to each player: $\mathcal{A}_i = \{R, P, S\}, i \in \mathcal{N}$
- **Payoff matrix** (win: 1€; lose: -1€; tie: 0€):



		Player 2		
		<i>R</i>	<i>P</i>	<i>S</i>
Player 1	<i>R</i>	(0, 0)	(-1, 1)	(1, -1)
	<i>P</i>	(1, -1)	(0, 0)	(-1, 1)
	<i>S</i>	(-1, 1)	(1, -1)	(0, 0)

- **Payoff functions:** for each player
 Player 1: $u_1 : \mathcal{A}_1 \times \mathcal{A}_2 \rightarrow \mathbb{R}$ defined by $u_1(R, R) = 0, u_1(R, P) = -1, u_1(R, S) = 1, \dots$
 Player 2: $u_2 : \mathcal{A}_1 \times \mathcal{A}_2 \rightarrow \mathbb{R}$ defined by $u_2(R, R) = 0, u_2(R, P) = 1, u_2(R, S) = -1, \dots$

Finite games

Definition 1 (Finite games)

A **finite game in normal (or strategic) form** is a tuple $(\mathcal{N}, \{\mathcal{A}_i\}_{i \in \mathcal{N}}, \{u_i\}_{i \in \mathcal{N}})$, where:

- $\mathcal{N} = \{1, 2, \dots, N\}$ is a finite set of **players**.
- For each player $i \in \mathcal{N}$, \mathcal{A}_i is a finite set of **actions** (or **pure strategies**) for player i .
- For each player $i \in \mathcal{N}$, $u_i : \prod_{j \in \mathcal{N}} \mathcal{A}_j \rightarrow \mathbb{R}$ is a **payoff function** mapping each combination (or **profile**) of actions (a_1, \dots, a_N) to a real number $u_i(a_1, \dots, a_N)$ that is the **payoff** to player i when players $1, 2, \dots, N$ do actions a_1, a_2, \dots, a_N , respectively.

Notation: $\mathcal{A} := \prod_j \mathcal{A}_j$ the set of all profiles of actions, with a generic element $a := (a_1, \dots, a_N)$.

Example 1: The Prisoner's Dilemma

Imagine the following situation:

- Two bank robbers, Thomas and Julian, have been arrested by the authorities and are being interrogated in separate rooms.
- The authorities need one robber to testify to convict them.
- Each robber faces a choice:
 - *cooperate* with his accomplice and remain silent
 - *defect* from the gang and testify for the prosecution
- There are a number of different scenarios that could occur:
 - If Thomas and Julian cooperate, they will each get 1 year in jail.
 - If one testifies against the other, the one who testifies goes free and the other gets 5 years.
 - If they both testify against each other, they will each get 3 years.

How to model this game in normal form?

Example 1: The Prisoner's Dilemma

Normal form representation

- **Players:** $\mathcal{N} = \{1 \text{ (Thomas)}, 2 \text{ (Julian)}\}$
- **Actions** associated to each player: $\mathcal{A}_i = \{C(\text{operate}), D(\text{efect})\}, i \in \mathcal{N}$
- **Payoff matrix:**

		Julian	
		<i>C</i>	<i>D</i>
Thomas	<i>C</i>	$(-1, -1)$	$(-5, 0)$
	<i>D</i>	$(0, -5)$	$(-3, -3)$

- **Payoff functions:** for each player,
 Thomas: $u_1(C, C) = -1, u_1(C, D) = -5, u_1(D, C) = 0, u_1(D, D) = -3$.
 Julian: $u_2(C, C) = -1, u_2(C, D) = 0, u_2(D, C) = -5, u_2(D, D) = -3$.

Example 2: Split or Steal?



- The game **Split or Steal** is a two-player game.
- Each player must decide whether to split the pot of money in front of them or steal from the other player.
- One of these situations will occur.
 - If both players choose split, they each get half of the money.
 - If both players choose steal, neither player gets any money.
 - If only one player steals, the player who chooses steal gets all of the money and the other player gets nothing.

Watch a [playthrough](#) of the £66885 “Split or Steal” game and **then model this game in normal form.**

Example 2: Split or Steal?

Normal form representation

- **Players:** $\mathcal{N} = \{1 \text{ (Tony)}, 2 \text{ (Lucy)}\}$
- **Actions** associated to each player: $\mathcal{A}_i = \{Sp(lit), St(eal)\}, i \in \mathcal{N}$
- **Payoff matrix:**

		Lucy	
		Sp	St
Tony	Sp	(£33442.5, £33442.5)	(£0, £66885)
	St	(£66885, £0)	(£0, £0)

- **Payoff functions:** for each player,
Tony: $u_1(Sp, Sp) = £33442.5$, $u_1(Sp, St) = £0$, $u_1(St, Sp) = £66885$, $u_1(St, St) = £0$.
Lucy: $u_2(Sp, Sp) = £33442.5$, $u_2(Sp, St) = £66885$, $u_2(St, Sp) = £0$, $u_2(St, St) = £0$.

Example 3: Chicken game

- The **Chicken Game** is a game in which two players drive towards each other on a collision course.
- Each driver has two choices: swerve or go straight.
 - If **both drivers swerve**, they will both have a minor accident and get 0 points.
 - If **one driver swerves and the other does not**, the driver who swerves will be hit and get -1 point, while the driver who goes straight will be unharmed and get 1 point.
 - If **neither driver swerves**, they will both crash head-on and be seriously injured, so they will get -1000 points.



How to model this game in normal form?

Example 3: Chicken game

Normal form representation

- **Players:** $\mathcal{N} = \{1 \text{ (Driver 1)}, 2 \text{ (Driver 2)}\}$
- **Actions** associated to each player: $\mathcal{A}_i = \{Sw(erve), St(raight)\}, i \in \mathcal{N}$
- **Payoff matrix:**

		Driver 2	
		Sw	St
Driver 1	Sw	(0, 0)	(-1, 1)
	St	(1, -1)	(-1000, -1000)

- **Payoff functions:** for each driver,
Driver 1: $u_1(Sw, Sw) = 0, u_1(Sw, St) = -1, u_1(St, Sw) = 1, u_1(St, St) = -1000$.
Driver 2: $u_2(Sw, Sw) = 0, u_2(Sw, St) = 1, u_2(St, Sw) = -1, u_2(St, St) = -1000$.

Dominant Strategies

In some games, there is a **dominant strategy** that always produces the best outcome for a player, regardless of what the other players do.

Before definitions, note that for $i \in \mathcal{N}$, $(a', a_{-i}) := (a_1, \dots, a_{i-1}, a', a_{i+1}, \dots, a_N)$, $\mathcal{A}_{-i} := \prod_{j \neq i} \mathcal{A}_j$.

Definition 2 (Dominant strategies)

- 1 A strategy $a_i \in \mathcal{A}_i$ **weakly dominates** $a'_i \in \mathcal{A}_i$ (noted by $a_i \succsim a'_i$) if

$$u_i(a_i, a_{-i}) \geq u_i(a'_i, a_{-i}) \text{ for all } a_{-i} \in \mathcal{A}_{-i} \text{ and } u_i(a_i, a_{-i}) > u_i(a'_i, a_{-i}) \text{ for some } a_{-i} \in \mathcal{A}_{-i}.$$

- 2 A strategy $a_i \in \mathcal{A}_i$ **strictly dominates** $a'_i \in \mathcal{A}_i$ (noted by $a_i \succ a'_i$) if

$$u_i(a_i, a_{-i}) > u_i(a'_i, a_{-i}) \text{ for all } a_{-i} \in \mathcal{A}_{-i}.$$

- 3 A strategy $a_i \in \mathcal{A}_i$ is **weakly dominant** if $a_i \succsim a'_i$ for all $a'_i \in \mathcal{A}_i$.

- 4 A strategy $a_i \in \mathcal{A}_i$ is **strictly dominant** if $a_i \succ a'_i$ for all $a'_i \in \mathcal{A}_i$, $a'_i \neq a_i$.

In other words, $a_i \succsim a'_i$ (resp. $a_i \succ a'_i$) means that a'_i is **weakly** (resp. **strictly**) **dominated** by a_i .

Return to Examples 1-3

Weakly / Strictly dominant strategies for players for each example?

Example 1: The Prisoner's Dilemma

Example 2: Split or Steal?

		Julian	
		<i>C</i>	<i>D</i>
Thomas	<i>C</i>	$(-1, -1)$	$(-5, 0)$
	<i>D</i>	$(0, -5)$	$(-3, -3)$

		Lucy	
		<i>Sp</i>	<i>St</i>
Tony	<i>Sp</i>	$(£33442.5, £33442.5)$	$(£0, £66885)$
	<i>St</i>	$(£66885, £0)$	$(£0, £0)$

Example 3: Chicken game

		Driver 2	
		<i>Sw</i>	<i>St</i>
Driver 1	<i>Sw</i>	$(0, 0)$	$(-1, 1)$
	<i>St</i>	$(1, -1)$	$(-1000, -1000)$

Iteratively Dominated Strategies

Given a 2-player game with the following payoff matrix:

		Player 2		
		A	B	C
Player 1	X	(4,10)	(1,0)	(1,2)
	Y	(3,5)	(6,4)	(5,3)
	Z	(2,3)	(0,6)	(8,2)

Questions: In this game,

- 1 What are the strictly dominated strategies (by which strategies) for players?
- 2 What happens to this game if eliminating one of these strategies? Does new strictly dominated strategies appear?
- 3 If repeating elimination iteratively, what does the game become?

Dominance-Solvable Game

After repeating elimination iteratively, the game becomes as follows:

		Player 2		
		<i>A</i>	<i>B</i>	<i>C</i>
Player 1	<i>X</i>	(4,10)	(1,0)	(1,2)
	<i>Y</i>	(3,5)	(6,4)	(5,3)
	<i>Z</i>	(2,3)	(0,6)	(8,2)

Definition 3 (Dominance-solvable game)

A game is called **dominance-solvable** if the iterated elimination of dominated strategies leads to a **singleton**.

Best Responses

How to make a good decision if we only know the strategy of the opposing players?

Definition 4 (Best responses)

- A strategy $a_i^* \in \mathcal{A}_i$ is a **best response** (or **best reply**) of player i to a profile of strategies $a_{-i} \in \mathcal{A}_{-i}$ for the other players if

$$u_i(a_i^*, a_{-i}) \geq u_i(a_i, a_{-i}) \text{ for all } a_i \in \mathcal{A}_i, \text{ equivalently, } a_i^* \in \operatorname{argmax}_{a_i \in \mathcal{A}_i} u_i(a_i, a_{-i}).$$

- A **best-response correspondence** of player i is a set-valued function $BR_i : \mathcal{A}_{-i} \rightarrow \mathcal{A}_i$ defined by

$$BR_i(a_{-i}) := \operatorname{argmax}_{a_i \in \mathcal{A}_i} u_i(a_i, a_{-i})$$

Return to Examples 1-3

Best-response correspondence for players for each example?

Example 1: The Prisoner's Dilemma

Example 2: Split or Steal?

		Julian	
		<i>C</i>	<i>D</i>
Thomas	<i>C</i>	$(-1, -1)$	$(-5, 0)$
	<i>D</i>	$(0, -5)$	$(-3, -3)$

		Lucy	
		<i>Sp</i>	<i>St</i>
Tony	<i>Sp</i>	$(£33442.5, £33442.5)$	$(£0, £66885)$
	<i>St</i>	$(£66885, £0)$	$(£0, £0)$

Example 3: Chicken game

		Driver 2	
		<i>Sw</i>	<i>St</i>
Driver 1	<i>Sw</i>	$(0, 0)$	$(-1, 1)$
	<i>St</i>	$(1, -1)$	$(-1000, -1000)$

Nash equilibrium

Definition 5 (Nash equilibrium)

A profile of strategies $\mathbf{a}^* = (a_1^*, \dots, a_i^*, \dots, a_N^*) \in \mathcal{A}$ is a **Nash equilibrium** (NE) if

$$a_i^* \in \text{BR}_i(\mathbf{a}_{-i}^*) \text{ for all } i \in \mathcal{N}$$

or, equivalently, if

$$u_i(a_i^*, \mathbf{a}_{-i}^*) \geq u_i(a_i, \mathbf{a}_{-i}^*) \text{ for all } i \in \mathcal{N} \text{ and for all } a_i \in \mathcal{A}_i.$$

Properties

- **Stability:** No player has any incentive to change their current strategy. In other words, no player regrets their decision in an NE.
- **Unilateral resilience:** An NE is resilient to **unilateral** deviations, but it may not be stable for **multi**-lateral deviations.
- **Non-uniqueness:** In many games, there are multiple Nash equilibria.

Return to Examples 1-3

Nash equilibrium for each example?

Example 1: The Prisoner's Dilemma

		Julian	
		<i>C</i>	<i>D</i>
Thomas	<i>C</i>	$(-1, -1)$	$(-5, 0)$
	<i>D</i>	$(0, -5)$	$(-3, -3)$

Example 2: Split or Steal?

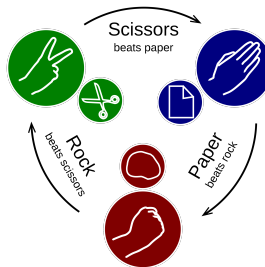
		Lucy	
		<i>Sp</i>	<i>St</i>
Tony	<i>Sp</i>	$(£33442.5, £33442.5)$	$(£0, £66885)$
	<i>St</i>	$(£66885, £0)$	$(£0, £0)$

Example 3: Chicken game

		Driver 2	
		<i>Sw</i>	<i>St</i>
Driver 1	<i>Sw</i>	$(0, 0)$	$(-1, 1)$
	<i>St</i>	$(1, -1)$	$(-1000, -1000)$

Return to the rock-paper-scissors game

		Player 2		
		<i>R</i>	<i>P</i>	<i>S</i>
Player 1	<i>R</i>	(0, 0)	(-1, 1)	(1, -1)
	<i>P</i>	(1, -1)	(0, 0)	(-1, 1)
	<i>S</i>	(-1, 1)	(1, -1)	(0, 0)



Nash equilibrium?

Summary

This lesson

- Finite games: definition + examples
- Strategic dominance: strict, weak, iterated
- Best responses and Nash equilibrium

Next lesson

- Mixed strategies
- Nash's existence theorem
- ...