

# Online Optimization, Learning, and Games (O2LG)

## Lesson 6: Online Learning in Discrete Time

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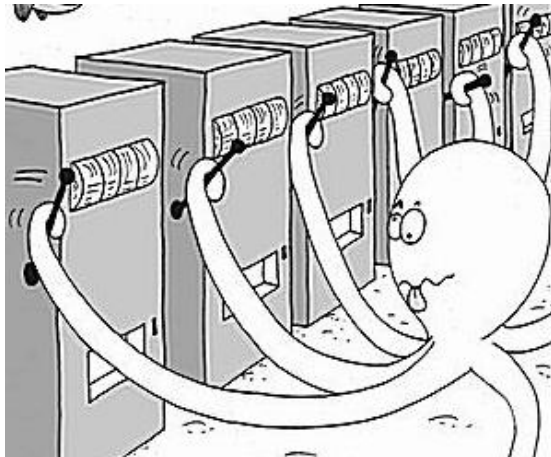
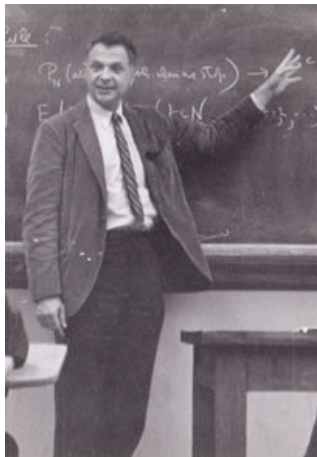


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# Multi-armed bandits

Robbins' multi-armed bandit problem (Robbins 1952): [how to play in a \(rigged\) casino?](#)



# Online learning in discrete time

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## Sequence of events — discrete time

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**Require:** set of actions  $\mathcal{A} = \{1, \dots, A\}$ , sequence of payoff vectors  $v_n$ ,  $n = 1, 2, \dots$   
**for all**  $n = 1, 2, \dots$  **do**  
    Choose **mixed strategy**  $x_n \in \mathcal{X} := \Delta(\mathcal{A})$ .  
    Play **action**  $a_n \sim x_n$ .  
    Encounter **payoff vector**  $v_n$  and receive **payoff**  $u_n(a_n) = v_{a_n, n}$ .  
**end for**

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**Features:** *discrete* time, *single* player, and *exogenous* payoffs.

Three types of **feedback** (from best to worst):

- **Full, exact information:** observe entire payoff vector  $v_n$ .
- **Full, inexact information:** observe noisy estimate of  $v_n$ .
- **Partial information / Bandit:** only chosen component  $u_n(a_n) = v_{a_n, n}$ .

# Feedback

## The oracle model

A **stochastic first-order oracle (SFO)** model of  $v_n$  is a random vector of the form

$$\hat{v}_n = v_n + U_n + b_n, \quad (\text{SFO})$$

where  $U_n$  is **zero-mean** and  $b_n = \mathbb{E}[\hat{v}_n \mid \mathcal{F}_n] - v(x_n)$  is the **bias** of  $\hat{v}_n$ .

## Assumptions 1

- **Bias:**  $\|b_n\| \leq B_n$ .
- **Variance:**  $\mathbb{E}[\|U_n\|^2 \mid \mathcal{F}_n] \leq \sigma_n^2$ .
- **Second moment:**  $\mathbb{E}[\|\hat{v}_n\|^2 \mid \mathcal{F}_n] \leq M_n^2$ .

# Recall: Reconstructing payoff vectors

## Definition 1 (Importance-weighted estimator)

Fix a payoff vector  $v \in \mathbb{R}^A$  and a probability distribution  $P$  on  $\mathcal{A}$ . Then, for a given  $a \in \mathcal{A}$ , the **importance-weighted estimator** of  $v_a$  relative to  $P$  is the **random variable**

$$\hat{v}_a = \frac{v_a}{P_a} \mathbb{1}_a = \begin{cases} \frac{v_a}{P_a} & \text{if } a \text{ is drawn,} \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

## Statistical properties of (1) in IWE

- **Unbiasedness:**  $\mathbb{E}[\hat{v}_a] = v_a$ .
- **Second moment:**  $\mathbb{E}[\hat{v}_a^2] = \frac{v_a^2}{P_a}$ .

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# Regret

The agent's **regret** in discrete time:

Realized regret:  $\overline{\text{Reg}}(T) = \max_{a \in \mathcal{A}} \sum_{n=1}^T [u_n(a) - u_n(a_n)].$

Mean regret:  $\text{Reg}(T) = \max_{p \in \mathcal{X}} \sum_{n=1}^T [u_n(p) - u_n(x_n)] = \max_{p \in \mathcal{X}} \underbrace{\sum_{n=1}^T \langle v_n, p - x_n \rangle}_{\text{Reg}_p(T)}.$



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# The exponential weights algorithm

## Basic idea:

- Score actions by aggregating oracle feedback signals.
- Choose an action with probability exponentially proportional to its score.
- Rinse / repeat.

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### Algorithm 1 Exponential Weights with oracle feedback (ExpWeight)

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**Require:** set of actions  $\mathcal{A}$ , sequence of payoff vectors  $v_n$ , and SFO feedback  $\hat{v}_n$ ,  $n = 1, 2, \dots$

**Initialize:**  $y_1 \in \mathbb{R}^{\mathcal{A}}$ .

**for all**  $n = 1, 2, \dots$  **do**

    set  $x_n \leftarrow \Lambda(y_n)$ .

    play  $a_n \sim x_n$  and receive  $v_{a_n, n}$ .

    observe  $\hat{v}_n \in \mathbb{R}^{\mathcal{A}}$ .

    set  $y_{n+1} \leftarrow y_n + \gamma_n \hat{v}_n$ .

**end for**

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▷ mixed strategy

▷ choose action / get payoff

▷ receive feedback

▷ update scores

# Regret analysis

## Theorem 1 (Auer et al. 1995)

- *Assume:*
  - SFO sequence  $(\hat{v}_n)_n$  unbiased and bounded in mean square ( $B_n = 0$ ,  $\sup_n M_n < M$ ).
  - $\gamma = M^{-1} \sqrt{(2 \log A)/T}$ .
- Then, for all  $p \in \mathcal{X}$ , ExpWeight enjoys the bound

$$\text{Reg}(T) \leq M \sqrt{2 \log A \cdot T} = \mathcal{O}(\sqrt{T}).$$

Mimic the continuous-time case:

- Use a constant  $\gamma_n \equiv \gamma$ .
- Fix the comparator  $p \in \mathcal{X}$  and consider the Fenchel coupling:

$$F_n := F(p, y_n) = \sum_{a \in \mathcal{A}} p_a \log p_a + \log \sum_{a \in \mathcal{A}} \exp(y_{a,n}) - \langle y_n, p \rangle.$$

# Energy inequality

$$F_n := F(p, y_n) = \sum_{a \in \mathcal{A}} p_a \log p_a + \log \sum_{a \in \mathcal{A}} \exp(y_{a,n}) - \langle y_n, p \rangle.$$

## Energy inequality

$$F_{n+1} \leq F_n + \gamma \langle \hat{v}_n, x_n - p \rangle + \mathcal{O}(\gamma^2). \quad (2)$$

## Lemma 1

For all  $y, w \in \mathbb{R}^A$ , we have:  $\log \sum_{a \in \mathcal{A}} \exp(y_a + w_a) \leq \log \sum_{a \in \mathcal{A}} \exp(y_a) + \langle \Lambda(y), w \rangle + \frac{1}{2} \|w\|_\infty^2$ .

## Task 1

Prove and use Lemma 1 to establish the energy inequality (2).

# Regret analysis

- By simplifying and taking expectations, we get

$$\text{Reg}_p(T) \leq \frac{F_1}{\gamma} + \mathcal{O}(\gamma).$$

- Balancing right-hand-side with the step-size  $\gamma$  (defined in the assumption) implies that

$$\text{Reg}(T) \leq M\sqrt{2 \log A \cdot T} = \mathcal{O}(\sqrt{T}). \quad (3)$$

## Task 2

Prove the regret's bound (3).

# Regret of ExpWeight

$$\text{Reg}(T) = \mathcal{O}(\sqrt{T}).$$

## Remarks:

- This bound is tight in  $T$ .
- Logarithmic dependence on  $A$ .
- Cannot achieve  $\mathcal{O}(1)$  regret as in continuous time.

# Abernethy et al. 2008

# Can deal with exponentially many arms!!

# Summary

## This lesson

- Online learning in discrete time
- $\mathcal{O}(\sqrt{T})$  regret in discrete time

## Next lesson

- Online convex optimization

# References

- [1] Jacob Abernethy et al. Optimal Strategies and Minimax Lower Bounds for Online Convex Games. In: Jan. 2008, pp. 415–424 (cited at slide -1).
- [2] P. Auer et al. Gambling in a rigged casino: The adversarial multi-armed bandit problem. In: *Proceedings of IEEE 36th Annual Foundations of Computer Science*. 1995, pp. 322–331 (cited at slide -4).
- [3] Herbert Robbins. Some aspects of the sequential design of experiments. In: *Bulletin of the American Mathematical Society* 58.5 (1952), pp. 527–535 (cited at slide -12).