

#### Goals

- The goal is to learn:
  - how an MPI program runs on a distributed memory system
  - how to write MPI programs
  - how to use basic point-to-point and collective MPI communication
  - how topologies can be defined
  - some useful examples for further work with MPI



#### **Content**

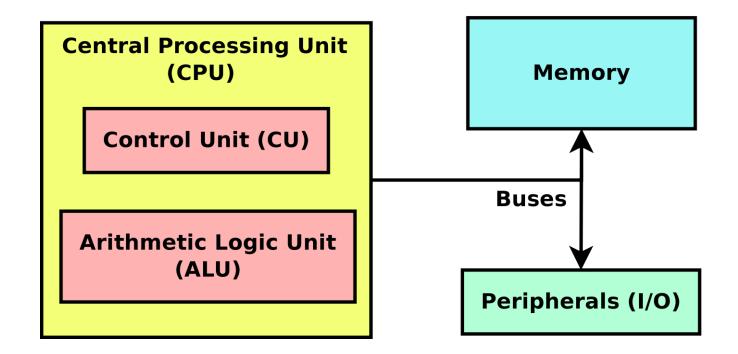
MPI and distributed memory parallelism

Structure of the library functions

Different hands-on exercises



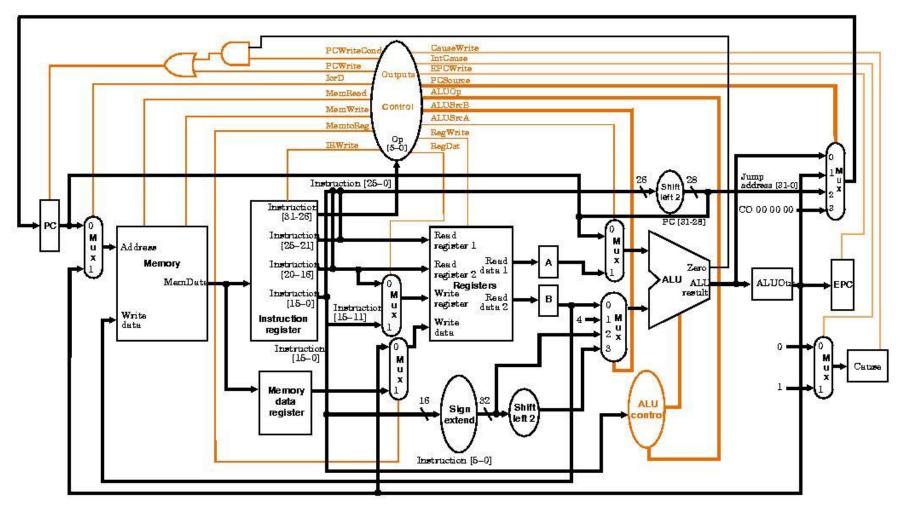
# Recap: a computer is...





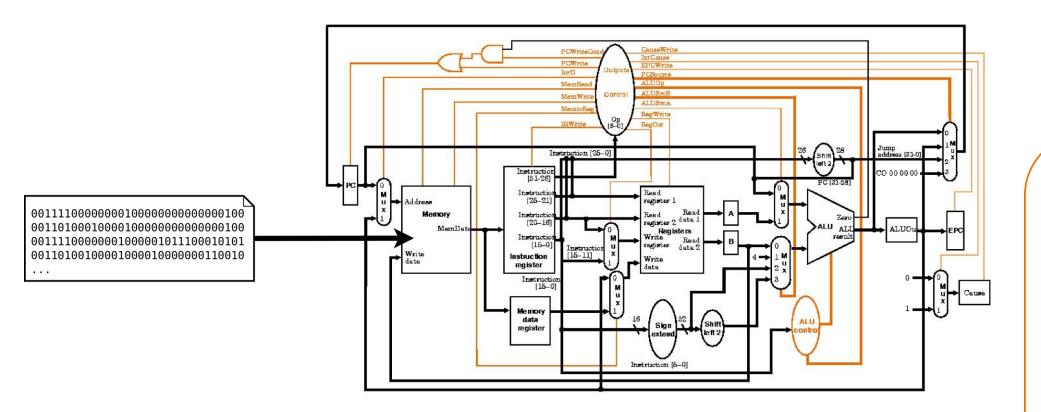
# Recap: a CPU is...

Example of the MIPS architecture: control unit lines in orange, data lines in black



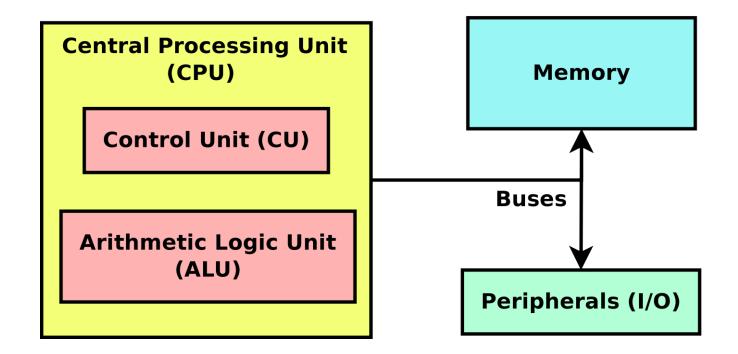


# Recap: a program becomes a process...



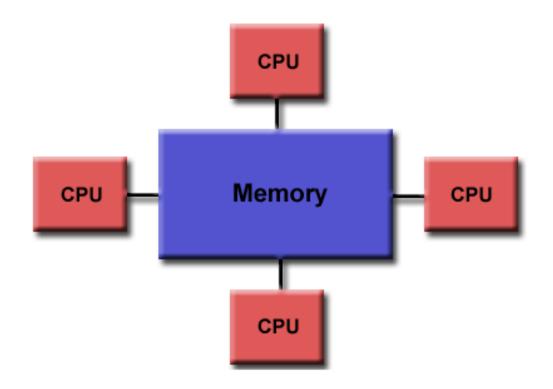


# Recap: different types of computer architectures



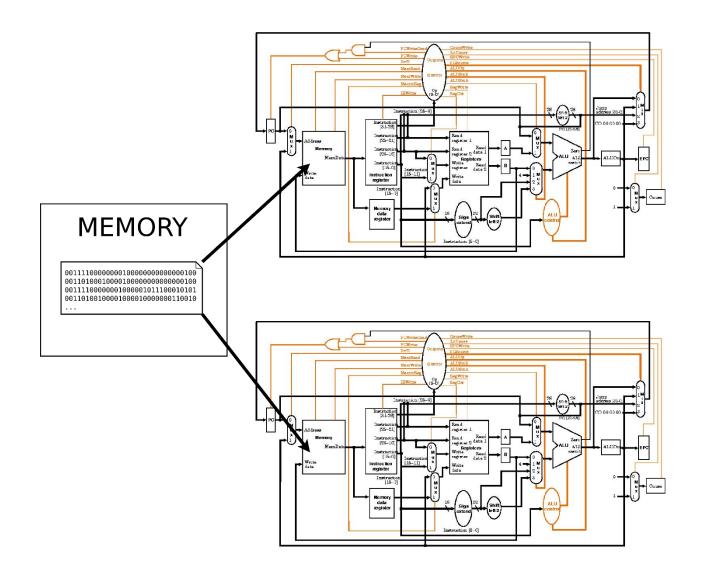


# Recap: different types of computer architectures

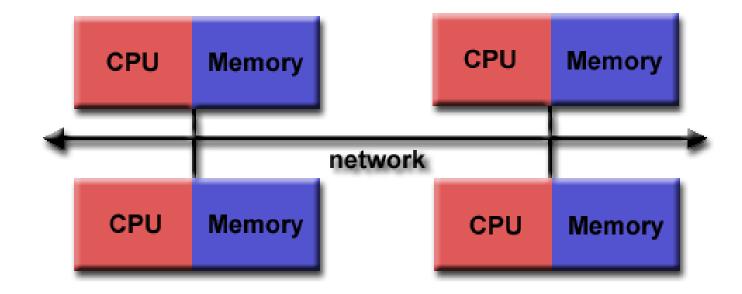




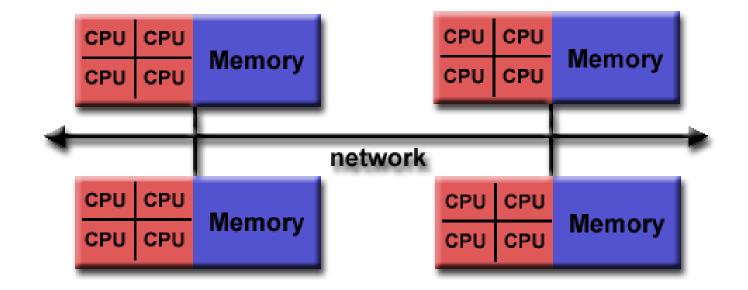
# Recap: different types of computer architectures



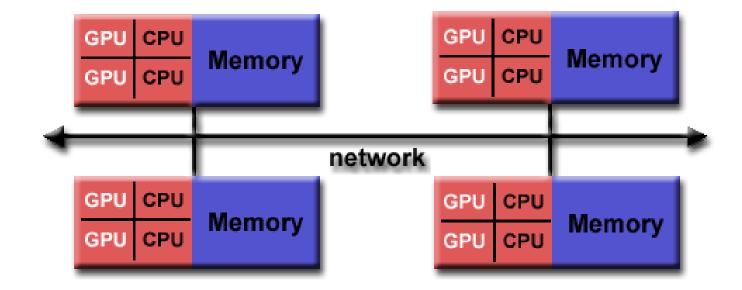




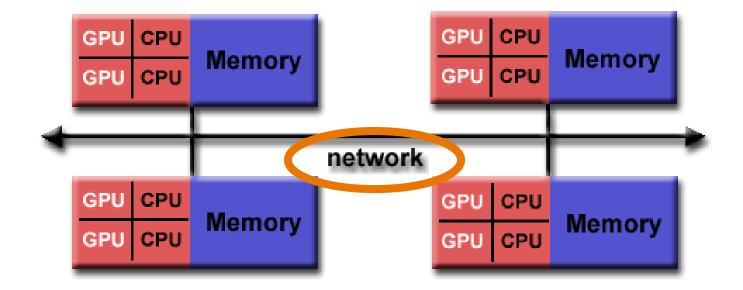






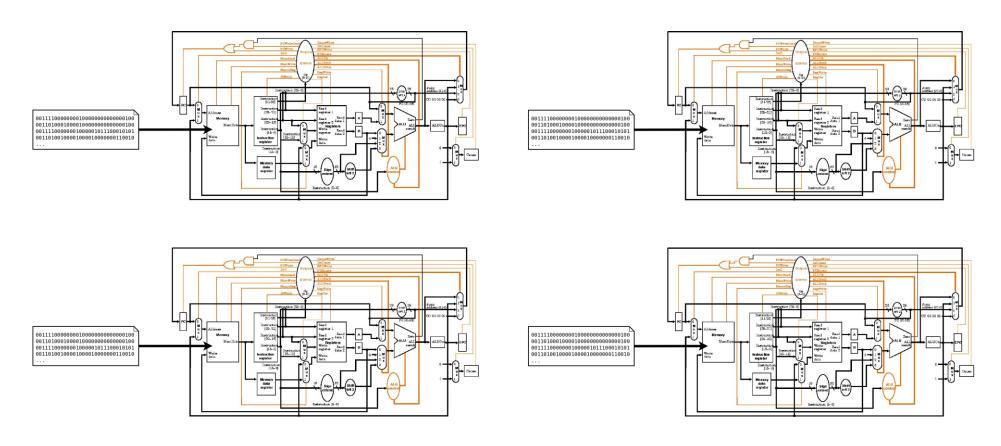






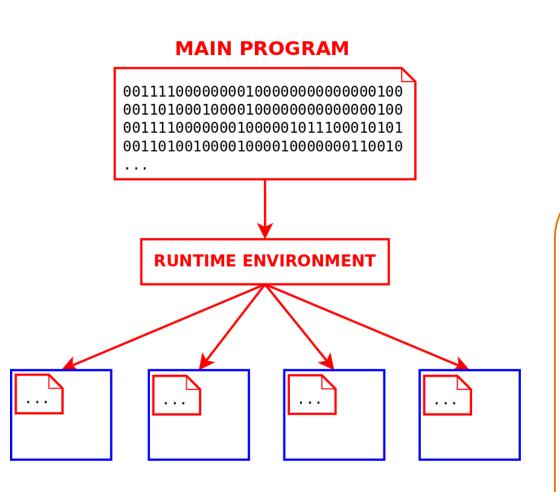


- Basic execution model: SPMD (Single Program, Multiple Data)
- Even MPMD (Multiple Program, Multiple Data) could be possible...



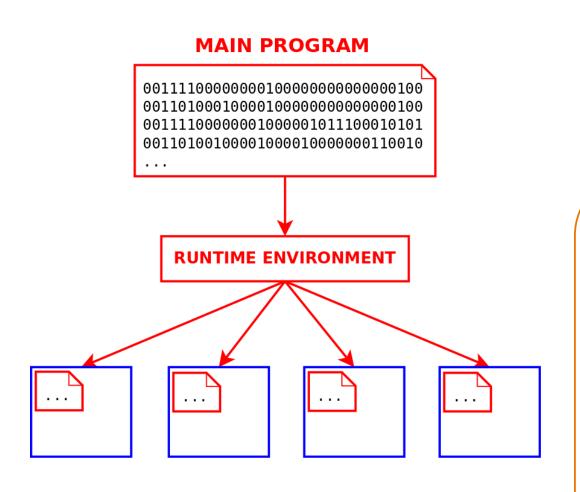


- MPI: Message Passing Interface
- Different processes are created on the one or many machines (nodes)
- Each process executes the same program and has a private copy of all variables
- Inter-process communication by sending/receiving messages andsynchronizations
- Bindings for several languages,
   like C/C++, Fortran, Java or Python



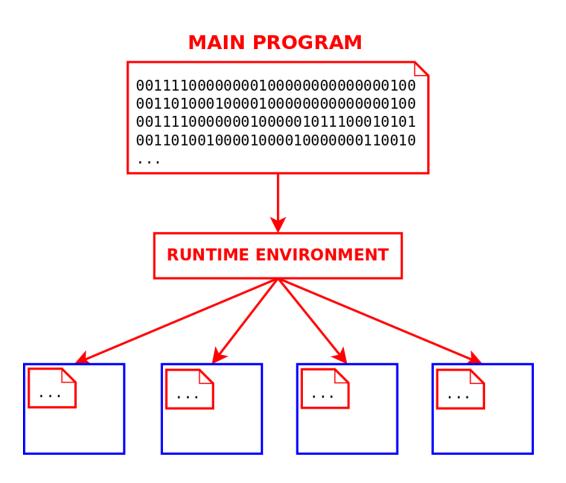


- The interface defines the protocol and the semantic specifications of its functional parts
- Different implementations of the interface can exist
  - IntelMPI
  - OpenMPI
  - MPICH / MVAPICH
- De-facto standard for parallel programming on distributed
   HPC architectures





- In general, MPI requires specific compilation (e.g. mpicc) and specific runtime environment (e.g. mpirun)
- The MPI compiler loads the necessary libraries from the selected MPI implementation
- The MPI runtime is the process that manages communications
  - Internally implemented with daemon processes





#### **Example of multi-process execution with MPI**

```
top - 11:05:19 up 41 days, 15:15, 1 user,
                                           load average: 0,52, 0,26, 0,16
Tasks: 473 total, 5 running, 468 sleeping,
                                              0 stopped,
                                                           0 zombie
%Cpu(s): 0,0 us, 0,1 sy, 16,7 ni, 83,2 id, 0,0 wa, 0,0 hi, 0,0 si, 0,0 st
KiB Mem : 49284800 total, 35059112 free,
                                          784368 used, 13441320 buff/cache
KiB Swap: 25165820 total, 25136612 free,
                                           29208 used. 46491000 avail Mem
 PID USER
               PR NI
                         VIRT
                                 RES
                                        SHR S %CPU %MEM
                                                             TIME+ COMMAND
28875 casparl
                   19
                       419216
                                6880
                                       4240 R/ 100,0 \ 0,0
                                                        0:04.27 my mp1 prog
28876 casparl
               39 19
                      419220
                                6876
                                       4236 R 100,0 0,0
                                                          0:04.27 my mpi prog
28877 casparl
                   19
                       419220
                                6868
                                       4240 R 100,0 0,0
                                                          0:04.26 my mpi proq
                                       4236 R 100,0 0,0
28878 casparl
                   19
                       419216
                                6876
                                                          0:04.26 my_mpi_prog
                        15944
                                1820
                                                         53:35.03 pim
3356 root
                    Θ
                                        956 S 1,7 0,0
                                                 .3 0,0 59:26.22 xfsaild/sda3
  477 root
               20
                    Θ
                                          0 S
```

4 processes, each using a single CPU core



### **Example of multi-process execution with MPI**

- Note the difference:
  - OpenMP: 1 process, 4 threads per process

PID USER	PR		VIRT	RES		%CPU %		TIME+ COMMAND
31648 casparl	39	19	228816	1656	1180 R	400,0	0,0	0:22.37 my_omp_prog
84 root	rt	0	Θ	Θ				0:08.41 migration/15
477 root	20	Θ	Θ	Θ	0 S	0,3	Θ,Θ	59:26.57 xfsaild/sda3

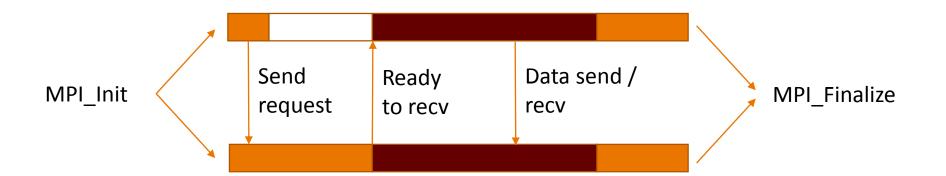
MPI: 4 processes, 1 thread per process

PID U	JSER	PR	NI	VIRT	RES	SHR S	S SCPU	%MEM	TIME+ COMMAND
28875 d	casparl	39	19	419216	6880	4240 F	₹ 100,0	0,0	0:04.27 my_mpi_prog
28876 d	casparl	39	19	419220			100,0		0:04.27 my_mpi_prog
28877 c	casparl	39	19	419220	6868	4240 F	100,0	Θ,Θ	0:04.26 my_mpi_prog
28878 d	casparl	39	19	419216	6876	4236 F	100,0	0,0	0:04.26 my_mpi_prog
3356 r	root	20		15944					53:35.03 pim
477 r	root	20	Θ	Θ	Θ	0 9	0,3	0,0	59:26.22 xfsaild/sda3

... and you may even combine MPI + OpenMP...



- The use of MPI requires some programming efforts to manage all processes coordinately
- In the beginning the MPI environment is initialized, and also finalized at the end of the parallel code
- The basic element is the communicator, which defines
  - communication context
  - set of processes that can communicate between each other inside that context





- The use of MPI requires some programming efforts to manage all processes coordinately
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  - communication context
  - set of processes that can communicate between each other inside that context

	MPI_COMM_WORLD	My_communicator
Process 0	Rank 0	
Process 1	Rank 1	Rank 0
Process 2	Rank 2	Rank 1



#### **General references for MPI**

- Specification documents in the web page of the MPI Forum
- Current specification document: <u>version 3.1</u>
- Revisions and discussions for the elaboration of the MPI standard 4.0 are ongoing



- MPI functions are used inside the code and require including a file or module
  - C/C++: #include <mpi.h>
  - Fortran: use mpi (with Fortran 2008, definitely do "use mpi\_f08")
- Essential structure for MPI routines
  - C/C++: error = MPI\_Routine(arg0, arg1, ...);(the error output may be ignored, but it is very useful for debugging)
  - Fortran: call MPI\_ROUTINE(arg1, arg2, ..., ierror)(the error output is always the last argument: VERY IMPORTANT!!!)
- Global communicator: predefined handle
  - C/C++ AND Fortran: MPI\_COMM\_WORLD (type "MPI\_Comm" or "integer")



Every MPI code begins with an initialization of the environment

```
C/C++: int MPI_Init(int *argc, char ***argv)
```

typical call: MPI\_Init(&argc, &argv);

argc and argv are taken from the main program, NULL is possible too

Fortran: subroutine MPI\_INIT(ierr) integer :: ierr

typical call: call MPI\_Init(ierr)

- Every MPI code ends with a finalize statement that stops the environment
  - C/C++: int MPI\_Finalize()
  - Fortran: subroutine MPI\_FINALIZE(ierr) integer :: ierr



- MPI has different handles that identify specific objects
- Most common handle: predefined constants
  - Defined in mpi.h (C/C++) or in the mpi/mpi\_f08 modules (Fortran)
  - E.g. global communicator MPI\_COMM\_WORLD
- Other handles: type definitions for MPI specific variables or error return codes
  - E.g. communicator types

C/C++:
MPI\_Comm my\_communicator

Fortran: integer :: my communicator

- with mpi\_f08: TYPE(MPI\_Comm)



Every MPI process is identified with a number, called "rank"

C/C++: int MPI\_Comm\_rank(MPI\_Comm comm, int \*rank)

MPI Communicator

Output argument with size value

ierr argument...

**NEVER FORGET** 

when using the

mpi module!!!



Fortran: subroutine MPI\_COMM\_RANK(comm, rank, ierr)

"use mpi": integer :: comm, rank, ierr

"use mpi\_f08": TYPE(MPI\_Comm) :: comm

integer :: rank; integer, optional :: ierr



ierr argument is optional with the module mpi\_f08. Try to use this module when possible!



The number of processes in a communicator can be obtained with another routine

C/C++: int MPI\_Comm\_size(MPI\_Comm comm, int \*size)

**MPI Communicator** 

Output argument with size value

ierr argument...

**NEVER FORGET** 

when using the

mpi module!!!



Fortran: subroutine MPI\_COMM\_SIZE(comm, size, ierr)

"use mpi":

integer :: comm, rank, ierr

"use mpi\_f08": TYPE(MPI\_Comm) :: comm

integer :: rank; integer, optional :: ierr



ierr argument is optional with the module mpi\_f08. Try to use this module when possible!



# Ready for a first hands-on exercise?

Go to the GitHub web page of the course

https://github.com/sara-nl/PRACE-MPI-OpenMP

- Try to write your first MPI code!
  - C/C++: mpi\_hello\_world.c
  - Fortran: mpi\_hello\_world.f

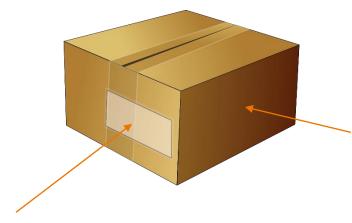


#### Some ideas about MPI execution model

- The execution environment (e.g. mpirun, srun...) creates the requested processes
- After executing MPI\_Init, the processes are located in the same communication environment: MPI\_COMM\_WORLD
- Before MPI\_Init and after MPI\_Finalize the processes still exist, but there is no possible interaction or coordination between them
- MPI follows the SPMD (Single Program, Multiple Data) execution model
  - All processes execute exactly the same program
  - The programmer has the responsibility of making processes cooperate
- General way of cooperation between processes
  - Manual distribution of data and/or tasks
  - Message exchanges (send / receive)



- MPI\_Send() and MPI\_Recv()
  - In order to send and receive it is necessary to create a "parcel"
  - Need for different information: mostly contents and "address label"



- 1. Variable(s) to send/receive
- 2. How many variables to send
- 3. The size of one variable

- 1. Source/Destination address
- 2. Tag
- 3. Communicator (MPI\_COMM\_WORLD)



- A message is any type of data that is communicated from one MPI process to another (or many) process(es)
- MPI datatypes can be basic or derived
  - Basic types are integer, float, double precision, etc.
  - Derived types are usually sets of basic datatypes and/or other derived datatypes
- The naming of datatypes varies with the programming language



Routine to send a message

```
    C/C++: int MPI_Send(void *buffer, int count, MPI_Datatype datatype,
    int dest, int tag, MPI_Comm comm);
```

Fortran: MPI\_SEND(buffer, count, datatype, dest, tag, comm, ierr)
<datatype> buffer(\*)
integer :: count, datatype, dest, tag, comm, ierr



Routine to receive a message

```
    C/C++: int MPI_Recv(void *buffer, int count, MPI_Datatype datatype,
    int dest, int tag, MPI_Comm comm, MPI_Status status);
```

Fortran: MPI\_RECV(buffer, count, datatype, src, tag, comm, status, ierr)

<datatype> buffer(\*)

integer :: count, datatype, src, tag, comm

integer :: status(MPI\_STATUS\_SIZE), ierr



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

Variable to send



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

#Variables to send



Send / receive: C example

Rank 0 int send\_val = 10;

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Datatype of the variable to send



Send / receive: C example

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Datatype of the variable to send



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

Destination rank



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

Tag of the package



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

**MPI** Communicator



Send / receive: C example

Rank 0 int send\_val = 10;

MPI\_Send(&send\_val, 1, MPI\_INT, 1, 10, MPI\_COMM\_WORLD)

Contains info about message & sender

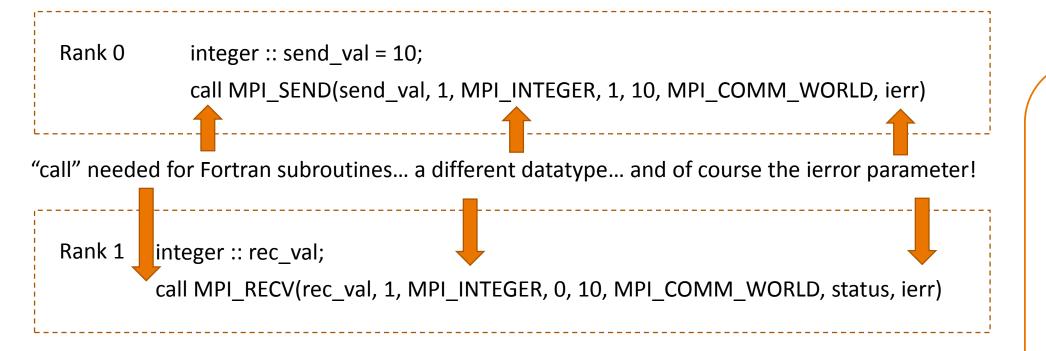
Rank 1 int rec\_val;

MPI\_Recv(&rec\_val, 1, MPI\_INT, 0, 10, MPI\_COMM\_WORLD, &status)

Expects message of size 1 MPI\_INT from rank 0 with tag 10



Send / receive: Fortran example (just a couple differences)





C Data Types		Fortran Data Types		
MPI_CHAR	char	MPI_CHARACTER	character(1)	
MPI_WCHAR	wchar_t - wide character			
MPI_SHORT	signed short int			
MPI_INT	signed int	MPI_INTEGER MPI_INTEGER1 MPI_INTEGER2 MPI_INTEGER4	integer integer*1 integer*2 integer*4	
MPI_LONG	signed long int			
MPI_UNSIGNED	unsigned int			
MPI_FLOAT	float	MPI_REAL MPI_REAL2 MPI_REAL4 MPI_REAL8	real real*2 real*4 real*8	
MPI_DOUBLE	double	MPI_DOUBLE_PRECISION	double precision	
MPI_LONG_DOUBLE	long double			
MPI_C_COMPLEX MPI_C_FLOAT_COMPLEX	float _Complex	MPI_COMPLEX	complex	
MPI_C_DOUBLE_COMPLEX	double _Complex	MPI_DOUBLE_COMPLEX	double complex	
MPI_C_BOOL	_Bool	MPI_LOGICAL	logical	
MPI_BYTE	8 binary digits	MPI_BYTE	8 binary digits	
MPI_PACKED	data packed or unpacked with MPI_Pack()/ MPI_Unpack	MPI_PACKED	data packed or unpacked with MPI_Pack()/ MPI_Unpack	



- Matching communication
  - Correct source and destination ranks inside the same communicator
  - Matching tags
  - Matching datatypes
  - ... and a sufficiently large buffer on the receiver's side
- If there are many matching communications, the order is always preserved in time
  - First come, first served
- Some status information is stored in the receiving side
  - It may be ignored by using the constant MPI\_STATUS\_IGNORE as an argument
  - ... but there is some valuable information inside



Contents of status

C/C++: MPI\_Status status

status.MPI\_SOURCE

status.MPI\_TAG

Fortran: integer status(MPI\_STATUS\_SIZE)

status(MPI\_SOURCE)

status(MPI\_TAG)



Contents of status: getting the message count

C/C++: int MPI\_Get\_count(MPI\_Status \*status,

MPI\_Datatype datatype, int \*count)

Fortran: MPI\_GET\_COUNT(status, datatype, count, ierror)

integer :: status(MPI\_STATUS\_SIZE)

integer :: datatype, count, ierror

 The "get\_count" functions will be very useful in some cases, in order to allocate the receive buffer in advance with enough data for a given message



# Hands-on (very quick)

- Try the code on point-to-point communication
  - C/C++: mpi\_pnt2pnt.c
  - Fortran: mpi\_pnt2pnt.f
- Put the correct source and destination, and the necessary tags



#### Different modes for sending data

- Synchronous send (MPI\_SSEND)
  - Requires synchronization between sender and receiver processes
  - It succeeds when a matching receive call is started
- Buffered send (MPI\_BSEND)
  - Asynchronous: the send is always completed, even without a matching receive
  - It requires a buffer declared with MPI\_BUFFER\_ATTACH
- Generic send (MPI\_SEND)
  - It may be either synchronous or buffered send: decision left to the MPI library
- Ready send (MPI\_RSEND)
  - Performs an immediate send without checking the receiver side (better avoid...)

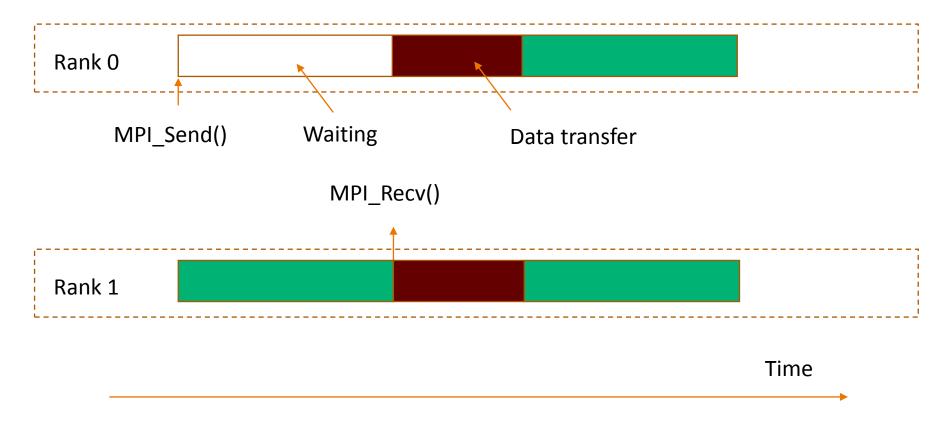


# Only one mode for receiving data

- Generic receive (MPI\_RECV)
  - Matches all possible send modes
  - It waits until a matching send is posted



MPI\_Send (in general) and MPI\_Recv are blocking functions



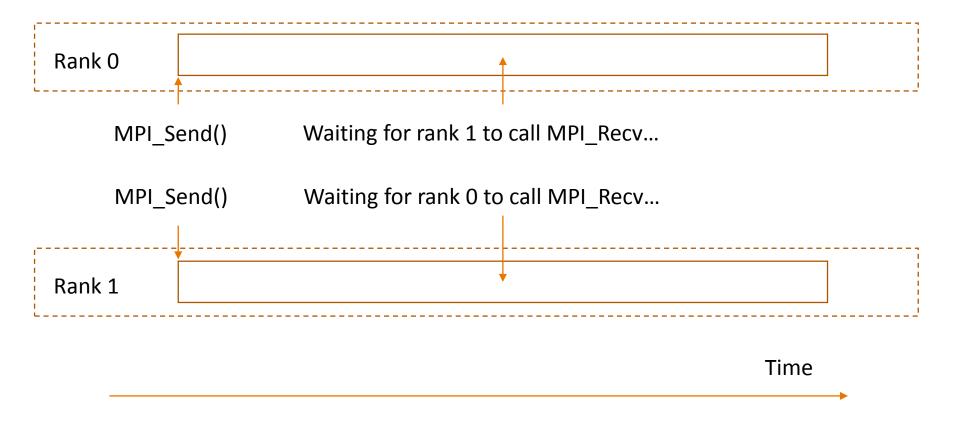


#### Hands-on

- Try the code of the ping-pong communication
  - C/C++: mpi\_pingpong.c
  - Fortran: mpi\_pingpong.f
- Have a look at the code and see how it is working
- What can be wrong?

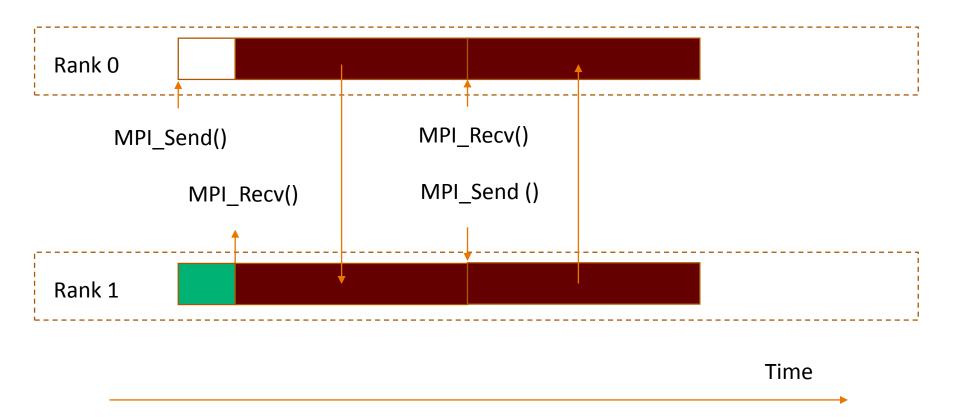


MPI\_Send and MPI\_Recv are blocking functions: a deadlock may occur!!!





 Solution: reverse the order of MPI\_Send and MPI\_Recv for one of the communications





## General problems with blocking communication

- If the MPI library implementation uses synchronous sends, a programmer may find
  - Deadlocks: complete block of the communication, in which two processes try to send at the same time
  - Serialization: inefficient communication because of a bad scheduling of communications



## General problems with blocking communication

- If the MPI library implementation uses synchronous sends, a programmer may find
  - Deadlocks: complete block of the communication, in which two processes try to send at the same time
  - Serialization: inefficient communication because of a bad scheduling of communications
- Solution: non-blocking communications



- It is possible to split the communication process (both send and recv) in two steps
- First step: post a communication request
  - Immediate return of the call and obtain an identifier for the MPI request
  - The effective communication will be done by the MPI library in the background
- Second step: wait for the communication to be completed
  - This will happen after the whole send buffer has been processed and the receive buffer contains all the necessary information



General routine to immediately send a message

```
    C/C++: int MPI_Isend(void *buffer, int count, MPI_Datatype datatype,
    int dest, int tag, MPI_Comm comm, MPI_Request request);
```

Fortran: MPI\_ISEND(buffer, count, datatype, dest, tag, comm, request, ierr)<datatype> buffer(\*)

integer :: count, datatype, dest, tag, comm, request, ierr



General routine to immediately receive a message

```
    C/C++: int MPI_Irecv(void *buffer, int count, MPI_Datatype datatype,
    int src, int tag, MPI_Comm comm, MPI_Request request);
```

Fortran: MPI\_IRECV(buffer, count, datatype, src, tag, comm, request, ierr)
 <datatype> buffer(\*)
 integer :: count, datatype, src, tag, comm, request, ierr



General routine wait for a communication to complete

C/C++: int MPI\_Wait(MPI\_Request request, MPI\_Status status);

Fortran: MPI\_WAIT(request, status, ierr)

integer :: request, status(MPI\_STATUS\_SIZE), ierr



- In a practical way, a call to the wait routine right after an immediate send or receive is analogous to a call to the blocking send or receive, respectively
- In any case, the request obtained from the isend or irecv should be matched in wait
- Between the two steps (immediate communication and wait) a process is allowed to perform additional operations that are unrelated to the communication
- This means the following:
  - The sending process is not allowed to access or reuse the sending buffer or any of the request information
  - The completeness of the operation is only ensured after calling the wait function
  - ...... at least for C/C++



## Non-blocking communication (Fortran only)

- There is a special issue with Fortran: it is an optimizing language, so a call to the wait routine may not imply that the send or recv buffers are ready for use again
- After MPI 3.0, an additional line of code is required In order to avoid any problem with buffer synchronization in Fortran
- Necessary steps:
  - Use the module mpi\_f08 and declare the isend or irecv buffer as asynchronous

```
<datatype>, asynchronous :: buffer
```

Execute the following line of code always immediately after MPI\_WAIT

```
IF (.NOT. MPI_ASYNC_PROTECTS_NONBLOCKING)
& CALL MPI_F_SYNC_REG( buf )
```



- It is also possible to perform a wait in a different way using the test routine
- The use of test requires a loop until the request is fulfilled
  - flag == 1 in C or flag == .TRUE. in Fortran
  - Fortran: this is equivalent to wait, so the asynchronous buffer should also be protected using MPI\_F\_SYNC\_REG as indicated
- Test function
  - C/C++: int MPI\_Test(MPI\_Request request, int flag, MPI\_Status status);
  - Fortran: MPI\_TEST(request, flag, status, ierr)

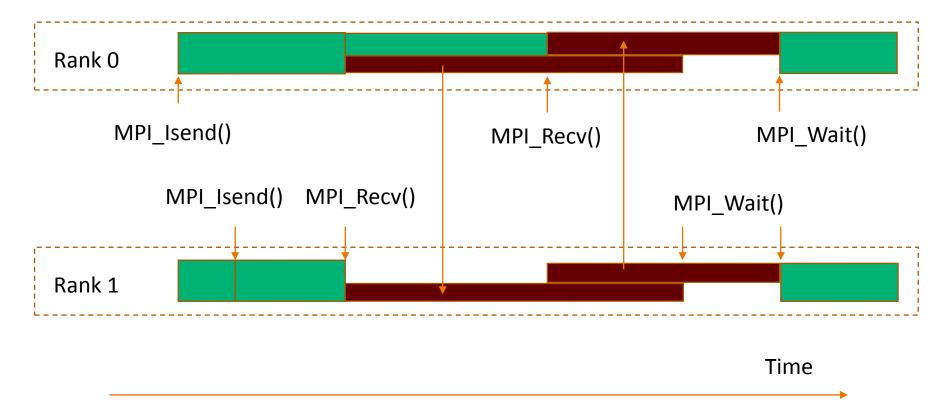
integer :: request, status(MPI\_STATUS\_SIZE), ierr

logical :: flag



## Non-blocking communication example

- The processing of two MPI\_Isend() and MPI\_Recv() calls may be overlapped
- Deadlocks are gone, and it provides a way to avoid serialization!





#### Hands-on

- Work with the following code:
  - C/C++: mpi\_pingpong\_nonblocking.c
  - Fortran: mpi\_pingpong\_nonblocking.f
- Adapt the code to be really non-blocking
- Use MPI\_Isend and/or MPI\_Irecv conveniently
- Check the performance of the code compared to the blocking version
  - C/C++: mpi\_pingpong\_blocking.c
  - Fortran: mpi\_pingpong\_blocking.f
- Which is the fastest version, and how much fast is it?
- There is another function called MPI\_SENDRECV... Can you check the standard specification and see if it would be possible to use it here?



- Sometimes it is necessary to use many point-to-point communications at a time, with specific coordination and synchronization between processes
- Collective functions provide optimized implementations for some common communication patterns
- Different types of collectives
  - Data movement
  - Computation
  - Synchronization



One-to-all

P0	Α	В	U	D
P1				
P2				
Р3				



One-to-all





Broadcast

```
C/C++: int MPI_Bcast(void *buffer, int count, MPI_Datatype datatype, int root, MPI_Comm comm);
```

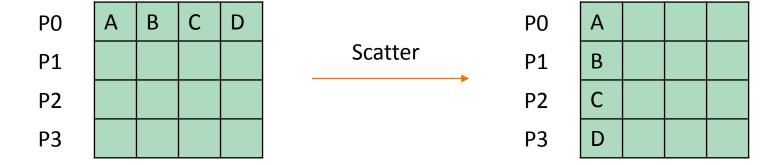
Fortran: MPI\_BCAST(buffer, count, datatype, root, comm, ierr)

<datatype> buffer(\*)

integer :: count, datatype, root, comm, ierr



One-to-all





```
Scatter (with the option of defining MPI_IN_PLACE as sendbuffer)C/C++: int MPI_Scatter(
```

void \*sendbuffer, int sendcount, MPI\_Datatype senddatatype,
void \*recvbuffer, int recvcount, MPI\_Datatype recvdatatype,
int root, MPI\_Comm comm);

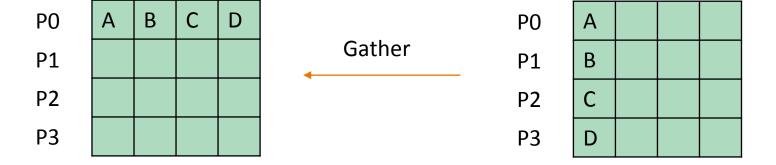
Fortran: MPI\_SCATTER(sendbuffer, sendcount, senddatatype, recvbuffer, recvcount, recvdatatype, root, comm, ierr)

<datatype> sendbuffer(\*), recvbuffer(\*)

integer:: sendcount, senddatatype, recvcount, recvdatatype, root, comm, ierr



All-to-one





Gather (with the option of defining MPI\_IN\_PLACE as sendbuffer)

```
    C/C++: int MPI_Gather(
        void *sendbuffer, int sendcount, MPI_Datatype senddatatype,
        void *recvbuffer, int recvcount, MPI_Datatype recvdatatype,
        int root, MPI_Comm comm);
```

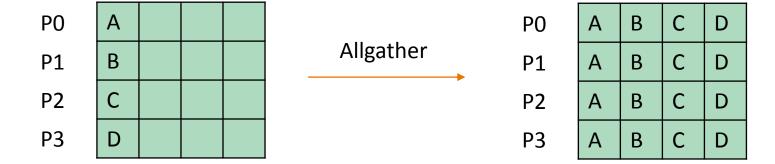
Fortran: MPI\_GATHER(sendbuffer, sendcount, senddatatype, recvbuffer, recvcount, recvdatatype, root, comm, ierr)

<datatype> sendbuffer(\*), recvbuffer(\*)

integer :: sendcount, senddatatype, recvcount, recvdatatype, root, comm, ierr



All-to-all





Allgather int MPI\_Allgather( C/C++: void \*sendbuffer, int sendcount, MPI\_Datatype senddatatype, void \*recvbuffer, int recvcount, MPI\_Datatype recvdatatype, MPI\_Comm comm); MPI\_ALLGATHER(sendbuffer, sendcount, senddatatype, Fortran: recvbuffer, recvcount, recvdatatype, comm, ierr) <datatype> sendbuffer(\*), recvbuffer(\*) integer:: sendcount, senddatatype, recvcount, recvdatatype, comm, ierr



All-to-all

P0	Α	Α	Α	Α		P0	Α	В	C	D
P1	В	В	В	В	Alltoall	P1	Α	В	C	D
P2	С	С	С	С		P2	Α	В	С	D
Р3	D	D	D	D		Р3	Α	В	С	D



```
Alltoall
```

```
int MPI_Alltoall(
C/C++:
              void *sendbuffer, int sendcount, MPI_Datatype senddatatype,
              void *recvbuffer, int recvcount, MPI_Datatype recvdatatype,
              MPI_Comm comm);
            MPI_ALLTOALL(sendbuffer, sendcount, senddatatype,
Fortran:
                           recvbuffer, recvcount, recvdatatype,
                           comm, ierr)
<datatype> sendbuffer(*), recvbuffer(*)
integer:: sendcount, senddatatype, recvcount, recvdatatype, comm, ierr
```



- Computational operations are also possible
  - Most common one: reduce





Reduce int MPI\_Reduce( C/C++: void \*sendbuffer, void \*recvbuffer, int count, MPI\_Datatype datatype, MPI\_Op op, int root, MPI\_Comm comm); MPI\_REDUCE(sendbuffer, recvcount, count, datatype Fortran: op, root, comm, ierr) <datatype> sendbuffer(\*), recvbuffer(\*) integer :: count, datatype, op, comm, ierr



#### Collective communication: reduction operations

- There are different predefined operations for reduce
  - MPI\_MIN, MPI\_MAX, MPI\_SUM, MPI\_PROD
- Another option: custom definition of the operation
  - C/C++: int MPI\_Op\_create(MPI\_User\_function \*function,int commute, MPI\_Op \*op);
  - Fortran: MPI\_OP\_CREATE(function, commute, op, ierr)

external :: function

logical :: commute

integer :: op, ierr



Other collective operation: synchronization barrier

C/C++: int MPI\_Barrier(MPI\_Comm comm);

Fortran: MPI\_BARRIER(comm, ierr)

integer :: comm, ierr



# Hands-on (1)

Try to solve the exercise on collective functions proposed in this directory

https://github.com/sara-nl/PRACE-MPI-OpenMP/tree/master/MPI/collectives

The original codes are stored in the <a href="PRACE CodeVault">PRACE CodeVault</a>

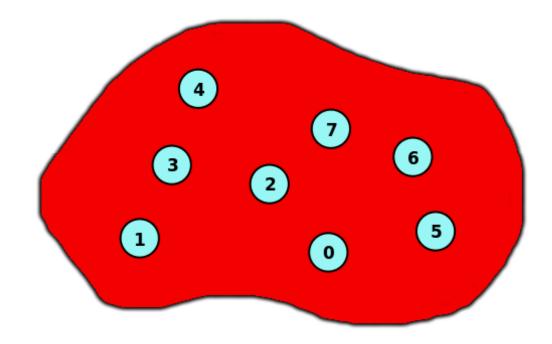


# Hands-on (2)

- ... we've already come a long way here. Time for a parallelization from scratch!
- Try to parallelize the computation of pi
  - C/C++: mpi\_pi.c
  - Fortran: mpi\_pi.f
- Three main tasks need to be performed
  - Distribution of the different iterations between processes
  - Getting the final complete result from all processes
  - Checking that there is scalability with a significant amount of threads



- Well known initial communicator: MPI\_COMM\_WORLD
- Main representation: pool of processes

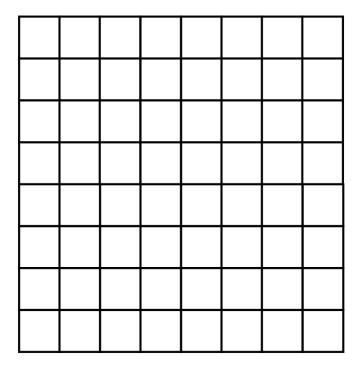




- Possible definition of specific connections between processes to obtain a more structured view of a communicator
- Reasons to obtain this?

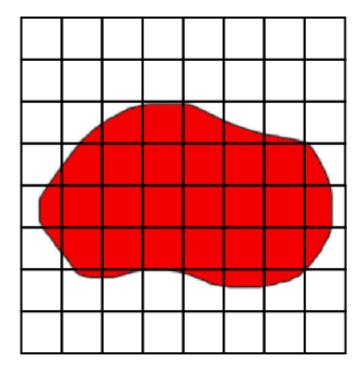


- Possible definition of specific connections between processes to obtain a more structured view of a communicator
- Reasons to obtain this?
- Mimic the structure of the data that we are working on!





- Possible definition of specific connections between processes to obtain a more structured view of a communicator
- Reasons to obtain this?
- Mimic the structure of the data that we are working on!





- MPI provides virtual topologies to organize processes
- Easy access to neighbor processes for communication
- Most common case: cartesian topology
  - C/C++: int MPI\_Cart\_create(MPI\_Comm comm\_old, int ndims, int dims[], int periods[], int reorder,
     MPI\_Comm \*comm\_cart);
  - Fortran: MPI\_CART\_CREATE(comm\_old, ndims, dims, periods, reorder, comm\_cart, ierr)

integer :: comm\_old, ndims, dims(\*), comm\_cart, ierr

logical :: periods(\*), reorder



 Connections between processes in cartesian topologies are established by their given coordinates: easy to calculate and to convert to/from rank

C/C++: int MPI\_Cart\_coords(MPI\_Comm comm, int rank, int maxdims, int coords[]);

Fortran: MPI\_CART\_COORDS(comm, rank, maxdims, coords, ierr)

integer :: comm, rank, maxdims, coords(\*), ierr



 Connections between processes in cartesian topologies are established by their given coordinates: easy to calculate and to convert to/from rank

```
C/C++: int MPI_Cart_rank(MPI_Comm comm, int coords[], int *rank);
```

Fortran: MPI\_CART\_RANK(comm, coords, rank, ierr)

integer :: comm, coords(\*), rank, ierr



Cartesian topologies may also be subdivided in their different dimensions

```
C/C++: int MPI_Cart_sub(MPI_Comm comm, int remain_dims[],
MPI_Comm *comm_new);
```

Fortran: MPI\_CART\_SUB(comm, remain\_dims, comm\_new, ierr)

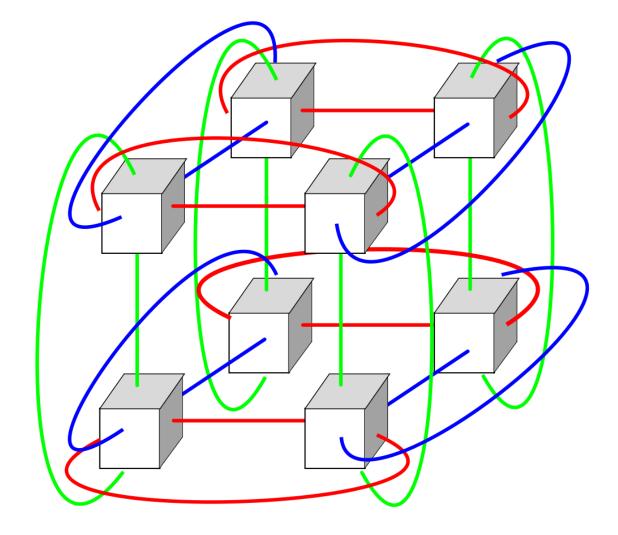
integer :: comm, comm\_new, ierr

logical :: remain\_dims(\*)



### **Hands-on**

- Just do this:
  - C/C++: mpi\_torus.c
  - Fortran: mpi\_torus.f





- Communicators also have maximum flexibility to be created with a custom amount of threads, and later reorganized
- It is necessary to operate at the level of groups of processes to define a completely custom communicator
  - C/C++: int MPI\_Comm\_split(MPI\_Comm comm, int color, int key,
     MPI Comm \*newcomm);
  - Fortran: MPI\_COMM\_SPLIT(comm, color, key, newcomm,ierr)
    - integer :: comm, color, key, newcomm, ierr



- Communicators also have maximum flexibility to be created with a custom amount of threads, and later reorganized
- It is necessary to operate at the level of groups of processes to define a completely custom communicator
  - C/C++: int MPI\_Comm\_group(MPI\_Comm comm, MPI\_Group \*group);
  - Fortran: MPI\_COMM\_GROUP(comm, group, ierr)

integer :: comm, group, ierr



- Communicators also have maximum flexibility to be created with a custom amount of threads, and later reorganized
- It is necessary to operate at the level of groups of processes to define a completely custom communicator
  - C/C++: int MPI\_Group\_incl(MPI\_Group group, int nranks, int ranks[],
    MPI Group \*newgroup);
  - Fortran: MPI\_GROUP\_INCL(group,nranks,ranks,newgroup, ierr)
    - integer :: group, nranks, ranks(\*), newgroup, ierr



- Communicators also have maximum flexibility to be created with a custom amount of threads, and later reorganized
- It is necessary to operate at the level of groups of processes to define a completely custom communicator
  - C/C++: int MPI\_Comm\_create(MPI\_Comm comm, MPI\_Group group,MPI Comm \*newcomm);
  - Fortran: MPI\_COMM\_CREATE(comm, group, newcomm, ierr)
    - integer :: comm, group, newcomm, ierr



#### Hands-on

- Take the previous example of the 3D torus
- Create communicators for each dimension of it
- Check the values of the ranks for every communicator



#### **General comments (1)**

- MPI is based on processes, but also provides threading possibilities
  - MPI\_InitThread(int \*argc, char \*\* argv[], int thr\_requested, int thr\_provided);
  - Varying level of support by the different MPI implementations
- MPI provides a quite complete I/O library with plenty of functionality
  - Recommended: use of high-level libraries that use it with wrappers
  - E.g. PnetCDF, SIONlib
- Derived data types can be defined and may be useful, but relatively cumbersome
  - Try to check if it is possible to codify relatively complex communication using basic data types
  - Use the general type MPI\_PACKED and different routines (MPI\_Pack and MPI\_Unpack to put different data types in the same stream



### **General comments (& 2)**

- MPI also supports one-sided and shared memory communication
  - MPI\_Get / MPI\_Put / MPI\_Win\_create ...
  - Efficient way of performing data movements without explicit "handshake"
  - More info in a forthcoming PRACE MOOC on FutureLearn
- MPI has lots of further possibilities
  - Keep checking the <u>standard documentation</u>
  - Keep practising and be challenged!



