

## Problem Set 2 Solution: Causal Graphs

### Problem 1 (2 points)

Consider the following two period TSCS model where we assume constant effects:

$$y_{i,2} = \beta_0 + \beta_1 x_{i,2} + \beta_2 x_{i,1} + \beta_3 y_{i,1} + \epsilon_{i,2}$$

$$\epsilon_{i,2} = \rho \epsilon_{i,1} + \nu_{i,2}$$

$$x_{i,2} = \delta_1 x_{i,1} + \delta_2 y_{i,1} + \gamma_{i,2}$$

You have the option of estimating the effect of  $x_{i,2}$  on  $y_{i,2}$  using the coefficient on  $x_{i,2}$  from the following regressions:

1.  $y_2 \sim x_2$
2.  $y_2 \sim x_2 + y_1$
3.  $y_2 \sim x_2 + x_1$
4.  $y_2 \sim x_2 + x_1 + y_1$

Consider the situation where some of following may equal zero:  $\beta_2$ ,  $\beta_3$ ,  $\rho$ ,  $\delta_1$ , and  $\delta_2$ .

- a) Suppose that  $\beta_2 = \beta_3 = \delta_2 = 0$ . Which regression or regressions will produce a consistent estimator for  $\beta_1$ ?

1, 3, and 4 will be consistent.

- b) Suppose that  $\beta_2 = 0$  which regression or regressions will produce a consistent estimator for  $\beta_1$ ?

With  $\beta_3 \neq 0$  and  $\delta_2 \neq 0$ , the lagged DV is a common cause of both  $x_{i,2}$  and  $y_{i,2}$ , hence it must be included and only 4 will remain consistent.

## Problem 2 (5 points)

Consider the following two period TSCS model where we assume constant effects:

$$y_{i,2} = \beta_0 + \beta_1 x_{i,2} + \beta_2 x_{i,1} + \beta_3 y_{i,1} + \epsilon_{i,2}$$

$$\epsilon_{i,2} = \rho_\epsilon \epsilon_{i,1} + \nu_{i,2}$$

$$x_{i,2} = \delta_1 x_{i,1} + \delta_2 y_{i,1} + \gamma_{i,2}$$

$$\gamma_{i,2} = \rho_\gamma \gamma_{i,1} + \omega_{i,2}$$

You have the option of estimating the effect of  $x_{i,2}$  on  $y_{i,2}$  using the coefficient on  $x_{i,2}$  from the following regressions:

1.  $y_2 \sim x_2$
2.  $y_2 \sim x_2 + y_1$
3.  $y_2 \sim x_2 + x_1$
4.  $y_2 \sim x_2 + x_1 + y_1$

Consider the situation where some of following may equal zero:  $\beta_2$ ,  $\beta_3$ ,  $\rho_\epsilon$ ,  $\delta_1$ ,  $\delta_2$ , and  $\rho_\gamma$ .

- a) Suppose that  $\beta_2 = \beta_3 = \rho_\epsilon = \delta_1 = \delta_2 = 0$  but that  $\rho_\gamma \neq 0$ . Which regression or regressions will produce a consistent estimator for  $\beta_1$ ?

All four will be consistent.

- b) Suppose that  $\beta_2 = \beta_3 = \delta_1 = \delta_2 = 0$  but that  $\rho_\gamma \neq 0$  and  $\rho_\epsilon \neq 0$ . Which regression or regressions will produce a consistent estimator for  $\beta_1$ ?

Regressions 1, 3, and 4 will produce consistent estimates

- c) Suppose that  $\beta_2 = \delta_1 = \delta_2 = 0$  but that  $\beta_3 \neq 0$ ,  $\rho_\gamma \neq 0$  and  $\rho_\epsilon \neq 0$ . Which regression or regressions will produce a consistent estimator for  $\beta_1$ ?

Regressions 3 and 4 will produce consistent estimates

- d) Suppose that  $\beta_1 = \beta_2 = \beta_3 = \delta_1 = \rho_\gamma = 0$  but that  $\delta_2 \neq 0$  and  $\rho_\epsilon \neq 0$ . Will regression 1 or 3 produce more bias for an estimate of  $\beta_1$ ?

Regression 3 will produce more bias due to bias amplification.

- e) Suppose that  $\beta_1 = \beta_2 = \beta_3 = \delta_1 = \rho_\gamma = 0$  but that  $\delta_2 \neq 0$  and  $\rho_\epsilon \neq 0$  and suppose you do not observe  $y_1$  (i.e., regressions 2 and 4 are no longer options). Propose a consistent estimator for  $\beta_1$ .

Regress  $y_2 \sim x_1$ , regress  $x_2 \sim x_1$ , take the ratio of the slope coefficients (i.e., use the Wald IV estimator).

### Problem 3 (3 points, plus bonus)

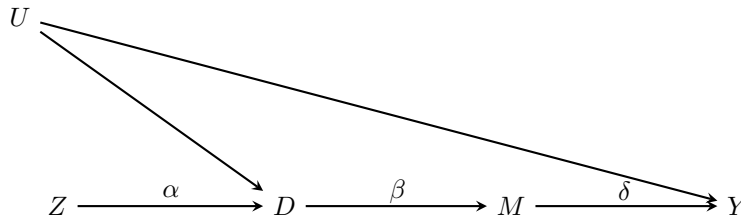


Figure 1: Linear Constant-Effects SEM.  $U$  is unobserved.

a) What is the effect of  $D$  on  $Y$ ?

$\beta \cdot \delta$

b) Describe how you could estimate the effect of  $D$  on  $Y$  using the Wald estimator.

$lm(y \sim z)$  provides  $\widehat{\alpha \cdot \beta \cdot \delta}$ .  $lm(d \sim z)$  provides  $\widehat{\alpha}$ . The ratio provides  $\widehat{\beta \cdot \delta}$

c) Which regression would produce more bias for the effect of  $D$  on  $Y$ :  $lm(y \sim d)$  or  $lm(y \sim d + z)$ ? Why?

$lm(y \sim d + z)$  produces more bias because of amplification.

d) (bonus) Describe some additional ways you could estimate the effect of  $D$  on  $Y$ .

1.  $lm(y \sim m + d)$  provides  $\widehat{\delta}$ .  $lm(m \sim d)$  provides  $\widehat{\beta}$ . Take product.

2.  $lm(m \sim z)$  provides  $\widehat{\alpha \cdot \beta}$ .  $lm(d \sim z)$  provides  $\widehat{\alpha}$ . The ratio provides  $\widehat{\beta}$ .  $lm(y \sim m + d)$  provides  $\widehat{\delta}$ . Take product.

3.  $lm(y \sim z)$  provides  $\widehat{\alpha \cdot \beta \cdot \delta}$ .  $lm(m \sim z)$  provides  $\widehat{\alpha \cdot \beta}$ . The ratio provides  $\widehat{\delta}$ .  $lm(m \sim d)$  provides  $\widehat{\beta}$ . Take product.

### Problem 4 (4 points)

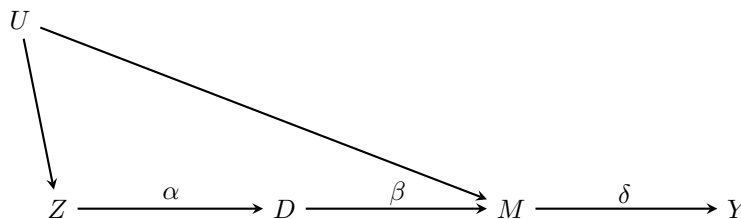


Figure 2: Linear Constant-Effects SEM.  $U$  is unobserved.

a) What is the effect of  $Z$  on  $Y$ ?

$$\alpha \cdot \beta \cdot \delta$$

b) Describe one way you could consistently estimate the effect of  $Z$  on  $Y$ .

$lm(y \sim m)$  provides  $\widehat{\delta}$ .  $lm(m \sim d + z)$  provides  $\widehat{\beta}$ .  $lm(d \sim z)$  provides  $\widehat{\alpha}$ . The product provides  $\widehat{\alpha \cdot \beta \cdot \delta}$

c) What is the effect of  $D$  on  $Y$ ?

$$\beta \cdot \delta$$

d) Describe two ways you could consistently estimate the effect of  $D$  on  $Y$ .

1.  $lm(y \sim d + z)$  provides  $\widehat{\beta \cdot \delta}$

2.  $lm(y \sim m)$  provides  $\widehat{\delta}$ .  $lm(m \sim d + z)$  provides  $\widehat{\beta}$ . Take product.