# Reversing C++

As recent as a couple of years ago, reverse engineers can get by with just knowledge of C and assembly to reverse most applications. Now, due to the increasing use of C++ in malware as well as most moderns applications being written in C++, understanding the disassembly of C++ object oriented code is a must. This paper will attempt to fill that gap by discussing methods of manually identifying C++ concepts in the disassembly, how to automate the analysis, and tools we developed to enhance the disassembly based on the analysis done.

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### I. Introduction and Motivation

As reverse engineers, it is important that we are able to understand C++ concepts as they are represented in disassemblies and of course, have a big picture idea on what are the major pieces (classes) of the C++ target and how these pieces relate together (class relationships). In order to achieve this understanding, the reverse engineer must able to (1) Identify the classes (2) Identify relationships between classes (3) Identify the class members. This paper attempts to provide the reader information on how to achieve these three goals. First, this paper discusses the manual approach on analyzing C++ targets in order to retrieve class information. Next, it discusses ways on how to automate these manual approaches.

Understanding C++ constructs in a disassembly is indeed a good skill to have, but what are our motivations behind learning this skill and writing this paper? The following are what motivated us in producing this paper:

#### 1) Increasing use of C++ code in malcode

Having experience as malcode analysts, there are cases in which the malcode we are trying to understand is written in C++. Loading the malcode in IDA and performing static analysis of virtual function calls is sometimes difficult because being an indirect call, it is not easy to determine where these calls will go. Some example of notorious malcodes that are written in C++ are Agobot, some variants of Mytob, we are also seeing some new malcodes developed in C++ from our honeypot.

### 2) Most modern applications use C++

For large and complex applications and systems, C++ is one of the languages of choice. This means that for binary auditing, reversers expects that there are targets that are written in C++. Information about how C++ concepts are translated into binary and being able to extract high level information such as class relationships is beneficial.

# 3) General lack of publicly available information regarding the subject of C++ reversing

We believe that being able to document the subject of C++ reversing and sharing it to fellow reverse engineers is a good thing. It is indeed not easy to gather information about this subject and there is only a handful of information that specifically focuses on it.

# **II. Manual Approach**

This section introduces the manual approach of analyzing C++ binaries; it specifically focuses on identifying/extracting C++ classes and their corresponding members (variables, functions, constructors/destructors) and relationships. Note

# A. Identifying C++ Binaries and Constructs

As a natural way to start, the reverser must first determine if a specific target is indeed a compiled C++ binary and is using C++ constructs. Below are some pertinent indications that the binary being analyzed is a C++ binary and is using C++ constructs.

1) **Heavy use of ecx** (*this* ptr). One of the first things that a reverser may see is the heavy use of ecx (which is used as the *this* pointer). One place the reverser may see it is that it is being assigned a value just before a function is about to be called:

```
.text:004019E4 mov ecx, esi
.text:004019E6 push 0BBh
.text:004019EB call sub_401120 ; Class member function
```

Another place is if a function is using ecx without first initializing it, which suggests that this is a possible class member function:

```
.text:004010D0 sub 4010D0
                          proc near
.text:004010D0
                          push esi
.text:004010D1
                           mov
                                  esi, ecx
.text:004010DD
                                  dword ptr [esi], offset off 40C0D0
                           mov
.text:00401101
                           mov
                                  dword ptr [esi+4], OBBh
                                 sub_401EB0
.text:00401108
                           call
.text:0040110D
                                  esp, 18h
                           add
.text:00401110
                           pop
                                   esi
                            retn
.text:00401111
.text:00401111 sub_4010D0
                           endp
```

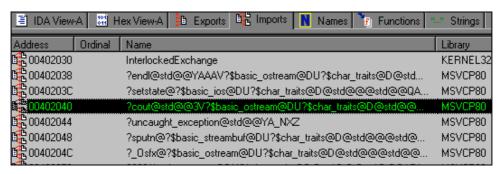
4) **Calling Convention**. Related to (1), Class member functions are called with the usual function parameters in the stack and with ecx pointing to the class's object (i.e. *this* pointer.). Here is an example of a class instantiation, in which the allocated class object (eax) will eventually be passed to ecx and then invocation of the constructor follows.

Additionally, reversers will notice indirect function calls which are more likely virtual functions; it is of course, difficult to follow where these calls go without first knowing the actual class or running the code under a debugger. Consider the following virtual function call example:

```
.text:00401996 call
                      ??2@YAPAXI@Z
                                      ; operator new(uint)
.text:004019B2 mov
                      esi, eax
.text:004019AD call
                      ClassA_ctor
                                    ;EAX = virtual function table
.text:004019FF mov
                      eax, [esi]
                             esp, 8
.text:00401A01
                      add
.text:00401A04
                      mov
                              ecx, esi
                              0CCh
.text:00401A06
                      push
.text:00401A0B
                      call
                              dword ptr [eax]
```

In this case, the reverser must first know where the virtual function table (vftable) of ClassA is located, and then determine the actual address of the function based from the list of functions listed in the vftable.

5) **STL Code and Imported DLLs**. Another way to determine if a sample is a C++ binary is if the target is using STL code, which can be determined via Imported functions or library signature identification such as IDA's FLIRT:



#### And the calls to STL code:

```
.text:00401201 mov ecx, eax
.text:00401203 call
ds:?sputc@?$basic_streambuf@DU?$char_traits@D@std@@@std@@QAEHD@Z;
std::basic_streambuf<char,std::char_traits<char>>::sputc(char)
```

### **Class Instance Layout**

Before going any further, the reverser should also be familiar with how classes are laid out in memory. Let's start with a very simple class.

```
class Ex1
{
    int var1;
    int var2;
    char var3;
public:
    int get_var1();
};
```

The layout for this class will look like this:

Padding was added to the last member variable because it must align on a 4-byte boundary. In Visual C++, member variables are placed in the memory in the same order as they are declared.

What if the class contains virtual functions?

```
class Ex2
{
        int var1;
public:
        virtual int get_sum(int x, int y);
        virtual void reset_values();
};
```

Here's the class layout:

Note that a pointer to the virtual functions table is added at the beginning of the layout. This table contains the address of virtual functions in the order they are declared. The virtual functions table for class Ex2 will look like this.

Now what if a class inherits from another class? Here's what happens when a class inherits from a single class i.e. single inheritance:

```
class Ex3: public Ex2
{
     int var1;
public:
     void get_values();
};
```

### And the layout:

As you can see, the layout of the derived class is simply appended to the layout of the base class. In the case of multiple inheritance, here's what happens:

```
class Ex4
{
     int var1;
     int var2;
public:
        virtual void func1();
        virtual void func2();
};
```

```
class Ex5: public Ex2, Ex4
        int var1;
public:
        void func1();
        virtual void v_ex5();
};
class Ex5 size(24):
       | +--- (base class Ex2)
       | | var1
       | +---
       | +--- (base class Ex4)
 8
       12
       | | var1
16
       | | var2
       | +---
       | var1
       +---
Ex5::$vftable@Ex2@:
     | &Ex2::get_sum
      | &Ex2::reset_values
1
 2
       | &Ex5::v ex5
Ex5::$vftable@Ex4@:
       | -8
 0
     | &Ex5::func1
     | &Ex4::func2
```

As you can see, a copy if each base class's instance data will be embedded in the derived class's instance, and each base class that contains virtual functions will have their own vftable. Take note that the fist base class shares a vftable with the current object. The current object's virtual functions will be appended at the end of the first base class's virtual functions list

# **B. Identifying Classes**

After identifying C++ binaries, discussing some important C++ constructs and how a class instance is represented in memory, this part now present ways on identifying C++ classes used in the target. The methods discussed below only tries to determine what are the classes (i.e. the target has ClassA, ClassB, ClassC, etc). The next sections of this paper will discuss how to infer relationships between these classes and determine their members

### 1) Identifying Constructors/Destructors

To identify classes in the binary, we need to examine how objects of these classes are created. How their creation are implemented in the binary level can provide us with hints on identifying them in the disassembly.

1) Global Object. Global objects, as the name implies, are objects declared as global variables. Memory spaces for these objects are allocated at compile-time and are placed in the data segment of the binary. The constructor is implicitly called before main(), during C++ startup, and the destructor is called at program exit.

To identify a possible global object, look for a function called with a pointer to a global variable as the *this* pointer. To locate the constructor and destructor, we have to examine cross-references to this global variable. Look for locations where this variable is passed as the *this* pointer to a function call. If this call lies between the path from program entry point and main(), it is probably the constructor.

2) Local Object. Local objects are objects that are declared as local variables. The scope of these objects are from the point of declaration until the block exit e.g. end of function, closing braces. Space the size of the object is allocated in the stack. The constructor is called at the point of object declaration, while the destructor is called at the end of the scope.

A constructor for a local object can be identified if a function is called with a *this* pointer that points to an uninitialized stack variable. The destructor is the last function called with this *this* pointer in the same block where the constructor was called i.e. the block where the object was declared.

### Here's an example:

```
.text:00401060 sub 401060
                          proc near
.text:00401060
.text:00401060 var C
                           = dword ptr -0Ch
.text:00401060 var_8
                           = dword ptr -8
.text:00401060 var 4
                           = dword ptr -4
.text:00401060
...(some code)...
.text:004010A4
                   add
                           esp, 8
.text:004010A7
                    cmp
                           [ebp+var_4], 5
.text:004010AB
                   jle
                           short loc_4010CE
.text:004010AB
.text:004010AB { ← block begin
.text:004010AD
                         ecx, [ebp+var 8] ; var 8 is uninitialized
                   lea
.text:004010B0
                   call sub 401000; constructor
.text:004010B5
                   mov edx, [ebp+var_8]
                  push
                         edx
.text:004010B8
.text:004010B9
                  push offset str->WithinIfX
                    call sub 4010E4
.text:004010BE
.text:004010C3
                    add
                           esp, 8
.text:004010C6
                   lea
                           ecx, [ebp+var_8]
.text:004010C9
                   call sub 401020 ; destructor
.text:004010CE \} \leftarrow block end
.text:004010CE
.text:004010CE loc_4010CE:
                                     ; CODE XREF: sub_401060+4B\[]
                         [ebp+var_C], 0
.text:004010CE
                  mov
.text:004010D5
                   lea ecx, [ebp+var_4]
.text:004010D8
                   call sub 401020.
```

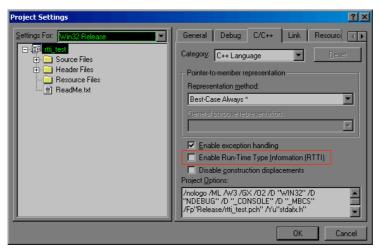
3) Dynamically Allocated Object. These objects are dynamically created via the new operator. The new operator is actually converted into a call to the new() function, followed by a call to the constructor, The new() function takes the size of the object as parameter, allocates memory of this size in the heap, then returns the address of this buffer. The returned address is then passed to the constructor as the this pointer. The destructor has to be invoked explicitly via the delete operator. The delete operator is converted into a call to the destructor, followed by a call to free to deallocate the memory allocated in the heap.

### Here's an example:

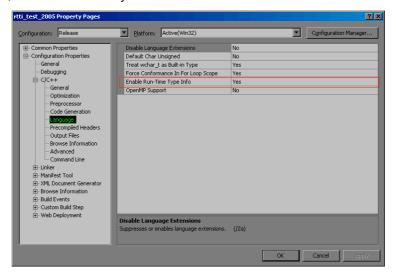
```
.text:0040103D main
                          proc near
.text:0040103D argc
                           = dword ptr 8
.text:0040103D argv
                           = dword ptr 0Ch
.text:0040103D envp
                           = dword ptr 10h
.text:0040103D
.text:0040103D
                   push esi
                    push 4
.text:0040103E
                                         ; size t
.text:00401040
                    call ??2@YAPAXI@Z ; operator new(uint)
.text:00401045
                    test eax, eax ;eax = address of allocated
memory
.text:00401047
                   pop
                           ecx
.text:00401048
                           short loc_401055
                   jΖ
.text:0040104A
                   mov
                         ecx, eax
.text:0040104C
                    call sub 401000; call to constructor
.text:00401051
                    mov
                           esi, eax
                    jmp short loc_401057
.text:00401053
.text:00401055 loc 401055:
                                       ; CODE XREF: _main+B□j
.text:00401055
                           xor
                                  esi, esi
.text:00401057 loc_401057:
                                       ; CODE XREF: _main+16□j
.text:00401057
                   push 45h
.text:00401059
                         ecx, esi
.text:0040105B
                   call sub_401027
.text:00401060
                   test esi, esi
                           short loc_401072
.text:00401062
                    jΖ
.text:00401064
                           ecx, esi
                   mov
.text:00401066
                   call sub 40101B; call to destructor
                    push esi ; void *
.text:0040106B
                    call j_free; call to free thunk function
.text:0040106C
.text:00401071
                    pop ecx
                                        ; CODE XREF: _main+25□j
.text:00401072 loc_401072:
.text:00401072
                    xor
                         eax, eax
.text:00401074
                    pop
                           esi
.text:00401075
                    retn
.text:00401075 main
                            endp
```

### 2) Polymorphic Class Identification via RTTI

Another way to identify classes, specifically *polymorphic classes* (classes with member virtual functions) is via Run-time Type Information (RTTI). RTTI is a mechanism in which the type of an object can be determined at runtime. This mechanism is the one being utilized by the typeid and dynamic\_cast operator. Both these operators need information about the classes passed to them, such as class name and class hierarchy. In fact, the compiler will display a warning if these operators are used without enabling RTTI. By default, RTTI is disabled on MSVC 6.0.



On MSVC 2005, RTTI is enabled by default.



As a side note, there is a compiler switch that enables the MSVC compiler to generate class layout, the switch is <code>-dlreportAllClassLayout</code> this switch generates a <code>.layout</code> file which contains a wealth of information regarding the layout of a class including offsets of the base classes within the derived class, virtual function table (vftable), virtual base class table

(vbtables, which is further described below), and member variables, etc.

To make RTTI possible, the compiler stores several data structures in the compiled code, these data structures contains information about classes (specifically, polymorphic classes) in the code. These data structures are as follows:

### RTTICompleteObjectLocator

This structure contains pointers to two structures that identify (1) the actual class information and (2) the class hierarchy:

Offset	Туре	Name	Description
0x00	DW	signature	Always 0?
			Offset of vftable within
0x04	DW	offset	the class
0x08	DW	cdOffset	
0x0C	DW	pTypeDescriptor	Class Information
			Class Hierarchy
0x10	DW	pClassHierarchyDescriptor	Information

Below is an example how the RTTICompleteObjectLocator pointer is laid out. The pointer to this data structure is just below the vftable of the class:

And this is an example of the actual RTTICompleteObjectLocator structure:

### **TypeDescriptor**

This structure is pointed to by the 4<sup>th</sup> DWORD field in RTTICompleteObjectLocator, it contains the class name, which if obtained will give the reverser a general idea what this class is supposed to do.

Offset	Type	Name	Description	
			Always point to type info's	
0x00	DW	pVFTable	vftable	
0x04	DW	spare	?	
0x08	SZ	name	Class Name	

This is an example of an actual TypeDescriptor:

### RTTIClassHierarchyDescriptor

This structure contains information about the hierarchy of the class including the number of base classes and an array of RTTIBaseClassDescriptor (discussed later) which will eventually point to the TypeDescriptor of the base classes.

Offset	Type	Name	Description
0x00	DW	signature	Always 0?
			Bit 0 - multiple inheritance
0x04	DW	attributes	Bit 1 - virtual inheritance
			Number of base classes.
			Count includes the class
0x08	DW	numBaseClasses	itself
			Array of
0x0C	DW	pBaseClassArray	RTTIBaseClassDescriptor

As an example, below is a class declaration of <code>ClassG</code> virtually inheriting from <code>ClassA</code> and <code>ClassE</code>.

```
class ClassA {...}
class ClassE {...}
class ClassG: public virtual ClassA, public virtual ClassE {...}
```

And below is the actual RTTIClassHierarchyDescriptor for ClassG:

There are 3 base classes (including the count for ClassG itself), the attribute is 3 (multiple, virtual inheritance), and finally, pBaseClassArray points to an array of pointers to RTTIBaseClassDescriptors.

#### RTTIBaseClassDescriptor

This structure contains information about the base class, which includes a pointer to the base class's TypeDescriptor and RTTIClassHierarchyDescriptor and additionally contains the PDM structure contains information on how the base class is laid out inside in the class.

Offset	Type	Name	Description
			TypeDescriptor of this base
0x00	DW	pTypeDescriptor	class
			Number of direct bases of
0x04	DW	numContainedBases	this base class
			vftable offset (if PMD.pdisp
0x08	DW	PMD.mdisp	is -1)
			vbtable offset (-1: vftable
			is at displacement PMD.mdisp
0x0C	DW	PMD.pdisp	inside the class)
			Displacement of the base
			class vftable pointer inside
0x10	DW	PMD.vdisp	the vbtable
0x14	DW	attributes	?
			RTTIClassHierarchyDescriptor
0x18	DW	pClassDescriptor	of this base class

A vbtable (virtual base class table) is generated for multiple virtual inheritance. Because it is sometimes necessary to *upclass* (casting to base classes), the exact location of the base class needs to be determined. A vbtable contains a displacement of each base class' vftable which is effectively the beginning of the base class within the derived class.

Consider the ClassG class declaration previously shown; the compiler will generate the following class structure:

```
class ClassG
                 size(28):
 0
         | {vfptr}
 4
         | {vbptr}
         +--- (virtual base ClassA)
8
         | {vfptr}
12
         | class_a_var01
16
         | class_a_var02
         | <alignment member> (size=3)
         +--- (virtual base ClassE)
20
         | {vfptr}
24
         | class e var01
```

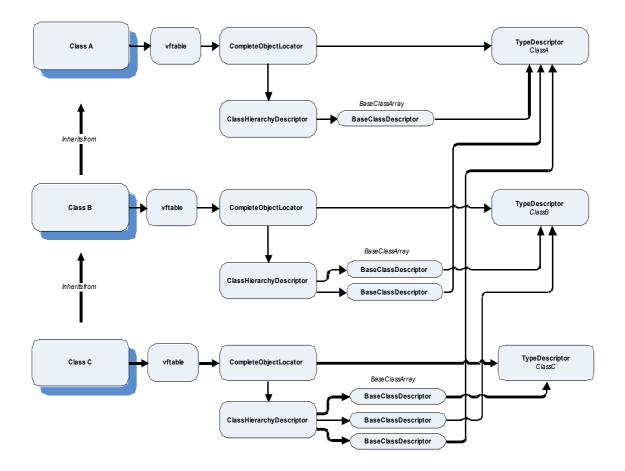
In this case, the <code>vbtable</code> is at offset 4 of the class. The <code>vbtable</code>, on the other hand contains the displacement of the each base class inside the derived class:

To determine the exact offset of ClassE within ClassG, the offset of the vbtable needs to fetched (4), then the displacement of ClassE from the vbtable (16) which if added equals to 20 (4 + 16).

The actual BaseClassDescriptor of ClassE within ClassG is as follows:

PMD.pdisp is 4 which is the offset of the vbtable within ClassG, and PMD.vdisp is 8 which means that  $3^{rd}$  DWORD within the vbtable.

The diagram below shows the how the overall RTTI data structures are connected and laid out.



# D. Identifying Class Relationship

### 1. Class Relationship via Constructor Analysis

Constructors contain code that initializes the object, such as calling up constructors for base classes and setting up vftables. As such, analyzing constructors can give us a pretty good idea about this class's relationship with other classes.

### Single Inheritance

```
.text:00401010 sub 401010
                          proc near
.text:00401010
.text:00401010 var 4
                          = dword ptr -4
.text:00401010
.text:00401010
                  push
                         ebp
.text:00401011
                  mov
                          ebp, esp
.text:00401013
                  push
.text:00401014
                   mov
                          [ebp+var_4], ecx; get this ptr to current object
.text:00401017
                  mov
                         ecx, [ebp+var 4];
.text:0040101A
                   call sub 401000 ; call class A constructor
.text:0040101F
                          eax, [ebp+var 4]
                   mov
.text:00401022
                          esp, ebp
.text:00401024
                   pop
                           ebp
.text:00401025
                   retn
.text:00401025 sub 401010
                           endp
```

Let's assume that we have determined that this is function is a constructor using methods mentioned in section II-B. Now, we see that a function is being called using the *this* pointer of the current object. This can be a member function of the current class, or a constructor for the base class.

How do we know which one is it? Actually, there's no way to perfectly distinguish between the two just by looking at the code generated. However, in real world applications, there is a high possibility that constructors will be identified as such prior to this step (see section II-B), so all we have to do is correlate this info to come up with a more accurate identification. In other words, if a function that was pre-determined to be a constructor is called inside another constructor using the current object's *this* pointer, it is probably a constructor for a base class.

Manually identifying this would entail checking other cross-references to this function and see if this function is a constructor called somewhere else in the binary. We will discuss automatic identification methods later in this document.

### **Multiple Inheritance**

```
.text:00401020 sub_401020 proc near
.text:00401020
.text:00401020 var 4
                            = dword ptr -4
.text:00401020
.text:00401020
                             push
                                     ebp
.text:00401021
                             mov
                                     ebp, esp
.text:00401023
                                     ecx
                             push
.text:00401024
                                     [ebp+var 4], ecx
                             mov
.text:00401027
                             mov
                                     ecx, [ebp+var_4] ; ptr to base class A
.text:0040102A
                                     sub_401000 ; call class A constructor
                             call
.text:0040102A
.text:0040102F
                                     ecx, [ebp+var 4]
                            mov
                                     ecx, 4 ; ptr to base class C
.text:00401032
                            add
                                     sub_401010 ; call class C constructor
.text:00401035
                             call
.text:00401035
.text:0040103A
                                     eax, [ebp+var_4]
                            mov
.text:0040103D
                             mov
                                     esp, ebp
.text:0040103F
                                     ebp
                             pop
.text:00401040
                             retn
.text:00401040
.text:00401040 sub_401020
                             endp
```

Multiple inheritance is actually much easier to spot than single inheritance. As with the single inheritance example, the first function called could be a member function, or a base class constructor. Notice that in the disassembly, 4 bytes is added to the *this* pointer prior to calling the second function. This indicates that a different base class is being initialized.

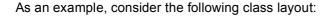
Here's the layout for this class to help you visualize. The disassembly above belongs to the constructor of class D. Class D is derived from two other classes, A and C:

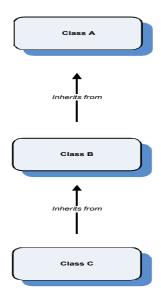
### 2. Polymorphic Class Relationship via RTTI

As what had been discussed in section II-B, Run-time Type Information (RTTI) can be used to identify class relationship of polymorphic classes, the related data structure used to determine this is RTTIClassHierarchyDescriptor. Once again, below are the fields of RTTIClassHierarchyDescriptor for the purpose of illustration:

Offset	Type	Name	Description
0x00	DW	signature	Always 0?
			Bit 0 - multiple inheritance
0x04	DW	attributes	Bit 1 - virtual inheritance
			Number of base classes.
			Count includes the class
0x08	DW	numBaseClasses	itself
			Array of
0x0C	DW	pBaseClassArray	RTTIBaseClassDescriptor

RTTIClassHierarchyDescriptor contains a field named pBaseClassArray which is an array of RTTIBaseClassDescriptor (BCD). These BCDs will then eventually point to the TypeDescriptor of the actual base class.



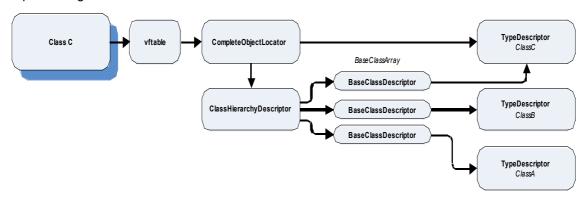


And here is the actual class declaration pertaining to the said class layout.

```
class ClassA {...}
class ClassB : public ClassA {...}
class ClassC : public ClassB {...}
```

### To illustrate, below is a layout between the relationships of

 ${\tt RTTIClassHierarchyDescriptor, RTTIBaseClassDescriptor} \ \textbf{and} \ {\tt TypeDescriptor} \\ \textbf{representing ClassC.}$ 



As you would have noticed, one caveat is that <code>pBaseClassArray</code> also points to the <code>BCD</code> of non-direct base classes. In this case, <code>ClassA's BaseClassDescriptor</code>. One solution to this is to also parse the <code>ClassHierarchyDescriptor</code> of <code>ClassB</code> and determine if <code>ClassA</code> is a base class of <code>ClassB</code>, if it is, then <code>ClassA</code> is not a direct base of <code>ClassC</code> and the appropriate inheritance can be deduced.

# **E. Identifying Class Members**

Identifying class members is a straight-forward, albeit slow and tedious, process. We can identify class member variables by looking for accesses to offsets relative to the *this* pointer:

We can also identify virtual function members by looking for indirect calls to pointers located at offsets relative to this objects virtual function table:

Non-virtual member functions can be identified by checking if the *this* pointer is passed as a hidden parameter to the function call.

To make sure that this is indeed a member function, we can check if the called function uses ecx without first initializing it. Let's look at sub\_401110's code

### III. Automation

This section discusses that approaches we had used to automate extraction of class information. For this purpose, we will discuss a tool we had created to perform this task and provide information on how we implemented this tool.

### A. OOP\_RE

OOP\_RE is the name of the tool we had created in-house to automate class information extraction. The information extracted includes identified classes (including class name if RTTI is available), class relationships and class members. It also enhances disassemblies by commenting identified C++-related structures. OOP\_RE is developed using python and runs in the IDAPython platform. IDAPython allows us to quickly and efficiently write and debug OOP\_RE.

# B. Why a Static Approach?

One of the first decisions we had to make is if we would develop a tool to perform static or dynamic analysis. We chose the static approach because it is difficult to do runtime analysis on some platforms that heavily use C++ such as Symbian - if the tool will be updated to handle compiled Symbian applications. However, a hybrid approach (static plus dynamic analysis) is also preferable since it may produce more accurate results.

# C. Automated Analysis Strategies

### 1. Polymorphic Class Identification via RTTI

The first step the tool does is to collect RTTI information if it is available. Leveraging RTTI data allows the tool to quickly and accurately extract the following:

- 1) Polymorphic Classes
- 2) Polymorphic class Name
- 3) Polymorphic class Hierarchy
- 4) Polymorphic class virtual table and virtual functions
- 5) Polymorphic class Constructors/Destructors

To search for RTTI-related structures, this tool first attempts to identify virtual function tables since the structure RTTICompleteObjectLocator is just below these virtual function tables. In order to identify virtual function tables, the tool perform the following checks:

- 1) If the Item is a DWORD
- 2) If the Item is a pointer to a Code
- 3) If the Item is being referenced by a Code and the instruction in this referencing code is a MOV instruction (suggesting a vftable assignment)

Once the vftables are identified, the tool will verify if the DWORD below the vftable is an actual RTTICompleteObjectLocator. This is verified by parsing RTTICompleteObject Locator and verifying if RTTICompleteObjectLocator.pTypeDescriptor is a valid TypeDescriptor. One method to verify a TypeDescriptor is by checking if TypeDescriptor.name starts with a string ".?AV" which is used as a prefix for class names.

In the example below, the identified vftable is at 004165B4:

The tool will then identify if 004165B0 is a valid RTTICompleteObjectLocator, by checking the TypeDescriptor pointed to by the RTTICompleteObjectLocator.

A TypeDescriptor is then validated by checking TypeDescriptor.name for ``.?AV''

Once the all the RTTICompleteObjectLocator is verified, the tool will parse all RTTI-related data structures to and create classes from the identified TypeDescriptors. Below is a list class information that is extracted using RTTI data:

```
new_class
    - Identified from TypeDescriptors
new_class.class_name
    - Identified from TypeDescriptor.name
new_class.vftable/vfuncs
    - Identified from vftable-RTTICompleteObjectLocator relationship
new_class.ctors_dtors
    - Identified from functions referencing the vftable
new_class.base_classes
    - Identified from RTTICompleteObjectLocator.pClassHierarchyDescriptor
```

### 2. Polymorphic Class Identification via vftables (w/o RTTI)

If RTTI data is not available, the tool will try to identify polymorphic classes by searching for vftables (the method is described section C.1). Once a vftable is identified, the following class information is extracted / generated:

```
new_class
   - Identified from vftable
new_class.class_name
   - Auto-generated (based from vftable address, etc.)
new_class.vftable/vfuncs
   - Identified from vftable
new_class.ctors_dtors
   - Identified from functions referencing the vftable
```

Notice that the base classes is not yet identified, the base classes of the identified class will be identified by constructor analysis which is described later.

### 3. Class Identification via Constructor / Destructor Search

Automation techniques to be discussed from this point on require us to be able to track values in registers and variables. To do this, we need to have a decent data flow analyzer. As most researchers who have tackled this problem before will attest, data flow analysis is a hard problem. Fortunately, we don't have to cover general cases, and we can get by with a simple data flow analyzer that will work in our specific case. At the very least, our data flow analyzer should be able to do decent register and pointer tracking.

Out tool will track a register or variable from a specific starting point. Subsequent instructions will be tracked and split into blocks. Each block will have a tracked variable assigned, which

indicates which register/pointer is being tracked in that particular block. During tracking, one of the following things could occur:

- 1) If the variable/register is overwritten, stop tracking
- 2) If EAX is being tracked and a call is encountered, stop tracking. (We assume that all calls return values in EAX).
- 3) If a call is encountered, treat the next instruction as a new block
- 4) If a conditional jump is encountered, follow the register/variable in both branches, starting a new block on each branch.
- 5) If the register/variable was copied into another variable, start a new block and track both the old variable and the new one starting on this block.
- 6) Otherwise, track next instruction.

To identify constructors for objects that are dynamically allocated, the following algorithm can be applied:

- 1) Look for calls to new().
- 2) Track the value returned in EAX
- 3) When tracking is done, look for the earliest call where the tracked register/variable is ECX. Mark this function as constructor.

For local objects, we do the same thing. Instead of initially tracking returned values of new(), we first locate instructions where an address of a stack variable is written to ECX, then start tracking ECX

There is a possibility that some of the constructors identified are overloaded and actually belong to one class. We can filter out non-overloaded constructors by checking the value passed to new(). If the object size is unique, then the corresponding constructor is not overloaded. We can then identify if the remaining constructors are overloaded by checking if their characteristics are identical with other classes e.g. has the same vftable, has the same member functions, etc.

### 4. Class Relationship Inferencing

As discussed in section II-D, relationships between classes can be determined by analyzing constructors. We can automate constructor analysis by tracking the current object's *this* pointer (ECX) within the constructor. When tracking is done, check blocks with ECX as the tracked

variable, and see if there is a call to a function that has been identified as a constructor. If there is, this constructor is possibly a constructor for a base class. To handle multiple inheritance, our tool should also be able to track pointers to offsets relative to the class's address. We will then track these pointers using the aforementioned procedure to identify other base classes.

### 5. Class Member Identification

#### **Member Variable Identification**

To identify member variables, we have to track the this pointer from the point the object is initialized. We then note accesses to offsets relative to the *this* pointer. These offsets will then be recorded as possible member variables.

#### Non-virtual Function Identification

The tool will track an initial register or pointer, which in our case should point to a *this* pointer for the current class.

Once tracking is done, note all blocks where ECX is the tracked variable, then mark the call in that block, if there is any, as a member of the current class.

### **Virtual Function Identification**

To identify virtual functions, we simply have to locate vftables first through constructor analysis.

After all of this is done, we then reconstruct the class using the results of these analysis.

# D. Enhancing the Disassembly

### 1. Reconstructing and Commenting Structures

Once class information is extracted,  $OOP_RE$  will reconstruct, name and comment C++-related data structures using doDwrd(),  $make_ascii_string()$  and  $set_name()$ .

For RTTI data, OOP\_RE properly changes the data types of data structure members and add comments to clarify the disassembly.

Here is an example for a vftable and RTTICompleteObjectLocator pointers:

```
Original
```

```
.rdata:004165A0
                       dd offset unk 4189E0
.rdata:004165A4 off_4165A4
                      dd offset sub 401170
                                            ; DATA XREF:...
.rdata:004165A8
                      dd offset sub 4011C0
.rdata:004165AC
                     dd offset sub 401230
.rdata:004165B0
                     dd offset unk 418A28
Processed
.rdata:004165A0 dd offset oop re$ClassA$RTTICompleteObjectLocator@00
.rdata:004165A4 oop_re$ClassA$vftable@00
                dd offset sub 401170 ; DATA XREF: ...
.rdata:004165A8 dd offset sub 4011C0
.rdata:004165AC dd offset sub 401230
.rdata:004165B0 dd offset oop_re$ClassB$RTTICompleteObjectLocator@00
```

And another example for the actual RTTICompleteObjectLocator structure:

#### Original

```
      .rdata:004189E0 dword_4189E0
      dd 0 ; DATA XREF:...

      .rdata:004189E4
      dd 0

      .rdata:004189E8
      dd 0

      .rdata:004189EC
      dd offset off_41B004

      .rdata:004189F0
      dd offset unk_4189F4
```

#### Processed

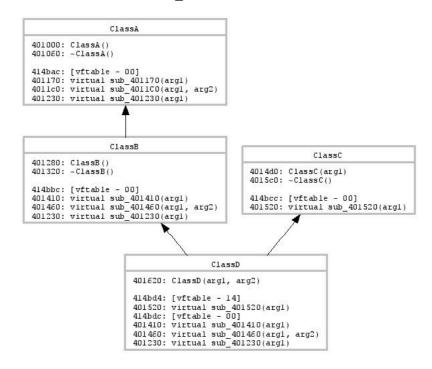
### 2. Improving the Call Graph

The results of the analysis done can be applied back to the IDA disassembly, for example, by adding cross-references on virtual function calls. This will yield a more accurate call graph, which in turn would result in improvements in the outcome of binary comparison tools such as BinDiff and DarunGrim. Locating vtables can also be used in a binary diffing technique, as described in Rafal Wojtczuk's blog entry (see References).

# E. Visualization: UML Diagrams

Finally, the coolest part – generating a UML class diagram for class members and class hierarchy. For this purpose, we had used  $pydot. OOP_RE$  basically creates a node for each class and then create edges from each of the base classes.

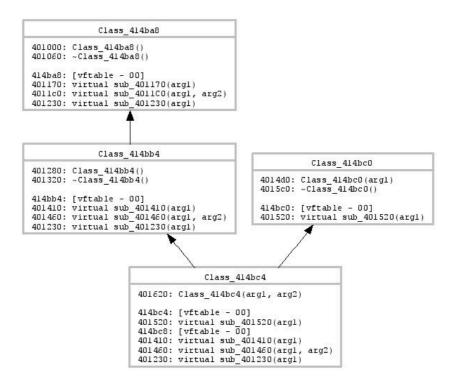
Below is an example of a generated OOP RE-generated UML diagram:



This UML diagram represents the following class declaration:

```
class ClassA {...}
class ClassB : public ClassA {...}
class ClassC {...}
class ClassD : public ClassB, public ClassC {...}
```

Of course, there will be instances in which RTTI is not available; in this case, the class names are auto-generated:



These UML diagrams provide a high-level overview of the classes and how they relate to each other. This provides the reverser important information on how the application is structured in terms of classes, the reverser can then have this structure in mind while further refining the disassembly.

# IV. Summary

In this paper, we had discussed ways on how to analyze and understand C++ compiled binaries. Specifically, it discusses methods on how to extract class information and class relationships. We hope that this paper will serve as a useful reference and encourage researchers to further explore the subject of C++ reversing.

### V. References

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