## Topics in Computer Graphics Chap 6: Bézier Curve Topics spring, 2014

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#### Degree Elevation

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### Degree Elevation

- What if we want to get more flexibility while keeping the shape of the current curve? → Degree elevation required
- Monomial form case?
- Can be used to make several curves have the same degree
- Useful for data transfer between different CAD/CAM or graphics systems
- Figure 6.1

## Degree Elevation: Algebraic Proof

$$(1-t)B_i^n(t) = \frac{n+1-i}{n+1}B_i^{n+1}(t)$$

$$tB_i^n(t) = \frac{i+1}{n+1}B_{i+1}^{n+1}(t)$$

$$B_i^n(t) = \frac{n+1-i}{n+1}B_i^{n+1}(t) + \frac{i+1}{n+1}B_{i+1}^{n+1}(t)$$

$$\mathbf{x}(t) = (1 - t)\mathbf{x}(t) + t\mathbf{x}(t)$$

$$= \sum_{i=0}^{n} \frac{n+1-i}{n+1} \mathbf{b}_{i} B_{i}^{n+1}(t) + \sum_{i=0}^{n} \frac{i+1}{n+1} \mathbf{b}_{i} B_{i+1}^{n+1}(t)$$

$$= \sum_{i=0}^{n+1} \left( \frac{i}{n+1} \mathbf{b}_{i-1} + \left( 1 - \frac{i}{n+1} \right) \mathbf{b}_{i} \right) B_{i}^{n+1}(t)$$

$$=: \sum_{i=0}^{n+1} \mathbf{b}_{i}^{(1)} B_{i}^{n+1}(t)$$

## Degree Elevation: Proof Using Blossoms

$$\mathbf{b}^{(1)}[t_1,\ldots,t_{n+1}] = \frac{1}{n+1} \sum_{i=1}^{n+1} \mathbf{b}[t_1,\ldots,t_{n+1}|t_j]$$

- $\mathbf{b}[t_1,\ldots,t_{n+1}|t_j]$ :  $t_j$  is omitted from  $\mathbf{b}[t_1,\ldots,t_{n+1}]$ .
- Why? → Definition of a blossom

$$\mathbf{b}_{i}^{(1)} = \mathbf{b}^{(1)}[0^{\langle n+1-i\rangle}, 1^{\langle i\rangle}]$$
$$= \frac{1}{n+1} (i\mathbf{b}_{i-1} + (n+1-i)\mathbf{b}_{i})$$

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### Repeated Degree Elevation

- ▶ Degree elevation:  $P \rightarrow \mathcal{E}P$
- After r degree elevation,  $\mathcal{E}^r\mathbf{P}$  has the vertices  $\{\mathbf{b}_i^{(r)}\}_{i=0}^{n+r}$  where

$$\mathbf{b}_{i}^{(r)} = \sum_{j=0}^{n} \mathbf{b}_{j} \binom{n}{j} \frac{\binom{r}{i-j}}{\binom{n+r}{i}}$$

$$\lim_{r \to \infty} \mathcal{E}^r \mathbf{P} = \mathcal{B} \mathbf{P} \quad \leftarrow \lim_{i/(n+r) \to t} \frac{\binom{r}{i-j}}{\binom{r+n}{i}} = t^j (1-t)^{n-j}$$

- $\mathcal{E}^{r}\mathbf{P}$  converges to the Bézier curve  $\mathcal{B}\mathbf{P}$ .
- But converges too slowly.

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### The Variation Diminishing Property

- The curve  $\mathcal{B}\mathbf{P}$  has no more intersections with any plane than does the polygon  $\mathbf{P}$ .
- Proof
  - 1. Degree elevation is a piecewise linear interpolation.
  - Piecewise linear interpolation is variation diminishing. (Sec 3.2)
    - $\rightarrow$  Each  $\mathcal{E}^r\mathbf{P}$  has fewer intersections than  $\mathcal{E}^{r-1}\mathbf{P}$ .
  - 3. Since  $\mathcal{E}^r\mathbf{P}$  converges to the curve, the proof is done.
- A convex polygon generates a convex curve. How about the inverse?

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### **Degree Reduction**

- Problem: Can we write a given curve of degree n+1 as one of degree n?
- In general, exact degree reduction is not possible.
  - → approximate method
- New problem: Given a Bézier curve with control vertices  $\{\mathbf{b}_i^{(1)}\}_{i=0}^{n+1}$ , can we find a Bézier curve with control vertices  $\{\mathbf{b}_i\}_{i=1}^n$  that approximates the first curve in a "reasonable" way?

$$egin{bmatrix} 1 & & & & & \ * & * & & & & \ & * & * & & & \ & & & \ddots & & & \ & & & & 1 \end{bmatrix} egin{bmatrix} \mathbf{b}_0 \ dots \ \mathbf{b}_n \end{bmatrix} = egin{bmatrix} \mathbf{b}_0^{(1)} \ dots \ \mathbf{b}_{n+1}^{(1)} \end{bmatrix}$$

## Degree Reduction (cont'd)

- $MB = B^{(1)}, \quad M \in \mathbb{R}^{(n+2)\times(n+1)}$ 
  - $\rightarrow$  Not solvable.
- Can be solved after converted to

$$(M^T M) B = M^T B^{(1)}$$

- Normal equation
- Guarantees that B is optimal in a least square sense.
- Problem?  $\mathbf{b}_0 = \mathbf{b}_0^{(1)}$  and  $\mathbf{b}_n = \mathbf{b}_{n+1}^{(1)}$  are not guaranteed.

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### Nonparametric Curves

- Functional curves: y = f(x)
- How can we express a functional curve in parametric form?

$$\mathbf{b}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} t \\ f(t) \end{bmatrix}$$

▶ If f is a polynomial,

$$f(t) = b_0 B_0^n(t) + \dots + b_n B_n^n(t), \quad b_i \in \mathbb{R} \text{ for } i = 0, \dots, n.$$

How to find the control polygon?

$$\mathbf{b}(t) = \sum_{i=0}^{n} \begin{bmatrix} j/n \\ b_j \end{bmatrix} B_j^n(t)$$

- $\rightarrow$  The control polygon is given by the points  $\{(j/n, b_j)\}_{i=0}^n$ .
- f(t) is called a Bézier function. (Figure 6.3)
- $\{(j/n, b_j)\}_{i=0}^n$  are called *Bézier ordinates*.
- $\{j/n\}_{i=0}^n$  are called the abscissae.

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#### **Cross Plots**

- For a 2D Bézier curve, plot each coordinate function as a Bézier function.
- ▶ Figure 6.4

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### **Integrals**

• The derivative of a polynomial function b(t):

$$\dot{b}(t) = n \sum_{i=0}^{n-1} \Delta b_i B_i^{n-1}(t)$$

The indefinite integral (or antiderivative) of a polynomial b(t) in Bernstein form defined by the ordinates  $\{b_i\}_{i=0}^n$  is the polynomial B(t) defined by the ordinates

$$\frac{1}{n+1}[c, c+b_0, c+b_0+b_1, \dots, c+\sum_{i=0}^n b_i]$$

$$\int_0^1 b(t) dt = B(1) - B(0) = \frac{1}{n+1} \sum_{i=0}^n b_i$$

- Can be obtained by setting  $b_i = \delta_{i,j}$ .
- All basis functions  $B_i^n$  have the same definite integral.

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### The Bézier Form of a Bézier Curve

The basis functions Bézier used:

$$\mathbf{b}^n(t) = \sum_{j=0}^n \mathbf{c}_j F_j^n(t)$$

•  $F_i^n$  are polynomials that obey the recursion

$$\begin{split} F_i^n(t) &= (1-t)F_i^{n-1}(t) + tF_{i-1}^{n-1}(t) \\ F_0^0(t) &= 1(t), \quad F_{r+1}^r(t) = 0(t), \quad F_{-1}^r(t) = 1(t) \end{split}$$

- Explicit form:  $F_i^n = \sum_{i=1}^n B_j^n$
- ►  $F_0^n \equiv 1(t)$  for all n→ Not a barycentric combination!
  - → How can it be defined then?

## The Bézier Form of a Bézier Curve (cont'd)

- $\mathbf{c}_0 = \mathbf{b}_0 \in \mathbb{E}^3$  and  $\mathbf{c}_j = \Delta \mathbf{b}_{j-1} \in \mathbb{R}^3$  for j > 0
- $F_i^n(t)$  is NOT symmetric w.r.t. t and 1-t.
- ▶ The value of  $\mathbf{x}(1)$  is the sum of all errors in the  $\mathbf{c}_i$ .

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### The Weierstrass Approximation Theorem

- 1. c(t): parametric curve defined over [0,1]
- 2. For some fixed n, sample c(t) at parameter values i/n.
- 3. Define a Bézier curve  $\mathbf{x}_n(t)$  by control points  $\{\mathbf{c}(i/n)\}_{i=0}^n$ :

$$\mathbf{x}_n(t) = \sum_{i=0}^n \mathbf{c} \left(\frac{i}{n}\right) B_i^n(t)$$

" $\mathbf{x}(t)$  is the  $n^{\text{th}}$  degree Bernstein-Bézier approximation to  $\mathbf{c}$ ."

4. Weierstrass approximation theorem:

$$\lim_{n\to\infty}\mathbf{x}_n(t)=\mathbf{c}(t)$$

- Not practical (too large n required)
- Every curve may be approximated arbitrarily closely by a polynomial curve.

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## Formulas for Bernstein Polynomials

A Bernstein polynomial is defined by

$$B_i^n(t) = \begin{cases} \binom{n}{i} t^i (1-t)^{n-i} & \text{if } i \in [0,n], \\ 0 & \text{else}. \end{cases}$$

• Relationship with the power basis  $\{t^i\}$ 

$$t^{i} = \sum_{j=i}^{n} \frac{\binom{j}{i}}{\binom{n}{i}} B_{j}^{n}(t)$$

and

$$B_i^n(t) = \sum_{i=j}^n (-1)^{j-i} \binom{n}{j} \binom{j}{i} t^j.$$

# Formulas for Bernstein Polynomials (cont'd)

Recursion:

$$B_i^n(t) = (1-t)B_i^{n-1}(t) + tB_{i-1}^{n-1}(t)$$

Subdivision:

$$B_i^n(ct) = \sum_{j=0}^n B_i^j(c) B_j^n(t)$$

Derivative:

$$\frac{d}{dt}B_i^n(t) = n \left[ B_{i-1}^{n-1}(t) - B_i^{n-1}(t) \right]$$

Integral:

$$\int_0^t B_i^n(x) dx = \frac{1}{n+1} \sum_{j=i+1}^{n+1} B_j^{n+1}(t)$$
$$\int_0^1 B_i^n(x) dx = \frac{1}{n+1}$$

## Formulas for Bernstein Polynomials (cont'd)

Degree elevation formulas:

$$(1-t)B_i^n(t) = \frac{n+1-i}{n+1}B_i^{n+1}(t)$$

$$tB_i^n(t) = \frac{i+1}{n+1}B_{i+1}^{n+1}(t)$$

$$B_i^n(t) = \frac{n+1-i}{n+1}B_i^{n+1}(t) + \frac{i+1}{n+1}B_{i+1}^{n+1}(t)$$

Product:

$$B_{i}^{m}(u)B_{j}^{n}(u) = \frac{\binom{m}{i}\binom{n}{j}}{\binom{m+n}{i+j}}B_{i+j}^{m+n}(u)$$