Mathematical Models for Engineering Problems and Differential Equations

Minho Kim

November 18, 2009

Introductory remarks

- 1. Only very special types of 1st order DE possess solutions which can be expressed in terms of the elementary functions.
- 2. The "look" of a DE doesn't tell you how easy (or difficult) it is to solve it.
- 3. Implicit solutions usually are not practical.
- 4. The solution you find may be *extraneous*. Therefore you should always verify that it does in fact satisfy the given DE.
- 5. The examples in the textbook are only for illustration and not from real applications.

Table of contents

Chapter 2: Special Types of Differential Equations of the First Order

Lesson 6: Meaning of the Differential of a Function. Separable Differential Lesson 7: First Order Differential Equation with Homogeneous Coefficients

Lesson 8: Differential Equations with Linear Coefficients

Lesson 9: Exact Differential Equations

Lesson 9. Exact Differential Equations

Lesson 10: Recognizing Exact Differential Equations. Integrating Fact

Lesson 11: The Linear Differential Equation of the First Order. Berno

Lesson 12: Miscellaneous Methods of Solving a First Order Differentia

Lesson 6: Meaning of the Differential of a Function. Separable Differential

Increment (Δy) and differential (dy)

Let y = f(x) define y as a function of x.

- ▶ Increament: "How much y increases from x to $x + \Delta x$?" $\Delta y = (\Delta f)(x, \Delta x) = f(x + \Delta x) f(x)$
- ▶ Differential: Approximates Δy using f'(x). $dy = (df)(x, \Delta x) = f'(x)\Delta x$
- $\rightarrow (dy)(x, \Delta x) = f'(x)(d\hat{x})(x, \Delta x)$
- $\rightarrow dy = f'(x)dx$

Type #1:
$$f(x)dx + g(y)dy = 0$$

A 1-parameter family of solutions of the DE with **separable** variables,

$$f(x)dx + g(y)dy = 0,$$

is

$$\int f(x)dx + \int g(y)dy = C.$$

Lesson 7: First Order Differential Equation with Homogeneous Coefficien

Homogeneous function

Definition

The function f(x,y) is n-th order homogeneous if it can be written as

$$f(x,y) = x^n g(u), u = y/x$$

or

$$f(x,y) = y^n h(u), u = x/y$$

Alternatively, f(x,y) is homogeneous of order n if

$$f(tx, ty) = t^n f(x, y).$$

Type #2: Homogeneous P(x,y)dx + Q(x,y)dy = 0

The 1st order DE with n-th order homogeneous coefficients,

$$P(x,y)dx + Q(x,y)dy = 0,$$

can be converted to the equation with separable variables (Type #1)

$$\frac{dx}{x} + \frac{g_2(u)}{g_1(u) + ug_2(u)} du = 0, x \neq 0, g_1(u) + ug_2(u) \neq 0,$$

where $P(x,y)=x^ng_1(u)$, $Q(x,y)=x^ng_2(u)$, and u=y/x. Alternatively, we can convert by substituting u=x/y.

Lesson 8: Differential Equations with Linear Coefficients

Type #3:
$$(a_1x + b_1y + c_1)dx + (a_2x + b_2y + c_2)dy = 0$$

Two lines are not parallel.
The DE with linear coefficients

$$(a_1x + b_1y + c_1)dx + (a_2x + b_2y + c_2)dy = 0$$

can be converted to the equation with homogeneous coefficients

$$(a_1\bar{x} + b_1\bar{y})d\bar{x} + (a_2\bar{x} + b_2\bar{y})d\bar{y} = 0$$

where $\bar{x}=x-h$, $\bar{y}=y-k$, and (h,k) is the unique intersection point of the two lines $a_1x+b_1y+c_1=0$ and $a_2x+b_2y+c_2=0$.

2. Two lines are parallel or coincide.



Lesson 9: Exact Differential Equations

Type #4: Exact
$$P(x,y)dx + Q(x,y)dy = 0$$

A DE

$$P(x,y)dx + Q(x,y)dy = 0$$

is **exact** if there exists a function f(x,y) such that

$$P(x,y) = \frac{\partial f(x,y)}{\partial x}$$

and

$$Q(x,y) = \frac{\partial f(x,y)}{\partial y}.$$

A 1-parameter family of solutions of this equation is

$$f(x,y) = c.$$

Type #4: Exact P(x,y)dx + Q(x,y)dy = 0 (cont'd)

Necessary and sufficient condition for exactness:

$$\frac{\partial P(x,y)}{\partial y} = \frac{\partial Q(x,y)}{\partial x}.$$

▶ The 1-parameter solution:

$$f(x,y) = \int_{x_0}^{x} P(x,y)dx + \int_{y_0}^{y} Q(x_0,y)dy = c$$

or

$$f(x,y) = \int_{y_0}^{y} Q(x,y)dy + \int_{x_0}^{x} P(x,y_0)dx = c.$$

Lesson 10: Recognizing Exact Differential Equations. Integrating Factors

Integrable combinations

- List of known exact DEs.
- ▶ Some exact DEs can be easily solved by rearranging the terms to extract integrable combinations.

Type #5: Integrating factors

Definition

A multiplying factor which will convert an inexact DE into an exact one is called an **integrating factor**.

Remark

Theoretically an integrating factor exists for every DE of the form P(x,y)dx+Q(x,y)dy=0, but no general rule is known to discover it.

- 1. h = h(x)
- 2. h = h(y)
- 3. h = h(u), u = xy
- 4. h = h(u), u = x/y
- 5. h = h(u), u = y/x

1. Integrating factor h(x)

$$h(x) = e^{\int F(x)dx}$$

$$F(x) = \frac{\frac{\partial}{\partial y}P(x,y) - \frac{\partial}{\partial x}Q(x,y)}{Q(x,y)}.$$

2. Integrating factor h(y)

$$h(y) = e^{\int G(y)dy}$$

$$G(y) = \frac{\frac{\partial}{\partial x}Q(x,y) - \frac{\partial}{\partial y}P(x,y)}{P(x,y)}.$$

3. Integrating factor h(u), u = xy

$$h(u) = e^{\int F(u)du}$$

$$F(u) = \frac{\frac{\partial}{\partial y} P(x, y) - \frac{\partial}{\partial x} Q(x, y)}{yQ(x, y) - xP(x, y)}.$$

4. Integrating factor h(u), u = x/y

$$h(u) = e^{\int G(u)du}$$

$$G(u) = \frac{y^2 \left[\frac{\partial P(x,y)}{\partial y} - \frac{\partial Q(x,y)}{\partial x} \right]}{xP(x,y) + yQ(x,y)}.$$

5. Integrating factor h(u), u = y/x

$$h(u) = e^{\int K(u)du}$$

$$K(u) = \frac{x^2 \left[\frac{\partial Q(x,y)}{\partial x} - \frac{\partial P(x,y)}{\partial y} \right]}{xP(x,y) + yQ(x,y)}.$$

Special form

The integrating factor of the DE of the form

$$y(Ax^py^q + Bx^ry^s)dx + x(Cx^py^q + Dx^ry^s)dy = 0$$

is

$$x^a y^b$$
.

Lesson 11: The Linear Differential Equation of the First Order. Bernoulli

Type #6:
$$\frac{dy}{dx} + P(x)y = Q(x)$$

The integrating factor of the **linear differential equation of the** 1st order

$$\frac{dy}{dx} + P(x)y = Q(x)$$

is

$$e^{\int P(x)dx}$$

and the solution is

$$y = e^{-\int P(x)dx} \int e^{\int P(x)dx} Q(x)dx + ce^{-\int P(x)dx}.$$

Note

For the 1-st order linear DE, the 1-parameter family of solutions is a true general solution.

Type #7: Bernoulli equation

The Bernoulli equation

$$\frac{dy}{dx} + P(x)y = Q(x)y^n$$

can be converted to Type #6 by multiplying $(1-n)y^{-n}$.

Lesson 12: Miscellaneous Methods of Solving a First Order Differential E