HANOI UNIVERSITY OF SCIENCE AND TECHNOLOGY SCHOOL OF INFORMATION AND COMMUNICATION TECHNOLOGY

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GRADUATION THESIS **DEPARTMENT OF COMPUTER SCIENCE**

Tiến hóa đa nhiệm trong huấn luyện mạng Neural nhân tạo

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Hanoi, May 2020

Graduation mission ticket

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• Program: Bachelor of Engineer-• Class: ICTx K6x ing

• Duration: From Month 202X to Month 202X

Main purpose of the thesis

1. Research about

2. Research and apply

Specific mission of the thesis

- 1. Research
- 2. Apply
- 3. Implement
- 4. Conduct the experiments, synthesize and analyze the result.

Pledge of student

I am $Nguyen\ Van\ X$ guarantee that this thesis is my own work under the supervision of Associate Professor X.

The proposals and results in this thesis are authentic and original. $Hanoi,\ xx^{th},\ Month\ 202X$ Author of thesis

 $Nguyen\ Van\ X$

ation for the completeness of the thesis and pe	r
or the thesis to be defense from supervisor	
$Hanoi, xx^{th}, Month 202X$ Supervisor	
f	

Assoc Prof. X

Acknowledgement

I would like to thanks

 $\begin{array}{c} \textit{Hanoi, } xx^{th}, \, \text{Month 202X} \\ \textit{Nguyen } \textit{Van X} \end{array}$

Abstract

Abstract of your thesis The thesis is organized as follows:

- Chapter 1 provides
- Chapter 2 introduces
- Chapter 3 presents
- ullet Chapter 4 represents

Preface

Describe overview of the field and your motivation why are you doing this topic $\,$

Glossaries

Acronym	Full terminology
EA	Evolutionary Algorithm
GA	Genetic Algorithm
EP	Evolutionary Programming
GP	Genetic Programming
ES	Evolution Strategies
MFO	Multifactorial Optimization
MOO	Multi Objective Optimization
ANN	Artificial Neural Network
MFEA	Multi Factorial Evolutionary Algorithm
MDP	Markov Decision Process
RL	Reinforcement Learning
SL	Supervised Learning
SBX	Simulated Binary Crossover
FSM	Functional Synergies Measure

Danh sách bảng

4.1	some description		_							_			_		1	5

Danh sách hình vẽ

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Chương 1 Introduction

 $1.0.1 \quad \text{Deep Q-Network}$

Deep Q-network [1]

Chương 2 Problem formulation

Chương 3

Proposed method

3.0.1 New algorithm

Algorithm 1 Assortative mating

Consider two parent candidates p_a and p_b randomly selected from current - pop

- 1: Generate a random number rand between 0 and 1
- 2: if $(\tau_a == \tau_b)$ or (rand < rmp) then
- 3: Parents p_a and p_b crossover to give two offspring individuals c_a and c_b
- 4: **else**
- 5: p_a is mutated slightly to give an offspring c_a
- 6: p_b is mutated slightly to give an offspring c_b
- 7: end if

Chương 4

Result

4.0.1 Small instance

Gravity]	$\mathbf{E}\mathbf{A}$			MFF	MFEA					
Gravity	Best	Mean	Std	Time (s)	Best	Mean	Std	Time				
gravity=0.80	200.00	200.00	0.00	1.10	200.00	200.00	0.00	1.13				
gravity=10.80	200.00	200.00	0.00	1.10	200.00	200.00	0.00	1.13				
gravity=20.80	200.00	200.00	0.00	1.10	200.00	200.00	0.00	1.13				
gravity=30.80	200.00	200.00	0.00	1.10	200.00	200.00	0.00	1.13				
gravity=40.80	200.00	200.00	0.00	1.10	200.00	200.00	0.00	1.13				
gravity=50.80	200.00	196.95	11.29	1.10	200.00	200.00	0.00	1.13				
gravity=60.80	200.00	199.99	0.04	1.10	200.00	200.00	0.00	1.13				
gravity=70.80	200.00	189.38	24.78	1.10	200.00	200.00	0.00	1.13				
gravity=80.80	200.00	191.43	18.90	1.10	200.00	199.31	2.95	1.13				
gravity=90.80	200.00	167.84	26.90	1.10	200.00	193.62	11.08	1.13				

Bång 4.1: some description

Conclusion

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Tài liệu tham khảo

[1] Volodymyr Mnih, Koray Kavukcuoglu, David Silver, Andrei A. Rusu, Joel Veness, Marc G. Bellemare, Alex Graves, Martin Riedmiller, Andreas K. Fidjeland, Georg Ostrovski, Stig Petersen, Charles Beattie, Amir Sadik, Ioannis Antonoglou, Helen King, Dharshan Kumaran, Daan Wierstra, Shane Legg, and Demis Hassabis. Human-level control through deep reinforcement learning. *Nature*, 518(7540):529–533, February 2015.