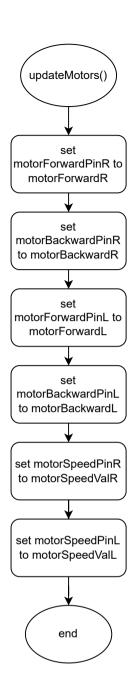
## Soccer Bot Main Loop start speedControl() rightWheelInputUp == 1? rightWheelInputDown == 1? motorForwardR = true motorForwardR = false motorForwardR = false motorBackwardR = true motorBackwardR = false motorBackwardR = false print right wheel dir leftWheelInputUp == 1? leftWheelInputDown == 1? motorForwardL = false motorForwardR = false motorForwardL = true motorBackwardL = false motorBackwardL = true motorBackwardL = false print left wheel dir updateMotors()



## **Speed Control Function**

