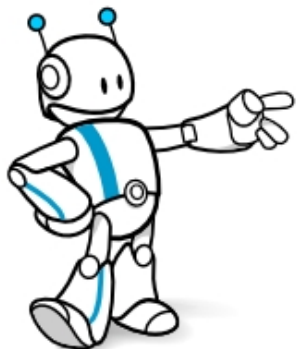
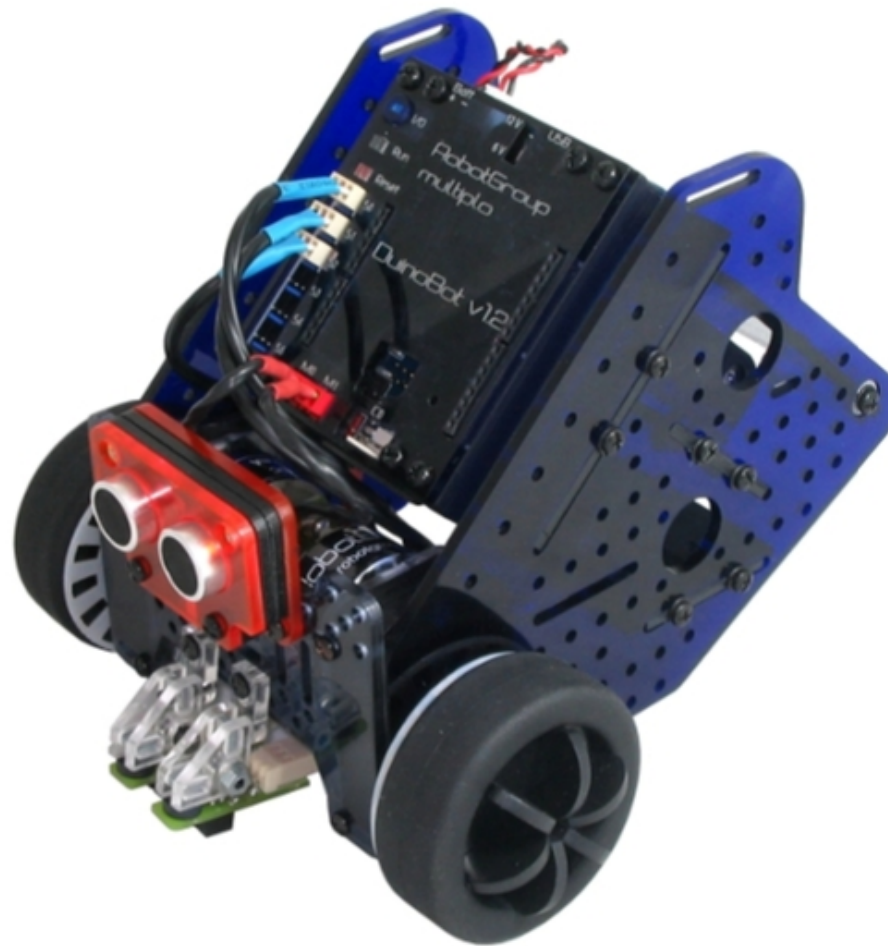
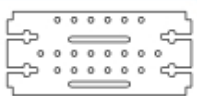


# N6 robot assembly guide



1

1x




4x ↑ (8mm) 4x ●

4x ○



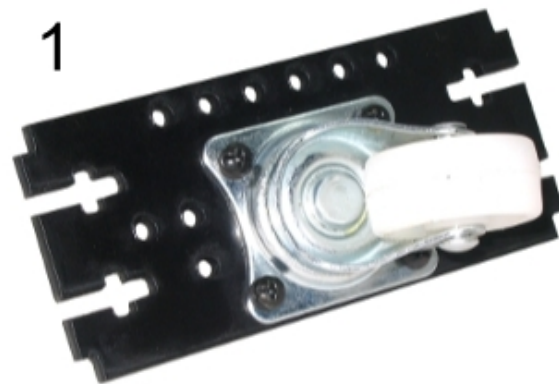
2

2x

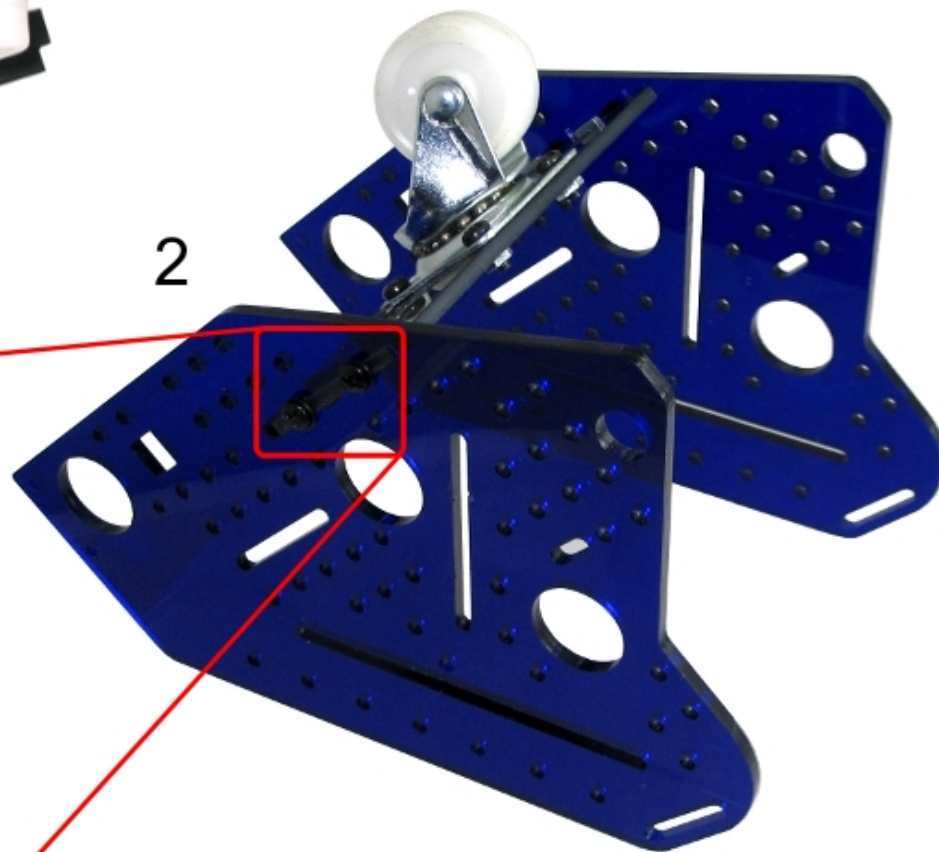


4x ↑ (16mm) 4x ■

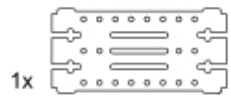
4x ○



2



3



1x

2x ↑ (12mm) 2x ⬤

2x ⊙

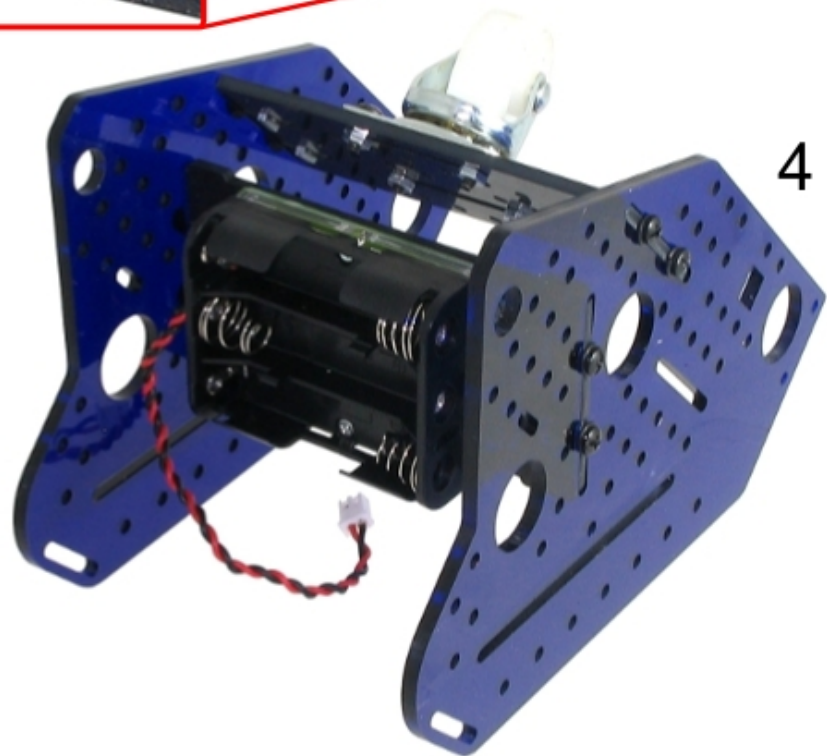
1x



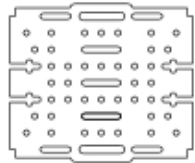
4

4x ↑ (16mm) 4x ⊞

4x ○



5



1x

2x ↑ (8mm)

2x ⬤

2x ⊙

6

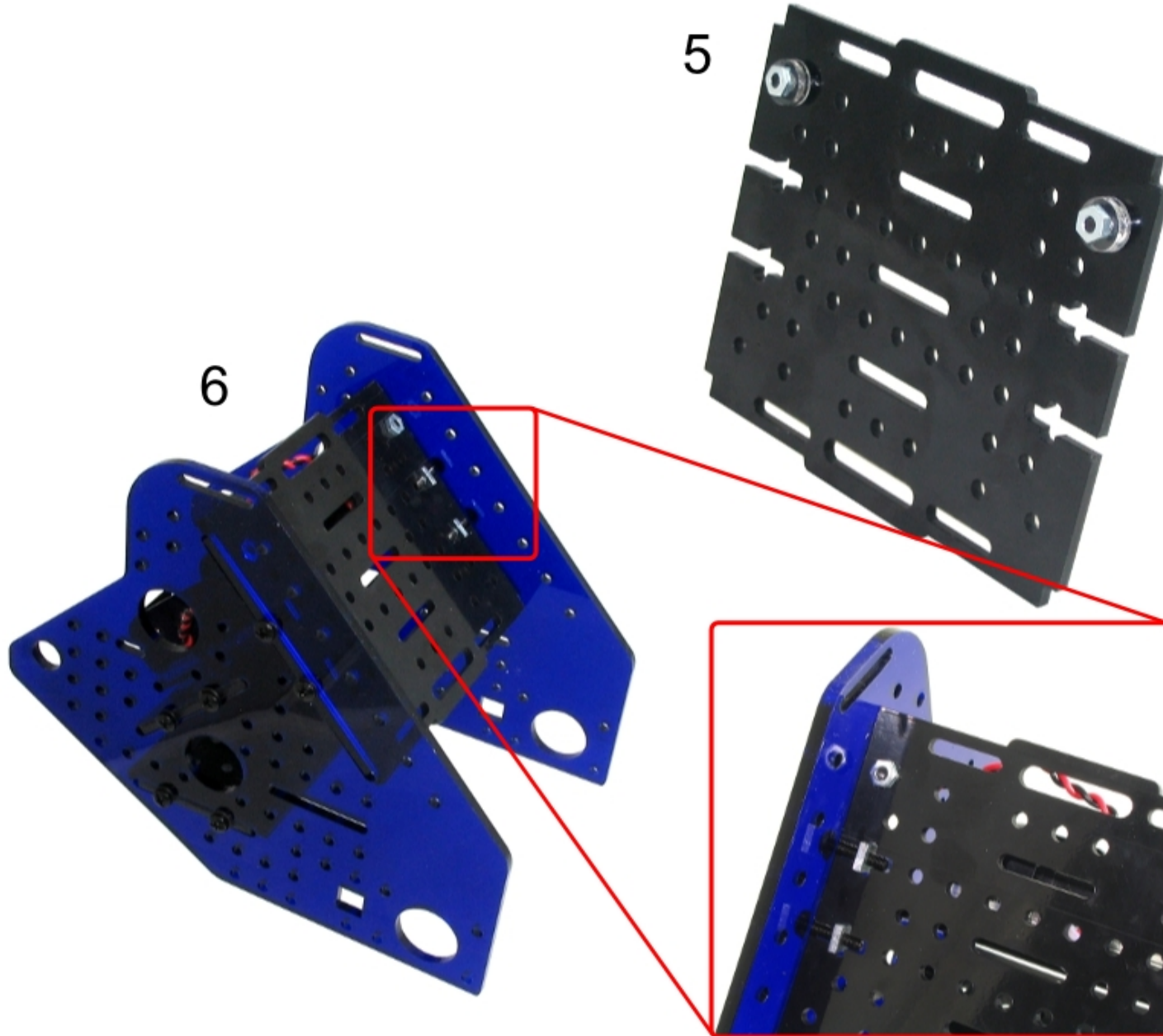
4x ↑ (16mm)

4x ▣

4x ○

5

6



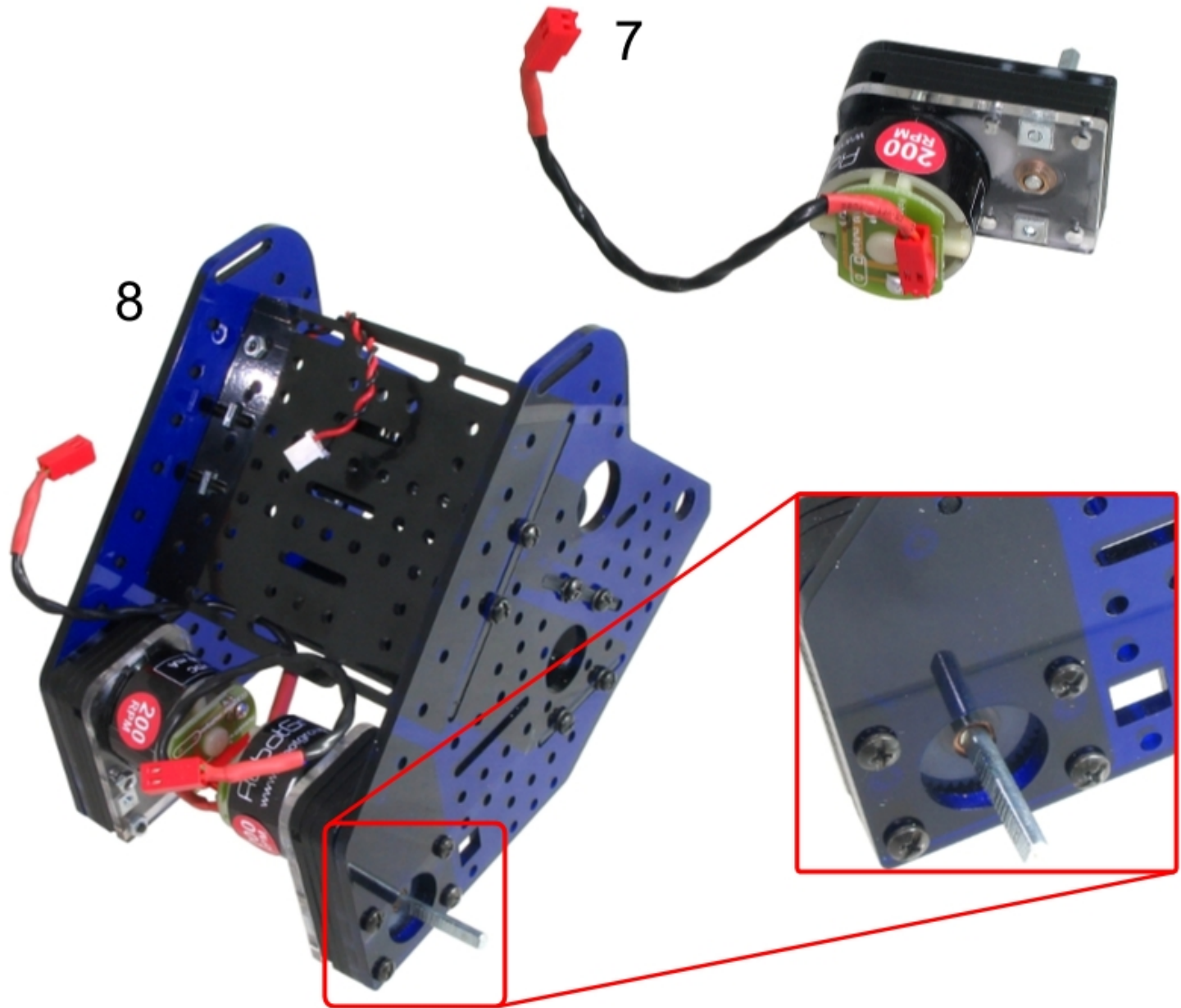


7



8

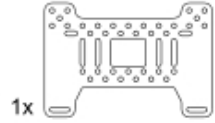
8x (22mm) 8x



9

4x ↑ (42mm) 4x ⬤

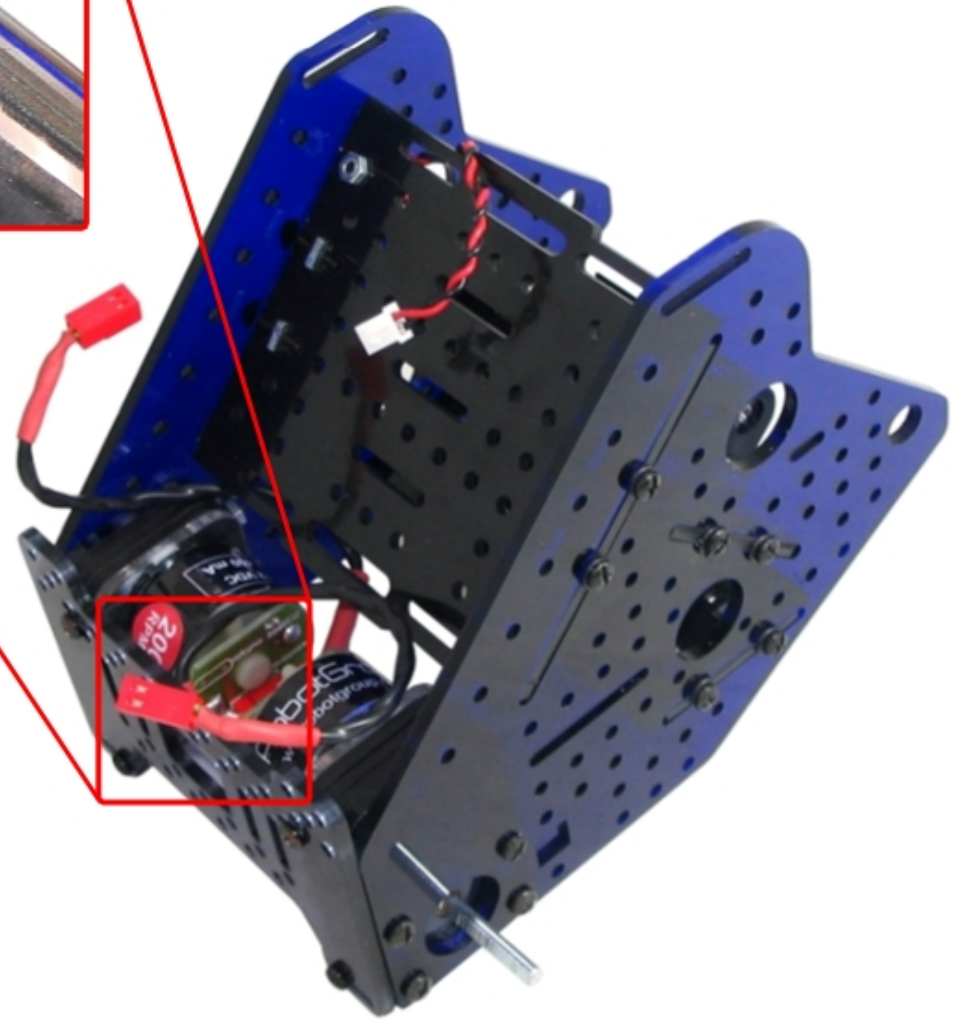
2x ○



1x



9



10



1x

2x ↑ (12mm) 2x ●

1x

1x

11

1x

1x ↑ (12mm) 1x ●

3x ● 1x ○

12

2x ↑ (18mm) 2x ■

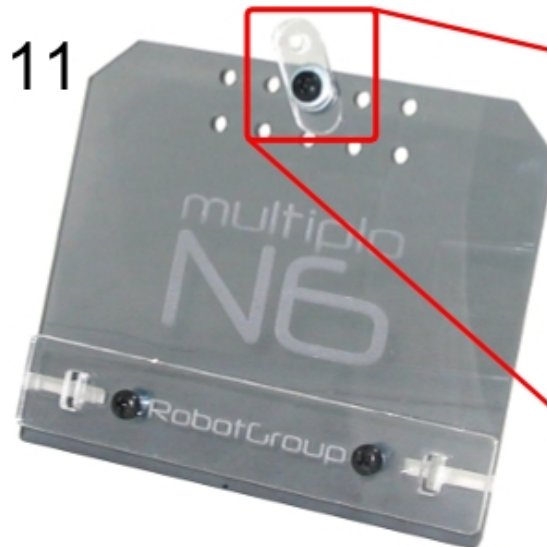
2x ○ 2x ●



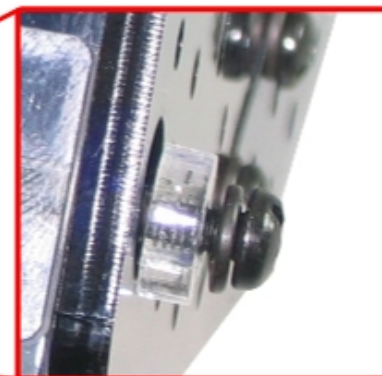
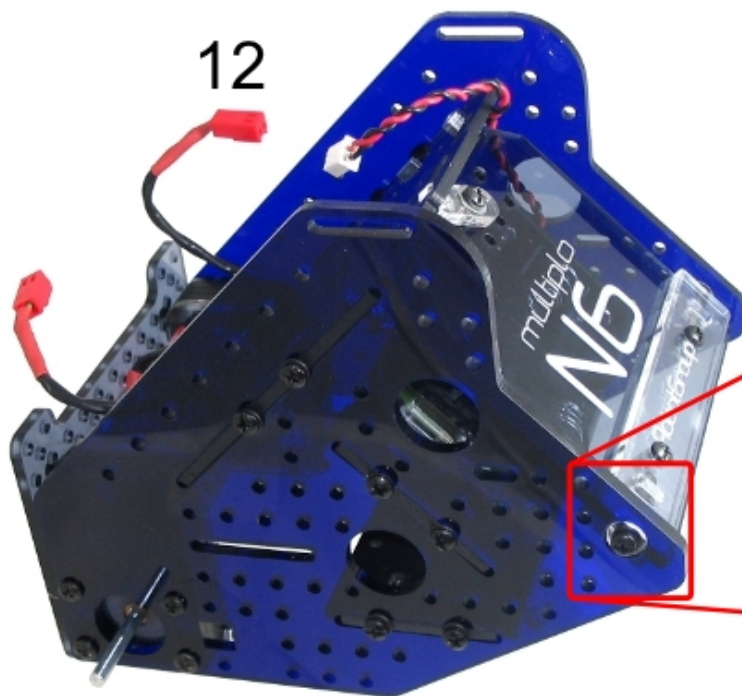
10



11

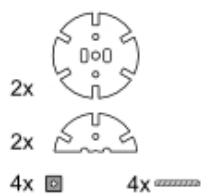


12





13



13



14



15



14



15



16



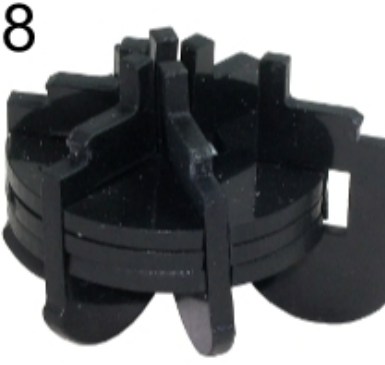
16



17



18



17



18



20



19




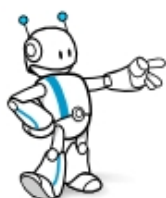
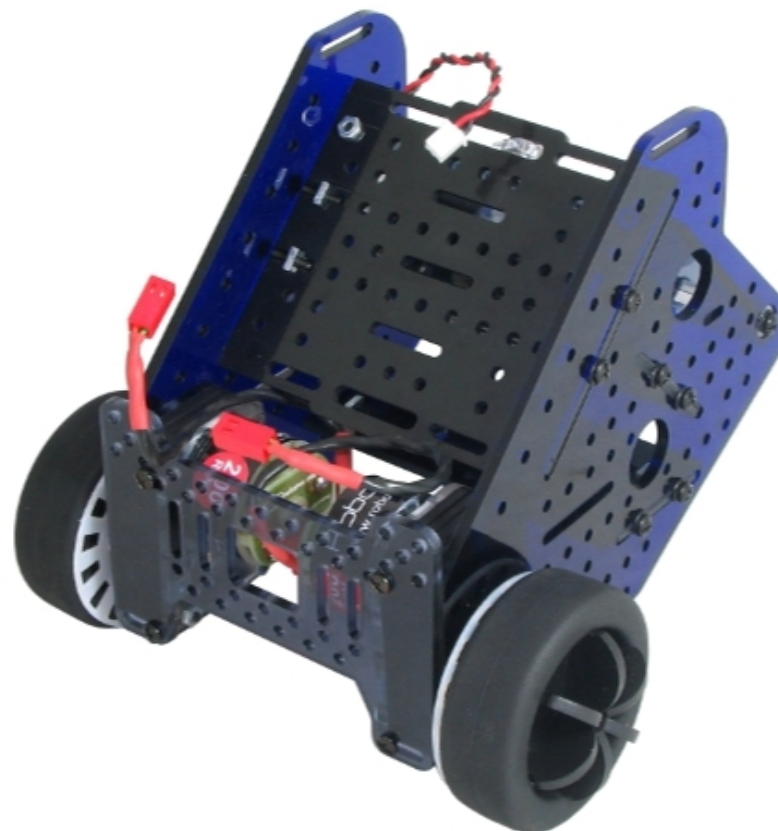
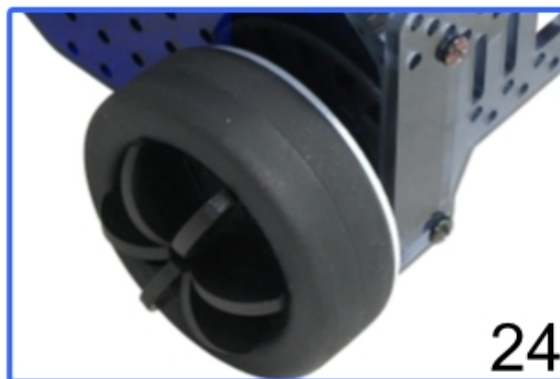
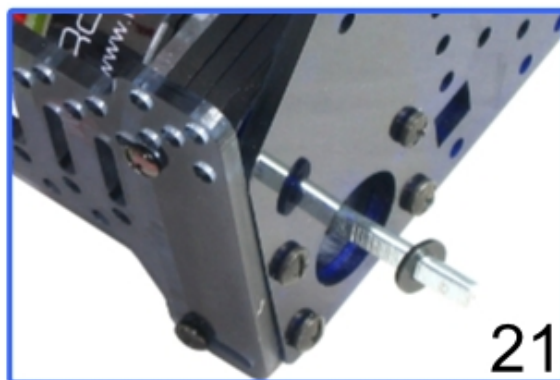
20





21 2x ●

24  2x



25



1x

4x ↑ (24mm) 4x ○

26



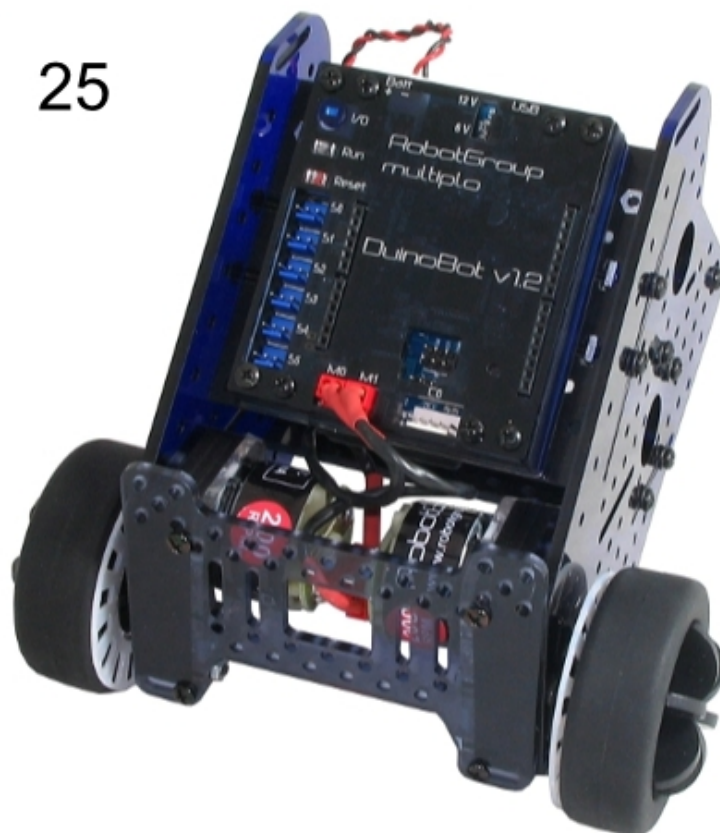
1x

2x ↑

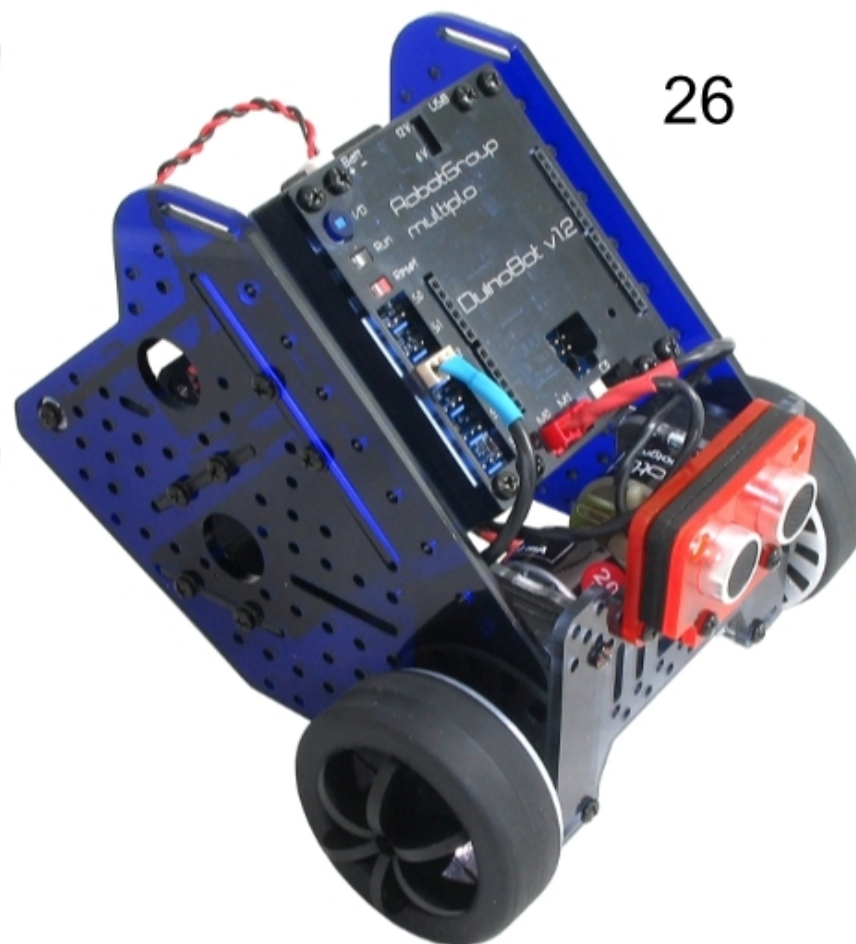


1x

25



26





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## Option I: N6 line follower

27

2x  2x   
4x  (12mm)

28

2x  (12mm) 2x 

2x



2x 

29

2x  2x 

30

2x  2x   
4x  (12mm) 2x 



27



28



29



30



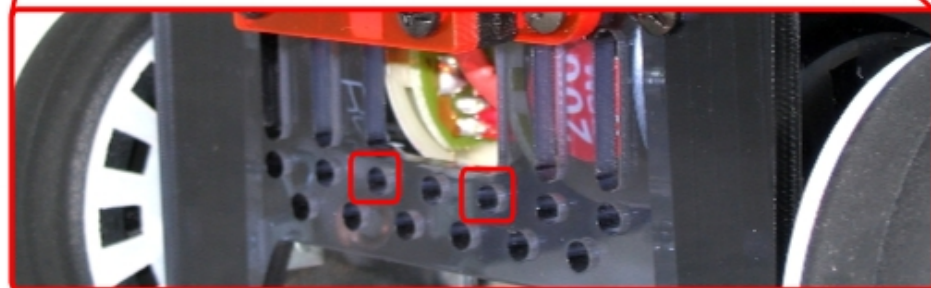
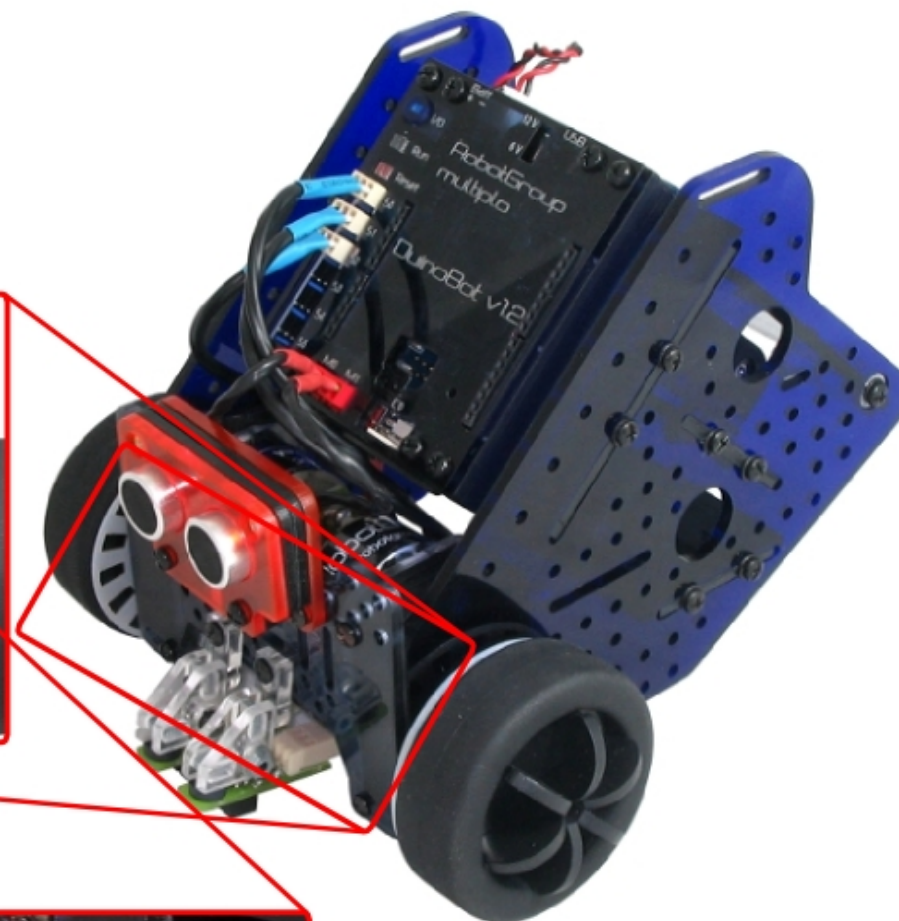
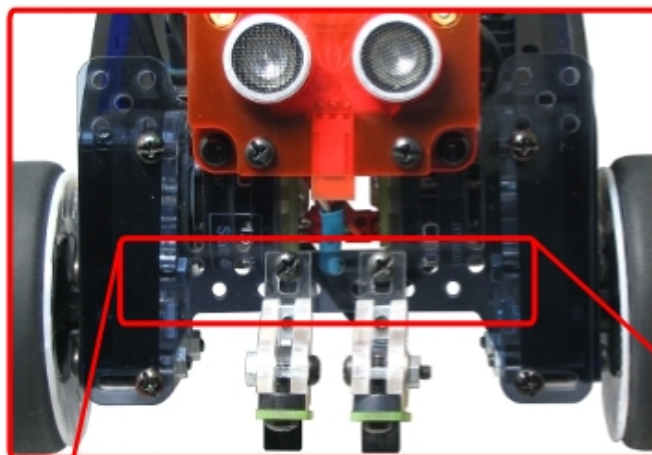


# 31

2x ↑ (12mm) 2x ⚙



# 31





29

2x ↑ (8mm) 2x ⚙

2x

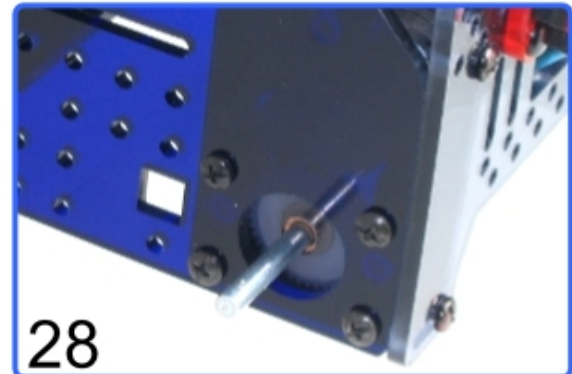
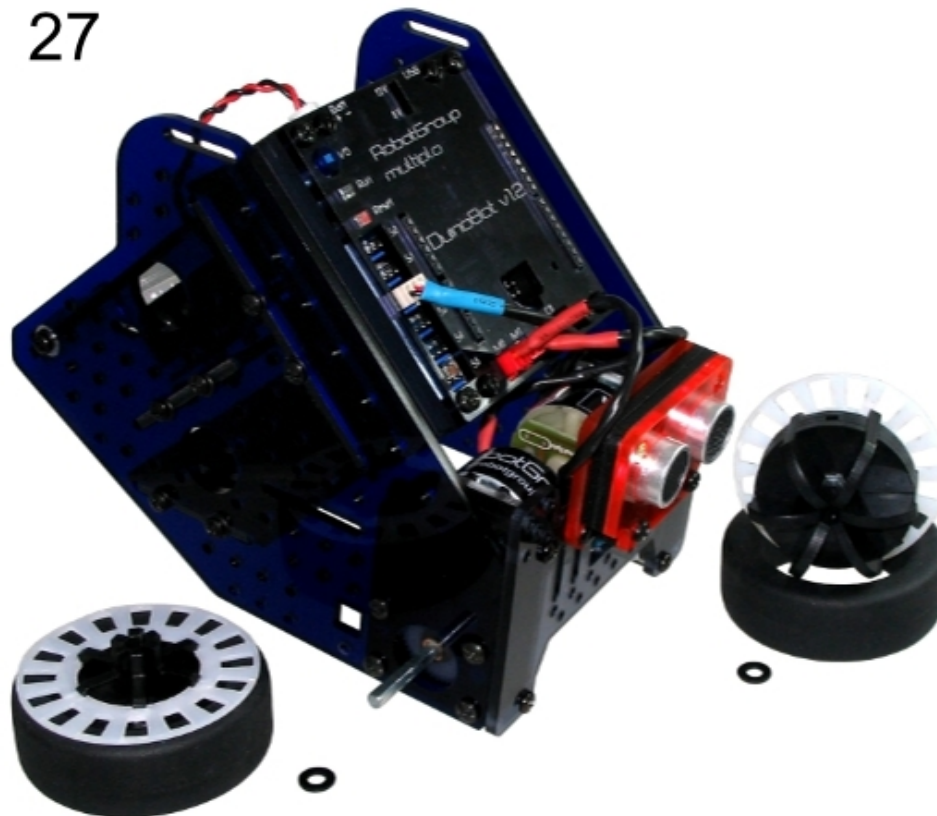


2x

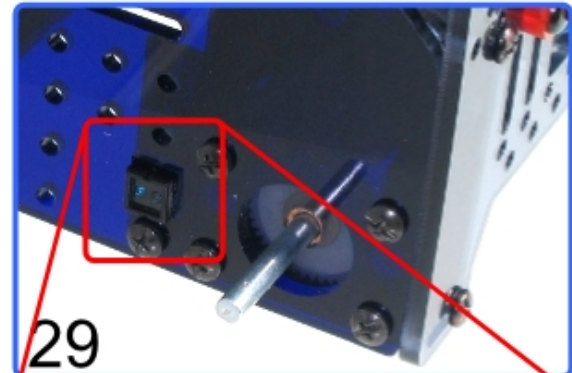


## Option 2: N6 with tachometer

27



28



29



30 2x ●

32 2x ○

