$$Z = [0.3 \ 0.7]$$

$$S_{1} = \frac{3}{3} \frac{$$

$$\beta_{t}(\vec{v}) = P(O_{t+1}, ..., O_{T} | g_{t} = S\vec{v}, \lambda)$$
  
己算的  $\beta_{t+1}(\vec{v}) = i_{t}, 2, ..., N$  知何 ボ  $\beta_{t}(\vec{v})$ ?  
①  $\beta_{t+1}(\vec{v}) \cdot b_{j}(O_{t+1}) = P(O_{t+1}, ..., O_{T} | g_{t+1} = \hat{v})$ 

$$=\frac{P(g_{t+1}=j,g_{t}=i,\lambda)}{P(g_{t}=i,\lambda)}$$

$$Z = \frac{P(\beta_{t+1} = j, \beta_{t} = i, \lambda)}{P(\beta_{t} = i, \lambda)}$$

$$= \frac{P(\beta_{t+1} = j, \beta_{t} = i, \lambda)}{P(\beta_{t} = i, \lambda)} \frac{P(O_{t+1}, \dots, O_{T}, \beta_{t+1} = j, \lambda)}{P(\beta_{t+1} = i, \lambda)}$$

$$Z = \frac{PCO_{t+1}, \dots, O_{\tau}, \vartheta_{t+1} = \hat{g}, \vartheta_{t} = \hat{\iota}, \lambda)}{PC\vartheta_{t} = \hat{\iota}, \lambda}$$

(3) 
$$\beta_{\pm}(i) = \Sigma$$

园为已知 Bt+1下, Ot+1、Ot+2...O7

发生的标准学的等于已知84.841下 0++1、0+42...0丁为至内积充率,国为公安 如道了北北地是给影响七十五以后的观测了(马尔司夫1年)

$$\begin{array}{lll}
\tilde{\beta} & \Omega : & \Omega_{\pm}(i) = P(O_1, \dots, O_{\pm}, l_{\pm} = S_i) & \lambda \\
0 & \Omega_{\pm}(j) & \alpha_{ji} = \frac{P(O_1, \dots, O_{\pm}, l_{\pm} = S_i)}{P(D_{\pm}(j))} & P(D_{\pm}(j) & P(D_{\pm}(j) = S_j, \lambda) \\
& = \Omega_{\pm}(j) & \frac{P(D_{\pm}(j) = S_j, l_{\pm} = S_j, \lambda)}{P(D_{\pm}(j))} & \frac{P(D_{\pm}(j) = S_j, \lambda)}{P(D_{\pm}(j))} & \frac{P(D_{\pm}(j) = S_j, \lambda)}{P(D_{\pm}(j))} \\
\tilde{\beta} & \tilde$$

Q+(i)β+(o) = PCO, B-... Ot, 9t=Si >) P(Ot+1... OT | gt=Si,λ)  $=\frac{P(O_1O_2...O_{t},Q_t=S_i,\lambda)}{P(\lambda)}\frac{P(O_{t+1}...O_{t},Q_t=S_i,\lambda)}{P(Q_t=S_i,\lambda)}$ 関め0+11·10-0+50,...0+ 数型 見 8+50,... 0+322  $=\frac{P(O,...,O_{T},\ell\epsilon=S_{i},\lambda)}{P(\lambda)}=P(O,...,O_{T},\ell\epsilon=S_{i}|\lambda)$ 

$$S_{3}(7) = man \begin{cases} \frac{3}{2}(1) & 0.11 = \frac{3}{500} \times \frac{7}{10} \\ \frac{3}{2}(1) & 0.11 = \frac{3}{100} \times \frac{7}{10} \\ \frac{49}{5000} & 0.11 = \frac{3}{100} \times \frac{7}{100} \\ \frac{49}{500} & 0.11 = \frac{3}{100} \times \frac$$

$$\sqrt{3} \text{ C(1)} = 1$$

$$S_{2}(1) \text{ C(1)} = \frac{7}{500} \times \frac{3}{10} = \frac{21}{5000}$$

$$S_{3}(2) = \text{mex} \left\{ S_{2}(1) \text{ C(1)} = \frac{3}{127} \times \frac{1}{5} = \frac{12}{127} \right\}$$

$$b_{3}(0) = \frac{3}{5} = \frac{30}{127} \times \frac{1}{5} = \frac{30}{127} \times \frac{1}{5}$$

$$\pi = [0.5 \ 0.5]$$

$$A = \begin{bmatrix} 0.6 & 0.4 \\ 0.5 & 0.5 \end{bmatrix} \qquad B = \begin{bmatrix} 0.4 & 0.4 & 0.2 \\ 0.2 & 0.3 & 0.5 \end{bmatrix}$$

$$B = \begin{bmatrix} 0.4 & 0.4 & 0.2 \\ 0.2 & 0.3 & 0.5 \end{bmatrix}$$

$$\delta(c_1) = \pi_1 b_1 c_0 c_1 = \frac{1}{2} x \frac{2}{5} = \frac{1}{5}$$
  $\psi(c_1) = 0$ 

$$\delta_{1}(2) = \lambda_{1} b_{2}(0_{1}) = \frac{1}{2} \lambda_{5} = \frac{1}{10}$$
  $\ell_{1}(x_{1}) = 0$ 

$$\delta_2(1) = \max \left[ \delta_1(1) \alpha_{i1} \right] b_1(0_2)$$

$$= \max \begin{cases} \frac{1}{5} \times \frac{3}{5} & \times \frac{2}{5} \\ \frac{1}{12} \times \frac{1}{3} & \times \frac{2}{5} \end{cases} = \frac{6}{125} \quad (9_2 \text{ ti}) = 1$$

$$= \max \begin{cases} \frac{1}{5} \times \frac{2}{5} \checkmark \\ \frac{1}{10} \times \frac{1}{2} \end{cases} \times \frac{3}{10} = \frac{3}{125} \qquad \text{(2.1)} = 1$$

$$= \max \begin{cases} \frac{6}{125} \times \frac{3}{5} \\ \frac{2}{125} \times \frac{1}{2} \end{cases} \times \frac{1}{5} = \frac{18}{3125} (\theta_3(1) = 1)$$

= max 
$$\begin{cases} \frac{b}{115} \times \frac{2}{5} \\ \frac{3}{2} \times \frac{1}{2} \end{cases} = \frac{3}{500} \quad \forall 3(2) = 2$$

$$\frac{3}{500} > \frac{18}{3(25)} \longrightarrow g_3^{*} = 2 \longrightarrow g_1^{*} = f_3(2) = 2 \longrightarrow g_1^{*} = f_2(2) = 1$$

$$\frac{97}{12} = 2$$

$$\rho_{2}^{*} = \beta_{3}(2) = 2$$

$$2.2 ht = Q \Lambda^t Q^T h.$$

do 人是对角阵 放入中元素入门=(入门)

若λ;
/ Λιι 会以指数形式超了0 → **精度逐渐**液失

(2) 
$$h_0 = g_i$$

$$h_t = (g_1 - g_n) \begin{bmatrix} \lambda_1^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots \\ \lambda_n^{\dagger} & \vdots & \vdots & \vdots \\$$

$$= \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{2} - - \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g, \lambda^{\dagger} g_{n} \right] \left[ \begin{array}{c} 0 \\ 0 \end{array} \right] = \left[ \lambda^{\dagger} g, \lambda^{\dagger} g$$

= \lambdaigs

$$\frac{\partial L}{\partial h_0} = \frac{\partial L}{\partial h_t} \frac{\partial h_t}{\partial h_0} = \lambda_i^{\dagger} \frac{\partial L}{\partial h_t}$$

(3) 
$$h_0 = \sum_{i=1}^n k_i \mathcal{E}_i$$
 由四中的名称可知

$$ht = \sum_{i=1}^{n} k_i \lambda_i \delta_i$$

$$\frac{\partial \mathcal{L}}{\partial h_0} = \sum_{i=1}^{n} \frac{\partial \mathcal{L}}{\partial g_i} = \sum_{i=1}^{n} \frac{\partial \mathcal{L}}{\partial h_t} \frac{\partial h_t}{\partial g_i} = \sum_{i=1}^{n} |k_i|^{\frac{1}{n}} \frac{\partial \mathcal{L}}{\partial h_t}$$

老所有入;绝对值均小于0,则入;随七增大而指数级湖外 图此人对较早时刻的的的稀度超近于0,当输入序列在时间 上足气度较长时,这一特点将导致新产生的上的稀度无法回传 到较早时刻的隐藏状态的,导致无法进行长距离相关信息建模。