

# Sufficiency

**Motivation.** We hope to separate the information contained in the data into the information relevant for making inference about  $\theta$  and the information irrelevant for these inferences. In other words, we would like to compress the data to, e.g.  $T(X)$ , without loss of information. (Actually, it often turns out that some part of the data carries no information about the unknown distribution that produces the data)

## Benefits:

1. increasing computational efficiency and decreasing storage requirements
2. involving irrelevant information may increase an estimator's risk (see Rao-Blackwell Theorem)
3. Improving the scientific interpretability of our data

## Definition of Sufficient Statistic

Suppose  $X$  has a distribution from  $\mathcal{P} = \{P_\theta : \theta \in \Omega\}$ . A statistic  $T$  is **sufficient** for  $\theta$  if, for every  $t$  in the range  $\mathcal{T}$  of  $T$ , the conditional distribution  $P_\theta(X \mid T(X) = t)$  is independent of  $\theta$ .

**Example:** Let  $X_i \sim \text{Ber}(\theta)$  i.i.d.,  $i = 1, \dots, n$ . Show that  $T = \sum_{i=1}^n X_i$  is sufficient for  $\theta$ .

**Neyman Factorization Theorem.** Suppose a family  $\{P_\theta : \theta \in \Omega\}$  of distributions have joint mass functions or densities  $\{p(x; \theta) : \theta \in \Omega\}$ . Then a statistic  $T$  is sufficient for  $\theta$  if and only if there are functions  $h$  and  $g$  such that the density/mass function can be written

$$p(x; \theta) = h(x) \cdot g(T(x), \theta).$$

**Proof:** To be presented in class (for the discrete case).

## Examples:

1. Let  $Y_i \sim \text{Uniform}(0, \theta)$  i.i.d.,  $i = 1, \dots, n$ . Show that  $T = Y_{(n)}$  is sufficient for  $\theta$ .
2. Let  $X_i \sim N(\theta, 1)$  i.i.d.,  $i = 1, \dots, n$ . Show that  $T = \sum_{i=1}^n X_i$  is sufficient for  $\theta$ .

# The Rao-Blackwell Theorem

Suppose  $X$  is distributed according to  $P_\theta(x) \in \{P_\theta : \theta \in \Omega\}$  and a statistic  $T(X)$  is sufficient for  $\theta$ . Given any estimator  $\delta(X)$  of  $\theta$ , define  $\eta(T) = E_\theta[\delta(X)|T(X)]$ . If the loss function  $\mathcal{L}(\theta, \delta(X))$  is convex and the risk function  $R(\theta, \delta(X)) = E[\mathcal{L}(\theta, \delta(X))] < \infty$ , then  $R(\theta, \eta) \leq R(\theta, \delta)$ . If  $\mathcal{L}$  is strictly convex, then the inequality is strict unless  $\delta = \eta$ .

Note that the loss function reflects the degree of wrongness of an estimate. The commonly used quadratic loss function is defined as  $\mathcal{L}(\theta, \delta) = (\theta - \delta(X))^2$ .

**Proof of Rao-Blackwell:** by Jensen's inequality and iterated expectation.

## Jensen's Inequality

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space, and let  $X : \Omega \rightarrow \mathbb{R}$  be an integrable random variable, i.e.  $E[|X|] < \infty$ .

Let  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  be a convex function such that  $\varphi(X)$  is integrable. Then

$$\varphi(\mathbb{E}[X]) \leq \mathbb{E}[\varphi(X)].$$

Moreover, if  $\varphi$  is strictly convex, then equality holds if and only if  $X$  is almost surely constant.

For example,  $(E(X))^2 \leq E(X^2)$ .

## Some notes

- Why we need  $T$  to be sufficient?
  - When  $T$  is sufficient,  $\eta(T) = E_{\theta}[\delta(X)|T(X)]$  will be independent of  $\theta$ , and so  $\eta(T)$  is a statistic.
  - Let us consider
$$\mathcal{L}(\theta, \eta(T)) = (\theta - \eta(T))^2 = (\theta - E_{\theta}[\delta(X)|T])^2 = (E_{\theta}[(\theta - \delta(X))|T])^2.$$
Note that
$$E_{\theta}[\theta|T] = \int \theta f(x|T; \theta) dx = \theta \int f(x|T; \theta) dx.$$
We have the last equation because  $f(x|T)$  is independent of  $\theta$  and so we do not have to worry that the support could be different

## Minimal Sufficiency

**Definition.** Suppose  $T(X)$  is sufficient for  $P = \{P_\theta : \theta \in \Omega\}$ . For any other sufficient statistic  $S(X)$ , if we can always find a function  $f$  such that  $T = f(S)$ , then  $T$  is minimally sufficient.

( $T = f(S)$  means (i) the knowledge of  $S$  implies the knowledge of  $T$ , and (ii)  $T$  provides a greater reduction of data unless  $f$  is one-to-one.)

A  $d$ -parameter exponential family has pdf in the following form

$$p(x, \theta) = h(x) \exp\left[\sum_{i=1}^d \eta_i(\theta) T_i(x) - A(\theta)\right],$$

which is of full rank if  $\eta(\Theta) = \{\eta_1(\theta), \dots, \eta_d(\theta)\}$  has non-empty interior in  $\Re^d$  and  $T_1(x), \dots, T_d(x)$  are linearly independent. In a full rank exponential family, the natural sufficient statistic  $T = (T_1, \dots, T_d)$  is minimally sufficient.

## Examples

- Let  $X_1, \dots, X_n$  be iid and follow a normal distribution  $N(\mu, \sigma^2)$ . Find the minimal sufficient statistic for  $\mu$  and  $\sigma^2$ .



# **Relevant Readings on Sufficient Statistics**

Chapters 2-5 of the Robert Keener book.