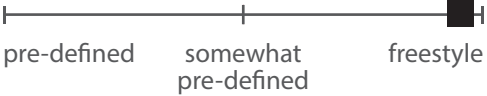


Solution space

Keepon

Environment

Situational flow



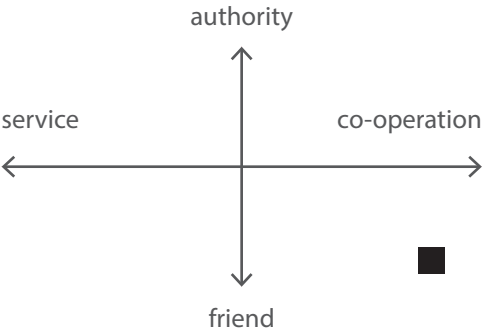
Human facilitation



Simultaneous users

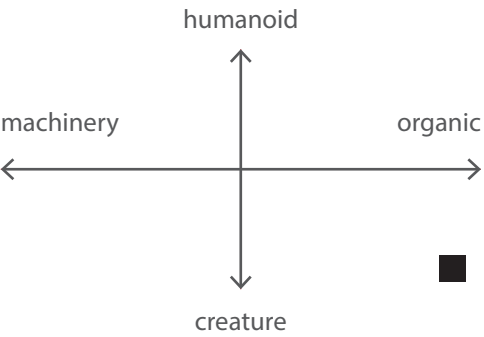


Role of the robot



Form

Apperance



Voice

none
description

Sounds

beeps and chirps
description

Tactile

plastic, soft, slightly sticky skin
description

Olfactory

unknown
description

Movement

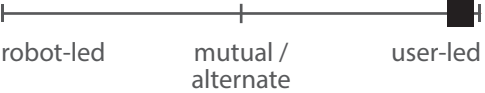


Interaction

Modalities

- ☒ voice / sounds
- ☒ movement / gestures
- ☐ digital visuals
- ☒ tactile
- ☐ facial expressions
- ☐ _____

Leadership



Goals



Behavior

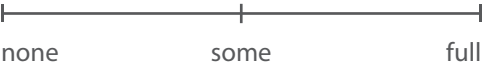
Contextual adaptation



Motivation



Social awareness



Autonomy

