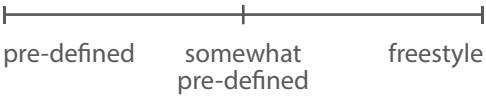


Solution space

Environment

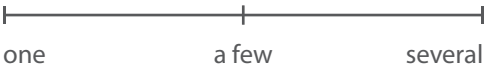
Situational flow



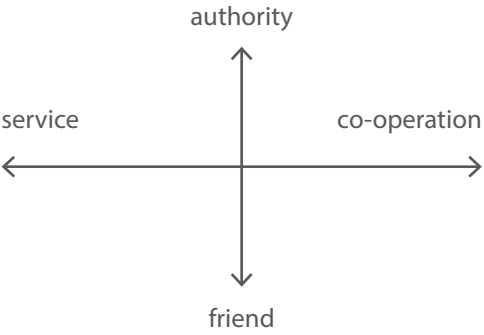
Human facilitation



Simultaneous users

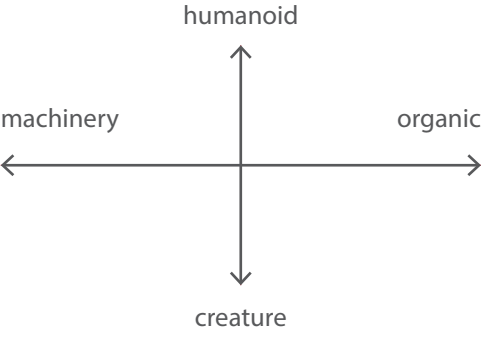


Role of the robot



Form

Apperance



Voice

description

Sounds

description

Tactile

description

Olfactory

description

Movement

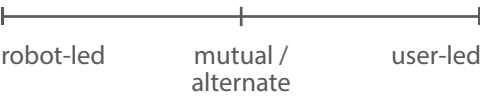


Interaction

Modalities

- ☐ voice / sounds
- ☐ movement / gestures
- ☐ digital visuals
- ☐ tactile
- ☐ facial expressions
- ☐ _____

Leadership



Goals



Behavior

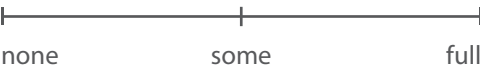
Contextual adaptation



Motivation



Social awareness



Autonomy

