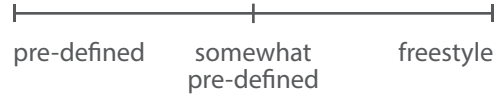


# Environment

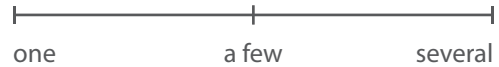
## Situational flow



## Human facilitation



## Simultaneous users



## Role of the robot

