## INTERACTION WITH THE ROBOT

What characterizes the interaction with the robot?

Leadership Is the robot's movement more machine-like or lifelike?			Goal(s) Is the robot's movement more machine-like or lifelike?		
bot-led	mutual / alternate	user-led	task completion	mixed	exploratio
		Mode What ways do the user			
	voice	olfactory			
	sounds	digital visuals	facial expres	ssions	
	gestures	tactile	other		
		start of in			
		during in	teraction		
		end of in	teraction		