

PROBLEM SPACE OF DESIGNING A ROBOT

What is the problem worth solving? Define it clearly through the user and the robot.

USER

<div><div>Group(s)</div><div>Name the user group(s).</div></div>	<div><div>Characteristics</div><div>What characterises the user group(s)?</div></div>	<div><div>Needs</div><div>What needs do these characteristics lead to?</div></div>																
<div><div>Goal(s)</div><div>What goal is the user trying to accomplish with the robot? Does the goal change short-term and long-term?</div><div><div>short-term</div><div>long-term</div></div></div>																		
<div><div>Ethical considerations</div><div>Use the separate ethics canvas to examine the ethical considerations, which emerge in the boundary between the robot and the user.</div></div>																		
<div><div>Task(s)</div><div>What task(s) is the robot aiming to fulfil for the user?</div><div><div>short-term</div><div>long-term</div></div></div>																		
<div><div>Advantage(s)</div><div>What are the potential advantages of using a robot to accomplish this task? Do the technological aspects of the robot enable something a human can't do? Do the social aspects of the robot enable it to do something other technologies can't? Are there other advantages?</div><table><tr><td>Social presence</td><td>Humans treat robots as social actors. Can the robot use its social presence to accomplish its task?</td></tr><tr><td>Emotional response</td><td>Can the user have a useful emotional response to the robot?</td></tr><tr><td>Personalization</td><td>Can the robot accomplish its task better through personalization?</td></tr><tr><td>Precision</td><td>Can the robot be used to accomplish a task that requires precision?</td></tr><tr><td>Mobility</td><td>Is mobility an advantage for the robot to accomplish its task?</td></tr><tr><td>Environmental manipulation</td><td>Is environmental manipulation an advantage for the robot to accomplish its task?</td></tr><tr><td>Data collection with sensors</td><td>Can the robot sense useful things from its environment or users?</td></tr><tr><td>Connectivity to technology</td><td>Can the robot make use of being connected to other technologies?</td></tr></table></div>			Social presence	Humans treat robots as social actors. Can the robot use its social presence to accomplish its task?	Emotional response	Can the user have a useful emotional response to the robot?	Personalization	Can the robot accomplish its task better through personalization?	Precision	Can the robot be used to accomplish a task that requires precision?	Mobility	Is mobility an advantage for the robot to accomplish its task?	Environmental manipulation	Is environmental manipulation an advantage for the robot to accomplish its task?	Data collection with sensors	Can the robot sense useful things from its environment or users?	Connectivity to technology	Can the robot make use of being connected to other technologies?
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ROBOT



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