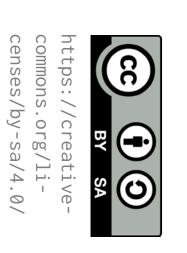# EXPERIENCE FLOW
SOCIAL ROBOT CO-DESIGN CANVASES

Describe the most important interaction of the robot.

Note: only fill the bottom row if your robot is teleoperated.

		BEFORE	DURING	AFTER
USER	**FEELING** e.g. confused			
	THINKING e.g. "I need help."			
	DOING e.g. pushes button			
ROBOT	**DOING** e.g. says "Hello!"			
	SENSOR INPUT e.g. sees user's face			
	CONNECTION TO SYSTEMS e.g. records data in database			
ROBOT OPERATOR (optional)	**DOING** e.g. controls robot's arm			

THRI paper:

Cite as: Axelsson, M., Oliveira, R., Racca, M., & Kyrki, V. (2021). Social robot co-design canvases: A participatory design framework. ACM Transactions on Human-Robot Interaction (THRI), 11(1), 1-39.