ROBOT OPERATOR (optional)

ROBOT

USER

Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

PERIENCE FLOW
DESIGNING A SOCIAL ROBOT

(optional)	KOBOI		USEK		
DOING e.g. controls robot's arm BEFORE	e.g. sees user's face CONNECTION TO SYSTEMS e.g. records data in database	e.g. says "Hello!"	DOING e.g. pushes button	THINKING e.g. "I need help."	FEELING e.g. confused
DURING					
AFTER					

