

DESIGNING A SOCIAL ROBOT

Describe the most important interaction of the robot.

Note: only fill the bottom row if your robot is teleoperated.

ROBOT		USER	
FEELING e.g. confused			
THINKING e.g. "I need help."			
DOING e.g. pushes button			
DOING e.g. says "Hello!"			
SENSOR INPUT e.g. sees user's face			
CONNECTION TO SYSTEMS e.g. records data in database			
DOING e.g. controls robot's arm			
BEFORE	DURING		AFTER



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