

# PROBLEM SPACE OF DESIGNING A ROBOT

What is the problem worth solving? Define it clearly through the user and the robot.

# USER

|  |   |  |
|--|---|--|
| <h3 style="text-align: center;">Group(s)</h3> <p style="text-align: center;">Name the user group(s).</p> | <h3 style="text-align: center;">Characteristics</h3> <p style="text-align: center;">What characterises the user group(s)?</p> | <h3 style="text-align: center;">Needs</h3> <p style="text-align: center;">What needs do these characteristics lead to?</p> |
|--|---|--|

### Goal(s)

What goal is the user trying to accomplish with the robot? Does the goal change short-term and long-term?

short-termlong-term

### Ethical considerations

Use the separate ethics canvas to examine the ethical considerations, which emerge in the boundary between the robot and the user.

### Task(s)

What task(s) is the robot aiming to fulfil for the user?

short-termlong-term

### Advantage(s)

What are the potential advantages of using a robot to accomplish this task?  
Do the technological aspects of the robot enable something a human can't do?  
Do the social aspects of the robot enable it to do something other technologies can't?  
Are there other advantages?

|                                     |   |
|-------------------------------------|---|
| <b>Social skills</b>                | Humans treat robots as social actors. Can the robot use its social skills to accomplish its task? |
| <b>Emotional response</b>           | Can the user have a useful emotional response to the robot?                                       |
| <b>Personalization</b>              | Can the robot accomplish its task better through personalization?                                 |
| <b>Precision</b>                    | Can the robot be used to accomplish a task that requires precision?                               |
| <b>Mobility</b>                     | Is mobility an advantage for the robot to accomplish its task?                                    |
| <b>Environmental manipulation</b>   | Is environmental manipulation an advantage for the robot to accomplish its task?                  |
| <b>Data collection with sensors</b> | Can the robot sense useful things from its environment or users?                                  |
| <b>Connectivity to technology</b>   | Can the robot make use of being connected to other technologies?                                  |

# ROBOT



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