



Canvas #10/10

Canvases:

Note: only fill the bottom row if your robot is teleoperated. Describe the most important interaction of the robot. SOCIAL ROBOT CO-DESIGN CANVASES

OPER	BOT RATOR ional)	F	ROBOT	•		USER	
BEFORE	DOING e.g. controls robot's arm	CONNECTION TO SYSTEMS e.g. records data in database	SENSOR INPUT e.g. sees user's face	DOING e.g. says "Hello!"	. O	THINKING e.g. "I need help."	FEELING e.g. confused
DURING							
AFTER							



censes/by-sa/4.0/



