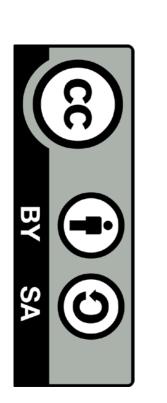
PERIENCE FLOW

OCIAL ROBOT CO-DESIGN CANVASES

Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

OPER	RATOR ional)		ROBOT	•		USER	
BEFORE	e.g. controls robot's arm	CONNECTION TO SYSTEMS e.g. records data in database	SENSOR INPUT e.g. sees user's face	e.g. says "Hello!"	e.g. pushes button	THINKING e.g. "I need help."	e.g. confused
DURING							
AFTER							



ROBOT