ROBOT OPERATOR

DODOT

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PERIFICE FIO

Note: only fill the bottom row if your robot is teleoperated.	Describe the most important interaction of the robot.

	(opti	onal)	ROBOT		USER			
8	BEFORE	DOING e.g. controls robot's arm	CONNECTION TO SYSTEMS e.g. records data in database	SENSOR INPUT e.g. sees user's face	e.g. says "Hello!"	e.g. pushes button	THINKING e.g. "I need help."	e.g. confused
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