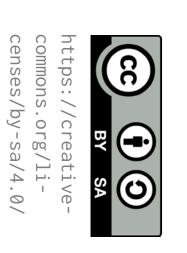


Canvas #10/10

Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

XPERIENCE FLOW
SOCIAL ROBOT CO-DESIGN CANVASES

ROBOT OPERATOR (optional)		ROBOT			USER		
e.g. controls robot's arm BEFORE	CONNECTION TO SYSTEMS e.g. records data in database	SENSOR INPUT e.g. sees user's face	e.g. says "Hello!"	e.g. pushes button	THINKING e.g. "I need help."	FEELING e.g. confused	
DURING							
AFTER							



participatory

design framework.

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