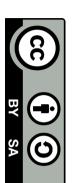
ROBOT OPERATOR

XPERIENCE FLOW SOCIAL ROBOT CO-DESIGN CANVASES

Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

(optional	F F	ROBOT		USER		
e.g. controls robot's arm BEFORE	CONNECTION TO SYSTEMS e.g. records data in database DOING	SENSOR INPUT e.g. sees user's face	DOING e.g. says "Hello!"	ı PZ	THINKING e.g. "I need help."	FEELING e.g. confused
DURING						
AFTER						



.IO/JG2T8