ROBOT
OPERATOR
(optional)

## **ROBOT**

## **USER**

## Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

DESIGNING A SOCIAL ROBOT

(optional)	KOBO		USEK
DOING e.g. controls robot's arm	e.g. sees user's face  CONNECTION TO SYSTEMS e.g. records data in database	e.g. pushes button  DOING e.g. says "Hello!"	FEELING e.g. confused THINKING e.g. "I need help."
DURING			

