



EXPERIENCE FLOW

SOCIAL ROBOT CO-DESIGN CANVASES

Describe the most important interaction of the robot.
Note: only fill the bottom row if your robot is teleoperated.

USER

FEELING e.g. confused		
THINKING e.g. "I need help."		
DOING e.g. pushes button		
DOING e.g. says "Hello!"		
SENSOR INPUT e.g. sees user's face		
CONNECTION TO SYSTEMS e.g. records data in database		
DOING e.g. controls robot's arm		
BEFORE	DURING	AFTER

ROBOT

ROBOT
OPERATOR
(optional)



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