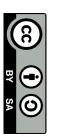
SOCIAL ROBOT CO-DESIGN CANVASES

Describe the most important interaction of the robot. Note: only fill the bottom row if your robot is teleoperated.

ROBOT OPERATOR (optional)	ROBOT			USER		
DOING e.g. controls robot's arm BEFORE	CONNECTION TO SYSTEMS e.g. records data in database	SENSOR INPUT e.g. sees user's face	DOING e.g. says "Hello!"	DOING e.g. pushes button	THINKING e.g. "I need help."	FEELING e.g. confused
DURING						
AFTER						



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