

$$1. \quad F''' + \theta = 0 \quad 0 \leq x \leq 5$$

$$\theta'' + F\theta' = 0 \quad F(0) = F'(0) = 0, \theta(0) = 1$$

$$F''(5) = 0, \theta(5) = 0$$

a) ① $F = y_1 \quad \theta = y_4$

$$F' = y_1' = y_2 \quad \theta' = y_4' = y_5$$

$$F'' = y_2' = y_3 \quad \theta'' = y_5' = -y_1 y_5$$

$$F''' = y_3' = -y_4$$

$$\therefore y' = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{bmatrix}' = \begin{bmatrix} y_2 \\ y_3 \\ -y_4 \\ y_5 \\ -y_1 y_5 \end{bmatrix} \quad +4$$

② function $y = \text{InCond}(u)$

$$y = [0 \ 0 \ u(1) \ 1 \ u(2)];$$

end +3

③ function $r = \text{residual}(u)$

$$x = \text{zeros}(\text{length}(u), 1);$$

$$x = x_{\text{Start}};$$

$$[x_{\text{Sol}}, y_{\text{Sol}}] = \text{hankut4}(@dEqs, x, \text{InCond}(u), x_{\text{Stop}}, h);$$

$$\text{lastrow} = \text{size}(y_{\text{Sol}}, 1);$$

$$r(1) = y_{\text{Sol}}(\text{lastrow}, 3);$$

$$r(2) = y_{\text{Sol}}(\text{lastrow}, 4); \quad \} +3$$

$$2. \quad \frac{d^2\theta}{dx^2} = \frac{1}{2}\theta e^{-(\theta+\mu x)} \quad -b \leq x \leq b \quad \theta'(-b) = -1$$

$$\theta'(b) = 0$$

$$a) \quad ① \quad \frac{\theta_{i+1} - 2\theta_i + \theta_{i-1}}{h^2} = \frac{1}{2}\theta_i e^{-(\theta_i + \mu x_i)}$$

+ 4

$$② \quad \text{BC} \quad \theta'(-b) = -1$$

$$\frac{\theta_2 - \theta_0}{2h} = -1 \quad \therefore \theta_0 = \theta_2 + 2h$$

+ 2

$$\frac{\theta_2 - 2\theta_1 + \theta_0}{h^2} = \frac{1}{2}\theta_1 e^{-(\theta_1 + \mu x_1)}$$

$$\Rightarrow \frac{2\theta_2 - 2\theta_1 + 2h}{h^2} = \frac{1}{2}\theta_1 e^{-(\theta_1 + \mu x_1)}$$

+ 2

$$③ \quad \text{BC} \quad \theta'(b) = 0$$

$$\frac{\theta_{n+1} - \theta_{n-1}}{2h} = 0 \quad \therefore \theta_{n+1} = \theta_{n-1}$$

+ 2

$$\Rightarrow \frac{2\theta_{n-1} - 2\theta_n}{h^2} = \frac{1}{2}\theta_n e^{-(\theta_n + \mu x_n)}$$

+ 2

$$④ \quad h(1) = \frac{2\theta_2 - 2\theta_1 + 2h}{h^2} - \frac{1}{2}\theta_1 e^{-(\theta_1 + \mu x_1)}$$

$$h(i) = \frac{\theta_{i+1} - 2\theta_i + \theta_{i-1}}{h^2} - \frac{1}{2}\theta_i e^{-(\theta_i + \mu x_i)}$$

$$h(n) = \frac{2\theta_{n-1} - 2\theta_n}{h^2} - \frac{1}{2}\theta_n e^{-(\theta_n + \mu x_n)}$$

+ 3

$$3. \frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + S(x, y)$$

$$T(\pm 1, y, t) = 0, T(x, \pm 1, t) = 0, T(x, y, 0) = 0, S(x, y) = 2(z - x^2 - y^2)$$

a)

$$\textcircled{1} \frac{T_{i,j}^{n+1} - T_{i,j}^n}{\Delta t} = \frac{\alpha}{2} \left(\frac{T_{i+1,j}^{n+1} - 2T_{i,j}^{n+1} + T_{i-1,j}^{n+1}}{h^2} + \frac{T_{i,j+1}^{n+1} - 2T_{i,j}^{n+1} + T_{i,j-1}^{n+1}}{h^2} \right) + \frac{\alpha}{2} \left(\frac{T_{i+1,j}^n - 2T_{i,j}^n + T_{i-1,j}^n}{h^2} + \frac{T_{i,j+1}^n - 2T_{i,j}^n + T_{i,j-1}^n}{h^2} \right)$$

$$\Rightarrow \frac{T_{i,j}^{n+1} - T_{i,j}^n}{\Delta t} = \frac{\alpha}{2} \delta_{xx} (T^{n+1} + T^n) + \frac{\alpha}{2} \delta_{yy} (T^{n+1} + T^n) + S + O(\Delta t^2, h^2)$$

$$\textcircled{2} \Rightarrow \left(I - \frac{\alpha \Delta t}{2} \delta_{xx} - \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^{n+1} = \left(I + \frac{\alpha \Delta t}{2} \delta_{xx} + \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^n + \Delta t S + \Delta t O(\Delta t^2, h^2) \quad +3$$

$$\Rightarrow \left(I - \frac{\alpha \Delta t}{2} \delta_{xx} \right) \left(I - \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^{n+1} - \frac{\alpha^2 \Delta t^2}{4} \delta_{xx} \delta_{yy} T^{n+1} = \left(I + \frac{\alpha \Delta t}{2} \delta_{xx} \right) \left(I + \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^n - \frac{\alpha^2 \Delta t^2}{4} \delta_{xx} \delta_{yy} T^n + \Delta t S + \Delta t O(\Delta t^2, h^2) \quad +2$$

$$\Rightarrow \left(I - \frac{\alpha \Delta t}{2} \delta_{xx} \right) \left(I - \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^{n+1} = \left(I + \frac{\alpha \Delta t}{2} \delta_{xx} \right) \left(I + \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^n + \Delta t S + \Delta t O(\Delta t^2, h^2) \quad +2$$

$$\left(\because \frac{\alpha^2 \Delta t^2}{4} \delta_{xx} \delta_{yy} (T^{n+1} - T^n) = O(\Delta t^3) \right) \therefore \text{we can neglect} \quad +2$$

$$\textcircled{3} \left(I - \frac{\alpha \Delta t}{2} \delta_{xx} \right) T^* = \left(I + \frac{\alpha \Delta t}{2} \delta_{xx} \right) \left(I + \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^n + \Delta t S \quad \dots (5)$$

$$\left(I - \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^{n+1} = T^*$$

(b) RHS

$$h_{i,j}^* = \left(I + \frac{\alpha \Delta t}{2} \delta_{yy} \right) T^n = T_{i,j}^n + \frac{\alpha \Delta t}{2h^2} (T_{i,j+1}^n - 2T_{i,j}^n + T_{i,j-1}^n) \quad +2$$

$$h_{i,j}^n = \left(I + \frac{\alpha \Delta t}{2} \delta_{xx} \right) h_{i,j}^* = h_{i,j}^* + \frac{\alpha \Delta t}{2h^2} (h_{i+1,j}^* - 2h_{i,j}^* + h_{i-1,j}^*) + \Delta t S_{i,j} \quad +2$$

$$(4) \quad T_{i,j}^* - \frac{\alpha \Delta t}{2h^2} (T_{i+1,j}^* - 2T_{i,j}^* + T_{i-1,j}^*) = r_{i,j}^n \quad +2$$

$$(5) \quad T_{1,j}^* = T_{1,j}^{n+1} - \frac{\alpha \Delta t}{2h^2} (T_{1,j+1}^{n+1} - 2T_{1,j}^{n+1} + T_{1,j-1}^{n+1})$$

$$T_{1,j+1}^{n+1} = T_{1,j}^{n+1} = T_{1,j-1}^{n+1} = 0 \quad \therefore T_{1,j}^* = 0.$$

In the same way,

$$T_{I,j}^* = 0$$

$$(6) \quad C = \frac{\alpha \Delta t}{2h^2}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ -C & 1+2C & -C \\ & \ddots & \ddots \\ & & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} T_{1,j}^* \\ T_{2,j}^* \\ \vdots \\ T_{I,j}^* \end{pmatrix} = \begin{pmatrix} 0 \\ r_{2,j}^n \\ \vdots \\ r_{I,j}^n \\ 0 \end{pmatrix} \quad +3$$

$$(7) \quad T_{i,j}^{n+1} - \frac{\alpha \Delta t}{2h^2} (T_{i,j+1}^{n+1} - 2T_{i,j}^{n+1} + T_{i,j-1}^{n+1}) = T_{i,j}^* \quad +2$$

$$(8) \quad T_{i,1}^{n+1} = 0$$

$$T_{i,I}^{n+1} = 0 \quad +2 \text{ from B.C. } T(x, \pm 1, t) = 0$$

$$(9) \quad \begin{pmatrix} 1 & 0 & 0 \\ -C & 1+2C & -C \\ & \ddots & \ddots \\ & & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} T_{i,1}^{n+1} \\ T_{i,2}^{n+1} \\ \vdots \\ T_{i,j}^{n+1} \\ \vdots \\ T_{i,I}^{n+1} \end{pmatrix} = \begin{pmatrix} 0 \\ T_{i,2}^* \\ \vdots \\ T_{i,j}^* \\ \vdots \\ 0 \end{pmatrix} \quad +3$$

(10) T^* and T^{n+1} are coupled, and these are expressed by tridiagonal matrices, respectively. Therefore, LUdec & LU b/s can be used to get T^* and T^{n+1} .

+2

4. (a) $\frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + S(x, y)$

$\therefore \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} = -\frac{1}{\alpha} S(x, y)$, elliptic equation

(b)

$$\frac{T_{i,j}^n - 2T_{i,j}^{n+1} + T_{i,j}^{n+1}}{\Delta x^2} + \frac{T_{i,j}^n - 2T_{i,j}^{n+1} + T_{i,j}^{n+1}}{\Delta y^2} = -\frac{1}{\alpha} S_{i,j}$$

$$\Rightarrow T_{i,j}^{n+1} = \frac{\beta}{4} (T_{i,j}^n + T_{i,j}^{n+1} + T_{i,j}^n + T_{i,j}^{n+1} + \frac{h^2}{\alpha} S_{i,j}) + (1-\beta) T_{i,j}^n$$

(c)

$$-\frac{1}{4} T_{i,j}^{n+1} + T_{i,j}^{n+1} - \frac{1}{4} T_{i,j}^{n+1} = \frac{1}{4} (T_{i,j}^{n+1} + T_{i,j}^n + \frac{h^2}{\alpha} S_{i,j})$$

$$\Rightarrow -\frac{1}{4} \tilde{T}_{i,j} + \tilde{T}_{i,j} - \frac{1}{4} \tilde{T}_{i,j} = \frac{1}{4} (T_{i,j}^{n+1} + T_{i,j}^n + \frac{h^2}{\alpha} S_{i,j})$$

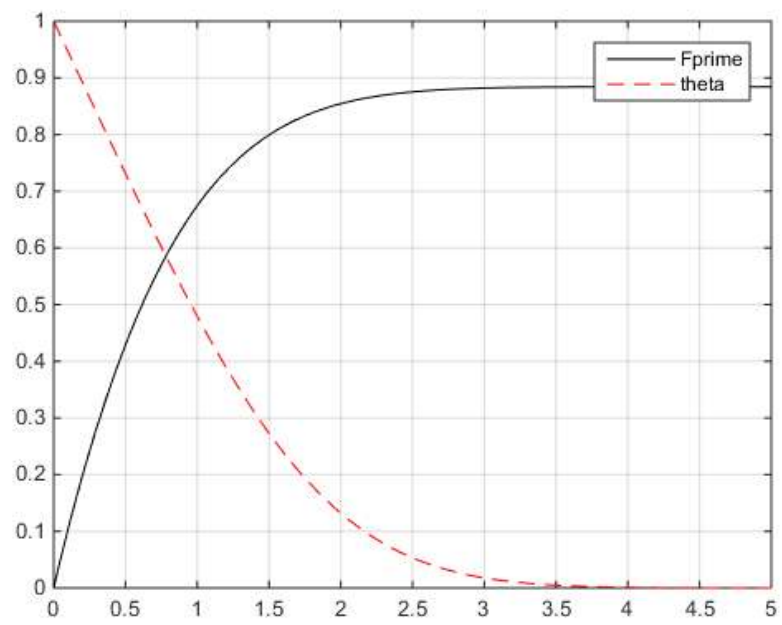
and then

$$T_{i,j}^{n+1} = \beta \tilde{T}_{i,j} + (1-\beta) T_{i,j}^n$$

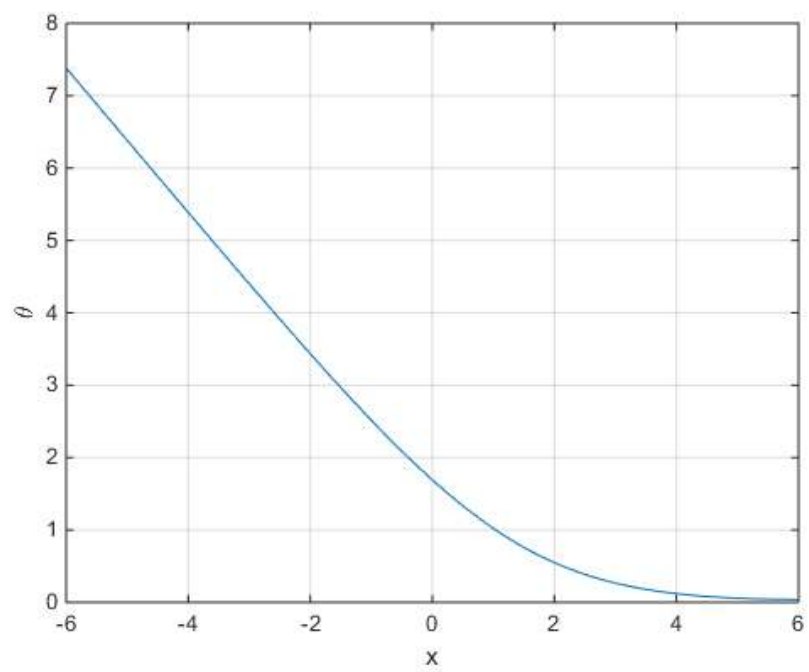
(d) Convergence rate : SLOR > SOR.

Because the boundary condition affect more faster when using SLOR.

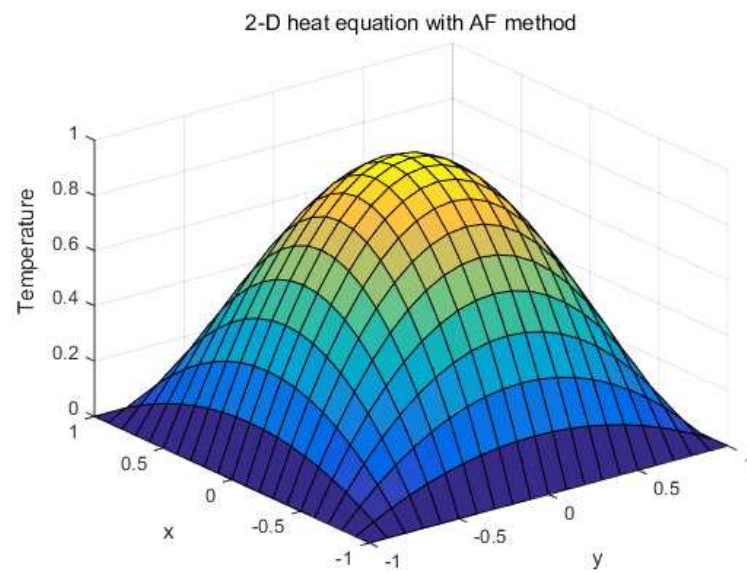
Problem 1



Problem 2



Problem 3



Problem 4 (The source term, S , should be correct.)

