

1. (a)

$$\begin{aligned} \textcircled{1} \quad f &= y_1 & T &= y_4 \\ f' &= y_2 = y_1' & T' &= y_5 = y_4' \\ f'' &= y_3 = y_1'' & T'' &= -3\alpha y_1 y_5 \\ f''' &= -3y_1 y_3 + 2y_2^2 - y_4 \end{aligned}$$

$$\vec{F} = \begin{bmatrix} y_1' \\ y_2' \\ y_3' \\ y_4' \\ y_5' \end{bmatrix} = \begin{bmatrix} y_2 \\ y_3 \\ -3y_1 y_3 + 2y_2^2 - y_4 \\ y_5 \\ -3\alpha y_1 y_5 \end{bmatrix}$$

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② function $y = \text{TnCont}(u)$

$$y = [0 \ 0 \ u(1) \ 1 \ u(2)];$$

end

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③ function $t = \text{testHual}(u)$

$$r = \text{Zeros}(\text{length}(u), 1);$$

$$x = x_{\text{Start}};$$

$$[x_{\text{Sol}}, y_{\text{Sol}}] = \text{RunKut4}(@\text{Hegs}, x, \text{TnCont}(u), x_{\text{Stop}}, h);$$

$$\text{lastRow} = \text{size}(y_{\text{Sol}}, 1);$$

$$r(1) = y_{\text{Sol}}(\text{lastRow}, 2);$$

$$r(2) = y_{\text{Sol}}(\text{lastRow}, 4);$$

end

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2.

$$\textcircled{1} \quad \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} = D(y_i - x_i)(y_i + x_i)e^{-y_i} \quad \leftarrow \text{ans}$$

$$\textcircled{2} \quad y'(-5) = y'_1 = \frac{y_2 - y_0}{2\Delta x} = -1 \Rightarrow y_0 = y_2 + 2\Delta x$$

$$i=1 \quad \frac{y_2 - 2y_1 + y_0}{\Delta x^2} = D(y_1 - x_1)(y_1 + x_1)e^{-y_1}$$

$$2 \frac{y_2 - y_1 + \Delta x}{\Delta x^2} = D(y_1 - x_1)(y_1 + x_1)e^{-y_1} \quad \leftarrow \text{ans}$$

$$\textcircled{2} \quad y'(5) = y'_n = \frac{y_{n+1} - y_{n-1}}{2\Delta x} = 1 \Rightarrow y_{n+1} = y_{n-1} + 2\Delta x$$

$$\frac{y_{n+1} - 2y_n + y_{n-1}}{\Delta x^2} = D(y_n - x_n)(y_n + x_n)e^{-y_n}$$

$$2 \frac{y_{n-1} - y_n + \Delta x}{\Delta x^2} = D(y_n - x_n)(y_n + x_n)e^{-y_n} \quad \leftarrow \text{ans}$$

$$\textcircled{4} \quad \begin{aligned} r_1 &= 2 \left(\frac{y_2 - y_1 + \Delta x}{\Delta x^2} \right) - D(y_1 - x_1)(y_1 + x_1)e^{-y_1} \\ r_i &= \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x^2} - D(y_i - x_i)(y_i + x_i)e^{-y_i} \quad (i=2, 3, \dots, n-1) \\ r_n &= 2 \left(\frac{y_{n-1} - y_n + \Delta x}{\Delta x^2} \right) - D(y_n - x_n)(y_n + x_n)e^{-y_n} \end{aligned}$$

$$3. \frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) + S(x, y) \quad r = \frac{\alpha \Delta t}{h^2}$$

$$\textcircled{1} T_{i,j}^{n+1/2} - T_{i,j}^n = \frac{\alpha \Delta t}{2h^2} \left((T_{i+1/2,j}^{n+1/2} - 2T_{i,j}^{n+1/2} + T_{i-1/2,j}^{n+1/2}) + (T_{i,j+1}^n - 2T_{i,j}^n + T_{i,j-1}^n) \right) + \frac{\Delta t}{2} S_{i,j}$$

$$\textcircled{2} \quad -\frac{1}{2} T_{i-1,j}^{n+1/2} + (1+r) T_{i,j}^{n+1/2} - \frac{1}{2} T_{i+1,j}^{n+1/2} = \frac{r}{2} T_{i,j-1}^n + (1-r) T_{i,j}^n + \frac{r}{2} T_{i,j+1}^n + \frac{\Delta t}{2} S_{i,j}$$

$$T_{1,j} = 1 \quad (\because T(0, y, t) = 1)$$

$$i = I$$

$$-\frac{1}{2} T_{I-1,j}^{n+1/2} + (1+r) T_{I,j}^{n+1/2} - \frac{1}{2} T_{I+1,j}^{n+1/2} = \frac{r}{2} T_{I,j-1}^n + (1-r) T_{I,j}^n + \frac{r}{2} T_{I,j+1}^n + \frac{\Delta t}{2} S_{I,j}$$

$$\Rightarrow -\frac{1}{2} T_{I-1,j}^{n+1/2} + (1+r) T_{I,j}^{n+1/2} = \frac{r}{2} T_{I,j-1}^n + (1-r) T_{I,j}^n + \frac{r}{2} T_{I,j+1}^n + \frac{\Delta t}{2} S_{I,j}$$

$$\textcircled{3}$$

$$\begin{bmatrix} 1 & 0 \\ -\frac{1}{2} & 1+r & -\frac{1}{2} \\ & \ddots & \ddots & \ddots \\ & & -\frac{1}{2} & 1+r \end{bmatrix} \begin{bmatrix} T_{1,j}^{n+1/2} \\ T_{2,j}^{n+1/2} \\ \vdots \\ T_{I,j}^{n+1/2} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{r}{2} T_{2,j-1}^n + (1-r) T_{2,j}^n + \frac{r}{2} T_{2,j+1}^n + \frac{\Delta t}{2} S_{2,j} \\ \vdots \\ \frac{r}{2} T_{I,j-1}^n + (1-r) T_{I,j}^n + \frac{r}{2} T_{I,j+1}^n + \frac{\Delta t}{2} S_{I,j} \end{bmatrix}$$

$$\textcircled{4} T_{i,j}^{n+1} - T_{i,j}^{n+1/2} = \frac{\alpha \Delta t}{2h^2} \left((T_{i+1,j}^{n+1/2} - 2T_{i,j}^{n+1/2} + T_{i-1,j}^{n+1/2}) + (T_{i,j+1}^n - 2T_{i,j}^n + T_{i,j-1}^n) \right) + \frac{\Delta t}{2} S_{i,j}$$

$$-\frac{1}{2} T_{i,j-1}^{n+1} + (1+r) T_{i,j}^{n+1} - \frac{1}{2} T_{i,j+1}^{n+1} = \frac{r}{2} T_{i-1,j}^{n+1/2} + (1-r) T_{i,j}^{n+1/2} + \frac{r}{2} T_{i+1,j}^{n+1/2} + \frac{\Delta t}{2} S_{i,j}$$

$$\textcircled{5} \quad j=1 \quad j=J$$

$$T_{i,1} = 0 \quad (\because T(x, 0, t) = 0) \quad T_{i,J} = 0 \quad (\because T(x, 1, t) = 0)$$

$$\textcircled{6} \begin{bmatrix} 1 & 0 \\ -\frac{1}{2} & 1+r & -\frac{1}{2} \\ & \ddots & \ddots & \ddots \\ & & -\frac{1}{2} & 1+r & 0 \\ & & & 0 & 1 \end{bmatrix} \begin{bmatrix} T_{i,1}^{n+1} \\ T_{i,2}^{n+1} \\ \vdots \\ T_{i,J}^{n+1} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{r}{2} T_{i-1,2}^{n+1/2} + (1-r) T_{i,2}^{n+1/2} + \frac{r}{2} T_{i+1,2}^{n+1/2} + \frac{\Delta t}{2} S_{i,2} \\ \vdots \\ \frac{r}{2} T_{i-1,J}^{n+1/2} + (1-r) T_{i,J}^{n+1/2} + \frac{r}{2} T_{i+1,J}^{n+1/2} + \frac{\Delta t}{2} S_{i,J} \\ 0 \end{bmatrix}$$



- ⑦ Instead of solving one set of linear equations for the 2-D heat equation, solve 1D equations for each grid line. It is ADI method, and it consists of first treating one row implicitly with backward Euler then reversing roles and treating the other by backward Euler.
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4.

(a) let $-\frac{\dot{Q}}{k} = S$. then,

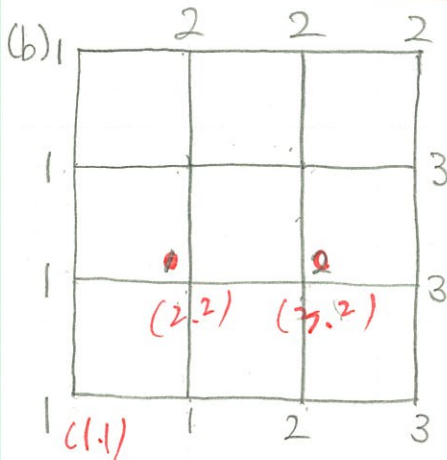
$$\frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{h^2} + \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{h^2} = S_{i,j}$$

$$\therefore T_{i,j} = \frac{1}{4} (T_{i+1,j} + T_{i-1,j} + T_{i,j+1} + T_{i,j-1}) - h^2 S_{i,j}$$

G-S

$$\Rightarrow T_{i,j}^{n+1} = \frac{1}{4} (T_{i+1,j}^n + T_{i-1,j}^n + T_{i,j+1}^n + T_{i,j-1}^n - h^2 S_{i,j})$$

+ 4



$$T_{2,2}^{n+1} = \frac{1}{4} (1 + 1 + 1 + 1) = \frac{5}{4} = 1.25$$

$$T_{2,3}^{n+1} = \frac{1}{4} (1 + 1 + 2 + \frac{5}{4} + 1) = 1.5625$$

$$T_{3,2}^{n+1} = \frac{1}{4} (3 + 1.25 + 1 + 2 + 1) = 2.0625$$

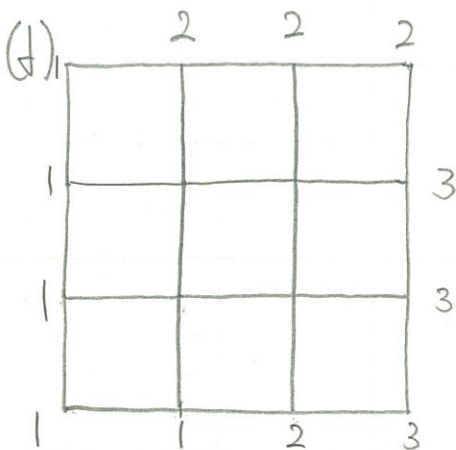
$$T_{3,3}^{n+1} = \frac{1}{4} (3 + 1.5625 + 2 + 2.0625 + 1) = 2.4063$$

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(c)

$$T_{i,j}^{n+1} = \frac{1}{4} (T_{i+1,j}^{n+1} + T_{i-1,j}^{n+1} + T_{i,j+1}^{n+1} + T_{i,j-1}^n - h^2 S_{i,j})$$

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$$T_{2,2}^{n+1} = \frac{1}{4} (1 + 1 + 1 + T_{3,2}^{n+1} + 1)$$

$$T_{3,2}^{n+1} = \frac{1}{4} (T_{2,2}^{n+1} + 2 + 3 + 1 + 1)$$

$$\therefore T_{2,2}^{n+1} = 1.533 \quad T_{3,2}^{n+1} = 2.1332$$

$$T_{2,3}^{n+1} = \frac{1}{4} (1 + 1.533 + 2 + T_{3,3}^{n+1})$$

$$T_{3,3}^{n+1} = \frac{1}{4} (2 + 3 + 1 + T_{2,3}^{n+1} + 2.1332)$$

$$\therefore T_{2,3}^{n+1} = 2.0174 \quad , \quad T_{3,3}^{n+1} = 2.5396$$

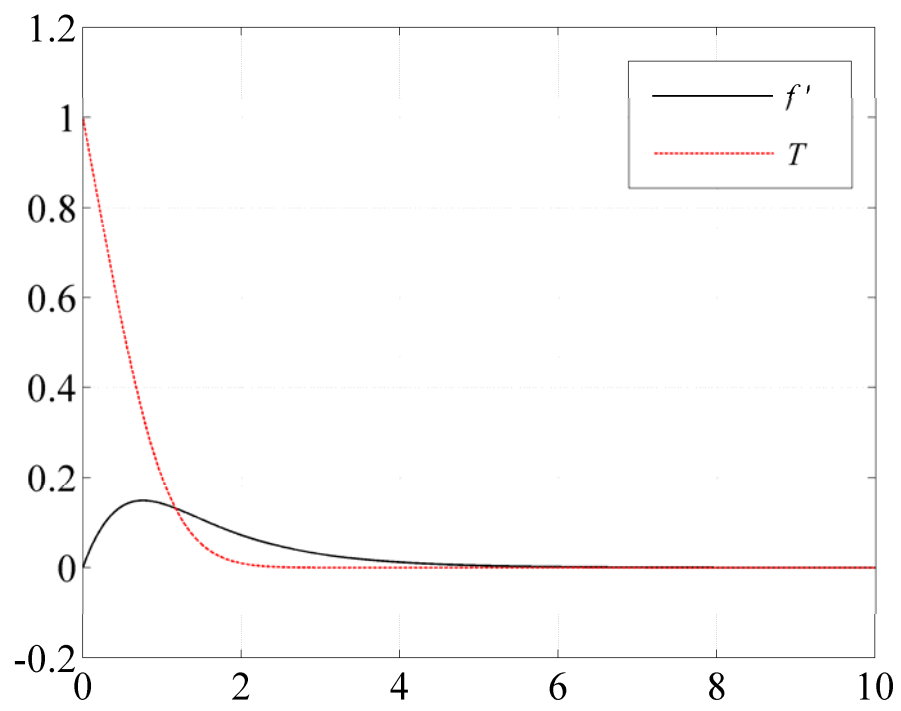
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(e) The LGS method is more faster than GS method

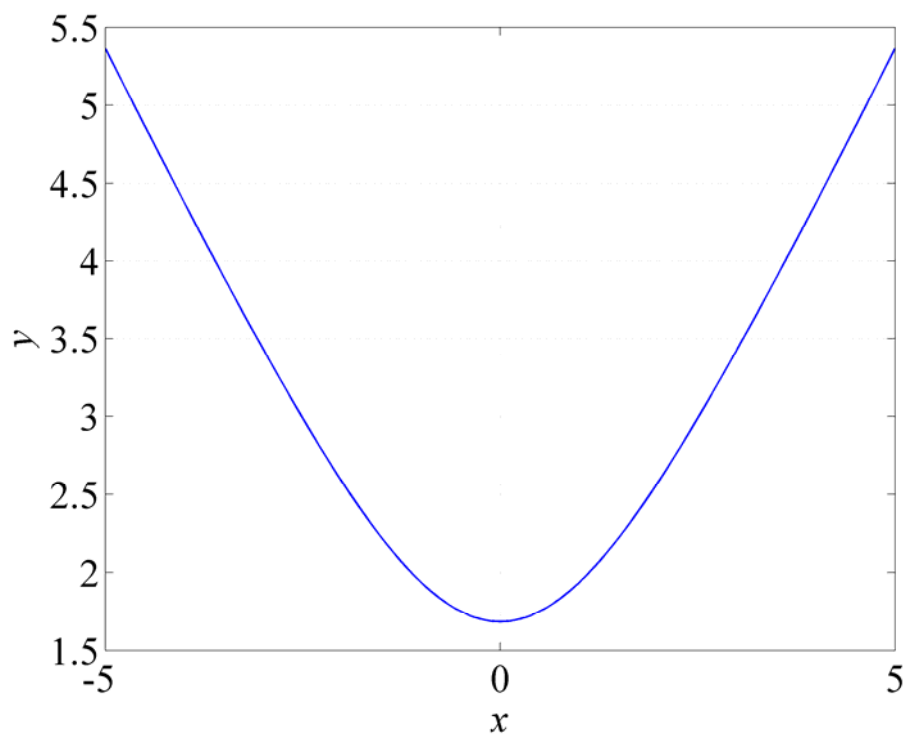
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Because the boundary condition can affect the interior point. (more easily)

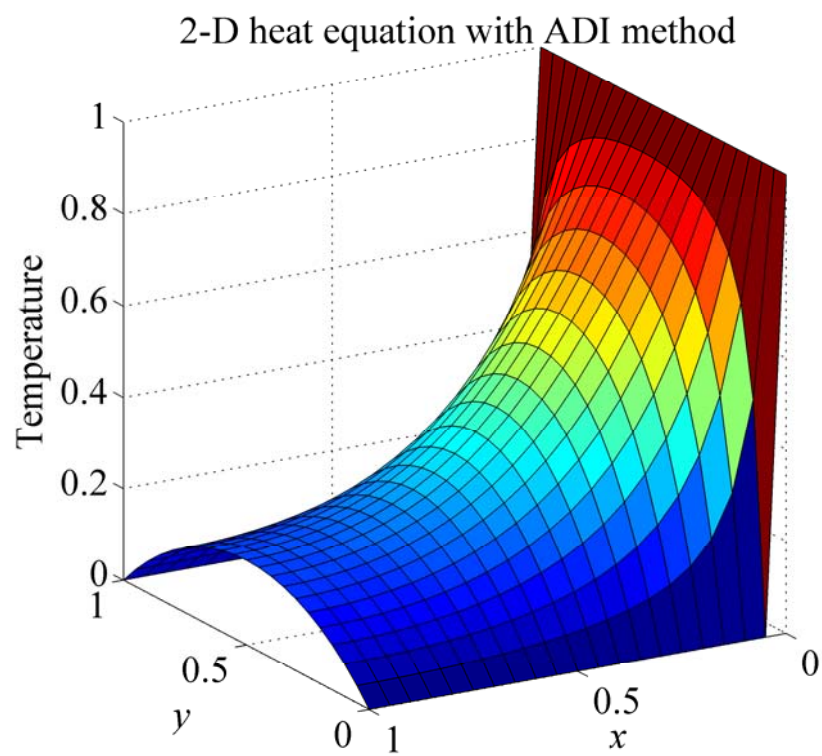
1-b



2-b



3-b



4-f

Successive Line Over-Relaxation (SLOR) Method

