

## Set 8.1)

### Problem 18

$$y^{(4)} = -2yy''$$

$$y(0) = y'(0) = 0 \quad y(4) = 0 \quad y'(4) = 1$$

```
function p8_1_18
% Shooting method for 4th-order boundary value problem
% in Problem 18, Problem Set 1.

xStat = 0; xStop = 4; % Range of integration.
h = 0.1; % Step size.
freq = 5; % Frequency of printout.
u = [0 0]; % Trial values of u(1)
% and u(2).

x = xStat;
u = newtonRaphson2(@residual,u,1e-10);
[xSol,ySol] = runKut4(@dEqs,x,inCond(u),xStop,h);
printSol(xSol,ySol,freq)

function F = dEqs(x,y) % Differential equations.
F = zeros(1,4);
F(1) = y(2); F(2) = y(3); F(3) = y(4);
F(4) = -2*y(1)*y(3);
end

function y = inCond(u) % Initial conditions; u(1)
y = [0 0 u(1) u(2)]; % and u(2) are unknowns.
end

function r = residual(u) % Bounday residuals.
r = zeros(length(u),1);
x = xStat;
[xSol,ySol] = runKut4(@dEqs,x,inCond(u),xStop,h);
lastRow = size(ySol,1);
r(1) = ySol(lastRow,1);
r(2) = ySol(lastRow,2) - 1;
end
end
```

>> p8\_1\_18

x	y1	y2	y3	y4
0.0000e+00	0.0000e+00	0.0000e+00	-3.6774e-01	2.6832e-01
5.0000e-01	-4.0382e-02	-1.5038e-01	-2.3409e-01	2.6459e-01
1.0000e+00	-1.3938e-01	-2.3485e-01	-1.0494e-01	2.5107e-01
1.5000e+00	-2.6476e-01	-2.5644e-01	1.7941e-02	2.4367e-01
2.0000e+00	-3.8559e-01	-2.1638e-01	1.4452e-01	2.7113e-01
2.5000e+00	-4.6971e-01	-1.0713e-01	3.0041e-01	3.6666e-01
3.0000e+00	-4.7723e-01	9.5906e-02	5.2803e-01	5.6249e-01
3.5000e+00	-3.5014e-01	4.4173e-01	8.7983e-01	8.5484e-01
4.0000e+00	-7.7875e-12	1.0000e+00	1.3714e+00	1.0619e+00

## Problem 19

$$\ddot{x} = -\frac{c}{m}v\dot{x} \quad \ddot{y} = -\frac{c}{m}v\dot{y} - g \quad v = \sqrt{\dot{x}^2 + \dot{y}^2}$$

$$x(0) = y(0) = 0 \quad x(10 \text{ s}) = 8000 \text{ m} \quad y(10 \text{ s}) = 0$$

We use the notation

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} = \begin{bmatrix} x \\ \dot{x} \\ y \\ \dot{y} \end{bmatrix}$$

```
function p8_1_19
% Shooting method for 4th-order boundary value problem
% in Problem 19, Problem Set 1.

xStart = 0; xStop = 10; % Range of integration.
h = 2; % Step size.
freq = 0; % Frequency of printout.
u = [1000 600]; % Trial values of u(1)
% and u(2).

x = xStart;
u = newtonRaphson2(@residual,u);
[xSol,ySol] = bulStoer(@dEqs,x,inCond(u),xStop,h);
printSol(xSol,ySol,freq)

function F = dEqs(x,y) % Differential equations.
c = 3.2e-4; m = 20; g = 9.80665;
v = sqrt(y(2)^2 + y(4)^2);
F = zeros(1,4);
F(1) = y(2); F(2) = -c/m*v*y(2);
F(3) = y(4); F(4) = -c/m*v*y(4) - g;
end

function y = inCond(u) % Initial conditions: u(1)
y = [0 u(1) 0 u(2)]; % and u(2) are unknowns.
end

function r = residual(u) % Boundary residuals.
r = zeros(length(u),1);
x = xStart;
[xSol,ySol] = bulStoer(@dEqs,x,inCond(u),xStop,h);
n = size(ySol,1);
r(1) = ySol(n,1) - 8000;
r(2) = ySol(n,3);
end
end
```

x	y1	y2	y3	y4
0.0000e+00	0.0000e+00	8.5349e+02	0.0000e+00	5.0150e+01
1.0000e+01	8.0000e+03	7.5089e+02	1.0248e-12	-4.8051e+01

$$v_0 = \sqrt{\dot{x}_0^2 + \dot{y}_0^2} = \sqrt{853.49^2 + 50.150^2} = 854.96$$

$$\theta = \tan^{-1} \frac{50.150}{853.49} = 0.058691 \text{ rad} = 3.363^\circ$$

## Set 4.1)

### Problem 2

$$f(x) = x^3 - 3.23x^2 - 5.54x + 9.84$$

We begin with a root search starting at  $x = 1$  and launch bisection once the root is bracketed.

$x$	$f(x)$	Interval
1.0	2.070	
1.2	0.269	
1.4	-1.503	(1.2, 1.4)
$(1.2 + 1.4)/2 = 1.3$	-0.624	(1.2, 1.3)
$(1.2 + 1.3)/2 = 1.25$	-0.179	(1.2, 1.25)
$(1.2 + 1.25)/2 = 1.225$	0.045	(1.225, 1.25)
$(1.225 + 1.25)/2 = 1.2375$	-0.067	(1.225, 1.2375)
$(1.225 + 1.2375)/2 = 1.2313$	-0.012	(1.225, 1.2313)
$(1.225 + 1.2313)/2 = 1.2282$	0.017	(1.2282, 1.2313)
$(1.2282 + 1.2313)/2 = 1.2298$	0.002	(1.2298, 1.2313)
$(1.2298 + 1.2313)/2 = 1.2306$	-0.005	(1.2298, 1.2306)
$(1.2298 + 1.2306)/2 = 1.2302$	-0.002	(1.2298, 1.2302)

The root is  $x = 1.230$  ◀

## Problem 3

The starting points are

$$x_1 = 4 \quad f_1 = \cosh(4) \cos(4) - 1 = -18.8499$$

$$x_2 = 5 \quad f_2 = \cosh(5) \cos(5) - 1 = 20.0506$$

Bisection yields the point

$$x_3 = 4.5 \quad f_3 = \cosh(4.5) \cos(4.5) - 1 = -10.4888$$

The improved root can be estimated with Ridder's formula:

$$x = x_3 \pm (x_3 - x_1) \frac{f_3}{\sqrt{f_3^2 - f_1 f_2}}$$

if  $f_1 - f_2 < 0$ , choose + sign

if  $f_1 - f_2 > 0$ , choose - sign

Here are the results of the iterations:

$x_1$	$x_2$	$x_3$	$f_1$	$f_2$	$f_3$	$x$	$f(x)$
4	5	4.5	-18.8499	20.0506	-10.4888	4.7374	0.4280
4.5	4.7374	4.6187	-10.4888	0.4280	-5.7415	4.7301	0.0017
4.6187	4.7301	4.6744	-5.7415	0.0017	-3.0359	4.7300	1.7308e-6
4.6744	4.7300	4.7022	-3.0359	1.7308e-6	-1.5606	4.7300	0

Hence the root  $x = 4.7300$

## Problem 4

Newton's formula is

$$x \leftarrow x - \frac{f(x)}{f'(x)}$$

where

$$f(x) = \cosh x \cos x - 1$$

$$f'(x) = \sinh x \cos x - \cosh x \sin x$$

Starting with  $x = 4.5$ , successive applications of the formula yield

$$\begin{aligned} x &\leftarrow 4.5 - \frac{-10.489}{34.52} = 4.804 \\ x &\leftarrow 4.804 - \frac{4.573}{66.31} = 4.735 \\ x &\leftarrow 4.735 - \frac{0.283}{58.20} = 4.730 \\ x &\leftarrow 4.730 - \frac{0.001}{57.65} = 4.730 \quad \blacktriangleleft \end{aligned}$$

## Problem 6

$$\begin{aligned}f(x) &= \sin x + 3 \cos x - 2 \\f'(x) &= \cos x - 3 \sin x\end{aligned}$$

$$x \leftarrow x - \frac{f(x)}{f'(x)}$$

Starting with  $x = -2$ , successive applications of Newton's iterative formula yield

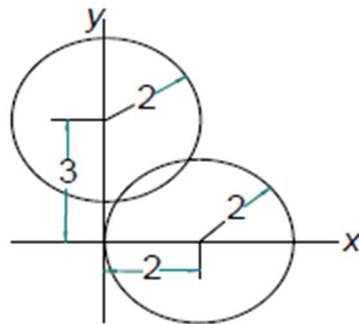
$$\begin{aligned}x &\leftarrow -2 - \frac{-4.1577}{2.3117} = -0.2015 \\x &\leftarrow -0.2015 - \frac{0.7392}{1.5801} = -0.6693 \\x &\leftarrow -0.6693 - \frac{-0.2676}{2.6456} = -0.5682 \\x &\leftarrow -0.5682 - \frac{-0.0093}{2.4571} = -0.5644 \\x &\leftarrow -0.5644 - \frac{0.0000}{2.445} = -0.5644 \quad \blacktriangleleft\end{aligned}$$

Starting with  $x = 2$ , we get

$$\begin{aligned}x &\leftarrow 2 - \frac{-2.3391}{-3.1440} = 1.2560 \\x &\leftarrow 1.2560 - \frac{-0.1203}{-2.5430} = 1.2087 \\x &\leftarrow 1.2087 - \frac{-0.0021}{-2.4512} = 1.2078 \\x &\leftarrow 1.2078 - \frac{0.0000}{-2.4495} = 1.2078 \quad \blacktriangleleft\end{aligned}$$

## Problem 23

$$\begin{aligned}f_1(x, y) &= (x - 2)^2 + y^2 - 4 \\f_2(x, y) &= x^2 + (y - 3)^2 - 4\end{aligned}$$



The rough locations of the intersection points are  $(2, 2)$  and  $(0, 1)$ . Letting  $x = x_1$  and  $y = x_2$ , the following function defined the equations:

```
function y = p4_1_23(x)
% Equations used in Problem 23, Problem Set 4.1
y = [(x(1) - 2)^2 + x(2)^2 - 4;
x(1)^2 + (x(2) - 3)^2 - 4];
end
```

The following command returns the coordinates of the first point:

```
>> newtonRaphson2(@p4_1_23, [2;2])
```

ans =

```
1.7206
1.9804
```

Changing the starting point to  $[0; 1]$ , we obtain the coordinates of the second point

```
>> newtonRaphson2(@p4_1_23, [0;1])
```

ans =

```
0.2794
1.0196
```

## Problem 30

Letting  $x = [\theta_1 \ \theta_2 \ \theta_3 \ T]^T$ , the equations to be solved are

```
function y = p4_1_30(x)
% Equations used in Prob. 30, Problem Set 4.1
y = [x(4)*(-tan(x(2)) + tan(x(1))) - 16;
x(4)*(tan(x(3)) + tan(x(2))) - 20;
-4*sin(x(1)) - 6*sin(x(2)) + 5*sin(x(3)) + 3;
4*cos(x(1)) + 6*cos(x(2)) + 5*cos(x(3)) - 12];
end
```

Rough estimates (starting values) of the variables are

$$\theta_1 = 0.8 \text{ rad} \quad \theta_2 = 0.3 \text{ rad} \quad \theta_3 = 0.4 \text{ rad} \quad T = 20 \text{ kN}$$

The solution is obtained with the command

```
>> newtonRaphson2(@p4_1_30, [0.8;0.3;0.4;20])
```

ans =

```
0.9358
0.4334
0.5800
17.8884
```

Therefore, the solution is

$$\begin{aligned}\theta_1 &= 0.9358 \text{ rad} = 53.62^\circ \quad \blacktriangleleft \\ \theta_2 &= 0.4334 \text{ rad} = 24.83^\circ \quad \blacktriangleleft \\ \theta_3 &= 0.5800 \text{ rad} = 33.23^\circ \quad \blacktriangleleft \\ T &= 17.89 \text{ kN}\end{aligned}$$