

Notion of graphs

- ▶ Graph $G = (V, E)$
 $V = \{v_i\}$ = set of vertices
 E = set of edges = a subset of $V \times V = \{(v_i, v_j)\}$
- ▶ $|E| = O(|V|^2)$
dense graph: $|E| \approx |V|^2$
sparse graph: $|E| \approx |V|$
- ▶ If G is connected, then $|E| \geq |V| - 1$.
- ▶ Some variants
 - ▶ undirected: edge $(u, v) = (v, u)$
 - ▶ directed: (u, v) is edge from u to v .
 - ▶ weighted: weight on either edge or vertex
 - ▶ multigraph: multiple edges between vertices
- ▶ Further reading: Appendix B.4, pp.1168-1172 of [CLRS,3rd ed.]

Notion of graphs

Representing graph by **Adjacency Matrix**

- ▶ $A = (a_{ij})$ is a $|V| \times |V|$ matrix, where

$$a_{ij} = \begin{cases} 1, & \text{if } (v_i, v_j) \in E \\ 0, & \text{otherwise} \end{cases}$$

- ▶ If G is undirected, A is symmetric, i.e., $A^T = A$.
- ▶ A is typically very sparse – use a sparse storage scheme in practice

Notion of graphs

Representing graph by **Incidence Matrix**

- ▶ $B = (b_{ij})$ is a $|V| \times |E|$ matrix, where

$$b_{ij} = \begin{cases} 1, & \text{if edge } e_j \text{ enters vertex } v_i \\ -1, & \text{if edge } e_j \text{ leaves vertex } v_i \\ 0, & \text{otherwise} \end{cases}$$

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Representing graph by **Adjacency List**

- ▶ For each vertex v ,

$$\text{Adj}[v] = \{ \text{vertices adjacent to } v \}$$

- ▶ Variation: could also keep second list of edges coming into vertex.
- ▶ How much storage is needed?

Answer: $\Theta(|V| + |E|)$ ("sparse representation")

Notion of graphs

- ▶ **Degree** of a vertex of a undirected graph = the number of incident edges
- ▶ For a digraph: **Out-degree** and **In-degree**
- ▶ For undirected graph:

$$\# \text{ of items in the adj. list} = \sum_{v \in V} \text{degree}(v) = 2|E|$$

- ▶ For digraph:

$$\# \text{ of items in the adj. list} = \sum_{v \in V} \text{out-degree}(v) = |E|$$