

# Minimum Spanning Tree (MST)

- ▶ Undirected connected graph  $G = (V, E)$
- ▶ Weight function  $w : E \rightarrow \mathbf{R}$
- ▶ **Spanning tree**: a tree that connects all vertices
- ▶ **Minimum Spanning Tree**  $T$ :

$$w(T) = \sum_{(u,v) \in T} w(u,v) \quad \text{is minimized}$$

# MST

Idea of “growing” a MST:

- ▶ construct the MST by successively select edges to include in the tree
- ▶ guarantee that after the inclusion of each new selected edge, it forms a subset of some MST.

*One of the most famous **greedy algorithms**, along with Huffman coding*

# MST

Basic properties:

- **Optimal substructure:** optimal tree contains optimal subtrees.

Let  $T$  be a MST of  $G = (V, E)$ . Removing  $(u, v)$  of  $T$  partitions  $T$  into two trees  $T_1$  and  $T_2$ . Then  $T_1$  is a MST of  $G_1 = (V_1, E_1)$  and  $T_2$  is a MST of  $G_2 = (V_2, E_2)$ .<sup>1</sup>

*Proof.* Note that

$$w(T) = w(T_1) + w(u, v) + w(T_2).$$

There can't be a better subtree than  $T_1$  or  $T_2$ , otherwise  $T$  would be suboptimal.

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<sup>1</sup>The subgraph  $G_1$  is induced by vertices in  $T_1$ , i.e.,  $V_1 = \{\text{vertices in } T_1\}$  and  $E_1 = \{(x, y) \in E; x, y \in V_1\}$ . Similarly for  $G_2$ .

# MST

Basic properties:

► **Greedy-choice property:**

Let  $T$  be a MST of  $G = (V, E)$ ,  $A \subseteq T$  be a subtree of  $T$ , and  $(u, v)$  be **min-weight edge** in  $G$  connecting  $A$  and  $V - A$ . Then  $(u, v) \in T$ .<sup>2</sup>

*Proof.* If  $(u, v) \notin T$ , then

- $(u, v) \cup T$  forms a cycle,
- replace one of edges of  $T$  by  $(u, v)$  form a new tree  $T$
- this is contradiction to  $T$  is MST

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<sup>2</sup>It is an abuse of notation we will view  $A$  as being both edges and vertices.

# MST

## Prim's algorithm

- ▶ Basic idea:
  - ▶ builds one tree, so that  $A$  is always a tree
  - ▶ starts from a root  $r$
  - ▶ at each step, find the **next lightest** edge crossing cut  $(A, V - A)$  and add this edge to  $A$  (*greedy choice*)
- ▶ How to find the **next lightest** edge quickly?

Answer: use a **priority queue**

## Review: Priority queue

A **priority queue** maintains a set  $S$  of elements, each with an associated value called a “key”, and supports the following operations:

- ▶ **Search( $S, k$ ):**  
returns  $x$  in  $S$  with  $\text{key}[x] = k$
- ▶ **Insert( $S, x$ )/Delete( $S, x$ ):**  
inserts/deletes the element  $x$  into the set  $S$
- ▶ **Maximum( $S$ )/Minimum( $S$ ):**  
returns  $x$  in  $S$  with largest/smallest key
- ▶ **Extract-max( $S$ )/Extract-min( $S$ ):**  
removes and returns  $x$  in  $S$  with largest/smallest key
- ▶ **Increase-key( $S, x, k$ )/Decrease-key( $S, x, k$ ):**  
increases/decreases the value of element  $x$ 's key to the new value  $k$

*The priority queue has been used in Huffman coding.*

# MST

## Prim's algorithm – pseudocode

```
MST-Prim( $G$ ,  $w$ ,  $r$ )
 $Q$  = empty
for each vertex  $u$  in  $V$ 
     $key[u]$  =  $\infty$ 
     $pi[u]$  = Nil
    Insert( $Q$ ,  $u$ )
endfor
Decrease-key( $Q, r, 0$ )
while  $Q$  not empty
     $u$  = Extract-Min( $Q$ )
    for each  $v$  in Adj[ $u$ ]
        if ( $v$  in  $Q$ ) and ( $w(u,v) < key[v]$ )
            Decrease-key( $Q$ ,  $v$ ,  $w(u,v)$ )
             $pi[v]$  =  $u$  // parent of  $v$ 
        endif
    endfor
endwhile
return  $A = \{ (v, pi[v]): v \text{ in } V - \{r\} \}$  // MST
```

# MST

**Prim's algorithm** – running time:

- ▶ depends on how the priority queue is implemented
- ▶ Suppose  $Q$  is a binary heap (see Section 6.1)
  - ▶ Initialize  $Q$  and the first for loop:  $O(|V| \lg |V|)$
  - ▶ Decrease key of root  $r$ :  $O(\lg |V|)$
  - ▶ While-loop:
    - a)  $|V|$  Extract-Min calls:  $O(|V| \lg |V|)$
    - b)  $\leq |E|$  Decrease-Key calls:  $O(|E| \lg |V|)$
- ▶ Total:  $O(|E| \lg |V|)$

*Note:  $G$  is connected,  $\lg |E| = \Theta(\lg |V|)$  (why?)*



# MST

## Kruskal's algorithm

- ▶ Basic idea:
  - ▶ scan edges in increasing of weight
  - ▶ put edge in if no loop created
- ▶ Why does this result in MST?  
Answer: min-weight edge is always in MST (the greedy-choice property).
- ▶ Implementation data structure: **disjoint-set**

# Review: Disjoint-Set data structure

**Disjoint-Set** maintains a collection of  $S = \{S_1, S_2, \dots, S_k\}$  of disjoint dynamic sets. Each set is identified by a representative, which is some member of the set.

A disjoint-set data structure supports the following operations:

- ▶ **Make-set( $x$ ):**  
creates a new set whose only member (and thus representative) is  $x$ .
- ▶ **Union( $x, y$ ):**  
unites the sets that contain  $x$  and  $y$ , say  $S_x$  and  $S_y$ , into a new set that is the union of these two sets:  $S_x \cup S_y$ . The representative is any member of  $S_x \cup S_y$ .
- ▶ **Find-set( $x$ ):**  
returns (a pointer to) the representative of the (unique) set containing  $x$ .

*To learn more about the disjoint-set data structure, see Chapter 21.*

# MST

**Kruskal's algorithm** – pseudocode:

```
MST-Kruskal( $G, w$ )  
   $A = \text{empty}$   
  for each vertex  $v$  in  $V$   
    Make-set( $v$ )  
  endfor  
  Sort the edges  $E$  in nondecreasing order by  $w$   
  for each edge  $(u,v)$  in  $E$   
    if Find-set( $u$ )  $\neq$  Find-set( $v$ )  
       $A = A \cup \{(u,v)\}$   
      Union( $u,v$ )  
    endif  
  endfor  
  return  $A$ 
```

# MST

**Kruskal's algorithm** – running time:

- ▶ depends on the implementation of the disjoint-set
- ▶ Sort:  $\Theta(|E| \lg |E|)$
- ▶  $|V|$  Make-Set ops
- ▶  $2|E|$  Find-Set ops
- ▶  $|V| - 1$  Union ops
- ▶ Total:  $O(|E| \lg |V|)$

*Note:  $G$  is connected,  $\lg |E| = \Theta(\lg |V|)$*