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In [2]: import heapq
        graph={
             'A':{'B':2,'C':3},
             'B':{'D':3,'E':1},
             'C':{'F':2},
             'D':{},
             'E':{'F':1},
             'F':{}
        }
        def dijkstra(graph, node):
            #Assign infinity to all other nodes
            distances={node:float('inf') for node in graph}
            #The distance value of start node is zero "0"
            distances[node]=0
            print("distances::",distances)
            #Predecessor of node is stored here
            previous={node:None for node in graph}
            queue=[(0,node)] #queue stores start "node" with edge distance value "0".
            while queue:
                #heapq of python maintains the priority queue (min queue)
                #heappop() method of heapq will pop the minimum val of the heap
                 current distance, current node = heapq.heappop(queue)
                # relaxation, visit all the successors of current node and get the edge cost of
                for next node, weight in graph[current node].items():
                     distance temp=current distance+weight
                #if the distance of the currently visited node is smaller than the earlier sto
                 #then update the distance value of current node with smaller cost
                     if distance temp<distances[next node]:</pre>
                         distances[next node]=distance temp
                         previous[next node]=current node
                         heapq.heappush(queue,(distance temp,next node))
                     print("Distances::",distances)
            return distances, previous
        #Driver Code
        Node_distance, Path = dijkstra(graph, 'A')
        print(Node distance)
        print(Path)
        distances:: {'A': 0, 'B': inf, 'C': inf, 'D': inf, 'E': inf, 'F': inf}
        Distances:: {'A': 0, 'B': 2, 'C': inf, 'D': inf, 'E': inf, 'F': inf}
        Distances:: {'A': 0, 'B': 2, 'C': 3, 'D': inf, 'E': inf, 'F': inf}
        Distances:: {'A': 0, 'B': 2, 'C': 3, 'D': 5, 'E': inf, 'F': inf}
        Distances:: {'A': 0, 'B': 2, 'C': 3, 'D': 5, 'E': 3, 'F': inf}
        Distances:: {'A': 0, 'B': 2, 'C': 3, 'D': 5, 'E': 3, 'F': 5}
        Distances:: {'A': 0, 'B': 2, 'C': 3, 'D': 5, 'E': 3, 'F': 4}
        {'A': 0, 'B': 2, 'C': 3, 'D': 5, 'E': 3, 'F': 4}
        {'A': None, 'B': 'A', 'C': 'A', 'D': 'B', 'E': 'B', 'F': 'E'}
In [ ]:
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