# Quiz 1: Classification task with CNN & BiLSTM

```
In [1]: enter_name = "Minn Banya"
In [2]: import pandas as pd
        import torch, torchdata, torchtext
        from torch import nn
        import time
        import os
        device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
        print(device)
        #make our work comparable if restarted the kernel
        SEED = 2422
        torch.manual seed(SEED)
        torch.backends.cudnn.deterministic = True
       C:\Users\minnb\AppData\Local\Packages\PythonSoftwareFoundation.Python.3.11_qbz5n2kfr
       a8p0\LocalCache\local-packages\Python311\site-packages\tqdm\auto.py:21: TqdmWarning:
       IProgress not found. Please update jupyter and ipywidgets. See https://ipywidgets.re
       adthedocs.io/en/stable/user install.html
         from .autonotebook import tqdm as notebook_tqdm
       cuda
In [3]: torch.__version__
Out[3]: '2.1.0+cu121'
In [4]: torchtext.__version__
Out[4]: '0.16.2+cpu'
        Load the given dataset
```

- 1. Create a variable to your dataset PATH example: ./data/
- 2. Load the csv files using pandas

```
In [7]: test_data_raw.shape
 Out[7]: (3263, 4)
 In [8]: ## Lets analyze the data a little
         #print and show how many unique classes are in the target
         classes = train_data_raw['target'].unique()
         num_classes = len(classes)
         print(num_classes)
 In [9]: assert num_classes > 1
In [10]: ##lets see how many columns are there
         #print the columns of the train_data_raw
         print(train_data_raw.columns) #write your code here
        Index(['id', 'keyword', 'location', 'text', 'target'], dtype='object')
           1. Lets remove the keywords and location columns. We only want to focus on the text and
             the predictions
           2. Lets split some training data to validation dataset
In [11]: SPLIT_PER = 2 #percentage of split for validation set 2 = 2%
         split = int(len(train_data_raw) * (SPLIT_PER/100))
         dropped_train = train_data_raw.drop(columns=['id', 'keyword', 'location']) #drop th
         train_data = dropped_train[:-split]
         valid_data = dropped_train[-split:]
         assert train_data.shape == (len(train_data_raw) - split, 2)
         assert valid_data.shape == (split, 2)
In [12]: print(train_data_raw.shape)
         print("After dropping columns and spliting!")
         print(train_data.shape, valid_data.shape)
        (7613, 5)
        After dropping columns and spliting!
```

#### Lets tokenize the data

(7461, 2) (152, 2)

```
In [13]: from torchtext.data.utils import get_tokenizer
tokenizer = get_tokenizer('spacy', language='en_core_web_sm')
```

```
tokens = tokenizer("We are learning torchtext in AIT!") #some test
         tokens
Out[13]: ['We', 'are', 'learning', 'torchtext', 'in', 'AIT', '!']
In [14]: from torchtext.vocab import build_vocab_from_iterator
         def yield_tokens(data_iter):
             #loop through the data_iter,
             # Mind that the data_iter in this case is pandas Dataframe
             for i in range(len(data_iter)):
                 yield tokenizer(data_iter['text'][i])
         specials = ['<unk>', '<pad>', '<bos>', '<eos>'] #create array of special tags for t
         vocab = build_vocab_from_iterator(yield_tokens(train_data), specials = specials, s
         #set_default_index of the vocab to unknown tag
         vocab.set_default_index(vocab["<unk>"])
In [15]: assert len(vocab) == 26442
In [16]: vocab_dict = vocab.get_stoi()
         vocab_dict
```

```
Out[16]: {'bells': 17043,
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```

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           ...}
In [17]: from torchtext.vocab import FastText
         fast_vectors = FastText(language='simple') ##Load fasttext with language=simple
In [18]: fast_embedding = fast_vectors.get_vecs_by_tokens(vocab.get_itos()).to(device)
```

```
#since the fasttext has 300 embedding
assert fast_embedding.shape == (len(vocab), 300)

In [19]: text_pipeline = lambda x: vocab(tokenizer(x))
label_pipeline = lambda x: int(x) ## Copy from the lab. Note that Something has to

In [20]: text_pipeline("I love to play football")

Out[20]: [13, 185, 10, 683, 2229]

In [21]: label_pipeline('0')
Out[21]: 0
```

# To fit the padnas dataframe to DataLoader first we must wrap it as DataSet

```
In [22]: from torch.utils.data import Dataset
         class PD_DATASET(Dataset):
             def __init__(self, dataframe):
                 self.dataframe = dataframe
             def len (self):
                 return len(self.dataframe)
             def __getitem__(self, idx):
                 return self.dataframe.iloc[idx]
In [23]: # Reset validation index to fix index error during collate_batch
         valid data = valid data.reset index()
         valid_data = valid_data.drop(columns='index')
In [24]: train = PD_DATASET(train_data)
         valid = PD DATASET(valid data)
         test = PD_DATASET(test_data_raw)
In [25]: from torch.utils.data import DataLoader
         from torch.nn.utils.rnn import pad_sequence
         pad_idx = vocab['<pad>'] ##get the pad index from the vocab
         def collate batch(batch):
             ## copy the collate_batch function from Professor's code. But it will not work
             #mind how the dataset that we use is structured (hint: columns)
             label_list, text_list, length_list = [], [], []
             for i in range(len(batch)):
                 label_list.append(label_pipeline(batch[i]['target']))
                 processed_text = torch.tensor(text_pipeline(batch[i]['text']), dtype=torch.
                 text_list.append(processed_text)
```

```
length_list.append(processed_text.size(0))
            return torch.tensor(label_list, dtype=torch.int64), pad_sequence(text_list, pad
In [26]: batch_size = 64
        train_loader = DataLoader(train, batch_size=batch_size,
                                   shuffle=True, collate fn=collate batch)
        valid_loader = DataLoader(valid, batch_size=batch_size,
                                   shuffle=True, collate_fn=collate_batch)
In [27]: next(iter(train_loader))
Out[27]: (tensor([0, 0, 1, 0, 0, 0, 0, 1, 0, 0, 1, 1, 1, 0, 1, 0, 0, 1, 1, 0, 0, 1, 0, 0,
                 0, 0, 1, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 1, 1]),
         tensor([[ 927, 1891, 298, ...,
                                             1,
                 [ 1606,
                        480, 1373, ...,
                                            1,
                                                    1,
                                                          1],
                    4, 11448, 7141, ..., 1, 1,
                                                          1],
                 [ 106, 17820, 17901, ...,
                                            1,
                                                          1],
                    4, 25073, 1078, ...,
                                            1,
                                                    1,
                                                          1],
                 [ 45, 25530, 1442, ...,
                                             1,
                                                    1,
                                                          1]]),
         tensor([13, 21, 21, 23, 21, 16, 19, 13, 27, 20, 12, 13, 12, 28, 18, 30, 20, 8,
                 14, 17, 15, 21, 15, 31, 22, 24, 20, 22, 7, 21, 18, 23, 13, 45, 2, 20,
                 12, 27, 14, 12, 21, 12, 19, 13, 13, 3, 19, 31, 15, 24, 32, 20, 12, 12,
                 17, 11, 18, 9, 8, 23, 21, 22, 19, 26]))
In [28]: for label, text, length in train_loader:
            break
        print("Label shape: ", label.shape) # (batch_size, )
        print("Text shape: ", text.shape) # (batch_size, seq len)
       Label shape: torch.Size([64])
       Text shape: torch.Size([64, 36])
```

### First lets try CNN

```
])
                 self.fc = nn.Linear(len(filter_sizes) * n_filters, output_dim)
                 self.dropout = nn.Dropout(dropout)
             def forward(self, text):
                 #text = [batch size, sent len]
                 embedded = self.embedding(text)
                 #embedded = [batch size, sent len, emb dim]
                 embedded = embedded.unsqueeze(1)
                 #embedded = [batch size, 1, sent len, emb dim]
                 conved = [F.relu(conv(embedded)).squeeze(3) for conv in self.convs]
                 #conved_n = [batch size, n_filters, sent len - filter_sizes[n] + 1]
                 pooled = [F.max_pool1d(conv, conv.shape[2]).squeeze(2) for conv in conved]
                 #pooled_n = [batch size, n_filters]
                 cat = self.dropout(torch.cat(pooled, dim = 1))
                 #cat = [batch size, n_filters * len(filter_sizes)]
                 return self.fc(cat)
In [30]: #explicitly initialize weights for better learning
         def initialize_weights(m):
             if isinstance(m, nn.Linear):
                 nn.init.xavier normal (m.weight)
                 nn.init.zeros_(m.bias)
             elif isinstance(m, (nn.Conv2d, nn.Conv2d)):
                 for name, param in m.named_parameters():
                     if 'bias' in name:
                         nn.init.zeros_(param)
                     elif 'weight' in name:
                         nn.init.kaiming_normal_(param)
In [31]: input_dim = len(vocab)
                  = 300 #how many embedding does the fasttext have
         output_dim = 2 #how many classes do we have
         dropout
                  = 0.5
         n_filters = 100
         filter\_sizes = [3, 4, 5]
         cnn_model = CNN(input_dim, emb_dim, output_dim, dropout, n_filters, filter_sizes).t
         cnn_model.apply(initialize_weights) #apply initialize_weight
         cnn_model.embedding.weight.data = fast_embedding #**<----applied the fast text em</pre>
In [32]: batch_size = 3
                  = 50
         seq_len
In [33]: import torch.optim as optim
         lr=1e-3
```

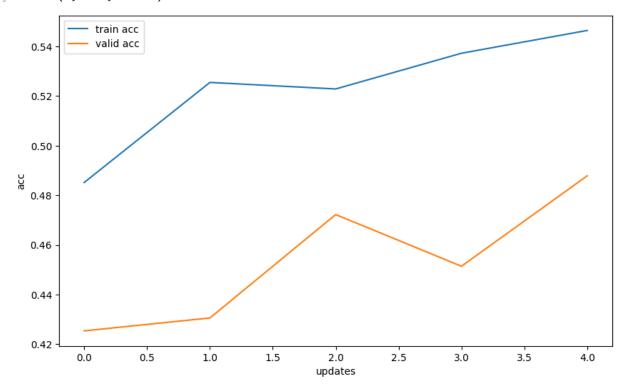
```
#training hyperparameters
         optimizer = optim.SGD(cnn_model.parameters(), lr=lr)
         criterion = nn.CrossEntropyLoss() #combine softmax with cross entropy
In [34]: def accuracy(preds, y):
             predicted = torch.max(preds.data, 1)[1]
             batch_corr = (predicted == y).sum()
             acc = batch_corr / len(y)
             return acc
In [35]: def train(model, loader, optimizer, criterion, loader_length):
             #write the code to train the model
             epoch_loss = 0
             epoch_acc = 0
             model.train() #useful for batchnorm and dropout
             for i, (label, text, length) in enumerate(loader):
                 label = label.to(device) #(batch_size, )
                 text = text.to(device) #(batch_size, seq len)
                 #predict
                 predictions = model(text).squeeze(1) #output by the fc is (batch_size, 1),
                 #calculate loss
                 loss = criterion(predictions, label)
                 acc = accuracy(predictions, label)
                 #backprop
                 optimizer.zero_grad()
                 loss.backward()
                 optimizer.step()
                 epoch_loss += loss.item()
                 epoch_acc += acc.item()
             return epoch_loss / loader_length, epoch_acc / loader_length
In [36]: def evaluate(model, loader, criterion, loader length):
             #write the code to evaluate
             epoch_loss = 0
             epoch_acc = 0
             model.eval()
             with torch.no_grad():
                 for i, (label, text, length) in enumerate(loader):
                     label = label.to(device) #(batch_size, )
                     text = text.to(device) #(seq len, batch_size)
                     predictions = model(text).squeeze(1)
                     loss = criterion(predictions, label)
                     acc = accuracy(predictions, label)
```

```
epoch_loss += loss.item()
                     epoch_acc += acc.item()
             return epoch_loss / loader_length, epoch_acc / loader_length
In [37]: train_loader_length = len(list(iter(train_loader)))
         val_loader_length = len(list(iter(valid_loader)))
In [38]: def epoch_time(start_time, end_time):
             elapsed_time = end_time - start_time
             elapsed_mins = int(elapsed_time / 60)
             elapsed_secs = int(elapsed_time - (elapsed_mins * 60))
             return elapsed_mins, elapsed_secs
In [39]: best_valid_loss = float('inf')
         num epochs = 5
         save_path = f'./models/{cnn_model.__class__.__name__}.pt'
         train_losses = []
         train_accs = []
         valid_losses = []
         valid_accs = []
         total_start_time = time.time()
         for epoch in range(num_epochs):
                 #write the code that starts the training, store the training and valid loss
             start_time = time.time()
             train_loss, train_acc = train(cnn_model, train_loader, optimizer, criterion, tr
             valid_loss, valid_acc = evaluate(cnn_model, valid_loader, criterion, val_loader
             #for plotting
             train_losses.append(train_loss)
             train_accs.append(train_acc)
             valid_losses.append(valid_loss)
             valid_accs.append(valid_acc)
             end time = time.time()
             epoch_mins, epoch_secs = epoch_time(start_time, end_time)
             if valid_loss < best_valid_loss:</pre>
                 best_valid_loss = valid_loss
                 torch.save(cnn_model.state_dict(), save_path)
             print(f'Epoch: {epoch+1:02} | Time: {epoch_mins}m {epoch_secs}s')
             print(f'\tTrain Loss: {train_loss:.3f} | Train Acc: {train_acc*100:.2f}%')
             print(f'\t Val. Loss: {valid_loss:.3f} | Val. Acc: {valid_acc*100:.2f}%')
             #also print the time it took to train the model
         total_end_time = time.time()
         total_mins, total_secs = epoch_time(total_start_time, total_end_time)
         print(f'Total Time: {total_mins}m {total_secs}s')
```

```
Epoch: 01 | Time: 0m 2s
                Train Loss: 0.836 | Train Acc: 48.51%
                 Val. Loss: 0.738 | Val. Acc: 42.53%
        Epoch: 02 | Time: 0m 2s
                Train Loss: 0.778 | Train Acc: 52.55%
                 Val. Loss: 0.720 | Val. Acc: 43.06%
        Epoch: 03 | Time: 0m 2s
                Train Loss: 0.767 | Train Acc: 52.28%
                 Val. Loss: 0.704 | Val. Acc: 47.22%
        Epoch: 04 | Time: 0m 2s
                Train Loss: 0.755 | Train Acc: 53.72%
                 Val. Loss: 0.703 | Val. Acc: 45.14%
        Epoch: 05 | Time: 0m 2s
                Train Loss: 0.738 | Train Acc: 54.64%
                 Val. Loss: 0.691 | Val. Acc: 48.78%
        Total Time: Om 11s
In [40]: ##Plot the training loss and the accuracy
         import matplotlib.pyplot as plt
         fig = plt.figure(figsize=(10, 6))
          ax = fig.add_subplot(1, 1, 1)
         ax.plot(train_losses, label = 'train loss')
          ax.plot(valid_losses, label = 'valid loss')
          plt.legend()
         ax.set xlabel('updates')
         ax.set_ylabel('loss')
Out[40]: Text(0, 0.5, 'loss')
          0.84
                                                                                       train loss
                                                                                       valid loss
          0.82
          0.80
          0.78
        S 0.76
          0.74
          0.72
          0.70
                                                               2.5
                                                                                 3.5
                                                                                          4.0
                 0.0
                          0.5
                                   1.0
                                            1.5
                                                     2.0
                                                                        3.0
                                                    updates
In [41]: fig = plt.figure(figsize=(10, 6))
          ax = fig.add_subplot(1, 1, 1)
          ax.plot(train_accs, label = 'train acc')
          ax.plot(valid_accs, label = 'valid acc')
```

```
plt.legend()
ax.set_xlabel('updates')
ax.set_ylabel('acc')
```

```
Out[41]: Text(0, 0.5, 'acc')
```



## Lets Try the LSTM model

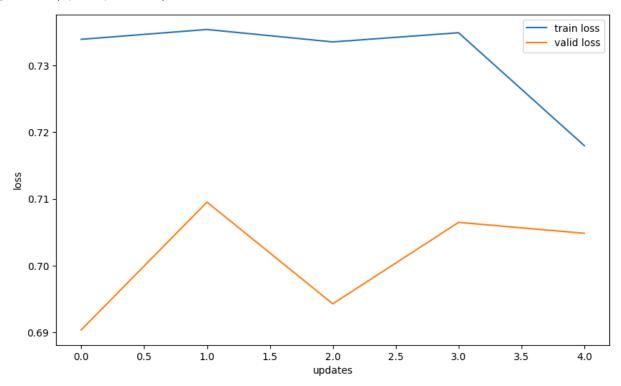
```
In [42]: train = PD_DATASET(train_data)
         valid = PD_DATASET(valid_data)
In [43]: import torch.nn as nn
         class LSTM(nn.Module):
             def __init__(self, input_dim, emb_dim, hid_dim, num_layers,
                           bidirectional, dropout, output_dim):
                  super(LSTM, self).__init__()
                  self.embedding = nn.Embedding(input_dim, emb_dim, padding_idx=pad_idx)
                  self.lstm
                                 = nn.LSTM(
                                      emb_dim,
                                      hid_dim,
                                      num_layers=num_layers,
                                      bidirectional=bidirectional,
                                      dropout = dropout,
                                      batch_first = True
                  self.fc
                                 = nn.Linear(hid_dim * 2, output_dim)
             def forward(self, text, text_length):
                  #text = [batch_size, seq len]
                  embedded = self.embedding(text)
```

```
#text = [batch_size, seq len, emb_dim]
                 #pack sequence
                 packed_embedded = nn.utils.rnn.pack_padded_sequence(embedded, text_length.t
                                                                     enforce_sorted=False, b
                 packed_output, (hn, cn) = self.lstm(packed_embedded)
                 #output is basically all the hidden states; hn is only last hidden state;
                 output, output_lengths = nn.utils.rnn.pad_packed_sequence(packed_output, ba
                 #output = [batch_size, seq len, hidden_dim * num directions]
                        = [num_layers * num_directions, batch_size, hid_dim] #3 layers bi
                        = [num_layers * num_directions, batch_size, hid_dim]
                 #cn
                         = torch.cat((hn[-2, :, :], hn[-1, :, :]), dim = 1)
                 hn
                 #hn
                         = [batch_size, hidden_dim * num_directions]
                 return self.fc(hn)
In [44]: input_dim = len(vocab)
         emb dim
                  = 300 #same as above
         hidden_dim = 256 #how many hidden dims do you want?
         output dim = 2 #same as above
         dropout = 0.5
         num_layers = 2
         bidirectional = True
         lstm_model = LSTM(input_dim, emb_dim, hidden_dim, num_layers, bidirectional, dropou
         lstm model.apply(initialize weights) #apply initialize weight
         lstm_model.embedding.weight.data = fast_embedding #**<----applied the fast text e
In [45]: import torch.optim as optim
         1r=1e-3
         #training hyperparameters
         optimizer = optim.Adam(lstm model.parameters(), lr=lr)
         criterion = nn.CrossEntropyLoss() #
In [46]: def train(model, loader, optimizer, criterion, loader length):
             #write the code to train the model
             epoch_loss = 0
             epoch_acc = 0
             model.train() #useful for batchnorm and dropout
             for i, (label, text, length) in enumerate(loader):
                 label = label.to(device) #(batch_size, )
                 text = text.to(device) #(batch_size, seq Len)
                 #predict
                 predictions = model(text).squeeze(1) #output by the fc is (batch_size, 1),
                 #calculate loss
                 loss = criterion(predictions, label)
                 acc = accuracy(predictions, label)
```

```
#backprop
                 optimizer.zero grad()
                 loss.backward()
                 optimizer.step()
                 epoch_loss += loss.item()
                 epoch_acc += acc.item()
             return epoch_loss / loader_length, epoch_acc / loader_length
In [47]: def evaluate(model, loader, criterion, loader_length):
             #write the code to evaluate the model
             epoch_loss = 0
             epoch_acc = 0
             model.eval()
             with torch.no_grad():
                 for i, (label, text, length) in enumerate(loader):
                     label = label.to(device) #(batch_size, )
                     text = text.to(device) #(seq len, batch_size)
                     predictions = model(text).squeeze(1)
                     loss = criterion(predictions, label)
                     acc = accuracy(predictions, label)
                     epoch_loss += loss.item()
                     epoch_acc += acc.item()
             return epoch_loss / loader_length, epoch_acc / loader_length
In [48]: train_loader_length = len(list(iter(train_loader)))
         val_loader_length = len(list(iter(valid_loader)))
In [49]: def epoch_time(start_time, end_time):
             elapsed_time = end_time - start_time
             elapsed_mins = int(elapsed_time / 60)
             elapsed_secs = int(elapsed_time - (elapsed_mins * 60))
             return elapsed mins, elapsed secs
In [50]: best_valid_loss = float('inf')
         num_epochs = 5
         save_path = f'./models/lstm_{lstm_model.__class__.__name___}.pt'
         train_losses = []
         train accs = []
         valid_losses = []
         valid_accs = []
         total_start_time = time.time()
         for epoch in range(num epochs):
             #write the code that starts the training, store the training and valid losses a
```

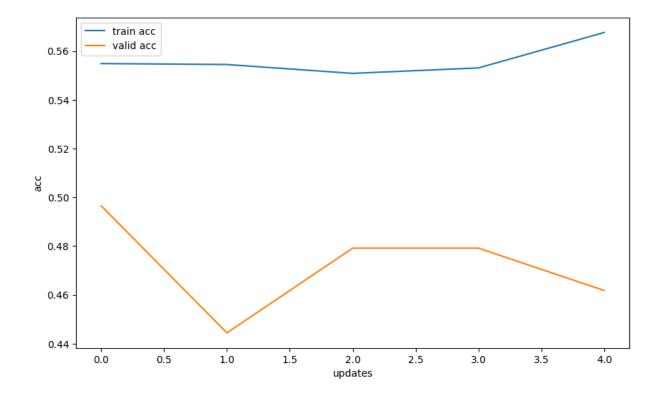
```
#also print the time it took to train the model
             start_time = time.time()
             train_loss, train_acc = train(cnn_model, train_loader, optimizer, criterion, tr
             valid_loss, valid_acc = evaluate(cnn_model, valid_loader, criterion, val_loader
             #for plotting
             train_losses.append(train_loss)
             train accs.append(train acc)
             valid_losses.append(valid_loss)
             valid_accs.append(valid_acc)
             end_time = time.time()
             epoch mins, epoch secs = epoch time(start time, end time)
             if valid_loss < best_valid_loss:</pre>
                 best_valid_loss = valid_loss
                 torch.save(cnn_model.state_dict(), save_path)
             print(f'Epoch: {epoch+1:02} | Time: {epoch_mins}m {epoch_secs}s')
             print(f'\tTrain Loss: {train_loss:.3f} | Train Acc: {train_acc*100:.2f}%')
             print(f'\t Val. Loss: {valid_loss:.3f} | Val. Acc: {valid_acc*100:.2f}%')
             #also print the time it took to train the model
         total end time = time.time()
         total_mins, total_secs = epoch_time(total_start_time, total_end_time)
         print(f'Total Time: {total_mins}m {total_secs}s')
        Epoch: 01 | Time: 0m 2s
                Train Loss: 0.734 | Train Acc: 55.48%
                Val. Loss: 0.690 | Val. Acc: 49.65%
        Epoch: 02 | Time: 0m 2s
                Train Loss: 0.735 | Train Acc: 55.44%
                Val. Loss: 0.710 | Val. Acc: 44.44%
        Epoch: 03 | Time: 0m 2s
               Train Loss: 0.734 | Train Acc: 55.08%
                Val. Loss: 0.694 | Val. Acc: 47.92%
        Epoch: 04 | Time: 0m 2s
                Train Loss: 0.735 | Train Acc: 55.30%
                Val. Loss: 0.706 | Val. Acc: 47.92%
        Epoch: 05 | Time: 0m 2s
                Train Loss: 0.718 | Train Acc: 56.76%
                 Val. Loss: 0.705 | Val. Acc: 46.18%
        Total Time: 0m 10s
In [51]: ##Plot the losses and accuracy over all epochs
         ##Plot the training loss and the accuracy
         import matplotlib.pyplot as plt
         fig = plt.figure(figsize=(10, 6))
         ax = fig.add_subplot(1, 1, 1)
         ax.plot(train_losses, label = 'train loss')
         ax.plot(valid_losses, label = 'valid loss')
         plt.legend()
         ax.set_xlabel('updates')
         ax.set ylabel('loss')
```

```
Out[51]: Text(0, 0.5, 'loss')
```



```
In [52]: fig = plt.figure(figsize=(10, 6))
    ax = fig.add_subplot(1, 1, 1)
    ax.plot(train_accs, label = 'train acc')
    ax.plot(valid_accs, label = 'valid acc')
    plt.legend()
    ax.set_xlabel('updates')
    ax.set_ylabel('acc')
```

Out[52]: Text(0, 0.5, 'acc')



### Conclusion

- 1. Compare the two models on their time and accuracy. Which one do you think did well for the disaster classification task. and Why?
- Answer:

Model	Train Loss	Train Acc	Val Loss	Val Acc	Time
CNN	0.738	54.64%	0.691	48.78%	11s
biLSTM	0.718	56.76%	0.705	46.18%	10s

The CNN model performed slightly better in terms of validation loss and accuracy with 5 epochs. The training time only took 10% longer than the biLSTM model. Thus, I believe the **CNN model** did better for the disater classification task. The reason being that the contextual information captured by the CNN model better represented the data given.

- 2. How do you think we get better results in this dataset for classification.
- Answer: Looking the trend in the loss and accuracy graphs, we can see with the CNN
  model that the loss is still going down and the accuracy graph shows that it is going up.
  As such I believe increasing the number of epochs would get us better results for this
  dataset.