

Microprocessors

Tuba Ayhan

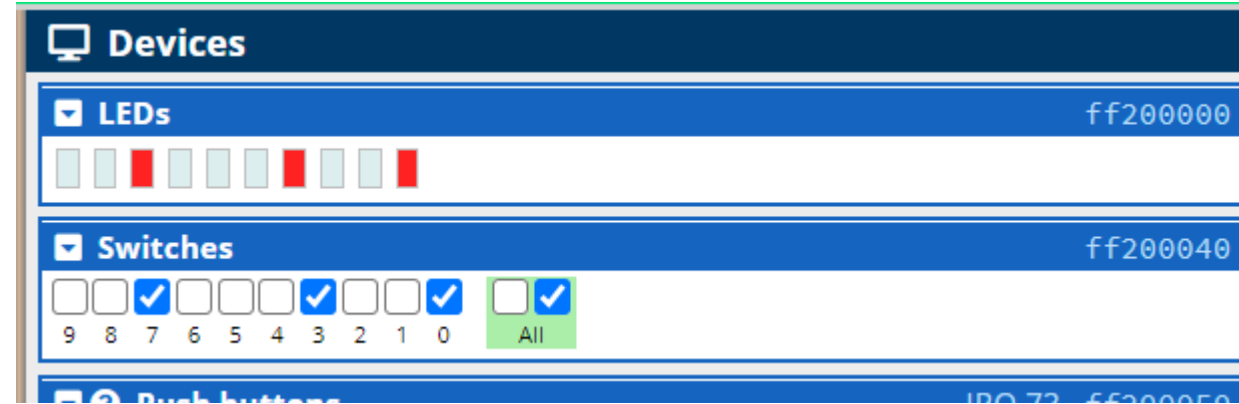
MEF University

Examples

DE1-SoC Computer System with ARM Cortex-A9

Simple I/O

- Echo the SWs on LEDs.



Simple I/O

- Echo the SWs on LEDs.

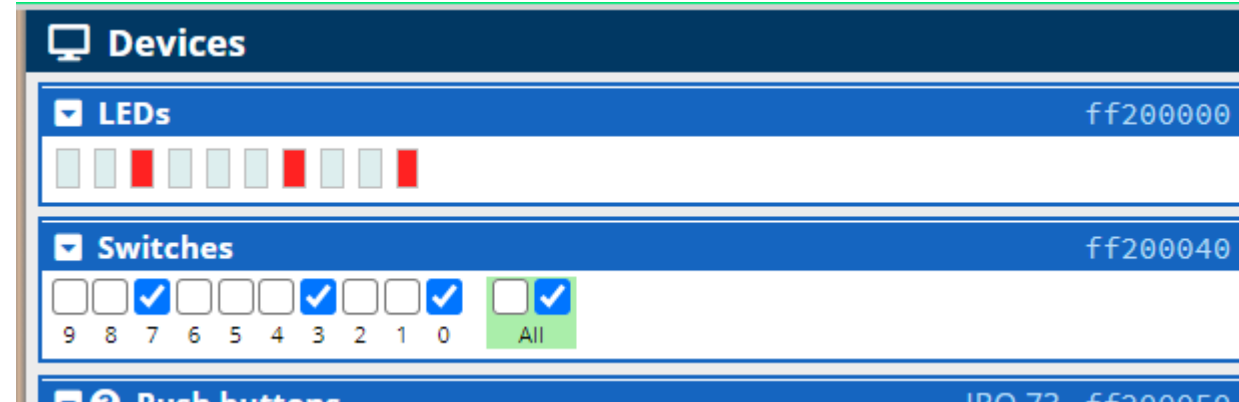
```
.global _start  
_start:
```

```
LDR R0,=0xFF200000 // R0 points to LEDs  
LDR R1,=0xFF200040 // R1 points to SWs
```

```
loop:
```

```
LDR R3,[R1]  
STR R3,[R0]  
B loop
```

```
.end
```



Set the private timer

- Set the timer to count for 1 second and start over when it reaches 0.
- Clk frequency = 200 MHz.

☒ **Cortex-A9 Private Timer**
IRQ 29 fffec600

183338125
Auto
Run
TO=1

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFFE600	Load value											Load
0xFFFE604	Current value											Counter
0xFFFE608	Unused					Prescaler		Unused	I	A	E	Control
0xFFFE60C	Unused										F	Interrupt status

Set the private timer

- Set the timer to count for 1 second and start over when it reaches 0.
- Clk frequency = 200 MHz.

```
LDR R2,=0xFFEC600
```

```
// R2 points to private  
//timer base
```

```
LDR R3,=200000000
```

```
STR R3, [R2]
```

```
MOV R3,#0b011
```

```
STR R3, [R2,#8]
```

Cortex-A9 Private Timer				IRQ 29	fffec600
183338125	Auto	Run	TO=1		

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFEC600	Load value											Load
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0xFFEC608	Unused					Prescaler		Unused	I	A	E	Control
0xFFEC60C	Unused										F	Interrupt status

Display the private timer current value

<input checked="" type="checkbox"/> Cortex-A9 Private Timer				IRQ 29	fffec600
183338125	Auto	Run	TO=1		

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFFE600	Load value											Load
0xFFFE604	Current value											Counter
0xFFFE608	Unused					Prescaler		Unused	I	A	E	Control
0xFFFE60C	Unused										F	Interrupt status

Display the private timer current value

loop:

LDR R3, [R2, #4]

STR R3, [R0]

B loop

☒ **Cortex-A9 Private Timer**
IRQ 29 fffec600

183338125
Auto
Run
TO=1

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFFFEC600	Load value											Load
0xFFFFEC604	Current value											Counter
0xFFFFEC608	Unused					Prescaler		Unused	I	A	E	Control
0xFFFFEC60C	Unused										F	Interrupt status

☒ **LEDs**
ff200000



Blink the LEDs

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFFE600	Load value											Load
0xFFFE604	Current value											Counter
0xFFFE608	Unused					Prescaler		Unused	I	A	E	Control
0xFFFE60C	Unused										F	Interrupt status

Blink the LEDs

```
LDR R0,=0xFF200000 // R0 points to LEDs
LDR R1,=0xFF200040 // R1 points to SWs
LDR R2,=0xFFFFEC600 // R2 points to private timer base
MOV R4,#3
LDR R3,=200000000
STR R3, [R2]
MOV R3,#0b011
STR R3, [R2,#8]
```

loop: →

Address	31	...	16	15	...	8	7	3	2	1	0	Register name
0xFFFFEC600	Load value											Load
0xFFFFEC604	Current value											Counter
0xFFFFEC608	Unused					Prescaler		Unused	I	A	E	Control
0xFFFFEC60C	Unused										F	Interrupt status

loop:

```
STR R4, [R0]
```

wait1sec:

```
LDR R3, [R2,#12]
```

```
CMP R3,#1
```

```
BNE wait1sec
```

```
STR R3, [R2,#12]
```

```
EOR R4, R4, #3
```

```
B loop
```


64-bit number comparison

- Write a compare routine to compare two unsigned 64-bit values.
 - a) The numbers are already in general purpose registers, use minimum number of instructions. (Hint: use conditional execution.)

Num1	R3	R1
Num2	R4	R2
	High order	Low order

- b) The numbers are in memory, avoid memory access if not required.

Num1:	High order
	Low order
Num2:	High order
	Low order

64-bit number comparison

- a) The numbers are already in general purpose registers, use minimum number of instructions. (Hint: use conditional execution.)

Num1	R3	R1
Num2	R4	R2
	High order	Low order

Solution

```
ldr r1, =num1
ldr r2, =num2
```

```
ldr r3, [r1]
ldr r4, [r2]
```

```
ldr r1, [r1,#4]
ldr r2, [r2,#4]
```

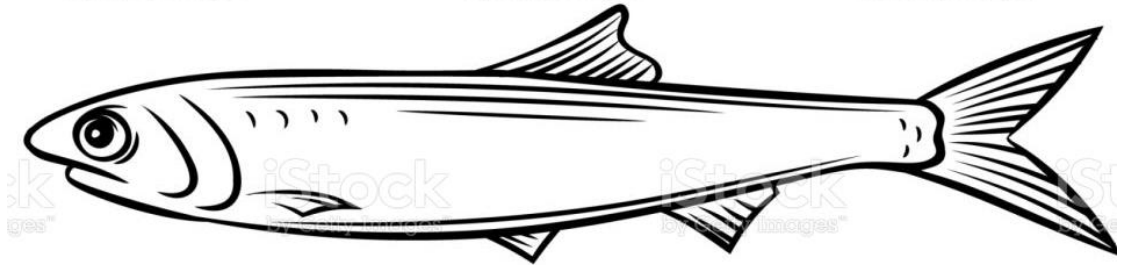
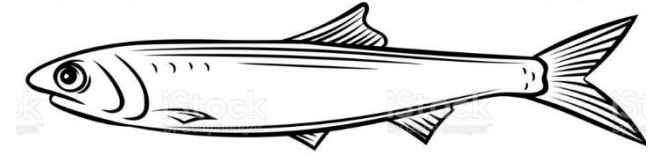
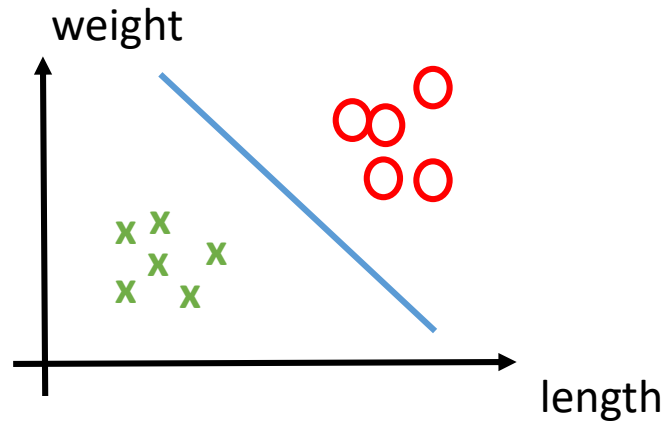
```
cmp r3, r4
cmpeq r1, r2
movlt r0, #2
movge r0, #1
```

```
end: b end
```

```
num1: .word 0x1fffff0f, 0x1fffff0
num2: .word 0x1fffff0f, 0x1fffff8
```

```
ldr r1, =num1
ldr r2, =num2
ldr r3, [r1]
ldr r4, [r2]
cmp r3, r4
ldreq r1, [r1,#4]
ldreq r2, [r2,#4]
cmpeq r1, r2
movlt r0, #2
movge r0, #1
```

Introduction to machine learning



Artificial neuron

- Write a program for **an artificial neuron: $y = f(v)$** .

$$v = x1.w1 + x2.w2, w1 = 192, w2 = -2.$$

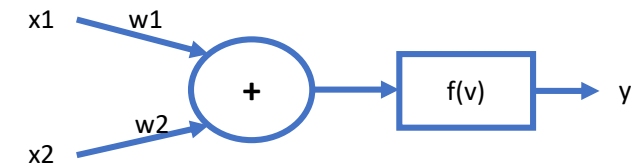
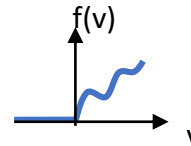
Calculate “v”, but do not use multiplication instructions.

$f(v)$ is a nonlinear function, as in the figure.

$f(v)$ is 0, if v is negative.

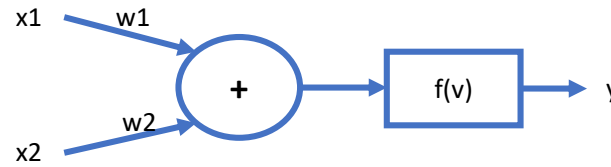
Else, it is a trigonometric function.

Use a “look-up table” to calculate $f(v)$



$x1$ and $x2$ are memory-mapped input, located at Input1 and Input2. Read the input data, when it is ready. Calculate “y” and display the result, if the display device is not busy.

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

$$v = x1.w1 + x2.w2, w1 = 192, w2 = -2.$$

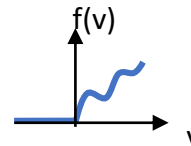
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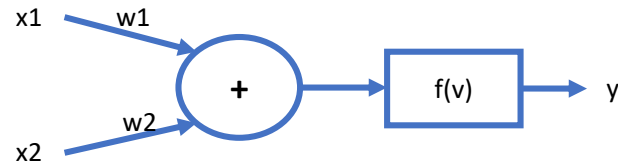
Use a “look-up table” to calculate $f(v)$



$x1$ and $x2$ are memory-mapped input, located at Input1 and Input2. Read the input data, when it is ready. Calculate “y” and display the result, if the display device is not busy.

Input1:		data	I/O device
		status	
		control	
Input2:		data	I/O device
		status	
		control	
Display:		data	I/O device
		status	
		control	
f:	$f(0)$	Look-up table	
	$f(1)$		
	$f(2)$		
	$f(3)$		
	...		

Artificial neuron 1



- Write a program for **an artificial neuron: $y = f(v)$** .

$v = x1.w1 + x2.w2$, $w1 = 192$, $w2 = -2$.

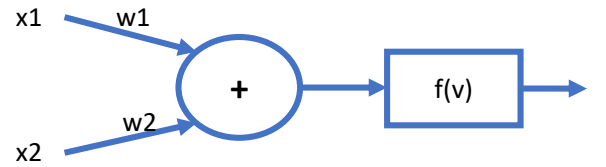
Calculate “v”, but do not use multiplication instructions.

// x1 is in R1 and x2 is in R2

// write the result v in R0

Calcv:

Artificial neuron 1



- Write a program for **an artificial neuron: $y = f(v)$** .

$v = x1.w1 + x2.w2$, $w1 = 192$, $w2 = -2$.

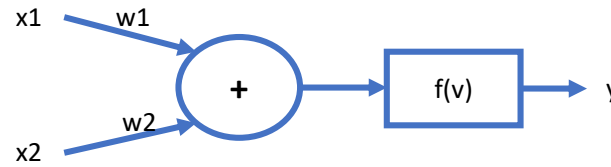
Calculate “v”, but do not use multiplication instructions.

// x1 is in R1 and x2 is in R2

// write the result v in R0

```
Calcv:  MOV R1, R1, LSL #6      // 64.x1
        ADD R1, R1, LSL #1      // 64.x1 + 64.2.x1
        MVN R2, R2, LSL #1      // -2.x2-1
        ADD R2,R2,#1            // -2.x2
        ADD R0,R1,R2            // v
```

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

$f(v)$ is a nonlinear function, as in the figure.

$f(v)$ is 0, if v is negative.

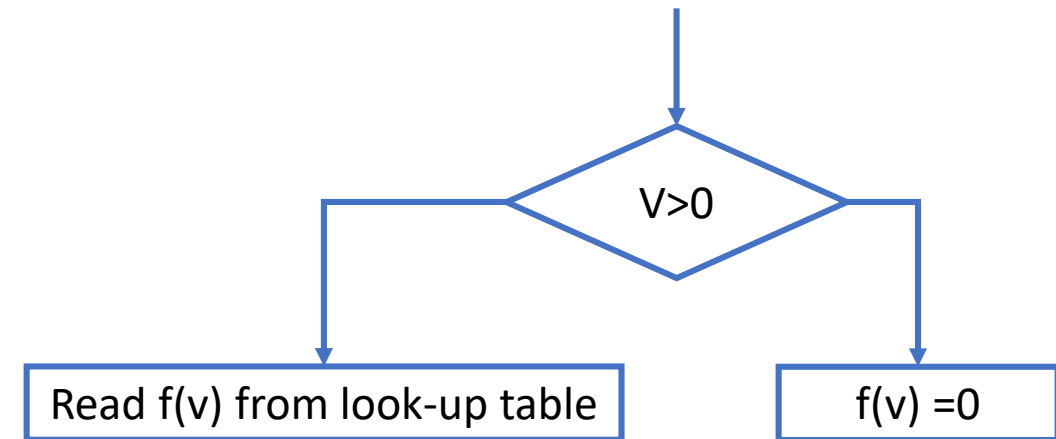
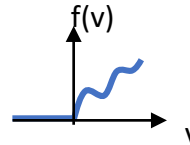
Else, it is a trigonometric function.

Use a “look-up table” to calculate $f(v)$.

// v is in R0. calculate $f(v)$ and return the result in R0

// Look-up table starts at address **f**.

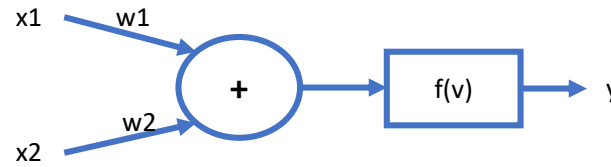
Fofv:



f:	f(0)
	f(1)
	f(2)
	f(3)
	...

Look-up table

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

$f(v)$ is a nonlinear function, as in the figure.

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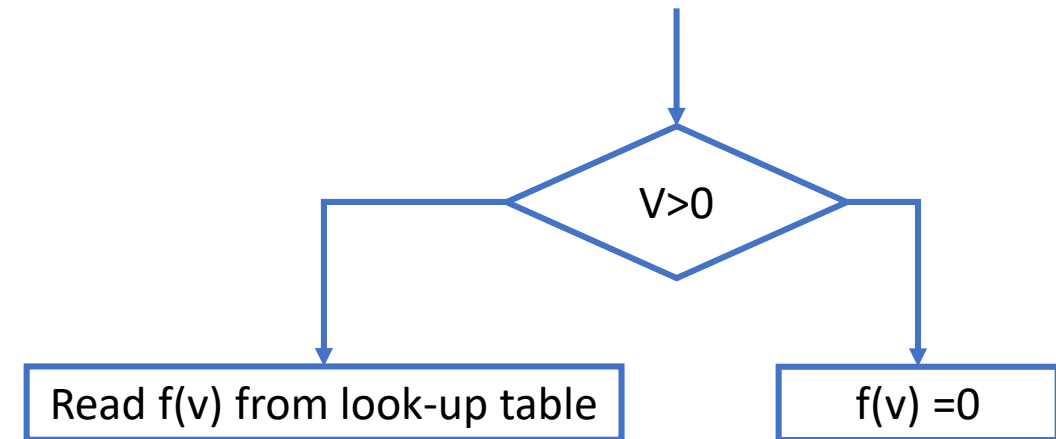
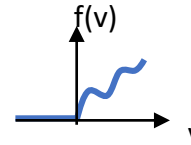
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Use a “look-up table” to calculate $f(v)$.

// v is in R0. calculate $f(v)$ and return the result in R0

// Look-up table starts at address **f**.

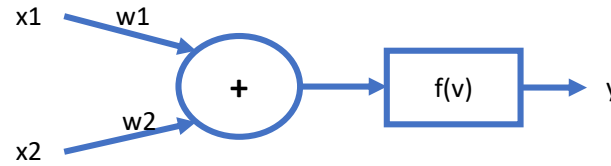
```
Fofv:  LDR R3,=f
      CMP R0, #0
      MOVLE R0, #0
      LDRGT R0, [R3, R0, LSL #2]
```



f:	$f(0)$
	$f(1)$
	$f(2)$
	$f(3)$
	...

Look-up table

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

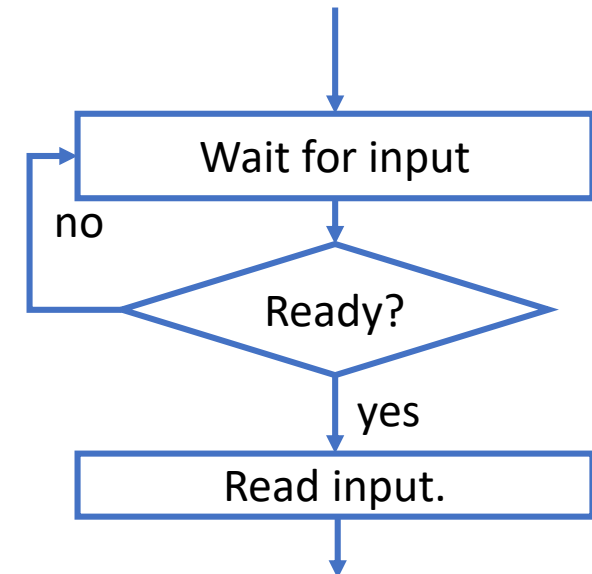
x1 and x2 are memory-mapped input, located at Input1 and Input2. Read the input data, when it is ready.

// Input1 and Input2 base addresses are in R5 and R6, resp.
 // Write one subroutine that reads the I/O, whose base
 // address is given with R0. Subroutine returns the data in R1.

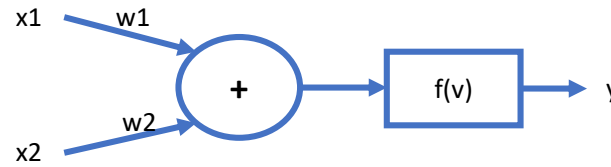
Readinput:

Readloop:

Input1:		data	I/O device
	_ RDY _	status	
		control	
Input2:		data	I/O device
	_ RDY _	status	
		control	



Artificial neuron



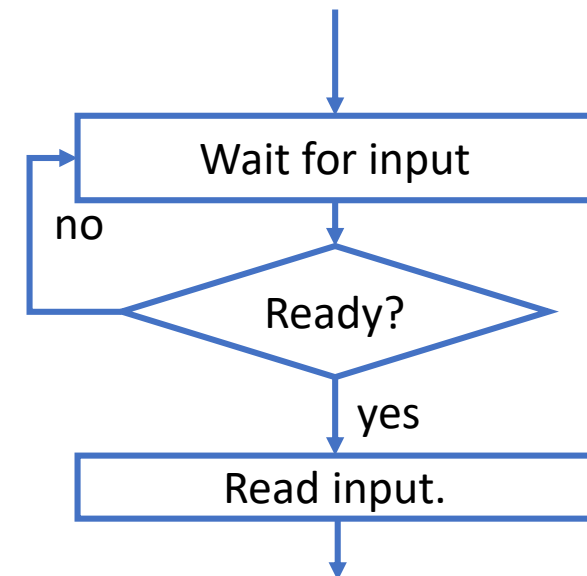
- Write a program for **an artificial neuron: $y = f(v)$** .

x1 and x2 are memory-mapped input, located at Input1 and Input2. Read the input data, when it is ready.

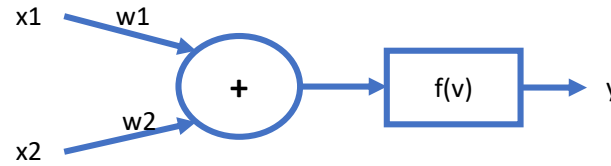
// Input1 and Input2 base addresses are in R5 and R6, resp.
 // Write one subroutine that reads the I/O, whose base
 // address is given with R0. Subroutine returns the data in R1.

```
Readinput:    PUSH {LR} // STMFD SP!, {LR}
Readloop:    LDR R1, [R0,#4] // read status
              AND R1,R1,#2 // mask RDY bit
              CMP R1,#2
              BNE Readloop
              LDR R1,[R0]
              POP {PC} // LDMFD SP!, {PC}
              //return from subroutine
```

Input1:		data	I/O device
	_ RDY _	status	
		control	
Input2:		data	I/O device
	_ RDY _	status	
		control	



Artificial neuron



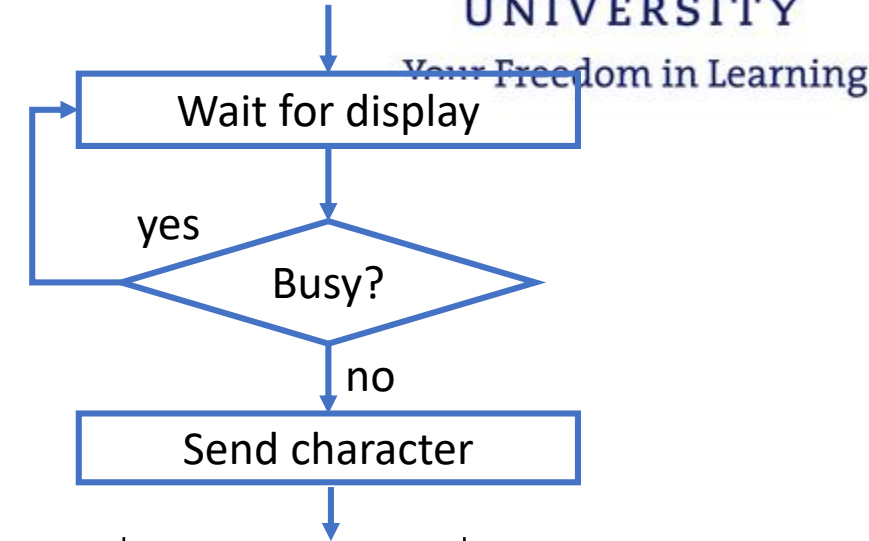
- Write a program for **an artificial neuron: $y = f(v)$** .

Calculate “y” and display the result, if the display device is not busy.

// Display base address is in R7. calculated $f(v)$ is in R0.

// If the BSY bit is 1, display is busy. Send R0 content to display,
//when display is not busy.

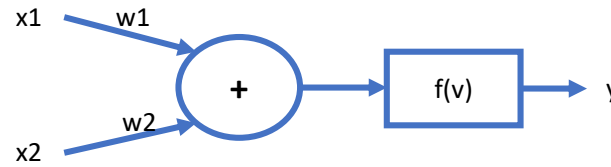
Waitdisplay:



Display:		<i>data</i>
	_ BSY _	<i>status</i>
		<i>control</i>

I/O device

Artificial neuron



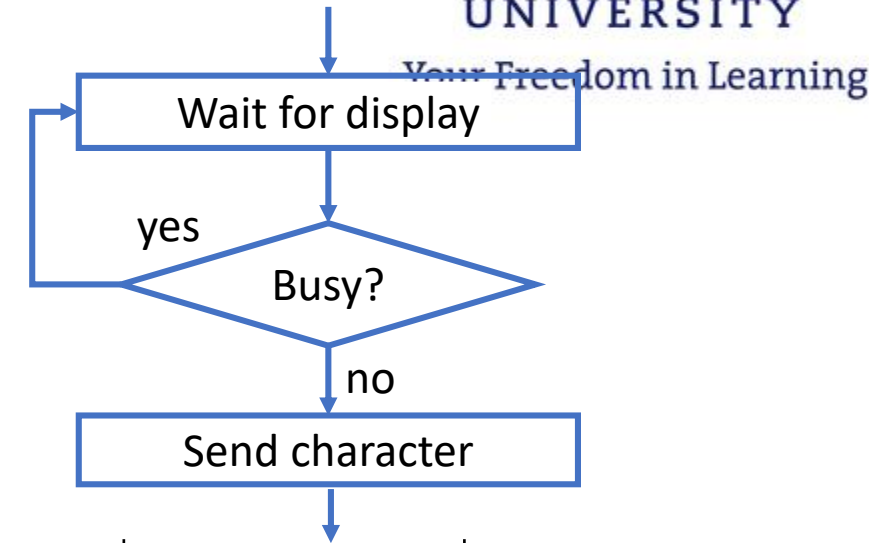
- Write a program for **an artificial neuron: $y = f(v)$** .

Calculate “y” and display the result, if the display device is not busy.

// Display base address is in R7. calculated $f(v)$ is in R0.

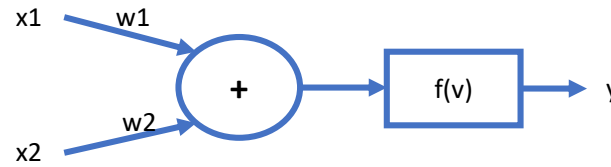
// If the BSY bit is 1, display is busy. Send R0 content to display,
//when display is not busy.

```
Waitdisplay:  LDR R1,[R7,#4]  // read status
               AND R1,R1,#2  // mask BSY bit
               CMP R1,#2
               BEQ Waitdisplay
               STR R0,[R7]
```



			I/O device
Display:		<i>data</i>	
	_ BSY _	<i>status</i>	
		<i>control</i>	

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

Read Input2

*R0 points the base address, Input2 (R6).
Call subroutine Readinput
R1 is x2, move it to R2*

Read Input1

*R0 points the base address, Input1 (R5).
Call subroutine Readinput
R1 is x1.*

Calculate v

*Calculate v: x1 and x2 are in R1 and R2.
V is in R0*

Calculate f(v)

*Calculate f(v)
v is in R0, result will return in R0*

Display f(v)

*Display base address is in R7.
calculated f(v) is in R0.*

```
LDR R5, =Input1
LDR R6, =Input2
LDR R7, =Display
```

```
// Read input2 (x2) and input1 (x1)
```

```
MOV R0, R6
```

```
BL Readinput
```

```
MOV R2, R1
```

```
MOV R0, R5
```

```
BL Readinput
```

Calcv:

```
MOV R1, R1, LSL #6
```

```
// 64.x1
```

```
ADD R1, R1, LSL #1
```

```
// 64.x1 + 64.2.x1
```

```
MVN R2, R2, LSL #1
```

```
// -2.x2-1
```

```
ADD R2, R2, #1
```

```
// -2.x2
```

```
ADD R0, R1, R2
```

```
// v
```

Fofv:

```
LDR R3, =f
```

```
CMP R0, #0
```

```
MOVLE R0, #0
```

```
LDRGT R0, [R3, R0, LSL #2]
```

Waitdisplay:

```
LDR R1, [R7, #4]
```

```
// read status
```

```
AND R1, R1, #2
```

```
// mask BSY bit
```

```
CMP R1, #2
```

```
BEQ Waitdisplay
```

```
STR R0, [R7]
```

END: B END

Readinput: STMFD SP!, {LR}

Readloop: LDR R1, [R0, #4]

```
// read status
```

```
AND R1, R1, #2
```

```
// mask RDY bit
```

```
CMP R1, #2
```

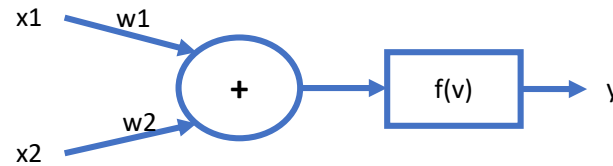
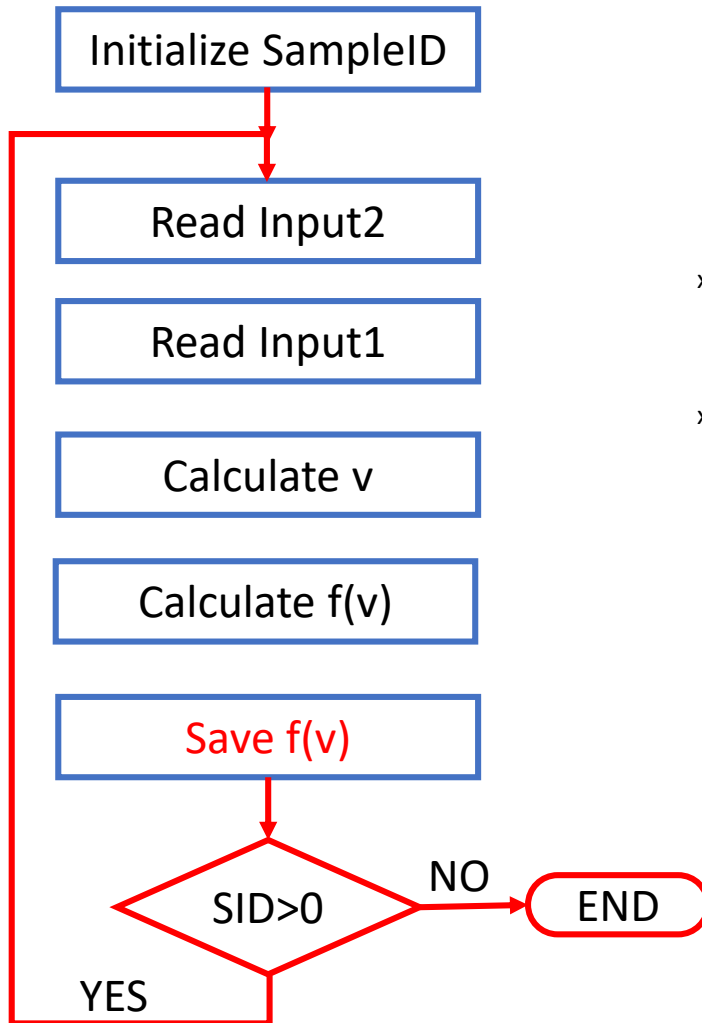
```
BNE Readloop
```

```
LDR R1, [R0]
```

```
LDMFD SP!, {PC}
```

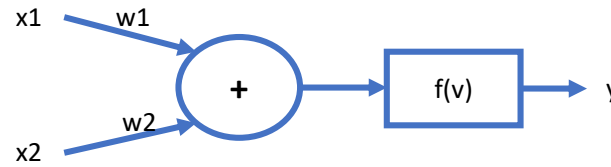
```
//return from subroutine
```

Artificial neuron – for an input set



SampleID	x1	x2	y
10	345	54098	?
9	8912	231	
8	5321	238	
7	7132	144	
6	43209	3	
...	
...	
...	
...	
1	53	234	

Artificial neuron



- Write a program for **an artificial neuron: $y = f(v)$** .

Read Input2

*R0 points the base address, Input2 (R6).
Call subroutine Readinput
R1 is x2, move it to R2*

Read Input1

*R0 points the base address, Input1 (R5).
Call subroutine Readinput
R1 is x1.*

Calculate v

*Calculate v: x1 and x2 are in R1 and R2.
V is in R0*

Calculate f(v)

*Calculate f(v)
v is in R0, result will return in R0*

Save f(v)

Save f(v) in stack

```

LDR R5, =Input1
LDR R6, =Input2
LDR R7, =Display
  
```

```
// Read input2 (x2) and input1 (x1)
```

Loop:

```

MOV R0, R6
BL Readinput
MOV R2, R1
MOV R0, R5
BL Readinput
  
```

Calcv:

```

MOV R1, R1, LSL #6      // 64.x1
ADD R1, R1, LSL #1      // 64.x1 + 64.2.x1
MVN R2, R2, LSL #1      // -2.x2-1
ADD R2, R2, #1          // -2.x2
ADD R0, R1, R2          // v
  
```

Fofv:

```

LDR R3, =f
CMP R0, #0
MOVL R0, #0
LDRGT R0, [R3, R0, LSL #2]
  
```

PUSH R0

// push result into stack

END: B END

Readinput: STMFD SP!, {LR}

Readloop: LDR R1, [R0, #4] *// read status*

AND R1, R1, #2 *// mask RDY bit*

CMP R1, #2

BNE Readloop

LDR R1, [R0]

LDMFD SP!, {PC}

//return from subroutine

C to Assembly – For loop

- translate the following C code to assembly

```
for (i = 0; i < 8; i++) {  
    a[i] = b[7-i];  
}
```

C to Assembly – For loop

- translate the following C code to assembly

```
.global _start
```

```
_start:
```

```
    MOV r0, #7 // i
```

```
    LDR r1, =arrayb // load address of arrayb
```

```
    LDR r2, =arraya // a[i] starts here
```

```
Loop:
```

```
    //RSB r3, r0, #7 // index = 7-i
```

```
    MVN r3, r0 // -i-1
```

```
    ADD r3, r3, #8 // -i-1+8=-i+7
```

```
    LDRB r5, [r1, r3] // load b[7-i]
```

```
    STRB r5, [r2, r0] // store into a[i]
```

```
    SUBS r0, r0, #1 // i— —
```

```
    BGE Loop
```

```
end:    B end
```

```
arrayb: .word 0x0A090807, 0x06050403
```

```
arraya: .byte 0x0, 0x0, 0x0, 0x0, 0x0, 0x0, 0x0, 0x0 // allocate some space
```

```
    .end
```

```
for (i = 0; i < 8; i++) {  
    a[i] = b[7-i];  
}
```