# Seokyoung Kim

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## RESEARCH INTEREST \_\_\_\_\_

- Sensor Fusion for Robot Vision
- Depth Estimation & Completion
- Autonomous Driving

## EDUCATION \_\_\_\_\_

**Chonnam National University** 

Gwangju, Korea

B.S. in IoT Artificial Intelligence Convergence (GPA: 3.98/4.5)

2018 - Present

## ACTIVITIES

### Artificial Intelligence Mobility Lab

Jan. 2022 - Present

• Leading a Al mobility team and won various autonomous driving competitions.

**Academic Service** Nov. 2021 - Feb. 2022

Teacher

• Mentoring program of local high school students - Python lecture

**Project** July - Dec. 2022

Leader

• Development of 'Self-Driving Fire Detection Robot' in Chonnam National University

#### Conference

Poster Session

 Vision based Vehicle and Lane Detection using YOLOv3 and M-LSD AICON 2022, Chonnam National University

Sep. 2022

· Towards precise depth completion guided by dense pointcloud based on LiDAR accumulation KSAE 2023 Annual Spring Conference

May 2023

AWARDS & HONORS	
Silver Prize, IEVE International Electric Vehicle Autonomous Driving Competition (1/10)	Apr. 2022
Grand Prize, Artificial Intelligence System Competition (Chonnam National University)	Nov. 2022
Scholarship for academic excellence	Spring 2021
Scholarship for academic excellence	Fall 2021
Scholarship for academic excellence	Spring 2022
Scholarship for academic excellence	Fall 2022

## Skills \_\_\_\_\_

Languages: Python, C++

Libraries: PyTorch, OpenCV, ROS

## References \_\_\_\_\_

Chansoo Kim (B.S Advisor), Assistant Professor, Department of Intelligent Mobility, Chonnam National University