

# Recent Progress on Euclidean (and Related) Spanners

Hung Le

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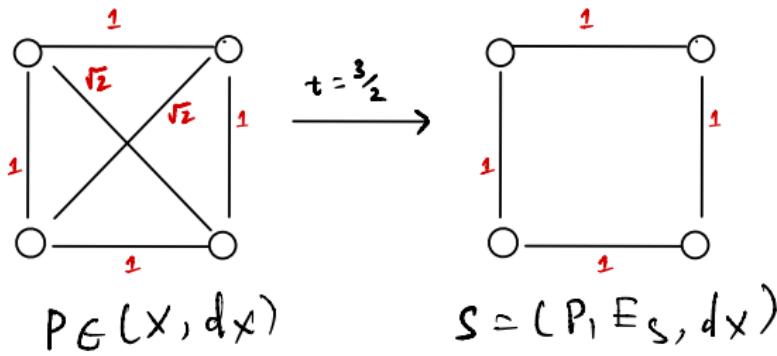
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& Computer Sciences

# Metric $t$ -Spanners

A  $t$ -spanner of a point set  $P$  in a metric space  $(X, d_X)$  is a graph  $S = (P, E_S, d_X)$  such that:

$$d_S(u, v) \leq t \cdot d_X(u, v) \quad \forall u \neq v \in P \quad (1)$$

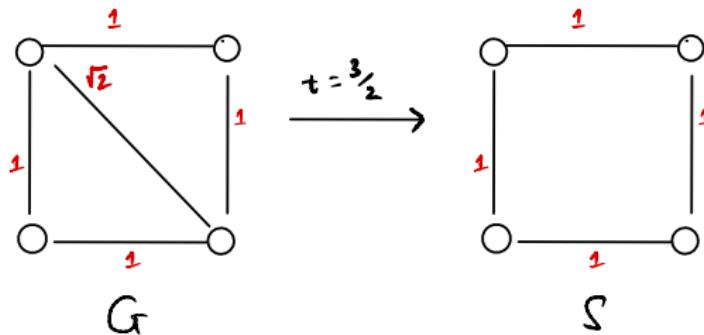


$t$  is called the **stretch** of the spanner.

- ▶ Sparsity:  $\frac{|E_S|}{|E(MST)|} = \frac{|E_S|}{n-1}$ .
- ▶ Lightness  $\frac{\omega(E_S)}{\omega(MST)}$

# Graph $t$ -Spanners

The  $t$ -spanner  $S$  is a **spanning subgraph** of the input graph  $G$ , preserving distances up to a factor of  $t$ .



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## Doubling Metrics

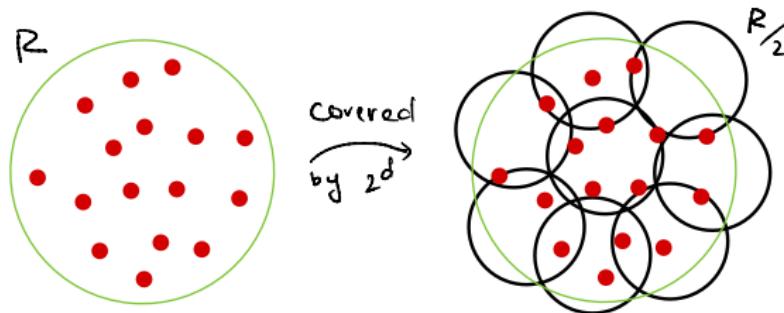
Two metrics: Euclidean  $(\mathbb{R}^d, \|\cdot\|_2)$ , and **doubling metrics** [Assouad;30][Gupta,Krauthgamer,Lee;03].

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## Doubling Metrics

A metric  $(X, d_X)$  has doubling dimension  $d$  if any ball of radius  $R$  can be covered by  $2^d$  balls of radius  $R/2$ ,  $\forall R \geq 0$ .



- ▶  $n$ -point set in  $(\mathbb{R}^d, \|\cdot\|_2)$  has doubling dimension  $d + O(1)$ .
- ▶ Any metric space has doubling dimension  $O(\log n)$ .

## Basic Results: Metric Spanners

[Chew86] constructed  $O(1)$ -spanner with  $O(n)$  edges (or  $O(1)$  sparsity) for  $P \in \mathbb{R}^2$ .

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$(1 + \epsilon)$ -spanner for  $P \in \mathbb{R}^d$  with:

- ▶  $O_d((1/\epsilon)^{d-1})$  sparsity [Yao;82][Clarkson;87][Keil;88]  
[Ruppert,Seidel;91][Althofer,Das, Dobkin, Joseph,Soares;93]  
[Callahan,Kosaraju;93] ...
- ▶  $O_d((1/\epsilon)^d)$  lightness [Das,Heffernan,Narasimhan;93]  
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$(1 + \epsilon)$ -spanner for  $P$  in **doubling metric** of dimension  $d$ :

- ▶  $O_d((1/\epsilon)^d)$  sparsity [Gao, Guibas,Nguyen;04][Har-Peled,Mendel;04][Smid,09][Chan,Gupta,Maggs,Zhou;16]
- ▶  $O_d((1/\epsilon)^{d+1})$  lightness [Gottlieb;15][Filtser,Solomon;16]  
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## Basic Results: Metric Spanners (cont.)

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- ▶  $O_d((1/\epsilon)^d)$  sparsity
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Observations:

1. Can get stretch  $1 + \epsilon$  in metric setting.
2. Sparsity and lightness are off by a factor of  $1/\epsilon$ .
3. Doubling is off by a factor of  $1/\epsilon$  compared to Euclidean, due to Euclidean geometry.

## Basic Results: Graph Spanners

$(2k - 1)$ -spanner with sparsity  $O(n^{1/k})$  for any  $k \geq 1$ .

[Peleg, Schäffer;89] [Althöfer, Das, Dobkin, Joseph, Soares;93]  
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$(2k - 1)(1 + \epsilon)$ -spanner with **lightness**  $O(n^{1/k}/\epsilon)$ .

[Althöfer, Das, Dobkin, Joseph, Soares;93]  
[Chandra, Das, Narasimhan, Soares;92]  
[Elkin, Neiman, Solomon;14][Chechik, Wulff-Nilsen;16]  
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- ▶ The dependency on  $\epsilon$  seems necessary, at least for  
 $\epsilon = kn^{-1/(2k-2)}$  [Bodwin, Flics; 24].

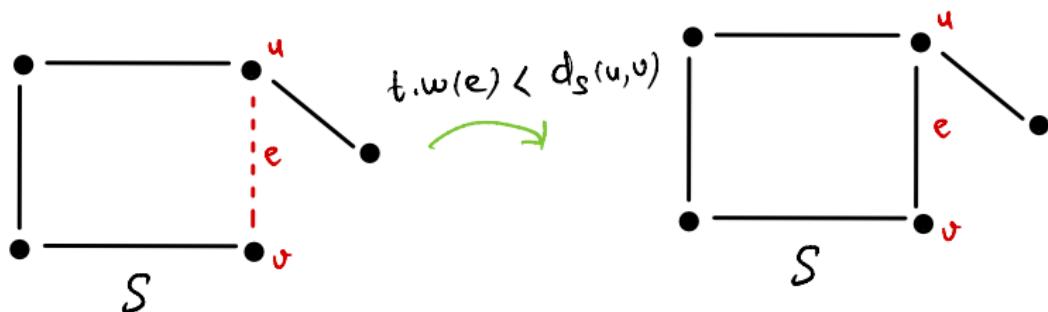
### Erdős' Girth Conjecture

$G = (V, E)$  with  $|E| = \Omega(n^{1+1/k})$  and girth  $\geq 2k + 1$  exists.

# One Algorithm Fits All

GREEDY( $G(V, E, w), t$ )

1. sort edges in  $E$  in the **increasing weight order**
2.  $S \leftarrow (V, \emptyset, w)$
3. **for each** edge  $e = (u, v)$  in the sorted order
4.     **if**  $d_S(u, v) > t \cdot w(e)$
5.          $E_S \leftarrow E_S \cup \{e\}$
6. **return**  $S$



- ▶ Achieve all aforementioned bounds in all settings.
- ▶ Existentially optimal [Filtser, Solomon;16].

# Outline

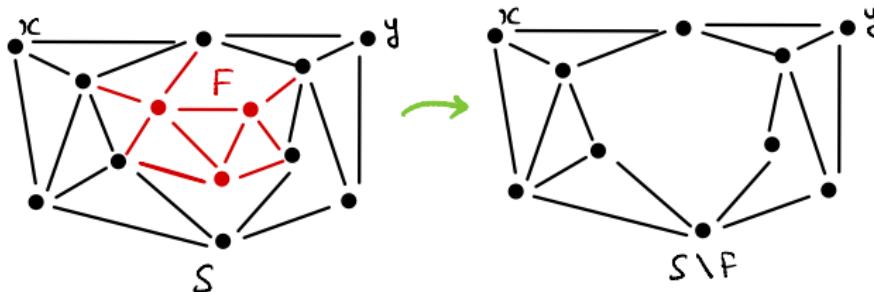
1. ~~Introduction.~~
2. ~~Basic Results.~~
3. Fault Tolerance.
4. Approximation/Instance Optimality.
5. Structural Alternatives.

# Fault-Tolerant Spanners

[Levcopoulos, Narasimhan, Smid; 98]: removing at most  $f$  points still leaves a  $t$ -spanner.

## Metric Fault Tolerance

A  $t$ -spanner  $S$  is  **$f$ -fault-vertex-tolerant** if for any set  $F \subseteq P$  of at most  $f$  points,  $S \setminus F$  is a  $t$ -spanner of  $P \setminus F$ .



## Graph Fault Tolerance

For graph  $G = (V, E, \omega)$ ,  $S$  is  **$f$ -fault-vertex-tolerant** if  $S \setminus F$  is a  $t$ -spanner of  $G \setminus F$  for any set  $F$  of at most  $f$  vertices.

## Fault-Tolerant Metric Spanners

Lower bounds for any **constant**  $\epsilon, d$ :

- ▶  $\Omega(f)$  for sparsity: every vertex must have degree at least  $f$ .
- ▶  $\Omega(f^2)$  for lightness [Czumaj,Zhao;03].

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Tolerating  $f$  vertex (edge) faults in  $\mathbb{R}^d$ :

- ▶  $O_{\epsilon,d}(f)$  sparsity. [Levcopoulos,Narasimhan,Smid;98]  
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These results are extensible to doubling metrics. [Chan,Li,Ning;12]  
[Chan,Li,Ning,Solomon;13][Solomon;14][L,Solomon,Than;23]

# Fault-Tolerant Graph Spanners

Recall: Erdős' Girth Conjecture (EGC) implies  $\Omega(n^{1/k})$  sparsity lower bound for  $(2k - 1)$ -spanners.

- ▶  $\Omega(f^{1-1/k}n^{1/k})$  sparsity/lightness lower bound for  $f$  vertex faults, assuming EGC. [Bodwin, Dinitz, Parter, Vassilevska Williams; 18]

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- ▶ Sparsity  $O(f^{1-1/k}n^{1/k})$ . [Chechik,Langberg,Peleg,Roditty;10] Dinitz,Krauthgamer;11][Bodwin,Dinitz,Parter,Vassilevska Williams;18] [Bodwin,Patel;19][Dinitz,Robelle;20] [Bodwin,Dinitz,Robelle;21][Parter;22]

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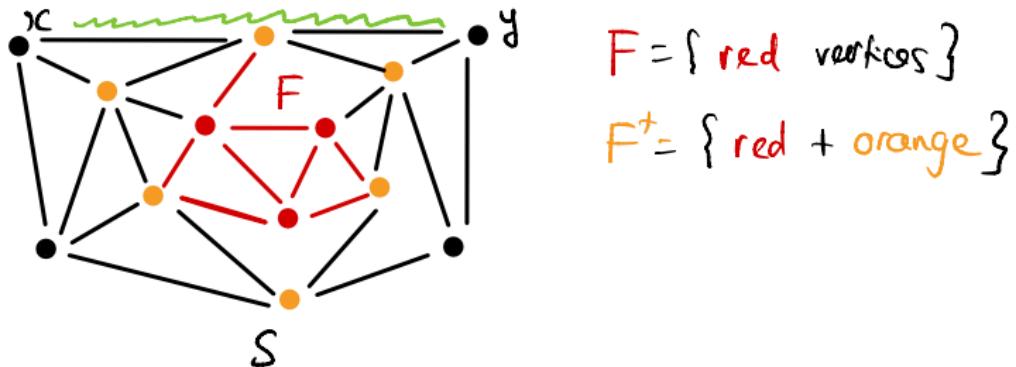
Open problem: Light fault-tolerant graph spanners?

Massive failure:  $f = \Omega(n)$

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Define a reasonable model for massive failure is tricky.

- ▶  $\nu$ -reliable: faulty set  $F$ , there exists  $F \subseteq F^+$  such that  $|F^+| \leq (1 + \nu)|F|$  and distances are preserved for points in  $P \setminus F^+$  in  $S \setminus F$ . [Bose, Dujmovic, Morin, Smid; 13] [Buchin, Har-Peled, Oláh; 20]



Remark: this model does not work for graphs: (reliably) preserving connectivity needs  $\Omega(n^2)$  edges. [Filtser, L; 22]

## Massive failure: $f = \Omega(n)$

Lower bounds:

- ▶ Any reliable  $O(1)$ -spanner in  $\mathbb{R}^d$  must have sparsity  $\Omega(\log n)$ .  
[Bose,Dujmovic,Morin,Smid;13].
- ▶ (Oblivious) lightness lower bound  $\Omega(\log n)$  for any finite stretch. [Filtser,Gitlitz,Neiman;23]

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Upper bounds:

- ▶  $\nu$ -reliable  $(1 + \epsilon)$ -spanner with  $O_{\nu,d,\epsilon}(\log n)$  edges in  $\mathbb{R}^d$  and doubling dim.  $d$ .  
[Buchin,Har-Peled,Oláh;19][Filtser,L;22].
- ▶ (Oblivious) lightness  $O_{\epsilon,d,\nu}(\log n)$ .  
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## Massive failure: $f = \Omega(n)$

Edge counter part of  $\nu$ -reliable:  **$\psi$ -dependable** where **every edge** of the spanner may fail independently with probability  $1 - \psi$ .  
[Har-Peled,Lusardi;24]

- ▶ Sparsity  $O_{\epsilon,d}(\log n(1/\psi)^{4/3})$  in  $\mathbb{R}^d$ , and lower bound  $O_{\epsilon,d}(\log n/\psi))$ . [Har-Peled,Lusardi;24]

## Massive failure: $f = \Omega(n)$

Color fault-tolerant spanners: vertices (or edges) are partitioned into color classes, and at most  $f$  color classes might fail.

[Petruschka, Sapir, Tzalik;23]

- ▶ Sparsity  $O(f n^{1/k})$  for edge-colored and  $O(f^{1-1/k} n^{1/k})$  for vertex-colored. [Petruschka, Sapir, Tzalik;23]

## Massive failure: $f = \Omega(n)$

Bounded degree fault: at most  $f$  faulty edges incident to a vertex.  
[Bodwin,Haeupler,Parter;24]

- ▶ Sparsity  $O_k(f^{1-1/k}n^{1/k})$  for graph  $(2k - 1)$ -spanners.  
[Bodwin,Haeupler,Parter;24]
- ▶ For points in  $\mathbb{R}^d$ , bounded degree fault  $f$  with  $O_{\epsilon,d}(f)$  sparsity.  
[Biniaz,Carufel,Maheshwari,Smid;24]
- ▶ For points in doubling dimension  $d$ ,  $O_{\epsilon,d}(f^2)$  sparsity.  
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Open problems:

1. Closing the gap between  $\mathbb{R}^d$  and doubling dimension  $d$ .
2. Light versions of color or bounded-degree faults.
3. Other models of massive failure

# Outline

1. ~~Introduction.~~
2. ~~Basic Results.~~
3. ~~Fault Tolerance.~~
4. Approximation/Instance Optimality.
5. Structural Alternatives.

## Approximation/Instance Optimality.

Find a (close to) optimal  $t$ -spanner for a given input graph  $G$  or point set  $P$ . (Optimal per instance.)

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- ▶  $O(\log n)$ -approximation for 2-spanners. [Kortsarz, Peleg; 94]
- ▶  $\tilde{O}(n^{1/4})$ -approximation for 3-spanners and 4-spanners.  
[Berman, Raskhodnikova, Ruan; 10] [Dinitz, Krauthgamer; 11]  
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Open problem:

- ▶  $O(n^\epsilon)$ -approximation for  $t$ -spanners for a constant  $t$ ?

## Metric Spanners

- ▶ There have been a few NP-hardness results.  
[Klein,Kutz;06][Giannopoulos, Klein,Knauer,Kutz,Marx;10]  
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Open problems:

1.  $(1 + \epsilon)$ -spanner with  $O(1)|OPT|$ ?
2.  $t$ -spanner with  $O(\log n)|OPT|$  for **high dimensional**  $\mathbb{R}^d$  for any constant  $t$ ?
3. Doubling metrics?

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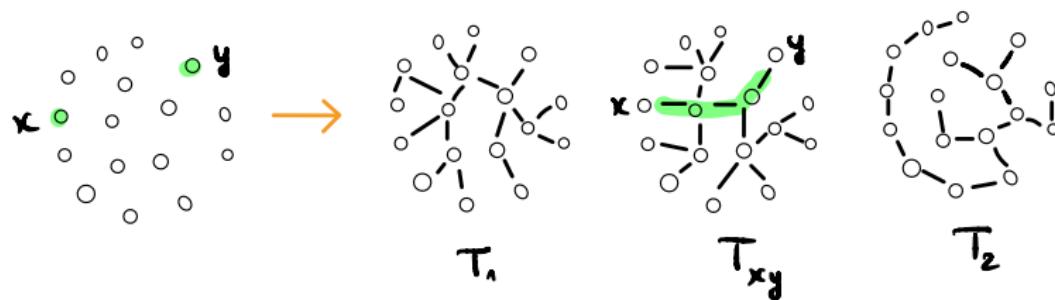
## Tree Covers

[Awerbuch, Peleg;92][Arya, Das, Mount, Salowe, Smid;95]

A  $t$ -tree cover  $\mathcal{T}$  for a point set  $P$  is **collection of trees** such that  
 $\forall x, y \in P$ , there exists  $T_{xy} \in \mathcal{T}$  where:

$$d_{T_{xy}}(x, y) \leq d_X(x, y) \leq t \cdot d_{T_{xy}}(x, y) \quad (2)$$

Want to construct a tree cover with a few trees.



The union  $S = \bigcup_{T \in \mathcal{T}} T$  is a  $t$ -spanner of  $P$ .

- More:  $\mathcal{T}$  allows approximate distances to be queried quickly: just query distances on each tree.

## Metric Tree Covers

- ▶ In  $\mathbb{R}^d$ ,  $(1 + \epsilon)$ -tree cover with  $O_d((1/\epsilon)^{d-1})$  trees.  
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Open problem: Do **light tree covers** exist? (Every tree in the tree cover has total edge weight  $O_{\epsilon,d}(1)\omega(MST)$ .)

- ▶ [Filtser, Gitlitz, Neiman;23] showed that each tree could be  $O_{\epsilon,d}(\log(n))\omega(MST)$ .

## Tree cover for general graphs

A stretch  $2k - 1$  tree cover with  $n^{1/k} \log^{1-1/k}(n)$  trees.

[Awerbuch,Peleg,92][Awerbuch,Kutten,Peleg,94][Thorup-Zwick-05]

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[Awerbuch,Peleg,92][Awerbuch,Kutten,Peleg,94][Thorup-Zwick-05]

[Bartal,Fandina,Neiman,19] asked: what stretch can we get with only 2 trees, 3 trees and so on.

- ▶ They showed 2 trees  $\tilde{O}(\sqrt{n})$  stretch,  $k$  trees  $\tilde{O}(n^{1/k})$  stretch.

No lower bounds known.

## Tree cover for general graphs

A stretch  $2k - 1$  tree cover with  $n^{1/k} \log^{1-1/k}(n)$  trees.

[Awerbuch,Peleg,92][Awerbuch,Kutten,Peleg,94][Thorup-Zwick-05]

[Bartal,Fandina,Neiman,19] asked: what stretch can we get with only 2 trees, 3 trees and so on.

- ▶ They showed 2 trees  $\tilde{O}(\sqrt{n})$  stretch,  $k$  trees  $\tilde{O}(n^{1/k})$  stretch.

No lower bounds known.

Open problem: what is the smallest stretch achieved with 2 trees?

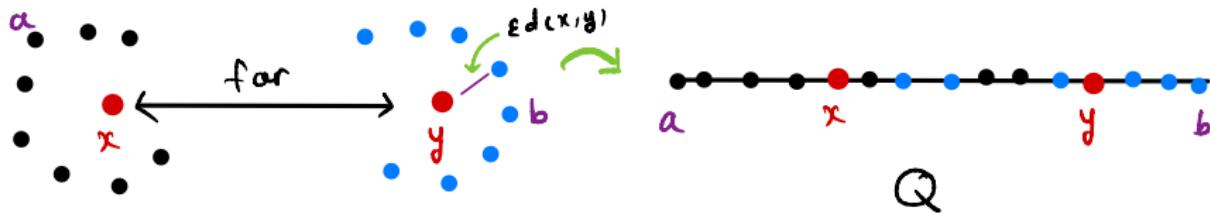
## A Path Cover?

A  $t$ -tree cover  $\mathcal{T}$  where every tree in  $\mathcal{T}$  is a path?

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- ▶ Impossible.



[Chan, Har-Peled, Jones; 19]

## Locality Sensitive Ordering (LSO)

A set of paths  $\mathcal{P}$  such that for every  $x \neq y$ , there is a path  $Q \in \mathcal{P}$  such that  $Q[x, y] \subseteq B(x, \epsilon d_X(x, y)) \cup B(y, \epsilon d_X(x, y))$

## LSO

Any  $P \in \mathbb{R}^d$  or doubling metric of dim.  $d$  has an LSO with  $O_{\epsilon,d}(1)$  paths, a.k.a., orderings. [Chan,Har-Peled,Jones;19][Filtser,L;22]

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Many other applications, for example: Given  $x \in P$ , find a  $(1 + \epsilon)$ -approximate nearest neighbor of  $P$ :

- ▶ Return the closest point to  $x$  among all neighbors of  $x$  in paths in  $\mathcal{P}$  (two neighbors per path  $Q \in \mathcal{P}$ )
- ▶ The total running time  $O(|\mathcal{P}|) = O_{\epsilon,d}(1)$ .

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Open problem: Other structural alternatives to spanners?

## Other Things Not Mentioned Here

- ▶ Spanners in high dimensional spaces.
- ▶ Spanners in different models of computations.
- ▶ Ramsey tree covers.
- ▶ Etc.

Thanks!