

# Numerical Optimization with applications: Homework 06

104021601 林俊傑

104021602 吳彥儒

104021615 黃翊軒

December 7, 2016

**Exercise 1.** *The following example from [268] with a single variable  $x \in \mathbb{R}$  and a single equality constraint shows that strict local solutions are not necessarily isolated. Consider*

$$\min_x x^2 \quad \text{subject to } c(x) = 0, \text{ where } c(x) = \begin{cases} x^6 \sin(1/x) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases} \quad (12.96)$$

- (a) *Show that the constraint function is twice continuously differentiable at all  $x$  (including at  $x = 0$ ) and that the feasible points are  $x = 0$  and  $x = 1/(k\pi)$  for all nonzero integers  $k$ .*
- (b) *Verify that each feasible point except  $x = 0$  is an isolated local solution by showing that there is a neighborhood  $\mathcal{N}$  around each such point within which it is the only feasible point.*

*Proof.* (a) We first show directly that constraint function is twice continuously differentiable at all  $x$ .

If  $x \neq 0$ , then

$$\begin{aligned} c(x) &= x^6 \sin(1/x) \\ c'(x) &= 6x^5 \sin(1/x) - x^4 \cos(1/x) \\ c''(x) &= (30x^4 - x^2) \sin(1/x) - 10x^3 \cos(1/x) \end{aligned}$$

If  $x = 0$ , then by definition we obtain

$$\begin{aligned} c'(0) &= \lim_{h \rightarrow \infty} \frac{h^6 \sin(1/h) - 0}{h} = 0 \\ c''(0) &= \lim_{h \rightarrow \infty} \frac{[6h^5 \sin(1/h) - h^4 \cos(1/h)] - 0}{h} = 0 \end{aligned}$$

Hence, the constraint function is twice continuously differentiable at all  $x$ .

Second, we show that the feasible points are  $x = 0$  and  $x = 1/(k\pi)$  for all nonzero integers  $k$ .

If  $x = 0$ , then  $c(x) = 0$  by definition. If  $x = 1/(k\pi)$ , then  $\sin(1/x) = 0$  and thus we have  $c(x) = 0$ .

- (b) If  $x = 1/(k\pi)$  for some fixed nonzero integers  $k$  and we choose  $r = \left| \frac{1}{k\pi} - \frac{1}{(k+1)\pi} \right|$ , then the open interval  $\mathcal{N} = (x - r, x + r)$  contains only a feasible point, which is  $x$  itself.

On the other hand, if  $x = 0$ , then for all  $r > 0$  there exists nonzero positive integers  $k$  such that  $x_k = 1/(k\pi) < r$ . However,  $x_k$  are feasible points in the neighborhood  $(-r, r)$ .

Therefore, combining discussion above, we have that each feasible point except  $x = 0$  is an isolated local solution by showing that there is a neighborhood  $\mathcal{N}$  around each such point within which it is the only feasible point.

□

**Exercise 15.** Consider the following modification of (12.36), where  $t$  is a parameter to be fixed prior to solving the problem:

$$\min_x (x_1 - \frac{3}{2})^2 + (x_2 - t)^4 \quad s.t. \quad \begin{bmatrix} 1 - x_1 - x_2 \\ 1 - x_1 + x_2 \\ 1 + x_1 - x_2 \\ 1 + x_1 + x_2 \end{bmatrix} \geq 0$$

(a) For what value of  $t$  does the point  $x^* = (1, 0)^T$  satisfy the KKT conditions?

(b) Show that when  $t = 1$ , only the first constraint is active at the solution, and find the solution.

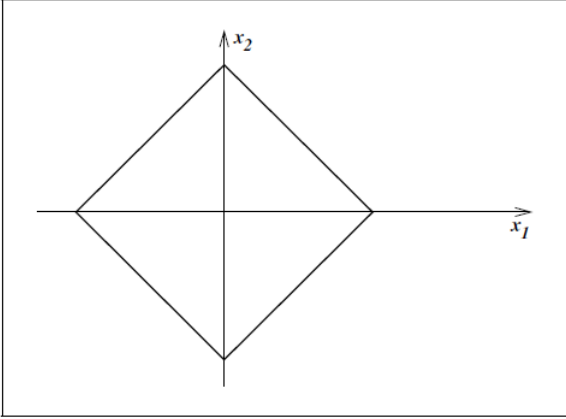
*Proof.* (a) First, we check the complementary condition of KKT, i.e.  $\lambda_i c_i(x^*) = 0$  for  $i = 1, 2, 3, 4$ .

$$\begin{cases} \lambda_1(1 - 1 - 0) = 0 \\ \lambda_2(1 - 1 + 0) = 0 \\ \lambda_3(1 + 1 - 0) = 0 \\ \lambda_4(1 + 1 + 0) = 0 \end{cases} \Rightarrow \begin{cases} \lambda_3 = 0 \\ \lambda_4 = 0 \end{cases} \quad (1)$$

Obviously,  $c(x^*) \geq 0$  holds. Consider

$$\begin{aligned} \nabla_x L(x^*, \lambda) &= \nabla_x L((0, 1)^T, \lambda) \\ &= \begin{bmatrix} -1 + \lambda_1 + \lambda_2 \\ -4t^3 + \lambda_1 - \lambda_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

Since  $\lambda_1, \lambda_2 \geq 0$  and  $\lambda_1 + \lambda_2 = 1$ , we have  $\lambda_1 - \lambda_2 \in [-1, 1]$ . Hence,  $4t^3 \in [-1, 1]$ , then  $t \in [-\sqrt[3]{4}, \sqrt[3]{4}]$ .



(b) We know the feasible set  $E = \{x \in \mathbb{R}^2 \mid \|x\|_1 = 1\}$ . Compute the gradient of  $f(x)$

$$\nabla f(x) = \begin{bmatrix} 2(x_1 - \frac{3}{2}) \\ 4(x_2 - 1)^3 \end{bmatrix} \leq 0 \quad \forall x \in E$$

From above,  $\forall x, y \in E$ , if  $x_1 \leq y_1$  and  $x_2 \leq y_2$  then  $f(y) \leq f(x)$ . Therefore, we only have to consider the case that the first constraint is active:  $1 - x_1 - x_2 = 0$ . Substituting  $x_2 = 1 - x_1$  into  $f(x)$  and find the minimum of  $f$ :

$$\begin{aligned} f(x) &= (x_1 - \frac{3}{2})^2 + (-x_1)^4 \\ f'(x) &= 2(x_1 - \frac{3}{2}) + 4x_1^3 \\ &= 4x_1^3 + 2x_1 - 3 \end{aligned}$$

$f'(x^*) = 0$  if  $x_1^* = \frac{\sqrt[3]{27+\sqrt{753}}}{2 \times 3^{2/3}} - \frac{1}{\sqrt[3]{3(27+\sqrt{753})}}$ . Consequently, the minimizer of  $f$  is  $(x_1^*, 1 - x_1^*)$ .

□

**Exercise 19.** Consider the problem

$$\min_{x \in \mathbb{R}^2} -2x_1 + x_2 \quad \text{subject to} \quad \begin{cases} (1 - x_1)^3 - x_2, & \geq 0 \\ x_2 + 0.25x_1^2 - 1, & \geq 0 \end{cases}$$

The optimal solution is  $x^* = (0, 1)^T$ , where both constraints are active.

(a) Do the LICQ hold at this point?

(b) Are the KKT conditions satisfied?

(c) Write down the set  $\mathcal{F}(x^*)$  and  $\mathcal{C}(x^*, \lambda^*)$ .

(d) Are the second-order necessary conditions satisfied? Are the second-order sufficient conditions satisfied?

*Proof.* (a)

$$A(x^*) = [\nabla C_i(x^*)]_{i \in \mathcal{A}(x^*)} = \begin{bmatrix} -3(1 - x_1)^2 & 0.5x_1 \\ -1 & 1 \end{bmatrix}_{x=x^*} = \begin{bmatrix} -3 & 0 \\ -1 & 1 \end{bmatrix}$$

$A(x^*)$  is nonsingular. Therefore, the LICQ holds.

(b)

$$\nabla f(x^*) = \begin{bmatrix} -2 \\ 1 \end{bmatrix}, \quad \nabla c_1(x^*) = \begin{bmatrix} -3 \\ -1 \end{bmatrix}, \quad \nabla c_2(x^*) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Therefore, the KKT conditions (12.34a)-(12.34e) are satisfied when we set

$$\lambda^* = \left( \frac{2}{3}, \frac{5}{3} \right)^T$$

(c)

$$\mathcal{F}(x^*) = \{d \mid \nabla c_i(x^*)^T d \geq 0\} = \{(d_1, d_2)^T \mid \begin{bmatrix} -3 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \end{bmatrix} \geq 0\} = \{(d_1, d_2)^T \mid d_2 \geq 0, 3d_1 + d_2 \leq 0\}$$

$$\begin{aligned} \mathcal{C}(x^*, \lambda^*) &= \{w \in \mathcal{F}(x^*) \mid \nabla c_i(x^*)^T w = 0 \ \forall i \in \mathcal{A}(x^*) \cap I \text{ with } \lambda_i^* > 0\} \\ &= \{w \in \mathcal{F}(x^*) \mid \nabla c_i(x^*)^T w = 0 \text{ for } i = 1, 2\} \\ &= \{(w_1, w_2)^T \in \mathcal{F}(x^*) \mid \begin{bmatrix} -3 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = 0\} \\ &= \{(0, 0)^T\} \end{aligned}$$

(d)

$$\forall w \in \mathcal{C}(x^*, \lambda^*) = \{(0, 0)^T\} \quad w^T \nabla_{xx} \mathcal{L}(x^*, \lambda^*) w = 0 \quad (2)$$

Since at  $x^*$  LICQ holds and  $(x^*, \lambda^*)$  satisfies KKT. By (2), the second-order necessary conditions is satisfied.

Since  $x^*$  is a feasible solution and  $(x^*, \lambda^*)$  satisfies KKT. By (2), the second-order sufficient conditions is satisfied.

□