## Numerical Optimization with applications: Homework 02

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**Exercise 5.** Prove that  $||Bx|| \ge \frac{||x||}{||B^{-1}||}$  for any nonsingular matrix B. Use this fact to establish (3.19).

*Proof.* For simplicity, we drop the iteration index k in the proof.

Note that from (3.2) we use the fact  $P = -B^{-1}\nabla f$ . Thus by multiplying both sides by B and taking transport, we have  $BP = -\nabla f$  and  $P^TB^T = -\nabla f^T$ . We are now prepared to estimate  $\cos \theta$ :

$$\cos \theta = \frac{-\nabla f^T P}{\|\nabla f\| \|P\|}$$

$$= \frac{\left(P^T B^T\right) P}{\|\nabla f\| \|B^{-1} B P\|}$$

$$= \frac{P^T B P}{\|BP\| \|B^{-1} B P\|}$$

$$\geq \frac{P^T B P}{\|B\| \|P\| \|B^{-1}\| \|BP\|}$$

$$= \left(\frac{P^T B P}{\|P\| \|BP\|}\right) \frac{1}{\|B\| \|B^{-1}\|}$$

$$\geq \frac{1}{\|B\| \|B^{-1}\|}$$

$$\geq \frac{1}{M},$$

where the last two inequality hold by the assumption that B is positive definite and has a uniformly bounded condition number. Therefore, (3.19) follows.

Exercise 7. Prove the result (3.28) by working through the following steps. First, use (3.26) to show that

$$||x_k - x^*||_Q^2 - ||x_{k+1} - x^*||_Q^2 = 2\alpha_k \nabla f_k^T Q(x_k - x^*) - \alpha_k^2 \nabla f_k^T Q \nabla f_k$$

where  $\|\cdot\|_Q$  is defined by (3.27). Second, use the fact that  $\nabla f_k = Q(x_k - x^*)$  to obtain

$$||x_k - x^*||_Q^2 - ||x_{k+1} - x^*||_Q^2 = \frac{2(\nabla f_k^T \nabla f_k)^2}{(\nabla f_k^T Q \nabla f_k)} - \frac{(\nabla f_k^T \nabla f_k)^2}{(\nabla f_k^T Q \nabla f_k)}$$

and

$$||x_k - x^*||_Q^2 = \nabla f_k^T Q^{-1} \nabla f_k.$$

Proof. (1)

$$||x_{k} - x^{*}||_{Q}^{2} - ||x_{k+1} - x^{*}||_{Q}^{2}$$

$$= 2f(x_{k}) - 2f(x_{k+1})$$

$$= x_{k}^{T}Qx_{k} - 2b^{T}x_{k} - (x_{k} - \alpha_{k}\nabla f_{k})^{T}Q(x_{k} - \alpha_{k}\nabla f_{k}) + 2b^{T}(x_{k} - \alpha_{k}\nabla f_{k})$$

$$= x_{k}^{T}Q(\alpha_{k}\nabla f_{k}) + (\alpha_{k}\nabla f_{k})^{T}Qx_{k} - \alpha_{k}^{2}\nabla f_{k}^{T}Q\nabla f_{k} - 2\alpha_{k}b^{T}\nabla f_{k}$$

$$= 2\alpha_{k}\nabla f_{k}^{T}Qx_{k} - \alpha_{k}^{2}\nabla f_{k}^{T}Q\nabla f_{k} - 2\alpha_{k}(Qx^{*})^{T}\nabla f_{k}$$

$$= 2\alpha_{k}\nabla f_{k}^{T}Q(x_{k} - x^{*}) - \alpha_{k}^{2}\nabla f_{k}^{T}Q\nabla f_{k}$$

(2) Combining the result of (1) and the fact that  $\nabla f_k = Q(x_k - x^*)$ , we have

$$||x_{k} - x^{*}||_{Q}^{2} - ||x_{k+1} - x^{*}||_{Q}^{2}$$

$$= 2\alpha_{k}\nabla f_{k}^{T}\nabla f_{k} - \alpha_{k}^{2}\nabla f_{k}^{T}Q\nabla f_{k}$$

$$= 2(\frac{\nabla f_{k}^{T}\nabla f_{k}}{\nabla f_{k}^{T}Q\nabla f_{k}})\nabla f_{k}^{T}\nabla f_{k} - (\frac{\nabla f_{k}^{T}\nabla f_{k}}{\nabla f_{k}^{T}Q\nabla f_{k}})^{2}\nabla f_{k}^{T}Q\nabla f_{k}$$

$$= \frac{2(\nabla f_{k}^{T}\nabla f_{k})^{2}}{(\nabla f_{k}^{T}Q\nabla f_{k})} - \frac{(\nabla f_{k}^{T}\nabla f_{k})^{2}}{(\nabla f_{k}^{T}Q\nabla f_{k})}$$

(3) The definition of the weight norm:  $||x||_Q^2 = x^T Q x$ , therefore

$$||x_k - x^*||_Q^2 = (x_k - x^*)^T Q(x_k - x^*)$$

$$= (x_k - x^*) T(QQ^{-1}) Q(x_k - x^*)$$

$$= (Q(x_k - x^*))^T Q^{-1} Q(x_k - x^*)$$

$$= \nabla f_k^T Q^{-1} \nabla f_k$$

Since Q is symmetric and nonsingular.

(4) Now we turn to prove (3.28) by using the result of (2) and (3).

$$||x_{k+1} - x^*||_Q^2 = ||x_k - x^*||_Q^2 - \frac{(\nabla f_k^T \nabla f_k)^2}{(\nabla f_k^T Q \nabla f_k)}$$

$$= ||x_k - x^*||_Q^2 - \frac{(\nabla f_k^T \nabla f_k)^2}{(\nabla f_k^T Q \nabla f_k)(\nabla f_k^T Q^{-1} \nabla f_k)} (\nabla f_k^T Q^{-1} \nabla f_k)$$

$$= (1 - \frac{(\nabla f_k^T \nabla f_k)^2}{(\nabla f_k^T Q \nabla f_k)(\nabla f_k^T Q^{-1} \nabla f_k)}) ||x_k - x^*||_Q^2$$

Therefore the proof is completed.

Exercise 8. Let Q be a positive definite symmetric matrix. Prove that for any vector x, we have

$$\frac{(x^T x)^2}{(x^T Q x)(x^T Q^{-1} x)} \ge \frac{4\lambda_n \lambda_1}{(\lambda_n + \lambda_1)^2}$$

where  $\lambda_n$  and  $\lambda_1$  are, respectively the largest and smallest eigenvalues of Q. (This relation, which is known as the Kantorovich inequality, can be used to deduce (3.29) from (3.28).)

*Proof.* Since Q is positive definite and symmetric, we have eigenvalue decompsition  $Q = U\Lambda U^T$ . Let x = Uy. Then

$$\frac{(x^Tx)^2}{(x^TQx)(x^TQ^{-1}x)} = \frac{(y^Ty)^2}{(y^T\Lambda y)(y^T\Lambda^{-1}y)} = \frac{(\sum_{i=1}^n y_i^2)^2}{(\sum_{i=1}^n \lambda_i y_i^2)(\sum_{i=1}^n y_i^2/\lambda_i)}$$

Let  $\eta_i = \frac{y_i^2}{\sum_{j=1}^n y_j^2}$  and  $f(\lambda) = \frac{1}{\lambda}$ . Then

$$\frac{(x^T x)^2}{(x^T Q x)(x^T Q^{-1} x)} = \frac{1}{(\sum_{i=1}^n \lambda_i \eta_i)(\sum_{i=1}^n f(\lambda_i) \eta_i)}$$

Let 
$$\lambda = \sum_{i=1}^{n} \lambda_i \eta_i$$
,  $\lambda_f = \sum_{i=1}^{n} f(\lambda_i) \eta_i$   
Since  $\eta_i \ge 0 \quad \forall i \text{ and } \sum_{i=1}^{n} \eta_i = 1, \lambda_1 \le \lambda \le \lambda_n$ 

Write  $\lambda_i = \frac{\lambda_n - \lambda_i}{\lambda_n - \lambda_1} \lambda_1 + \frac{\lambda_i - \lambda_1}{\lambda_n - \lambda_1} \lambda_n$ . This shows  $\lambda_i$  is a convex combination of  $\lambda_1$  and  $\lambda_n \quad \forall i$  f is convex  $f(\lambda_i) \leq \frac{\lambda_n - \lambda_i}{\lambda_n - \lambda_1} f(\lambda_1) + \frac{\lambda_i - \lambda_1}{\lambda_n - \lambda_1} f(\lambda_n)$ 

Therefore.

$$\lambda_{f} \leq \sum_{i=1}^{n} \left[ \frac{\lambda_{n} - \lambda_{i}}{\lambda_{n} - \lambda_{1}} f(\lambda_{1}) + \frac{\lambda_{i} - \lambda_{1}}{\lambda_{n} - \lambda_{1}} f(\lambda_{n}) \right] \eta_{i} = \sum_{i=1}^{n} \left[ \frac{\lambda_{n} - \lambda_{i}}{\lambda_{n} - \lambda_{1}} \frac{1}{\lambda_{1}} + \frac{\lambda_{i} - \lambda_{1}}{\lambda_{n} - \lambda_{1}} \frac{1}{\lambda_{n}} \right] \eta_{i}$$

$$= \sum_{i=1}^{n} \frac{\eta_{i}}{\lambda_{n} - \lambda_{1}} \left[ \frac{\lambda_{n} - \lambda_{i}}{\lambda_{1}} + \frac{\lambda_{i} - \lambda_{1}}{\lambda_{n}} \right] = \sum_{i=1}^{n} \frac{\eta_{i}}{\lambda_{n} - \lambda_{1}} \left[ \frac{\lambda_{n}^{2} - \lambda_{i}\lambda_{n} + \lambda_{i}\lambda_{1} - \lambda_{1}^{2}}{\lambda_{n}\lambda_{1}} \right]$$

$$= \sum_{i=1}^{n} \frac{\eta_{i}}{\lambda_{n} - \lambda_{1}} \left[ \frac{(\lambda_{n} + \lambda_{1})(\lambda_{n} - \lambda_{1}) - \lambda_{i}(\lambda_{n} - \lambda_{1})}{\lambda_{n}\lambda_{1}} \right] = \sum_{i=1}^{n} \frac{\lambda_{n} + \lambda_{1}1 - \lambda_{i}}{\lambda_{n}\lambda_{1}} \eta_{i}$$

$$= \frac{\lambda_{n} \sum_{i=1}^{n} \eta_{i} + \lambda_{1} \sum_{i=1}^{n} \eta_{i} - \sum_{i=1}^{n} \lambda_{i}\eta_{i}}{\lambda_{n}\lambda_{1}} = \frac{\lambda_{n} + \lambda_{1} - \lambda_{1}}{\lambda_{n}\lambda_{1}}$$

We conclude that

$$\frac{(x^T x)^2}{(x^T Q x)(x^T Q^{-1} x)} = \frac{1}{\lambda \lambda_f} \ge \frac{\lambda_n \lambda_1}{\lambda(\lambda_n + \lambda_1 - \lambda)} \ge \frac{\lambda_n \lambda_1}{\max_{\lambda \in [\lambda_1, \lambda_n]} \lambda(\lambda_n + \lambda_1 - \lambda)}$$

Let  $g(\lambda) = \lambda(\lambda_n + \lambda_1 - \lambda) = -\lambda^2 + (\lambda_n + \lambda_1)\lambda$ . Then  $g(\lambda)$  has maxmun at  $\bar{\lambda} = \frac{\lambda_n + \lambda_1}{2} \in [\lambda_1, \lambda_n]$ .

$$g(\bar{\lambda}) = -\frac{(\lambda_n + \lambda_1)^2}{4} + \frac{(\lambda_n + \lambda_1)^2}{2} = \frac{(\lambda_n + \lambda_1)^2}{4}$$

This implies that

$$\frac{(x^T x)^2}{(x^T Q x)(x^T Q^{-1} x)} \ge \frac{\lambda_n \lambda_1}{g(\bar{\lambda})} = \frac{4\lambda_n \lambda_1}{(\lambda_n + \lambda_1)^2}$$

Exercise 13. Show that the quadratic function that interpolates  $\phi(0)$ ,  $\phi'(0)$ , and  $\phi(\alpha_0)$  is given by (3.57). Then, make use of the fact that the sufficient decrease condition (3.6a) is not satisfied at  $\alpha(0)$  to show that this quadratic has positive curvature and that the minimizer satisfies

$$\alpha_1 < \frac{\alpha_0}{2(1-c_1)}.$$

Since  $c_1$  is chosen to be quite small in practice, this inequality indicates that  $\alpha_1$  cannot be much greater than  $\frac{1}{2}$  (and may be smaller), which gives us an idea of the new step length.

*Proof.* By assuming a quadratic function

$$\phi_q(\alpha) = a\alpha^2 + b\alpha + c$$

and solving coefficients through standard calculations, we have

$$\phi_q(0) = c = \phi(0).$$

Also, since

$$\phi_a'(\alpha) = 2a\alpha + b,$$

we find

$$\phi_a'(0) = b = \phi'(0).$$

On the other hand,

$$\phi_q(\alpha_0) = \phi(\alpha_0) = a\alpha_0^2 + \phi'(0)\alpha_0 + \phi(0),$$

we obtain

$$a = \frac{\phi(\alpha_0) - \phi(0) - \phi'(0)\alpha_0}{\alpha_0^2}.$$

By assumptions, we now discuss a senario that (3.6a) is not satisfied at  $\alpha_0$ . Thus we have

$$\phi(\alpha_0) > \phi(0) + c_1 \alpha_0 \phi'(0).$$

Hence, a minor manipulation of this inequality gives

$$a = \frac{\phi(\alpha_0) - \phi(0) - \phi'(0)\alpha_0}{\alpha_0} > 0,$$

which guarantees that the quadratic has positive curvature. Moreover, since the minimizer of a quadratic is -b/2a, we obtain

$$\alpha_{1} = \frac{-b}{2a} = \frac{-\alpha_{0}^{2}\phi'(0)}{2[\phi(\alpha_{0}) - \phi(0) - \phi'(0)\alpha_{0}]}$$

$$= \frac{\alpha_{0}}{2[1 - \frac{\phi(\alpha_{0}) - \phi(0)}{\alpha_{0}\phi'(0)}]}$$

$$\leq \frac{\alpha_{0}}{2(1 - c_{1})},$$

where the second equality holds by dividing  $-\alpha_0\phi'(0)$  both upper and lower sides, and the last inequality follows from the given senario.