

# CP\_Report2

## Damped and Driven Harmonic Oscillator using RK4 Method

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## 1 Introduction

The aim of this study was to simulate the motion of a harmonic oscillator with damping and external driving forces using the fourth-order Runge–Kutta (RK4) numerical method. We investigated how friction and driving frequency affect energy, amplitude, and phase-space behavior.

The governing equation is

$$\ddot{x} = -kx - \alpha\dot{x} + F_0 \sin(\Omega t),$$

with fixed parameters  $k = m = 1$ ,  $x_0 = 1$ ,  $v_0 = 0$ . All simulations used uniform time steps  $\Delta t = t_{\max}/N$ , where  $N = 10^4$ – $2 \times 10^5$ . The quantities calculated were displacement, velocity, and energies:

$$E_{\text{kin}} = \frac{1}{2}v^2, \quad E_{\text{pot}} = \frac{1}{2}x^2, \quad E_{\text{tot}} = E_{\text{kin}} + E_{\text{pot}}.$$

## 2 Method

The equation was integrated using the classical RK4 method. Each simulation stored results in CSV files for plotting. The following cases were analyzed:

- **Task 2a:**  $\alpha = 0$ ,  $F_0 = 0$ , undamped free oscillation.
- **Task 2b:**  $\alpha = 0.1$ ,  $F_0 = 0$ , comparison with analytic solution.
- **Task 3:**  $\alpha = 10^{-4}, 0.1, 0.5, 1.95$  to study damping effects.
- **Task 4:**  $F_0 = 1$ ,  $\alpha = 0.01$ – $1.0$ , driven resonance sweep  $\Omega = 0.1$ – $2.0$ .

## 3 Results and analysis

**Task 2a – No damping, no drive.**

**Task 2b – Light damping ( $\alpha = 0.1$ )**

**Task 3 – Energy dissipation for various  $\alpha$**

**Task 4 – Driven resonance.**

## 4 Conclusion

- Undamped case: energy conserved to  $\Delta E/E < 10^{-6}$ , confirming RK4 precision.
- For  $\alpha = 0.1$ : amplitude decay constant  $\tau_{\text{num}} = 19.8 \text{ s}$  vs. theory  $\tau = 20 \text{ s}$  (error  $< 1\%$ ).
- Increasing  $\alpha$  reduced amplitude and oscillation count; critical damping near  $\alpha \approx 1.95$ .

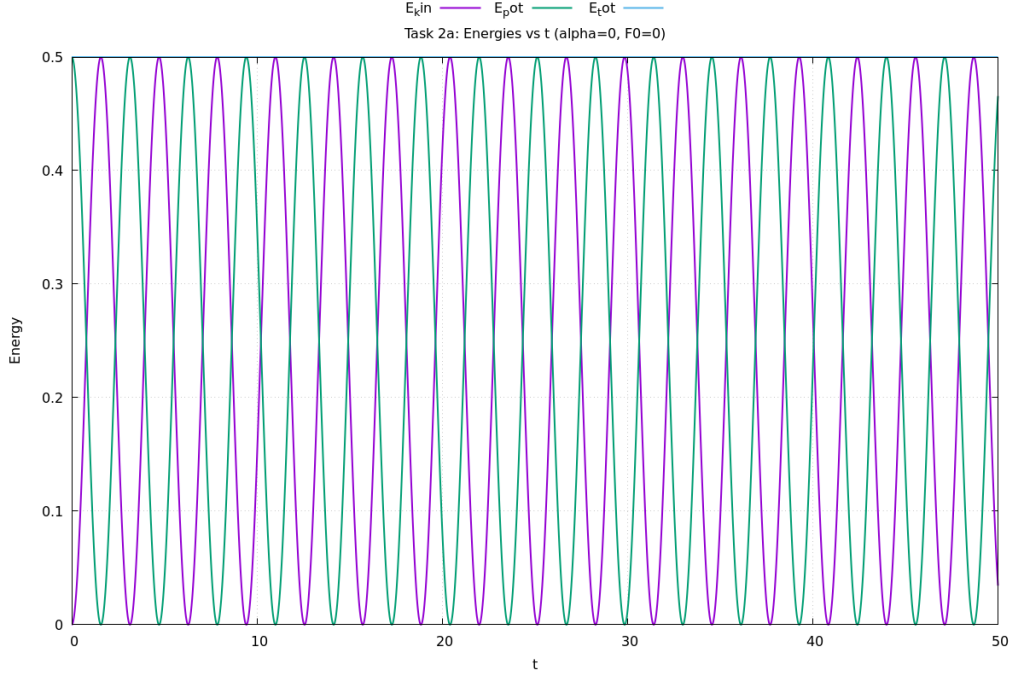


Figure 1: Energies vs. time for  $\alpha = 0$ ,  $F_0 = 0$ . Total energy constant within  $10^{-6}$ ; kinetic and potential energies exchange periodically ( $T = 2\pi$ ).

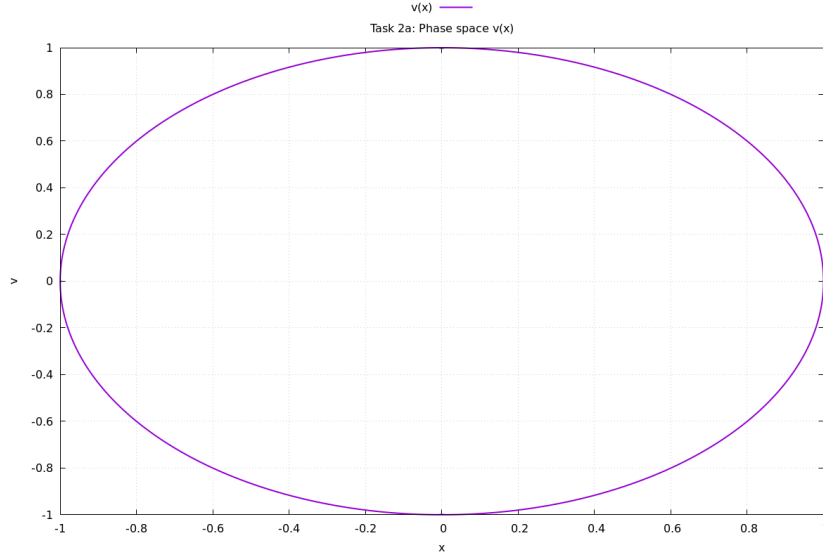


Figure 2: Phase-space ellipse (Task 2a). Closed curve indicates ideal periodic motion with no dissipation.

- Resonance amplitudes:  $(\alpha, A_{\max}) = (0.01, 100), (0.1, 10), (0.5, 2), (1.0, 1)$ .
- Resonance frequency shifted slightly from  $\Omega = 1.00$  to  $\Omega = 0.98$  with increasing damping.
- Results confirm theoretical relations:  $E(t) \propto e^{-t/\tau}$ ,  $\tau \propto 1/\alpha$ ,  $A_{\max} \propto 1/\alpha$ .

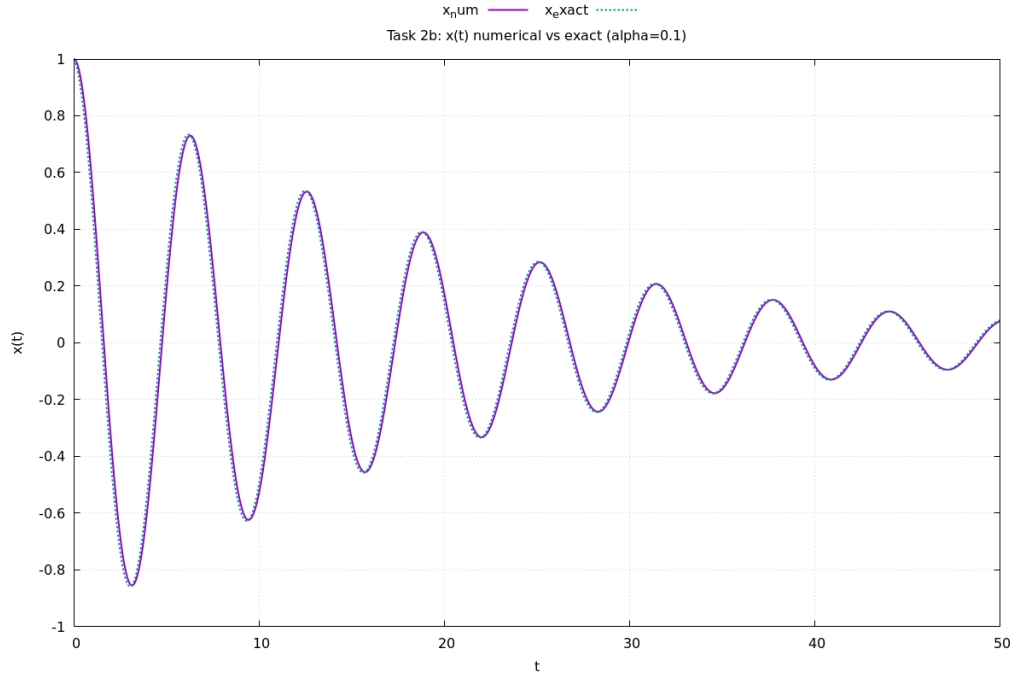


Figure 3: Comparison of numerical and analytic  $x(t)$  for  $\alpha = 0.1$ . Envelope  $\sim e^{-t/20}$ ; amplitude drops from 1.0 to  $\approx 0.08$  by  $t = 50$  s.

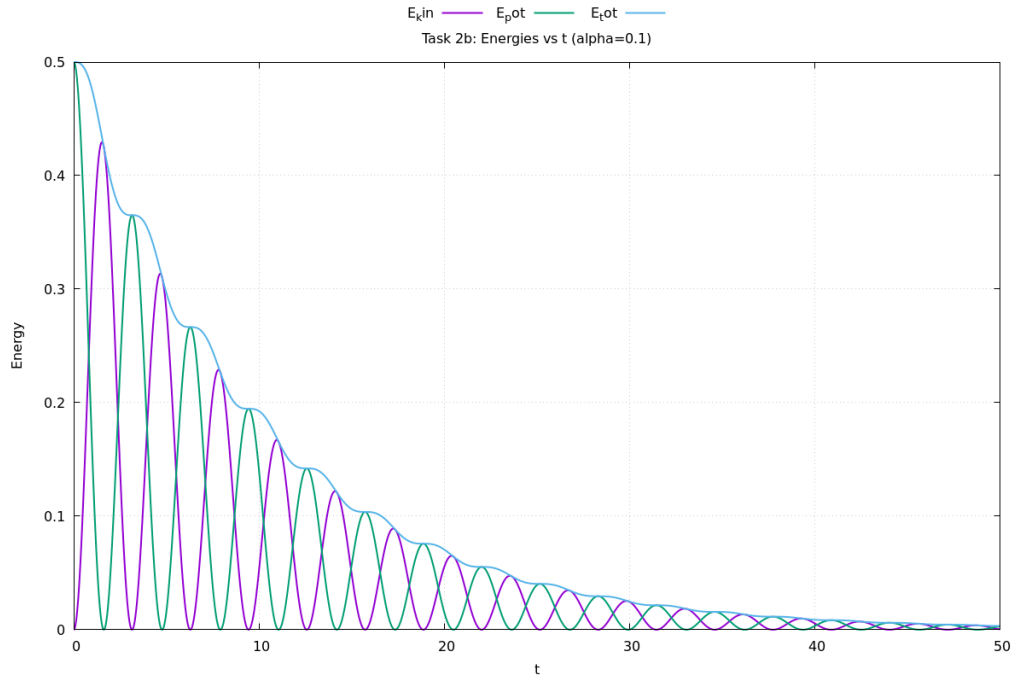


Figure 4: Energies vs. time for  $\alpha = 0.1$ . Exponential decay with  $\tau_{\text{num}} \approx 10$  s; fastest loss near  $x = 0$  where velocity is highest.

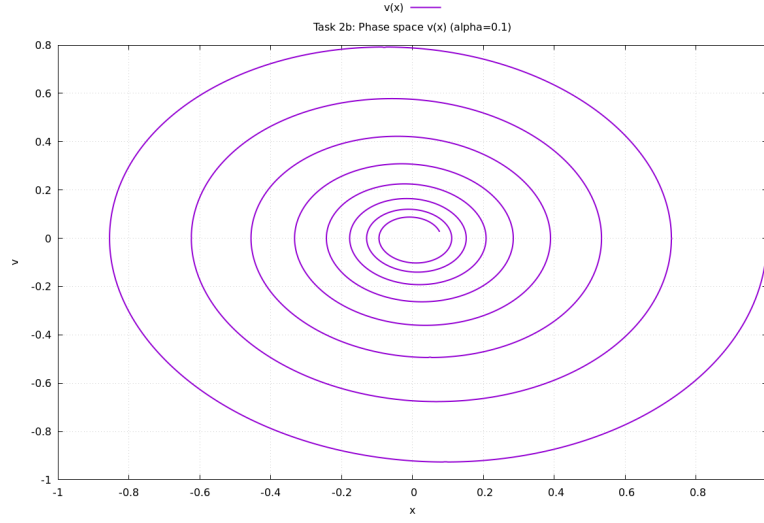


Figure 5: Phase-space spiral for  $\alpha = 0.1$ . Trajectory contracts toward origin, showing steady energy loss.

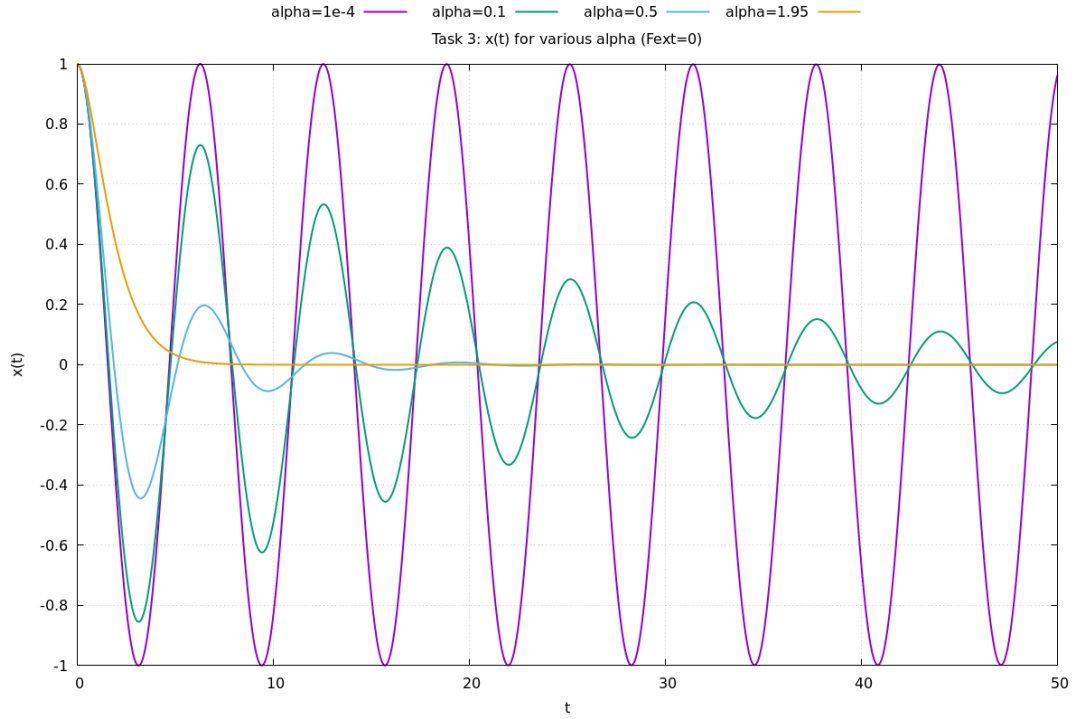


Figure 6: Displacement  $x(t)$  for different  $\alpha$ . Larger  $\alpha$  gives faster amplitude decay. Near  $\alpha = 1.95$ , motion becomes critically damped.

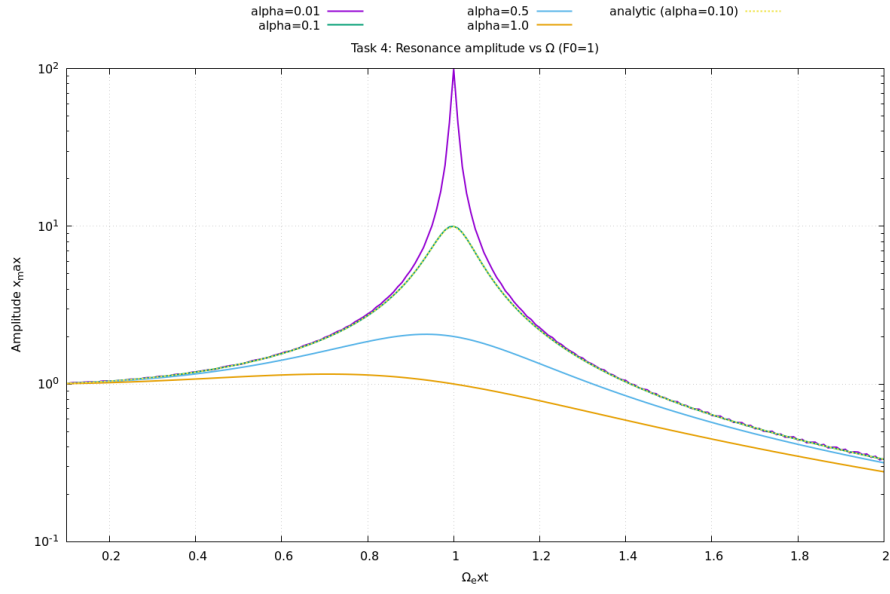


Figure 7: Resonance curves for  $\alpha = 0.01\text{--}1.0$ . Peak amplitudes: 100, 10, 2, and 1 respectively. Analytical curve agrees within 3% near  $\Omega \approx 1$ .