

Storing large amounts of Data

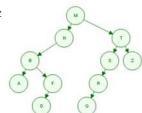
- B Trees, B+ Trees: data structures and algorithms for
 - large data
 - stored on disk (ie, slow access)
- File systems:
 - Lots of files, each file stored as lots of blocks.
- Databases:
 - large tables of data
 - each indexed by a key (or perhaps multiple alternative keys)

Problem:

- How do we access the data efficiently:
 - individual items (given key)
 - sequence of all items (preferably in order)
 - assume data is stored in files on hard drives (slow access time)
- Use some kind of index structure
 - assume the index is also stored in a file

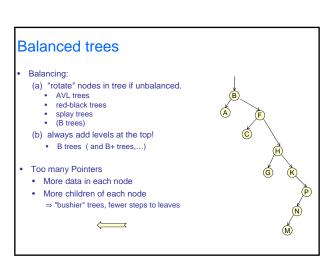
COMP103 approaches:

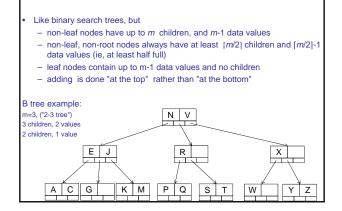
- Efficient Set and Map implementations:
 - Hash Tables.
 - Binary Search Tree
- http://www.cs.usfca.edu/~galles/visualization
- Binary search tree
 - Add MHTSRQBAFDZ



- Search: Log(n)

Problems with Binary Search - Unbalanced trees are inefficient ⇒ must keep the tree balanced • AVL trees: self-balanced by tree rotations • red-black trees: node with a color bit • splay trees: move recently access node to the roof • B trees - lots of pointer following ⇒ if each node is stored in a file, this will be slow!



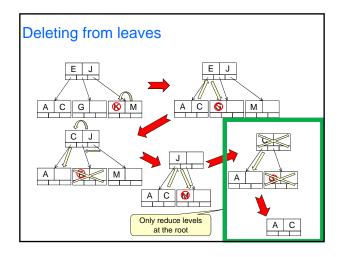


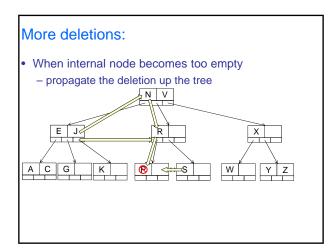
B Trees

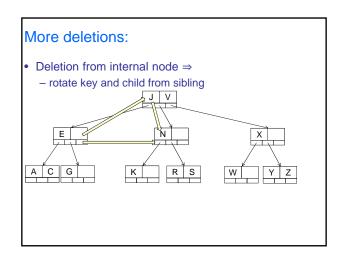
2-3 trees • Every internal node is a 3-node or a 2-node - 3-node: 3 children, 2 values - 2-node: 2 children, 1 value All leaves are at the same level - Leaf node has 1 or 2 values All data is kept in sorted order B Trees: Search Data values might be - single items (set of values) key:value pairs (map) Search(key, node): - Just like binary search, but more comparisons at each node: if node is null return fail **for** i = 0 to k-1 (k is number of keys in node) if key < keys[i]</pre> return search(key, children[i]) A C G K M if key == keys[i] return value[i] return search(key, children[k]) B Trees: Insert To insert item (eg key:value pair): Search for leaf where the item should be. If leaf is not full, add item to the leaf. If leaf is full: Identify the middle item (existing item or the new item) Create a new leaf node: retain items before middle key in original node put items after middle key in new leaf node, push item up to parent, along with pointer to new node To add new item to parent: if parent is not full: add new item to parent, and add new child pointer just right of new item

else: split parent node into two nodes (like leaf)
push middle item up to grandparent.
add pointer to new child just right of pushed up item

2-3 B Tree: Inserting values • Add MHTSRQBAFDZ M s http://www.cs.usfca.edu/~galles/visualization/BTree.html 2-3 B Tree: Inserting values Add 8, 5, 1, 7, 3,12, 9, 6 http://www.cs.usfca.edu/~galles/visualization/BTree.html 2-3 BTree: Deletion Opposite of inserting: if a node becomes empty, if possible, rotate a value from a sibling through the parent to ensure minimum number of values per node. if two siblings, require >= 5 keys in parent and siblings if one sibling, require >=3 keys in parent and siblings else merge nodes: - if two siblings, merge - Easier at a leaf. - Harder if at an internal node.







Analysis • B trees are balanced: - A new level is introduced only at the top - A level is removed only from the top Therefore: • all leaves are at the same level. • Cost of search/add/delete: • O(log_[m/2](n)) (at worst) = depth of tree with all half full nodes • O(log_m(n)) (at best) = depth of tree with full nodes • of 100 million items in a B tree with m = 20, log₁₀(10,000,000) = ? 8 log₂₀(10,000,000) = ? 6.14 • if billion items in a B tree with m = 100, log₅₀(1,000,000,000) = ? 5.3 log₁₀₀(1,000,000,000) = ? 4.5