

Theory of statistics and probability

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1 Statistics

The dichotomy of Bayesian and Frequentist approach is mostly a matter of division based on foundational philosophical differences, and in some situation is not necessarily natural; each instance can be formally simply seen as a choice of analysis. The dichotomy has mainly developed based on two philosophical school of thoughts: subjective belief (via prior distribution) vs. long-run frequency (via sampling distribution). Frequentist

- They avoid making probabilistic claims about model parameters and hypothesis. Instead, they describe the behavior of statistics and procedures over many hypothetical repeated samples.
- They use Statistics derived from data, and use deterministic approach for inference, with methods like hypothesis testing and confidence intervals to draw conclusions about population parameters based on sample data.
- examples: T-test, linear regression, etc

Bayesian

- They assign prior beliefs (distribution function) on parameters of model.
- They use probabilistic argument on specific hypothesis or parameter values.
- examples: MCMC, Bayesian hierarchical modeling, etc

2 Probability Theory

Definition 1. *Distribution Function (F)*: A function $F : \mathbb{R} \rightarrow [0, 1]$ that:

1. Is non-decreasing.
2. Is right-continuous.
3. Limits to 0 as $x \rightarrow -\infty$ and 1 as $x \rightarrow \infty$.

Random Variable (X): A measurable function $X : \Omega \rightarrow \mathbb{R}$ where:

1. Ω is a sample space equipped with a probability measure.
2. \mathbb{R} is the real line equipped with the Lebesgue measure.

Probability Measure (P): A measure defined on a sample space Ω whose total measure is 1.

Distribution (D): Given a random variable X , its distribution is the measure induced by X on \mathbb{R} .

Density Function (f): For a random variable X , its density function f is any measurable function that satisfies:

$$\Pr(X \in A) = \int_A f d\mu$$

for every measurable set $A \subset \mathbb{R}$, where μ is the Lebesgue measure.

There are several theorems/properties that look trivial but are not really trivial.

- The Skorokhod Representation Theorem states that for every CDF, there exists a canonical probability space and a random variable on that space with the given CDF.
- Kolmogorov's Existence theorem states that given finite dimensional sets of distribution, under some conditions, there exists a canonical probability space with random variables whose corresponding distributions coincide with our original distributions.
- The existence of distribution function does not guarantee the existence of density function. By Radon-Nikodym, there is a nice characterization when this happens: when distribution (which is a measure defined on \mathbb{R}) corresponding to distribution function is absolutely continuous with respect to Lebesgue measure.
- The existence of distribution function guarantees the existence of distribution, and vice versa.
- Thus, Kolmogorov's existence theorem is more general than Skorokhod Representation theorem.

Throughout the theory of probability, we usually assume that the probability measure is complete, because of the following proposition.

Proposition 1. *Let us assume that probability measure is complete. Let $X_t = Y_t$ almost everywhere for every $t \geq 0$. Then there exists $\tilde{Y}_t = Y_t$ almost everywhere for every t such that $X_t(w) = \tilde{Y}_t(w)$ for every $w \in P$ for every t for measurable set P whose measure is 1.*