

Part 1 summary & Part 2

key definition

- 1) Macroscopic parameter: para which can be determined by large-scale measurements
- 2) Macrostate: state of the system described without attention to the microscopic detail.
- 3) Microstate: a state described in microscopic detail by the most complete specification.
- 4) Equilibrium: A macroscopic state which don't tend to change in time.

Equilibrium:

1. time-independent: average value of the macroscopic parameter remain \bar{C} in time.
2. the equilibrium state: most random macrostate.
3. independent of its past history
4. random \Rightarrow can be defined with very few macroscopic parameters.

Second law of Thermodynamics (P V)

An isolated system in non-random situation
 \Rightarrow evolve in time so as to approach ultimately
its most random situation. (equilibrium)

Probability basics

$P_r \equiv \frac{N_r}{N}$ (the probability of occurrence of
outcome r).

Statistical ensembles: an ensemble
consisting of a very large number N of
"similar systems"

"Time average" & "ensemble average"

the system is in equilibrium.

Start from a "typical" point \Rightarrow the point of
a moving system will eventually visit all parts
of the space. In free motion of particle

of the spins almost satisfy the condition. so the behavior of a particle can be equal with ensemble average.

$$\sum_{r=1}^n P_r = 1$$

$$P(r=i \text{ or } r=j) = P_i + P_j$$

$$P_{rs} = P_r \cdot P_s$$

$$\overline{f(u)} = \sum f(u_i) P_i$$

$$\overline{f+g} = \bar{f} + \bar{g}$$

$$\overline{cf(u)} = c \overline{f(u)}$$

in dependent variables, $\Rightarrow \overline{f(u) g(u)} = \bar{f} \cdot \bar{g}$

$$\begin{aligned} \sum \sum f(u_i) g(u_j) \cdot P_{ij} & \quad P_{ij} = P_i P_j \\ &= \sum f(u_i) P_i \sum g(u_j) P_j = \bar{f} \cdot \bar{g} \end{aligned}$$

$$N=4 \quad \text{ident spin } \frac{1}{2}$$

$$h \approx 1/\sim \quad \sim 1/\sim$$

$$M = \mu_1 + \mu_2 + \dots + \mu_n$$

$$M = 2, 1, 0, -1, -2 \quad \text{with} \quad \mu_i \quad i=1, 2, 3, 4, 5$$

$$\bar{m} = \sum \mu_i$$

$$\begin{aligned} \overline{(M - \bar{m})^2} &= \overline{M^2} - (\bar{m})^2 \\ &= \left(\frac{C_0^0}{2^4} \cdot 4 + \frac{C_0^1}{2^0} \cdot 1 \right) \cdot 2 - 0 \\ &= 2 \left(\frac{1}{4} + \frac{1}{2} \right) = \frac{3}{2} \cdot 2 = 3 \end{aligned}$$

$$D = \sqrt{(M - \bar{m})^2} = \Delta M = \frac{\sqrt{3}}{2}$$

$$p, q \quad \bar{n} = ap + bq$$

$$\bar{m} = \sum_{i=0}^n C_n^i p^{n-i} q^i (ib + (n-i)a)$$

$$= (b-a) \sum_{i=0}^n C_n^i i p^{n-i} q^i$$

$$i C_n^i = \frac{n!}{(i-1)!(n-i)!} = n \frac{(n-i)!}{(i-1)!(n-i)!}$$

$$= np \sum_{i=0}^{n-1} C_{n-i}^i p^{n-i} q^i (b-y)$$

$$+ nq = n(pb + (1-p)q)$$

$$= n \bar{\mu} \Rightarrow n \bar{\mu} = \bar{\mu}$$

$$\text{Also } \text{Var}(K) N = \text{Var}(N)$$